Regulations and Curriculum for Master of Technology (M. Tech.) in <u>Electric Vehicle Technology</u>



(Deemed to be University under Section 3 of UGC Act, 1956) (Placed under Category 'A' by MHRD, Govt. of India, Accredited with 'A+' Grade by NAAC) University Enclave, Medical Sciences Complex, Deralakatte, Mangalore – 575 018, Karnataka INDIA Tel: +91-824-2204300/01/02/03, Fax: 91-824-2204305 Website: www.nitte.edu.in E-mail: info@nitte.edu.in

REGULATIONS GOVERNING THE DEGREE OF MASTER OF TECHNOLOGY (M.Tech.)

UNDER OUTCOME BASED EDUCATION (OBE)

AND

CHOICE BASED CREDIT SYSTEM (CBCS) SCHEME

OF

NMAM INSTITUTE OF TECHNOLOGY, NITTE

(Effective from academic year 2022 -23)

VISION

To build a humane society through excellence in the education and healthcare

MISSION

To develop

Nitte (Deemed to be University) As a centre of excellence imparting quality education, Generating competent, skilled manpower to face the scientific and social challenges with a high degree of credibility, integrity, ethical standards and social concern



Off-campus Centre, Nitte (Deemed to be University) NITTE-574110, Karkala Taluk, Udupi District, Karnataka, India

Vision Statement

Pursuing Excellence, Empowering people, Partnering in Community Development

Mission Statement

To develop N.M.A.M. Institute of Technology, Nitte, as Centre of Excellence by imparting Quality Education to generate Competent, Skilled and Humane Manpower to face emerging Scientific, Technological, Managerial and Social Challenges with Credibility, Integrity, Ethics and Social Concern.

M. Tech. Regulations and Curriculum

Batch 2022 – 2024

With Scheme of Teaching & Examination

REGULATIONS: 2022 for M. Tech. Programs (Academic year 2022-23)

COMMON TO ALL M.Tech. DEGREE PROGRAMS CHOICE BASED CREDIT SYSTEM (CBCS)

Key Information

Program Title	Master of Technology, abbreviated as
	M.Tech. (Electric Vehicle Technology)
Short description	Two-year, four semester Choice Based Credit System (CBCS) type
	of Postgraduate Engineering Degree Program with English as
	medium of instruction
Program Code	22ENGR15D2
Revision version	2022.02
	These regulations may be modified from time to time as mandated
	by the policies of the University. Revisions are to be recommended
	by the Board of Studies for Electrical & Electronics Engineering
	and approved by the Academic Council.
Effective from	12-09-2022
Approvals	• Approved in the 50 th meeting of Academic Council of NITTE
	(Deemed to be University), held on 30-05-2022 and vide
	Notification of NITTE (DU), N(DU)/REG/N-MCE/2022-
	23/76B dated 19-08-2022.
	• Notification of Nitte (DU), N(DU)/REG/AC/-SA/2022-23/909
	dated 24-04-2023.
Program offered at	NMAM Institute of Technology, Nitte Off Campus centre, Nitte
	(Deemed to be University)
Grievance and	All disputes arising from this set of regulations shall be addressed to
dispute resolution	the Board of Management. The decision of the Board of
	Management is final and binding on all parties concerned. Further,
	any legal disputes arising out of this set of regulations shall be
	limited to jurisdiction of Courts of Mangalore only



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1. INTRODUCTION:

- 1.1 The general regulations are common to all Degree of Master of Technology Program under Outcome Based Education (OBE) and Choice Based Credit System (CBCS) conducted by Nitte (Deemed to be University), at the NMAM Institute of Technology, Nitte off Campus Centre and shall be called "Nitte (DU) Regulations for M.Tech.- 2022".
- **1.2** The provisions contained in this set of regulations govern the policies and procedures on the Registration of students, imparting Instructions of course, conducting of the examination and evaluation and certification of students' performance and all amendments there to leading to the said degree program(s)
- 1.3 This set of Regulations, on approval by the Academic Council and Governing Council, shall supersede all the corresponding earlier sets of regulations of the M.Tech. Degree program (of Nitte (DU)) along with all the amendments thereto, and shall be binding on all students undergoing M.Tech. Degree Program (s) (Choice Based Credit System) conducted at the NMAMIT, Nitte with effect from its date of approval and is applicable for students admitted to 1st year after September 2022. This set of regulations may evolve and get modified or changed through appropriate approvals from the Academic Council / Governing Council from time to time, and shall be binding on all stake holders, (the Students, Faculty, Staff of Departments of NMAMIT, Nitte). The decision of the Academic Council/ Governing Council shall be final and binding.
- **1.4** In order to guarantee fairness and justice to the parties concerned in view of the periodic evolutionary refinements, any specific issues or matters of concern shall be addressed separately, by the appropriate authorities, as and when found necessary.
- **1.5** The Academic Council may consider any issues or matters of Concern relating to any or all the academic activities of the NMAMIT courses for appropriate action, irrespective of whether a reference is made here in this set of Regulations or otherwise.
- 1.6 The course shall be called Master of Technology program abbreviated as M.Tech. (subject of specialization) Choice Based Credit System.
- 2. **DEFINITIONS OF KEYWORDS:** The following are the definitions/descriptions that have been followed for the different terms used in the Regulations of M.Tech. Programs:



- **2.1 Program:** Is an educational program in a particular stream/branch of Engineering/branch of specialization leading to award of Degree. It involves events/activities, comprising of lectures/ tutorials/ laboratory work/ field work, outreach activities/ project work/ vocational training/ viva/ seminars/ Internship/ assignments/ presentations/ self-study etc., or a combination of some of these.
- **2.2 Branch:** Means Specialization or discipline of M. Tech Degree Program, like Electrical Vehicle Technology, Structural Engineering, Machine Design, etc.
- **2.3 Semester:** Refers to one of the two sessions of an academic year (vide: serial number 4), each session being of sixteen weeks duration (with working days greater than or equal to 90). The odd semester may be scheduled from August/September and even semester from February/March of the year.
- **2.4** Academic Year: Refers to the sessions of two consecutive semesters (odd followed by an even) including periods of vacation.
- 2.5 Course: Refers to usually referred to as 'subjects' and is a component of a program. All Courses need not carry the same credit weightage. The Courses should define learning objectives and learning outcomes. A Course may be designed to comprise lectures/ tutorials/ laboratory work/ field work/ outreach activities/ project work/ vocational training/ viva/ seminars/ term papers/ assignments/ presentations/ selfstudy etc.. or a combination of some of these.
- **2.6 Credit:** Refers to a unit by which the Course work is measured. It determines the number of hours of instructions required per week. One credit is equivalent to one hour of lecture or two hours of laboratory/ practical Courses/ tutorials/ fieldwork per week etc.
- 2.7 Audit Courses: Means Knowledge/ Skill enhancing Courses without the benefit of credit for a Course.
- **2.8 Choice Based Credit System (CBCS):** Refers to customizing the Course work, through Core, Elective and soft skill Courses, to provide necessary support for the students to achieve their goals.
- **2.9 Course Registration:** Refers to formal registration for the Courses of a semester (Credits) by every student under the supervision of a Faculty Advisor (also called Mentor, Counsellor etc.,) in each Semester for the Institution to maintain proper record.
- **2.10 Course Evaluation:** Means Continuous Internal Evaluation (CIE) and Semester End Examinations (SEE) to constitute the major evaluations prescribed for each



Course. CIE and SEE to carry 50 % and 50 % respectively, to enable each Course to be evaluated for 100 marks, irrespective of its Credits.

- **2.11 Continuous Internal Evaluation (CIE):** Refers to evaluation of students' achievement in the learning process. CIE shall be by the Course Instructor and includes tests, homework, problem solving, group discussion, quiz, mini-project and seminar throughout the Semester, with weightage for the different components being fixed at the University level.
- **2.12 Semester End Examinations (SEE):** Refers to examination conducted at the University level covering the entire Course Syllabus. For this purpose, Syllabi to be modularized and SEE questions to be set from each module, with a choice confined to the concerned module only. SEE is also termed as university examination.
- **2.13 Make Up Examination:** Refers to examination conducted for the candidates who has a CIE>=35 marks and may have missed to attend the SEE covering the entire course syllabus. The standard of Make Up Examination is same as that of the SEE.
- 2.14 Supplementary Examination: Refers to the examination conducted to assist slow learners and/or failed students through make up courses for a duration of 8 weeks. This comprises of both the CIE & SEE and will be conducted after the completion of First year M.Tech. even semester.
- **2.15 Credit Based System (CBS):** Refers to quantification of Course work, after a student completes teaching learning process, followed by passing in both CIE and SEE. Under CBS, the requirement for awarding Degree is prescribed in terms of total number of credits to be earned by the students.
- **2.16 Credit Representation:** Refers to Credit Values for different academic activities considered, as per the Table.1. Credits for seminar, project phases, project viva–voce and internship shall be as specified in the Scheme of Teaching and Examination.

Table 1: Credit Values					
Theory/Lectures (L) (hours/week/Semester)	Tutorials (T) (hours/week/ Semester)	Laboratory /Practical (P) (hours/week/ Semester)	Credits (L: T:P)	Total Credits	
4	0	0	4:0:0	4	



3	0	0	3:0:0	3		
2	2	0	2:1:0	3		
2	0	2	2:0:1	3		
2	2	2	2:1:1	4		
0	0	2	0:0:1	1		
NOTE · Activities like	NOTE: Activities like practical training study tour and participation in Guest					

NOTE: Activities like, practical training, study tour and participation in Guest lectures not to carry any credits.

- **2.17 Letter Grade:** It is an index of the performance of students in a said Course. Grades are denoted by letters O, A+, A, B+, B, C and F.
- **2.18 Grading:** Grade refers to qualitative measure of achievement of a student in each Course, based on the percentage of marks secured in (CIE+SEE). Grading is done by Absolute Grading. The rubric attached to letter grades are as follows:

Letter	0	A+	А	B+	В	С	F
Grade							
Academic	Outstanding	Excellent	Very	Good	Above	Average	Fail
Level			Good		Average		

2.19 Grade Point (GP): Refers to a numerical weightage allotted to each letter grade on a 10-point scale as under.

Letter Grade and corresponding Grade Points on a typical 10 – Point scale							
Letter Grade	0	A+	А	B+	В	С	F
Grade Point	10	09	08	07	06	05	00

- **2.20 Passing Standards:** Refers to passing a Course only when getting GP greater than or equal to 05 (as per serial number 2.20).
- **2.21** Credit Point: Is the product of grade point (GP) and number of credits for a Course i.e., Credit points $CrP = GP \times Credits$ for the Course.
- **2.22** Semester Grade Point Average (SGPA): Refers to a measure of academic performance of student/s in a semester. It is the ratio of total credit points secured by a student in various Courses of a semester and the total Course credits taken during that semester.
- **2.23** Cumulative Grade Point Average (CGPA): Is a measure of overall cumulative performance of a student over all semesters. The CGPA is the ratio of total credit points



earned by a student in various Courses in all semesters and the sum of the total credits of all Courses in all the semesters. It is expressed up to two decimal places.

- **2.24 Grade Card:** Refers to a certificate showing the grades earned by a student. A grade card shall be issued to all the registered students after every semester. The grade card will display the program details (Course code, title, number of credits, grades secured) along with SGPA of that semester and CGPA earned till that semester.
- **2.25** University: Nitte (Deemed to be University), Mangalore. NMAM Institute of Technology is an off-campus centre of Nitte (DU) and located at Nitte.

3. CLAU	JSE
CLAUSE	PARTICULARS
22NMT1.0	DURATION AND CREDITS OF THE PROGRAM OF STUDY
	There shall be one category of program: Full-time Program (FT)
	Full-time Program: The Program shall extend over a period of four semesters
	(2 years).
	First Semester:
	i) 16 weeks – Class Work according to the scheme.
	ii) 4 weeks – Revision holidays and examinations
	iii) 2 weeks – Vacation
	Second Semester:
	i) 16 weeks – Class Work according to the scheme
	ii) 4 weeks – Revision holidays and examinations.
	Summer Semester/Vacation
	i) 4 weeks — Class work, Examination & Display of Grades
	Third Semester: 20 weeks
	i) 8 weeks — Industrial Training/Mini Project
	ii) 12 weeks — Project Part-I
	— Industrial Training/Mini Project evaluation, Seminar on Special
	Topic Evaluation & Project Part-I Evaluation
	Fourth Semester: 24 weeks
	i) 22 weeks — Project Part-II
	ii) 2 weeks – Submission, viva -voce
	Prescribed Number of Credits for the Program: 80



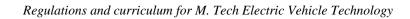
	The number of credits to be completed	for the award of Degree shall be 80.			
22NMT1.1	M.Tech Degree Programs are offered	in the following specialization and the			
	respective program hosting departments are listed below:				
	Program	<u>Department</u>			
	i) Computer Science & Engineering	Computer Science & Engineering			
	ii) Constructional Technology	Civil Engineering			
	iii) Structural Engineering	Civil Engineering			
	iv) VLSI Design & Embedded	Electronics and Communication			
	Systems	Engineering			
	v) Machine Design	Mechanical Engineering			
	vi) Energy Systems Engineering	Mechanical Engineering			
	vii) Cyber security	Computer Science Engineering			
	viii) Electric Vehicle Technology	Electrical and Electronics Engineering			
	The provisions of these Regulatio	ns shall be applicable to any new			
	specialization that may be introduced	from time to time and appended to the			
	above list.				
22NMT1.2	Maximum Duration for Program Co	mpletion:			
	A full-time candidate shall be allowed a maximum duration of 4 years from the				
	I semester of admission to become eligible for the award of master's degree,				
	failing which he/she may discontinue of register once again as a fresh candidate				
	to I semester of the program.				
22NMT2.0	ELIGIBILITY FOR ADMISSION				
	(As per the Government orders issued	from time to time):			
	Admission to I year/ I semester Master of Technology Program shall be open				
	to all the candidates who have passed I	B.E./ B. Tech. Examinations (in relevant			
	field) or any other recognized Univer-	ersity/ Institution. AMIE in respective			
	branches shall be equivalent to B.E.	/ B. Tech. Programs for admission to			
	M.Tech. The decision of the equiva	lence committee shall be the final in			
	establishing the eligibility of candidate	es for a particular Program.			
	For the foreign Degrees, Equivalence c	vertificate from the Association of Indian			
	Universities shall be a must.				
1					
22NMT2.1	Admission to M.Tech. Program shal	I be open to the candidates who have			



	marks in the aggregate of all the years of the Degree examination. Rounding
	off percentage secured in qualifying examination is not permissible.
22NMT2.2	For admissions under GATE/ NUCAT qualification
	The candidates should be GATE qualified or should have appeared for the
	NUCAT Entrance Examination conducted by Nitte (Deemed to be University)
	[Nitte (DU)]
22NMT2.3	For admissions under Sponsored Quota:
	The candidates should be GATE qualified or should have appeared for the
	NUCAT Entrance Examination conducted by Nitte (DU)
22NMT2.4	The candidates, who are qualified in the GATE Examination for the
	appropriate branch of engineering, shall be given priority. They are exempted
	from taking NUCAT Entrance Examination.
	In case a GATE qualified Candidate appears for entrance examination and
	become qualified to claim a seat under entrance examination quota, he/she will
	be considered in the order of merit along with other candidates appeared for
	the entrance examination.
22NMT2.5	If sufficient number of GATE qualified candidates are not available, the
	remaining vacant seats shall be filled from amongst the candidates appeared
	for NUCAT Entrance Examination in the order of merit.
22NMT2.6	Engineering graduates other than the Karnataka candidates shall get their
	Eligibility verified from Nitte (DU) to seek admission to M.Tech. Program at
	NMAMIT, Nitte
22NMT2.7	Admission to vacant seats: Seats remaining vacant (unfilled), after the
	completion of admission process through GATE/NUCAT Entrance Exam, the
	remaining seats shall be filled by Candidates based on merit in the entrance
	test conducted at the Institution level. An admission Committee, consisting of
	the Principal, Head of the concerned Department and the subject experts, shall
	oversee admissions.
22NMT3.0	REGISTRATION:
	Every student after consulting his Faculty-Advisor in parent department is
	required to register for the approved courses with the Departmental Post



	of each Semester on the day	ys fixed for	such registr	ation and n	otified in th		
	academic calendar.						
22NMT3.1	Lower and Upper Limits	for Course	Credits Reg	gistered in	a Semester		
	Course Credit Assignment:	:					
	All courses comprise of spec	ific Lecture/	/ Tutorial/ Pr	actical (L-T	-P) schedule		
	The course credits are fixed l	based on the	following no	orms.			
	Lecture/Tutorials/ Practical:						
	(i) a 1-hour Lect	ure per week	t is assigned	1.0 Credit.			
	(ii) a 2-hour Tuto	rial session j	per week is a	ssigned 1.0	Credit.		
	(iii) a 2-hour Lab.	session per	week is assig	gned 1.0 cre	dits		
	For example, a theory cour	rse with L-T	T-P schedule	of 3-2-0 ł	nours will b		
	assigned 4.0 credits.						
	A laboratory practical course with L-T-P schedule of 0-0-2 hours will be						
	assigned 1.0 credit.						
	Calculation of Contact Hou	Calculation of Contact Hours / Week – A Typical Example					
	Typical Academic Load (I	Typical Academic Load (I & II Semester)					
	No. of Courses	LTP	Credits	Total	Contact		
			Per course	Credits	Hours		
					per Week		
	2 Lecture Courses	4-0-0	04	08	08		
	2 Lab Courses	0-0-2	01	02	04		
	2 Lab Courses 1 Research based Course	0-0-2 0-0-4	01 02	02 02	04 04		
	1 Research based Course	0-0-4	02	02	04		
	1 Research based Course 3 Elective Courses	0-0-4 3-0-0	02 03	02 09	04 09		
	1 Research based Course3 Elective Courses1 Audit Course	0-0-4 3-0-0 2-0-0	02 03 0	02 09 0 21	04 09 02 27		
	1 Research based Course3 Elective Courses1 Audit CourseTotal: 9 Courses	0-0-4 3-0-0 2-0-0	02 03 0 culty Adviso	02 09 0 21 r, between a	04 09 02 27 minimum c		
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	of higher semesters (2 nd and above) at least two weeks before the end of the
	current semester choosing the courses offered by each department in the next
	higher semester which is displayed on the Departmental Notice Board at least
	4 weeks prior to the last working day of the semester. Students who fail to
	register on or before the specified date will have to pay a late fee. Registration
	in absentia is allowed only in exceptional cases with the permission of the Dean
	(Academic).
	Registration to a higher semester is allowed only if the student fulfills the
	following conditions-
	i) Satisfied all the academic requirements to continue with the program of
	studies without termination
	ii) Cleared all institute, hostel and library dues and fines, if any, of the
	previous semester.
	iii) Paid all required advance payments of the Institute and the hostel for the
	current semester.
	Has not been debarred from registering on any specific grounds by the Institute.
22NMT3.3	Course Pre-Requisites:
	In order for a student to register for some course(s), it may be required either
	to have completed satisfactorily or to have prior earned credits in some
	specified course(s). In such instances, the DPGC shall specify clearly, any such
	course pre-requisites, as part of the curriculum.
22NMT3.4	Students who do not register before the dead line day of registration may be
	permitted LATE Registration up to the notified day in academic calendar on
	payment of late fee.
22NMT3.5	REGISTRATION in ABSENTIA will be allowed only in exceptional cases on
	the recommendation of DPGC through the authorized representative of the
	student.
22NMT3.6	Medium of Instruction/Evaluation/etc. shall be English.
22NMT4.0	COURSES:
	The curriculum of the Program shall be any combination of following type of
	courses:
	i) Professional Core Courses (PCC) - relevant to the chosen
	specialization/ branch [May be split into Hard (no choice) and Soft (with



choice), if required]. The core course is to be compulsorily studied by a student and is mandatory to complete the requirements of a program in a said discipline of study.

- ii) Professional Electives Courses (PEC) relevant to the chosen specialization/ branch: these are the courses, which can be chosen from the pool of papers. It shall be supportive to the discipline/ providing extended scope/enabling an exposure to some other discipline / domain / nurturing student skills.
- iii) **Research Experience** Through Practice-I and Research Experience Through Practice-II
- iv) Project Work
- v) Seminar
- vi) Audit Courses (AC):
 - a) The Audit course can be any credit course offered by the program to which the candidate is admitted (other than the courses considered for completing the prescribed program credits) or other programs offered in the institution, where the student is studying.
 - b) The students are required to register for one audit course during I and II semesters. Students who have registered to audit the courses, considered on par with students registered to the same course for credit, must satisfy attendance and CIE requirements. However, they need not have to appear for SEE.
- c) Registration for any audit course shall be completed at the beginning of I and II semesters. The Department should intimate the Controller of Examination about the registration at the beginning of the semester and obtain a formal approval for inclusion of the audit course/s in the Grade card issued to the students

vii) Internship/ Mini Project: Preferably at an industry/ R&D organization/IT company/ Government organization of significant repute or at the Research Centre of parent Institution for a specified period mentioned in Scheme of Teaching and Examination.

22NMT4.1 Program Structure:

The number of credits to be registered in a semester is between 16 and 28





Minimum Credit Requirement for the M.Tech. Degree is 80. The total course package for an M.Tech. Degree Program will typically consist of the following components.

Course type	Range	Suggested Credits
i) Program Core Courses	⁷⁰ 20 - 25	20
		-
ii) Program Elective Courses	18 - 20	15
iii) Elective Courses (MOOCS)	4	03
iv) Industrial Internship/Research	10	08
Internship/Mini Project		
v) Project	35	28
vi) Seminar	2.5	02
vii) Research Experience Through	5	04
Practice		
viii)Audit courses (two courses)	-	-
Total credits	1	80

The Department Post Graduate Committee (DPGC) will discuss and recommend the exact credits offered for the program for the above components, the semester-wise distribution among them, as well as the syllabi of all postgraduate courses offered by the department from time to time before sending the same to the Board of Studies (BOS).

The BOS will consider the proposals from the departments and make recommendations to the Academic Council for consideration and approval.

Mandatory Learning Courses:

These are courses that must be completed by the student at appropriate time as suggested by the Faculty Adviser or the DPGC. Courses that come under the category are as following:

Industrial Training:

This is a 08-credit course. A full-time student will complete the Industrial Training (or a Mini Project) at appropriate time stipulated by DPGC and register for it in the following Semester and shall also submit a bound copy of training report certified by the authority of Training Organization. The



duration and the details, including the assessment scheme, shall be decided by the faculty advisor, with approval from DPGC.

Seminar:

This also carries 2-credits to be completed at appropriate time stipulated by DPGC. The student will make presentations on topics of academic interest, as suggested by DPGC.

Research Experience through Practice-I and Research Experience through Practice-II:

- Research Experience through Practice-I and II are 2-credit courses in the first and second semesters respectively.
- The student will work under a faculty supervisor approved by the DPGC and submits a research proposal at the end of the first semester which is evaluated jointly by the faculty supervisor and a co-examiner.
- Students shall be offered inputs like how to conduct a literature survey, how to identify a research problem, how to write a research paper, research report, research proposal, and systematic way of conducting research etc.
- Department specific/PG Program specific skill sets required for carrying out a research work may be offered to the students like software tools for system/device simulation and analysis, software/ hardware tools for signal acquisition, data processing, control simulation, Testing/measuring equipment used in research and Testing/measuring procedure.
- At the end of Research Experience through Practice-I in the first semester, M. Tech. students should be able to identify a research problem, with clear objectives and methodologies backed by extensive literature review.
- Two internal examiners will evaluate the Research Experience through Practice-I out of which one will be the guide and the other examiner will a faculty member who is having expertise in the research area of the student being evaluated. The research proposal report and the research proposal presentation are evaluated for 100 marks in the first semester.
- The student will work on the proposed research in the second semester and submit a research paper at the end of the second semester which is evaluated jointly by the faculty supervisor and a co-examiner.



	• In the second semester, the students are expected to carry out Mathematical
	modelling / Design calculations / computer simulations / Preliminary
	experimentation / testing of the research problems identified during
	Research Experience through Practice-I carried out in the first semester. At
	the end of the second semester, students are expected to write a full research
	paper based on the Mathematical modelling/ Design calculations/computer
	simulations/Preliminary experimentation/testing carried out during second
	semester.
	The research paper submitted by the student and the presentation of the research
	work carried out is evaluated for 100 marks in the second semester.
22NMT5.0	INTERNSHIP/MINI PROJECT:
	The student shall undergo Internship/Mini Project as per the Scheme of
	Teaching and Examination.
	1. The internship can be carried out in any industry/R&D
	Organization/Research Institute/Institute of national repute/R&D Centre
	of Parent Institute.
	2. The Department/college shall nominate a faculty to facilitate, guide and
	supervise students under internship.
	3. The students shall report the progress of the internship/Mini Project to the
	internal guide in regular intervals and seek his/her advice.
	4. The Internship shall be completed during the period specified in Scheme
	of Teaching and Examination.
	5. After completion of Internship/mini project, students shall submit a report
	to the Head of the Department with the approval of both internal and
	external guides and with the approval of internal guide if the
	Internship/Mini-Project is carried out in the Institute.
	6. The Internship/Mini Project will be evaluated jointly by two internal
	examiners appointed by the Head of the Department/Controller of
	Examination.
	7. The Internship/Mini Project report and the presentation by the student will
	be evaluated for 50 marks each immediately after completion of the
	Internship/Mini Project.



The students are permitted to carry out the internship anywhere in India or Abroad. The Institution will not provide any kind of Financial Assistance to any student for Internship/Mini Project and for the conduct of Viva-Voce on internship. 22NMT5.1 Failing to undergo Internship/Mini Project: Securing a pass grade in Internship/Mini Project is mandatory as a partial requirement for the award of Degree. Internship/Mini Project, Internship/Mini Project, Securing a pass grade in Internship/Mini Project, is mandatory. If any student fails to undergo/complete the Internship/Mini Project, he/she shall be considered as fail in that Course. 22NMT6.0 SEMINAR: Securing a pass grade in Seminar is mandatory as a partial requirement for the award of Degree. i) Each candidate shall deliver seminar as per the Scheme of Teaching and Examination on the topics chosen from the relevant fields for about 30 minutes. The Head of the Department shall make arrangements for conducting seminars through concerned faculty members of the department. The Panel of Examiners constituted for the purpose by the Head of the Department shall award the CIE marks for the seminar. 22NMT7.0PROJECT WORK: Securing a pass grade in Project Work is mandatory as a partial requirement for the award of Degree. Project work shall be on individual basis. Project Part-I and Part-II: Project Part-I: (In third Semester) The duration of the Project Part-I will be done during the end of third semester.		
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		The duration of the Project Part-I is of 12 weeks as notified in the academic
third semester.		calendar. The evaluation of the Project Part-I will be done during the end of
		third semester.



Each department will prepare the Panel of Examiners in advance and also prepare the Project Part-I evaluation schedule indicating the names of the students, their USN, Title of the Project, Name of the Examiners, and time and Venue of the evaluation which will be submitted to the Controller of Examination Office in advance.

Project Part-I evaluation will be done by two internal Examiners, one of them will be the Guide and other is preferably one of the experts in the area of PG Project being evaluated.

The mark distribution of Project Phase-I evaluation is: 100 marks for report and 100 marks for presentation jointly awarded by the both the examiners.

Project Part-II: (In the fourth Semester)

The total duration of Project Part-II is of 22 weeks as notified in the academic calendar. There will be two Continuous Internal Evaluation of Project Part-II in fourth semester followed by Semester End Evaluation of the Project Phase-II, namely, Project Progress Evaluation-I (PPE-I), Project Progress Evaluation -II(PPE-II) and SEE.

The same Panel of Examiners which was formed during Project Part-I evaluation is to be continued for the Project Progress Evaluation in the fourth semester.

PPE-I and PPE-II will be scheduled as per the academic calendar and will be evaluated for 100 marks each (50 marks for report and 50 marks for presentation jointly conducted by the two internal examiners).

Each department will prepare the Panel of Examiners in advance and also prepare the Project Part-II Project Progress Evaluation Schedule indicating the names of the students, their USN, Title of the Project, Name of the Examiners, and time and Venue of the evaluation as per the format which will be submitted to the Controller of Examination Office in advance.

For the Off-Campus projects, the Internal Guide should visit the organization in which the M.Tech Student is carrying out his Project at least once during the project term.

The candidate shall submit a soft copy of the dissertation work to the Institute. The soft copy of the dissertation should contain the entire Dissertation in monolithic form as a PDF file (not separate chapters).



	The Guide, after checking the report for completeness shall check the report
	for Plagiarism content. The allowable plagiarism index is less than or equal to
	25%. If the check indicates a plagiarism index greater than 25%, the guide
	should advice the student to resubmit the dissertation after modifying the
	report. The report has to be once again checked for the plagiarism content and
	the signed hard copy of the Plagiarism Report along with the two hard copies
	of the dissertation is to be submitted to the Head of the Institution through the
	Head of the Department. The dissertation will be evaluated by two examiners,
	one of the examiners shall be the Guide of the candidate and the other examiner
	shall be an external expert in the area of the dissertation being evaluated.
	The guide shall submit panel of two approved external examiners to the office
	of the Controller of Examination through the head of the Department. The
	Controller of Examination will randomly select one of the external examiners
	and invites him/her formally for the evaluation of the dissertation and Viva-
	Voce examination giving sufficient time for the external examiner for reading
	the dissertation.
22NMT7.1	The dissertation will be evaluated by two examiners, one of the examiners shall
	be the guide of the candidate and the other examiner shall be preferably an
	external expert in the area of the dissertation being evaluated. The evaluation
	of the dissertation shall be made independently by each examiner.
22NMT7.2	Examiners shall evaluate the dissertation normally within a period of not more
	than two weeks from the date of receipt of dissertation through email.
22NMT7.3	The examiners shall independently submit the marks for the dissertation during
	the viva-voce examination date
22NMT7.4	Sum of the marks awarded by the two examiners shall be the final evaluation
	marks for the Dissertation.
22NMT7.5	(a) Viva-voce examination of the candidate shall be conducted, if the
	dissertation work and the reports are accepted by the external examiner.
	(b) If the external examiner finds that the dissertation work is not up to the
	expected standard and the minimum passing marks cannot be awarded, the
	dissertation shall not be accepted for SEE.
	(c) If the dissertation is rejected during the Project Part II, then the Second
	Examiner (external) will be appointed by the COE against whom the



candidate has to re-present the same dissertation. The decision of the
Second Examiner (external) will be final.
If the second examiner (external) accepts the dissertation, then the viva-voce
examination of the candidate shall be conducted as per the norms. If the second
examiner (external) rejects the dissertation, then the student has to take an
extension for a minimum period of 3 months and re-work on the project. After
the completion of the extension period, viva-voce examination of the candidate
shall be conducted as per the norms, if the dissertation work is accepted by the
external examiner.
The candidate, whose dissertation is rejected, can rework on the same topic or
choose another topic of dissertation under the same Guide or new Guide if
necessary. In such an event, the report shall be submitted within four years from
the date of admission to the Program.
Viva-voce examination of the candidate shall be conducted jointly by the
external examiner and internal examiner/ guide at a mutually convenient date.
The relative weightages for the evaluation of dissertation and the performance
at the viva-voce shall be as per the scheme of teaching and examination.
The marks awarded by both the Examiners at the viva-voce Examination shall
be sent jointly to the office of Controller of Examination immediately after the
examination.
Examination fee as fixed from time to time by the Institute for evaluation of
dissertation report and conduct of viva-voce shall be remitted to the Institute as
per the instructions of Dean-Academics, from time to time.
The candidates who fail to submit the dissertation work within the stipulated
time have to apply for the extension of the Project duration through the Guide
and the head of the department to the Office of the Controller of Examination.
Such candidate is not eligible to be considered for the award of rank.
ATTENDANCE REQUIREMENT:
1. Each semester is considered as a unit and the candidate has to put in a
minimum attendance of 85% in each subject with a provision of
condoning 10% of the attendance by Principal for reasons such as medical
grounds, participation in University level sports, cultural activities,
seminars, workshops and paper presentation etc.



	2. The basis for the calculation of the attendance shall be the period of term
	prescribed by the institution in its calendar of events. For the first
	semester students, the same is reckoned from the date of admission to the
	course
	3. The students shall be informed about their attendance position in the first
	week of every month by the College so that the students shall be cautioned
	to make up the shortage.
	4. The head of the department shall notify regularly, the list of such
	candidates who fall short of attendance. The list of the candidates falling
	short of attendance shall be sent to the Principal with a copy to Controller
	of Examinations.
	5. A candidate having shortage of attendance (<75%) in any course(s)
	registered shall not be allowed to appear for SEE of such course(s). Such
	students will be awarded 'N' grade in these courses.
	6. He/she shall have to repeat those course(s) with 'N' grade and shall re-
	register for the same course(s) core or elective, as the case may be when
	the particular course is offered next either in a main (odd/even) or summer
	semester.
	7. If a candidate, for any reason, discontinues the course in the middle he/she
	may be permitted to register to continue the course along with subsequent
	batch, subject to the condition that he/she shall complete the class work,
	lab work and seminar including the submission of dissertation within
	maximum stipulated period. Such candidate is not eligible to be
	considered for the award of rank.
22NMT9.0	ADD/ DROP/ AUDIT OPTIONS:
	1. ADD-option: A student has the option to ADD courses for registration
	till the date specified for late registration.
	2. DROP-option: A student has the option to DROP courses from
	registration until one week after the mid-semester examination.
	AUDIT-option: A student can register for auditing a course, or a course can
	even be converted from credit to audit or from audit to credit, with the consent
	of faculty advisor and course instructor until one week after the mid-semester
	exam. However, CORE courses shall not be made available for audit. It is not
	exam. However, CONE courses shall not be made available for audit. It is not



	mondatory for the student to (1,1, (1,1)) (1,1)
	mandatory for the student to go through the regular process of evaluation in an
	audit course. However, the student has to keep the minimum attendance
	requirement, as stipulated by the corresponding DPGC for getting the 'U' grade
	awarded in a course, failing which that course will not be listed in the Grade
	Card.
22NMT10.0	ABSENCE DURING THE SEMESTER:
	Leave of Absence
	(a) If the period of leave is more than two days and less than three weeks, prior
	application for leave shall have to be submitted to the Head of the
	Department concerned, with the recommendation of the Faculty-Advisor
	stating fully the reasons for the leave request along with supporting
	documents.
	It will be the responsibility of the student to intimate the course instructors,
	Head of the Department and also Chief Warden of the hostel, regarding his
	absence before availing leave.
22NMT10.1	Absence during Mid-Semester Examinations:
	A student who has been absent from a Mid-Semester Examination (MSE) due
	to illness and other contingencies may give a request for additional MSE within
	two working days of such absence to the office of the respective Head of the
	Department (HOD) with necessary supporting documents and certification
	from authorized personnel. The HOD may consider such requests depending
	on the merits of the case, may permit the additional Mid-Semester Examination
	for the concerned student.
22NMT10.2	Absence during Semester End Examination:
	In case of absence for a Semester End Examination, on medical grounds or
	other special circumstances the student can apply for 'I' grade in that course
	with necessary supporting documents and certifications by authorized
	personnel to the Controller of Examination through Chairman of The
	Department. The Controller of Examination may consider the request
	depending on the merits of the case and permit the make-up Semester End
	Examination for the concerned student. The student may subsequently
	complete all course requirements within the date stipulated by DPGC (which



	may be extended till first week of next semester under special circumstances)
	and 'I' grade will then be converted to an appropriate letter grade. If such an
	application for the 'I' grade is not made by the student, then a letter grade will
	be awarded based on his in-semester performance.
22NMT11.0	WITHDRAWAL FROM THE PROGRAM:
	Temporary Withdrawal: A student who has been admitted to a Post Graduate
	Degree program of the College may be permitted to withdraw temporarily, for
	a period of one semester or more on the grounds of prolonged illness or grave
	calamity in the family etc. The student should abide by the applicable rules and
	regulations of the college/University at the time of Temporary Withdrawal.
22NMT11.1	Permanent Withdrawal:
	Any student who withdraws admission before the closing date of admission
	for the Academic Session is eligible for the refund of the deposits only. Fees
	once paid will not be refunded on any account.
	Once the admission for the year is closed, the following conditions govern
	withdrawal of admissions:
	a) A student who wants to leave the College for good, will be permitted to do
	so (and can take Transfer Certificate from the College, if needed), only after
	remitting the Tuition fees as applicable for all the remaining semesters and
	clearing all other dues, if any.
	b) Those students who have received any scholarship, stipend or other forms
	of assistance from the College shall repay all such amounts in addition to those
	mentioned in (a) above.
	The decision of the Principal of the Institute regarding withdrawal of a student
	is final and binding.
22NMT12.0	EVALUATION SYSTEM:
	Continuous Internal Evaluation (CIE) and Semester End Evaluation
	(SEE)
22NMT12.1	For all the theory and laboratory courses, the CIE marks shall be 50.
	For Research Experience through Practice-I, Research Experience through
	Practice-II, seminar, Industrial Training/Mini Project, the CIE marks shall be
	100.
	For Project Phase-I, the CIE Marks shall be 200
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	For Project Phase-II, the CIE Marks shall be 200 and for SEE 200
22NMT12.2	CIE Marks for courses shall be based on
	a) Tests MSE-I and MSE-II (for 30 Marks): MSE in a theory course, for 30
	marks, shall be based on two tests covering the entire syllabus.
	Assignments, Quizzes, Simulations, Experimentations, Mini project, oral
	examinations, field work etc., (for 20 Marks) conducted in respective courses.
22NMT12.3	a) An additional MSE may be conducted for those students absent for valid
	reasons/ with prior permission.
	b) For those students who could not score minimum required CIE marks
	(25 marks), an additional MSE may be conducted, however the maximum CIE
	marks shall be restricted to 25 out of 50.
22NMT12.4	The candidates shall write the Tests in Blue Book/s. The Blue book/s and other
	documents relating to award of CIE marks shall be preserved by the Head of
	the Department for at least six months after the announcement of University
	results and made available for verification at the directions of the Controller of
	Examination.
22NMT12.5	Every page of the CIE marks list shall bear the signatures of the concerned
	Teacher and Head of the Department.
22NMT12.6	The CIE marks list shall be displayed on the Notice Board and corrections, if
	any, shall be incorporated before submitting to the office of the Controller of
	Examination (COE).
22NMT12.7	The CIE marks shall be sent to the office of the COE well in advance before
	the commencement of Semester End Examinations. No corrections of the CIE
	marks shall be entertained after the submission of marks list to the Office of
	the COE.
22NMT12.8	Candidates obtaining less than 50% of the CIE marks in any course (Theory
	/Laboratory/ Seminar/ Internship/ Project) shall not be eligible to appear for the
	Semester end examination in that course/s. In such cases, the Head of the
	Department shall arrange for the improvement of CIE marks in the course/
	Laboratory when offered in the subsequent semester subject to the maximum
	duration allowed for completion of a M.Tech. program.
22NMT12.9	Semester End Evaluation: There shall be a Semester End Examination at the
	end of each semester.
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22NMT12.10	There shall be double valuation of theory papers. The theory Answer booklets
	shall be valued independently by two examiners appointed by the Controller of
	Examination.
22NMT12.11	If the difference between the marks awarded by the two examiners is not more
	than 15 per cent of the maximum marks, the marks awarded to the candidate
	shall be the average of two evaluations.
22NMT12.12	If the difference between the marks awarded by the two examiners is more than
	15 per cent of the maximum marks, the answer booklet shall be evaluated by a
	third Examiner appointed by the Controller of Examination. The average of the
	marks of nearest two valuations shall be considered as the marks secured by
	the candidate. In case, if one of the three marks falls exactly midway between
	the other two, then the highest two marks shall be taken for averaging.
22NMT12.13	Summer Semester: Summer semester is primarily to assist weak and/or
	students having N/F grade in courses, for a duration of 4 weeks after the
	completion of regular even SEE. The institute may also offer Add-on/ Audit
	Courses during this semester.
22NMT12.14	Each candidate shall obtain not less than 50% of the maximum marks
	(25 marks) prescribed for the CIE of each subject, including seminars. CIE
	Marks shall be based on assignments, tests, oral examinations and seminar
	(minimum of two are compulsory) conducted in respective subjects. The
	candidates obtaining less than 50% of the CIE marks in any subject shall not
	be eligible to appear for the SEE in that subject(s). Only in such cases, the
	Controller of Examination may arrange for reregistering the subject(s) in
	subsequent semester or may refer to DPGC for necessary remedial measures.
	The candidates shall write the Internal Assessment Test in Blue Books, and this
	shall be maintained by the Head of the Department for at least six months after
	the announcement of result and is available for verification. The CIE marks
	sheet shall bear the signature of the concerned Teacher and the Chairman of the
	Department. The CIE marks list shall be displayed on the Notice Board and
	corrections, if any, shall be incorporated before sending to the Controller of
	Examinations.
22NMT12.15	The Academic Performance Evaluation of a student shall be according to a
	Letter Grading System, based on the Class Performance Distribution.



	The Letter grades O, A+, A, B+, B, C and F indicate the level of academic
	achievement, assessed on a decimal (00) scale. The Letter grade awarded to a
	student in a course, for which he has registered shall be based on his
	performance in quizzes, tutorials, assignments etc., as applicable, in addition
	to two mid-semester examination and one semester end examination. The
	distribution of weightage among these components may be as follows:
	Semester End Examination (SEE)50%
	Continuous Internal Evaluation (CIE)
	(i) Quizzes, Tutorials, Assignments etc., 20%
	(ii) Mid-semester Examination: 30%
	Any variation, other than the above distribution, requires the approval of the
	pertinent DPGC and Academic Council.
	The letter grade awarded to a student in a 0-0-P (Practical) course, is based on
	an appropriate continuous evaluation scheme that the course instructor shall
	evolve, with the approval of the pertinent DPGC.
	The course Instructor shall announce in the class, and/or display in the display
	boards or at the website, the details of the Evaluation Scheme, including the
	distribution of the weightage for each of the components, and method of
	conversion from the raw scores to the letter-grades; within the first week of the
	semester in which the course is offered, so that there are no ambiguities in
	communicating the same to all the students concerned.
22NMT12.16	The Transitional Grades 'I', 'W' and 'X' would be awarded in the following
	cases. These would be converted into one or the other of the letter grades (O-
	F) after the student completes the course requirements.
	Grade "I": To a student having attendance $\ge 85\%$ and CIE $\ge 70\%$, in a course,
	but remained absent from SEE for valid & convincing reasons acceptable to
	the College, like:
	i. Illness or accident, which disabled him/her from attending SEE.
	ii. A calamity in the family at the time of SEE, which required the student
	to be away from the College.
	iii. However, the committee chaired by the Principal is authorized to relax
	the requirement of CIE \geq 70% if the student is hospitalized or advised
	long term rest after discharge from the hospital by the Doctor.



22NMT12.20	Rules for grace marks
	CGPA
	against the subject and not to be taken into account while calculating SGPA &
	course when offered next. The letter grade 'W' to be entered in the grade card
	scoring less than 50% in CIE are advised to withdraw and to reregister for the
	a grade better or at least equal to C. For maintaining high standards, the students
22NMT12.19	The suggested passing standards are CIE to have >=50% and CIE+SEE to have
	their CIE and (CIE+SEE).
	these courses in a main/summer semester and fulfil the passing standards for
	the appropriate letter grades only after the concerned students re-register for
22NMT12.18	All the 'W' grades awarded to the students would be eligible for conversion to
	the standard of SEE would be the same as the normal SEE.
	with the permission of the Academic Council of the College. In all these cases,
	made possible to hold a make-up examination at any other time in the semester
	be held as per dates notified in the Academic Calendar. However, it should be
	be eligible to take advantage of this facility. The makeup examination would
	reasons and given the 'I' grade. Also, students having the 'X' grade shall also
	have missed to attend the SEE of one or more courses in a semester for valid
22NMT12.17	The Make Up Examination facility would be available to students who may
	maintained separately).
	"F" grade awarded in this case, but student's performance record will be
	course but SEE performance could result in a 'F' grade in the course. (No
	• Grade "X": To a student having attendance $\geq 85\%$ and CIE $\geq 70\%$, in a
	per Faculty Advice.
	withdrawing from that course before the prescribed date in a semester as
	• Grade "W": To a student having satisfactory attendance at classes but
	which they will not be given permission.
	working days of that examination for which he or she is absent, failing
	Controller of Examinations to write Make up Examinations within 2
	submit the necessary documents along with their request to the
	reasons and those who are absent due to health reasons are required to
	iv. Students who remain absent for Semester End Examinations due to valid



	a.	Grace marks u	p to 1% of the m	aximum total mar	ks of the courses for which	
		he/she is eligible and have registered (non-credit courses excluded) in the				
		examination or 10 marks whichever is less shall be awarded to the failed				
		course(s), (with a restriction of a maximum of 5 marks per course) provided				
		on the award of such grace marks the candidate passes in that course(s)				
22NMT13.0	LE	LETTER GRADES AND GRADE POINTS:				
	The Institute adopts absolute grading system wherein the marks are converted					
	to g	to grades, and every semester result will be declared with semester grade point				
	average (SGPA) and Cumulative Grade Point Average (CGPA). The CGPA					
	wil	will be calculated for every semester, except for the first semester.				
	The	The grading system with the letter grades and the assigned range of marks				
	unc	under absolute grading system are as given below:				
	I	Letter Grade	Grade- Points	Raw Scores	Level of Academic	
				%	Achievement	
		0	10	≥90	Out standing	
		A+	09	80-89	Excellent	
		А	08	70-79	Very Good	
		B+	07	60-69	Good	
		В	06	55-59	Above average	
		С	05	50-54	Average	
		F	00	<50	Fail	
		U			Audited	
	A student obtaining Grade F in a Course shall be considered fail and is required					
	to	to reappear in subsequent SEE. Whatever the letter grade secured by the				
	stu	student during his /her reappearance shall be retained. However, the number				
	of	of attempts taken to clear a Course shall be indicated in the grade cards/				
	trai	transcripts.				
	Ea	rned Credits:				
	Thi	is refers to the o	credits assigned	to the course in w	hich a student has obtained	
	any	any one of the letter grades O, A+ A, B+, B and C				
22NMT14.0	PROMOTION AND ELIGIBILITY:					
22NMT14.1	Promotion:					
	a) All students are promoted to their next semester or year of their program,					



	irrespective of the academic performance.				
	However, for submission for M.Tech. Major Project report in 4 th semester,				
	student should have completed all the courses up to 3 rd semester				
22NMT14.2	The mandatory non-credit courses, if any, shall not be considered for the				
	award of class, calculation of SGPA and CGPA. However, a pass grade (PP)				
	in the above courses is mandatory for the award of Degree.				
22NMT15.0	ELIGIBILITY FOR PASSING AND AWARD OF DEGREE:				
22NMT15.1	1. A student who obtains any grade O to C shall be considered as passed and				
	if a student secures F grade in any of the head of passing, he/she has to				
	reappear in that head for SEE.				
	2. A student shall be declared successful at the end of the program for the				
	award of Degree only on obtaining CGPA≥5.00, with none of the courses				
	remaining with F grade.				
	In case, the CGPA falls below 5.00, the student shall be permitted to appear				
	again for SEE for required number of courses (other than seminar and practical)				
	and times, subject to the provision of University, to make up CGPA≥5.0. The				
	student should reject the SEE results of previous attempt and obtain written				
	permission form the Controller of Examinations to reappear to the subsequent				
	SEE.				
22NMT15.2	For a pass in a theory course, the student shall secure a minimum of 40% of the				
	maximum marks prescribed in the Semester End Examination and 50% of				
	marks in CIE and 50% in the aggregate of CIE and SEE marks. The minimum				
	passing grade in a course is C.				
22NMT15.3	For a pass in Internship/ Practical/ Project/ Dissertation/ Viva-voce				
	examination, a student shall secure a minimum of 50% of the maximum marks				
	prescribed for the SEE in Internship/ Practical/ Project/ Dissertation/ Viva-				
	voce. The minimum passing grade in a course is C.				
22NMT15.4	For a pass, a candidate shall obtain a minimum of 50% of maximum marks in				
	Seminar.				
22NMT15.5	IV Semester full time candidates having backlog courses are permitted to				
	upload the dissertation report and to appear for SEE. The IV semester grade				
	card shall be released only when the candidate completes all the backlog				
	courses and become eligible for the award of Degree.				



22NMT15.6	Eligibility for Award of Degree:				
	A student shall be declared to have completed the Degree of Master of				
	Technology, provided the student has undergone the stipulated course work as				
	per the regulations and has earned the prescribed credits, as per the scheme of				
	teaching and examination of the program				
22NMT16.0	EVALUATION OF PERFORMANCE:				
	Computation of SGPA and CGPA				
	SGPA and CGPA: The credit index can be used further for calculating the				
	Semester Grade Point Average (SGPA) and the Cumulative Grade Point				
	Average (CGPA), both being important academic performance indices of the				
	student. While SGPA is equal to the credit index for a semester divided by the total number of credits registered by the student in that semester, CGPA gives				
	the sum total of credit indices of all the previous semesters divided by the total				
	number of credits registered in all these semesters. Both the equations together				
	facilitate the declaration of academic performance of a student, at the end of a				
	semester and at the end of successive semesters respectively				
	SGPA is computed as follows:				
	SGPA				
	$\sum [(Course \ Credits) \times (Grade \ Point)]$ (for all courses with letter grades including F grades in that semester)				
	$=$ $\sum [Course Credits]$				
	(for all courses with letter grades including F grades in that semester) CGPA is computed as follows:				
	CGPA				
	$\sum[(Course Credits) \times (Grade Point)]$				
	$= \frac{\text{(for all courses excluding those with F grades until that semester)}}{\sum [Course Credits]}$				
	(for all courses excluding those with F grades until that semester)				
22NMT16.1	Communication of Grades:				
	• The SGPA and CGPA respectively, facilitate the declaration of academic				
	performance of a student at the end of a semester and at the end of				
	successive semesters. Both of them would be normally calculated to the				



	second decimal position, so that the CGPA, in particular, can be made use
	of in rank ordering the students' performance in the Institute.
	• If two students get the same CGPA, the tie could be resolved by considering
	the number of times a student has obtained higher SGPA, But, if it is still
	not resolved, the number of times a student has obtained higher grades like
	O, A, B etc. could be taken into account.
22NMT16.2	Challenge evaluation
	If a student is not satisfied with the marks allotted to him/her in the semester
	end examinations, he/she could apply for challenge evaluation within the
	prescribed time specified. In such cases the answer papers will be valued by
	the DPGC committee and marks secured by the students in the challenge
	evaluation will be final.
22NMT16.3	Grade Card: Based on the secured letter grades, grade points, SGPA and
	CGPA, a grade card for each semester shall be issued. On specific request on
	paying prescribed fee, a transcript indicating the performance in all semesters
	may be issued.
22NMT16.4	Conversions of Grades into Percentage and Class Equivalence
	Conversion formula for the conversion of CGPA into percentage is given
	below:
	Percentage of marks secured, $P = CGPA$ Earned $\times 10$
	Illustration: for CGPA of 8.18:
	$P = CGPA Earned 8.18 \times 10 = 81.8 \%$
22NMT17.0	DEGREE REQUIREMENTS:
	The Degree requirements of a student for the M.Tech Degree program are as
	follows:
	1. College Requirements:
	i) Minimum Earned Credit Requirement for M.Tech. Degree is 80
	ii) Satisfactory completion of all Mandatory Learning courses
	2. Program Requirements:
	i) Minimum Earned Credit Requirements on all core courses,
	ii) Elective Courses and major project as specified by the DPGC.
	The maximum duration for a student for complying to the Degree requirements
	is 8 semesters from the date of first registration for his first semester.
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22NMT18.0	TERMINATION FROM THE PROGRAM/READMISSION:						
	A student shall be required to leave the College without the award of the						
	Degree, under the following circumstances:						
	ii) Failing to complete the degree requirements in double the duration of the						
	program						
	Based on disciplinary action suggested by the Academic Council/Governing						
	Council.						
22NMT19.0	GRADUATION REQUIREMENTS AND CONVOCATION:						
	1. A student shall be declared to be eligible for the award of the Degree if he						
	has						
	 b) No Dues to the College, Departments, Hostels, Library Central Computer Centre and any other center 						
	c) No disciplinary action pending against him.						
	 The award of the Degree must be recommended by the Academic council 						
	and approved by Governing Council of Nitte (DU)						
	Convocation: Degree will be awarded in person for the students who hav						
	graduated during the preceding academic year. Degrees will be awarded in						
	absentia to such students who are unable to attend the Convocation. Student						
	are required to apply for the Convocation along with the prescribed fees, after						
	having satisfactorily completed all the Degree requirements within the						
	specified date in order to arrange for the award of the Degree during						
	convocation.						
22NMT20.0	AWARD OF CLASS, PRIZES, MEDALS & RANKS:						
	• Award of Class: Sometimes, it would be necessary to provide equivalence						
	of SGPA and CGPA with the percentages and/or Class awarded as in the						
	conventional system of declaring the results of University examinations.						
	This can be done by prescribing certain specific thresholds in these						
	averages for Distinction, First Class and Second Class as described below.						
	Percentage Equivalence of Grade Points (For a 10-Point Scale)						
	GPA Percentage of Class						
	Marks*						
	≥ 7.00 $\geq 70\%$ Distinction						



(Deemed to	rersity)
	≥ 6.00 $\geq 60\%$ First Class
	$5.0 \ge \text{GPA} \le 6.00$ $50 \ge \text{Percentage} \le 60\%$ Second Class
	Percentage * = (GPA) x 10
	• For the award of Prizes, Medals and ranks: The conditions stipulated
	by the Donor may be considered as per the statutes framed by the University
	for such awards.
	\circ An attempt means the appearance/registration of a candidate for an
	examination in one or more courses either in part or failing a particular
	examination.
	• A candidate who fails/remaining absent (after submitting exam application)
	in the main examination and passes one or more subjects/courses or all
	subjects/courses in the supplementary/Make-up examination such
	candidates shall be considered as taken more than an attempt.
	• Merit Certificates and University Medals/ will be awarded on the basis of
	overall CGPA, governed by the specific selection criteria that may be
	formulated by the University for such Medals / Awards
	• Only those candidates who have completed the Program and fulfilled all
	the requirements in the minimum number of years prescribed (i.e., 2 years)
	and who have passed each semester in the first attempt are eligible for the
	award of Merit Certificates and /or Ranks and University Medals.
	Candidates with W, N, I, X & F grades and who passes the courses in the
	subsequent/supplementary/make up examinations are not eligible for the award
	of Gold Medal or Merit Certificate.
22NMT21.	CONDUCT AND DISCIPLINE:
	1. Students shall conduct themselves within and outside the premises of the
	Institute, in a manner befitting the students of an Institution of National
	Importance

- 2. As per the order of Honorable Supreme Court of India, ragging in any form is considered as a criminal offence and is banned, any form of ragging will be severely dealt with.
- 3. The following acts of omission/ or commission shall constitute gross Violation of the code of conduct and are liable to invoke disciplinary measures:



a) Ragging b) Lack of courtesy and decorum; indecent behavior anywhere within or outside the campus. c) Willful damage or stealthy removal of any property /belongings of the Institute /Hostel or of fellow students/ citizens d) Possession, consumption or distribution of alcoholic drinks or any kind of hallucinogenic drugs. e) Mutilation or unauthorized possession of Library books. f) Noisy and unseemly behavior, disturbing studies of fellow Students. g) Hacking in computer systems (such as entering into other Person's area without prior permission, manipulation and/or Damage of computer hardware and software or any other Cybercrime etc.,). h) Plagiarism of any nature. i) Any other act of gross indiscipline as decided by the University from time to time. i) Smoking in College Campus and supari chewing. k) Unauthorized fund raising and promoting sales 4. Commensurate with the gravity of offense, the punishment may be: reprimand, expulsion from the hostel, debarment from an examination, disallowing the use of certain facilities of the College, rustication for a specified period or even outright expulsion from the College, or even handing over the case to appropriate law enforcement authorities or the judiciary, as required by the circumstances. For an offence committed in i) a) A hostel b) A department or in a classroom c) Elsewhere, the Chief Warden, the Head of the Department and the Dean (Students Welfare), respectively, shall have the authority to reprimand or impose fine. ii) All cases involving punishment shall be reported to the Principal. 5. Cases of adoption of unfair means and/or any malpractice in an

examination shall be reported to the Controller of Examination.



Note: Students are required to be inside the examination hall 20 minutes before the commencement of examination. This is applicable for all examinations (Semester end/Supplementary/makeup) henceforth. Students will not be allowed inside the examination hall after the commencement, under any circumstances.



Department Vision

Pursuing excellence in Electrical & Electronics Engineering, creating a research environment to promote innovation and address global challenges

Department Mission

- To equip students to face global challenges by excelling in professional career and higher education.
- To offer high quality graduate and post graduate programs in electrical & electronics engineering.
- To promote excellence in research, collaborative activities and contribute to social development with ethical values.

Programme Educational Objectives (PEO)

- **PEO1:** Excel in professional career in industry, academia and entrepreneurial ventures by applying the knowledge of power electronics.
- **PEO2:** Engage in designing power electronics systems and contribute in multidisciplinary engineering projects.
- **PEO3:** Inculcate and exhibit ethical values, communication skills and adapt to current trends by engaging in research by providing supportive and leadership roles.

At the end of M.Tech (Electric Vehicle Technology) program the students will have an ability to

PO1:	Independently carry out research /investigation and development work to solve
	practical problems
PO2:	Write and present a substantial technical report/document
PO3:	demonstrate a degree of mastery over the area as per the specialization of the
	program. The mastery should be at a level higher than the requirements in the
	appropriate bachelor program
PO4:	Use modern tools to simulate and model Electrical Vehicular systems and carry out
	performance evaluation.
PO5:	Engage in lifelong learning with a commitment to improve knowledge in a
	technologically changing scenario.
PO6:	Appreciate and Practice professional ethics for sustainable development of society.
	Programme Specific Outcomes (PSO)
PSO-1	An ability to analyse and design power electronic converters used in electric vehicles
PSO-2	An ability to analyse battery parameters and design battery management system.



List Of Faculty

Sl. No	Name of Faculty	Qualification	Designation		
1.	Dr. Suryanarayana K.	Ph.D.	Professor & HOD		
2.	Dr. Nagesh Prabhu	Ph.D.	Professor		
3.	Dr. Sathyendra Kumar	Ph.D.	Professor		
4.	Dr. Rajalaxmi Samaga	Ph.D.	Professor		
5.	Dr. Nayana Shetty	Ph.D.	Associate Professor		
6.	Dr. Anitha Marina Colaco	Ph.D.	Associate Professor		
7.	Dr. Latha Shenoy	Ph.D.	Associate Professor		
8.	Mr. Naveen J.	M.Tech	Asst. Prof Gd III		
9.	Mr. Drodoon Kumor	M.Tech	Asst. Prof Gd III		
9.	Mr. Pradeep Kumar	(Ph.D.)	Asst. Flor Gu III		
10.	Mr. Dinash Shatty	M.Tech	A agt. Drof Cd III		
10.	Mr. Dinesh Shetty	(Ph.D.)	Asst. Prof Gd III		
11.	Dr. Girisha Joshi	Ph.D.	Asst. Prof Gd III		
12.	Dr. Krishna Rao	Ph.D.	Asst. Prof Gd III		
13.	Mr. Mahabaleshwara Sharma K.	M.Tech(Ph.D.)	Asst. Prof Gd II		
14.	Mrs. Raksha Adappa	M.Tech	Asst. Prof Gd II		
15.	Mrs. Soumus Dani Mastha	M.Tech	Asst. Prof Gd II		
13.	Mrs. Soumya Rani Mestha	(Ph.D.)	Assi. Fioi Gu II		
16.	Mr. Gururaj K.	M.Tech	Asst. Prof Gd II		
17.	Mr. Ravikiran Rao	M.Tech	Asst. Prof Gd II		
18.	Md. Abdul Raheman	M.E(Ph.D.)	Asst. Prof Gd II		
19.	Mrs. Swathi Hatwar H.	M.Tech(Ph.D.)	Asst. Prof Gd II		
20.	Mrs. Palimaru Aparna	M.Tech	Asst. Prof Gd I		
21.	Ms. Deepa K	M.Tech	Asst. Prof Gd I		
22.	Ms. Anupama B	M.Tech	Asst. Prof Gd I		
23.	Ms. Nutana Shetty	M.Tech	Asst. Prof Gd I		
24.	Mr. Anup Shetty	M.Tech	Asst. Prof Gd I		



CREDIT DISTRIBUTION

No.	Course Category	Suggested Credits
1.	Professional Courses (PCC) – core	16
2.	Professional Courses (PEC) – elective	18
3.	Research Methodology & IPR/RETP	04
4.	Labs	04
5.	Project Work (UCC) (Phase 1 & 2)	08+20
6.	Audit Courses (2 Nos)	00
7.	Seminar on Current Topic (UCC)	02
8.	Internship (UCC)	08
	Total Credits to be earned:	80



Regulations and curriculum for M. Tech Electric Vehicle Technology

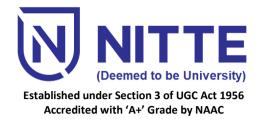
NMAM INSTITUTE OF TECHNOLOGY

Scheme & Syllabus for

M. Tech. (Electric Vehicle Technology)

DEPARTMENT OF ELECTRICAL & ELECTRONICS ENGINEERING 2022-24







Off-Campus Centre, Nitte - 574 110, Karkala

M.Tech. (EVT): Scheme of Teaching and Examinations 2022-24

Outcome Based Education (OBE) and Choice Based Credit System (CBCS)

(Effective from the academic year 2022 - 23)

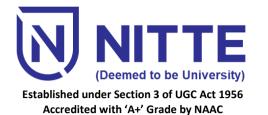
]	SEMES	ГER							
SI.	Type		Course Title	Teaching Department	Teaching Hours /Week			Examination				:
0				Teac	Lecture	Tutorial	Practical/ Drawin	Duration in hours	CIEMarks	SEEMarks	Total Marks	
					L	Т	Р					
1	PCC	22EVT101	Electric and Hybrid Vehicles	EEE	4	0	0	3	50	50	100	4
2	PCC	22EVT 102	Vehicle Dynamics	EEE	4	0	0	3	50	50	100	4
3	RETP	22 EVT 103	Research Experience Through Practice -I	EEE	/weel out F In betwe	contact l c for car lesearch teractio en the fa l studen	rying and n aculty	-	100	0	100	2
4	PCC	22 EVT 104	Electric and Hybrid Vehicles Lab	EEE	0	0	2	3	50	50	100	1
5	PCC	22 EVT 105	Powertrain Lab	EEE	0	0	2	3	50	50	100	1
6	PEC	22 EVT 11X	Elective – I	EEE	3	0	0	3	50	50	100	3
7	PEC	22 EVT 12X	Elective - II	EEE	3	0	0	3	50	50	100	3
8	PEC	22 EVT 13X	Elective - III	EEE	3	0	0	3	50	50	100	3
9	AUDIT	22 EVT AU1X	Audit Course-I	EEE	2	-	-	-	-	-	-	-
				Total	19	0	4	21	450	350	800	21





Sl. Cours e No Type	Course Code	Course Title	Course Title	Teaching Department	Teac /Wee	hing H ek	ours		Exam	ination		
	Туре			Teac Depa	Lecture	Tutorial	Practical/ Drawin	Duration in hours	CIEMarks	SEEMarks	Total Marks	
					L	Т	Р					
1	PCC	22 EVT 201	Power Electronic Converters	EEE	4	0	0	3	50	50	100	4
2	PCC	22 EVT 202	EV Motor drives and control	EEE	4	0	0	3	50	50	100	4
3	RETP	22 EVT 203	Research Experience Through Practice -II	EEE	/weel out F Ir betwe	contact l x for car Research nteractio en the fa d studen	rying and n aculty	-	100	0	100	2
4	PCC	22 EVT 204	Power Electronic Converters Lab	EEE	0	0	2	3	50	50	100	1
5	РСС	22 EVT 205	EV Motor drives and control Lab	EEE	0	0	2	3	50	50	100	1
6	PEC	22 EVT 21X	Elective – IV	EEE	3	0	0	3	50	50	100	3
7	PEC	22 EVT 22X	Elective – V	EEE	3	0	0	3	50	50	100	3
8	PEC	22 EVT 23X	Elective - VI	EEE	3	0	0	3	50	50	100	3
9	AUDI T	22 EVT AU2X	Audit Course-II	EEE	2	-	-	-	-	-	-	-
				Total	19	0	4	21	450	350	800	21

L -Lecture, T - Tutorial, P- Practical/ Drawing, CIE: Continuous Internal Evaluation, SEE: Semester End Examination.





Off-Campus Centre, Nitte - 574 110, Karkala

M.Tech. (EVT): Scheme of Teaching and Examinations 2022-24

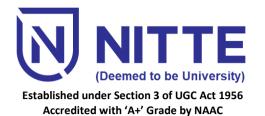
Outcome Based Education (OBE) and Choice Based Credit System (CBCS)

(Effective from the academic year 2022 - 23)

2nd Year Scheme

SI. No	Course Type	Course Code	Course Title	Teaching Department	Teach /Weel		lours]	Examir	nation		Credite
				Teae Depa	Theory Lecture	Tutorial	Practical/ Drawin	Duration in hours	CIEMarks	SEEMarks	Total Marks	
					L	Т	Р					
1	UCC	22EVT301	Industry Internship/ Research Internship/Mini Project	EEE			l Time week]	3	100	0	100	8
2	UCC	22EVT302	Seminar on Special Topic	EEE	0	0	2	3	100	0	100	2
3	UCC	22EVT303	Project Part	EEE	[Mi	12 Weeks Full Time [Minimum 30 Hrs/week]		3	200	0	200	8
				Total	0	0	2	9	400	0	400	18
Sem	ester End E	Examination.	I, P- Practical/ Drawing for 100 Marks where 5	,-		Ĩ					luation,	, SEE

L Tutorial		d Practical/ Drawin	Duration in hours	CIEMarks	SEEMarks	Total Marks	Canalite	
Т	T 1	Р	1			° H		
22 Weeks Full Time [36 Hrs/week]				3	200	200	400	20
0	0	0	3	200	200	400	20	
		0 Continuou	0 0 Continuous Internal	0 0 3 Continuous Internal Evaluat	0 0 3 200	0 0 3 200 200 Continuous Internal Evaluation, SEE: Seme	0 0 3 200 200 400 Continuous Internal Evaluation, SEE: Semester End	





M.Tech. (EVT): Scheme of Teaching and Examinations 2022-24 Outcome Based Education (OBE) and Choice Based Credit System (CBCS) (Effective from the academic year 2022 - 23)

List of Domain Specific Skill Development Audit Course (AUDIT)							
Course Code	Course Title						
22EVTAU11	Programming Digital Signal Controller						
22EVTAU21	PCB Design						

	List of E	Electives [PEC]				
	Elective - I	Elective - II				
Code	Course Title	Code	Course Title			
22EVT111	Advanced Battery Technology for Electrical Vehicles	22EVT121	Automotive Electronics for EVs			
22EVT112	Energy Storage Systems for EV	22EVT122	Modeling and Analysis of Electrical Machines			
22EVT113	Special Electrical Machines	22EVT123	Power Semiconductor Devices			
	Elective - III		Elective - IV			
Code	Course Title	Code	Course Title			
22EVT131	Embedded System	22EVT211	Battery Management System			
22EVT132	Applied Mathematics	22EVT212	Thermal Management of EV systems			
22EVT133	Digital Controller	22EVT213	Vehicle Body Engineering			
	Elective - V	Elective – VI				
Code	Course Title	Code	Course Title			
22EVT221	PWM Controlled Power Electronic Converters	22EVT231	Automotive Computer Controlled Systems			
22EVT222	Solar Battery Charging System	22EVT232*	Automotive Security			
22EVT223	EV Standards & Testing	22EVT233*	Vehicle management and control			
22EVT224	EVs in Smart Grid	22EVT234**	Fundamentals of Automotive Systems			

 * 22EVT232 and 22EVT233 are offered in association with Microchip Technology Inc.

** Elective course 22EVT234 may be registered under NPTEL

Course Code	22EVT101	Course Type:	PCC
Teaching Hours/Week (L: T: P)		Credits:	04
Total Teaching Hours		CIE + SEE Marks:	50+50
			50150
Course Objectives:		lectronics Engineering	
1. To introduce configurations of EV and	HEVs		
 To design electric vehicle & HEV for v 		5	
 To select appropriate motor and conv 			
4. To select battery, battery indication s			
5. To develop battery charger for an EV	· · · · · ·		
	UNIT-I		
ntroduction to EV & HEV			09 Hours
ntroduction:			
Past, Present & Future of EV, Current Ma		•	icept, Key E
echnology, State-of-the Art EVs & HEVs, Cor	-	-	
V System: EV Configuration: Fixed & variable	0 0 0	•	drives
V Parameters: Weight, size, force, energy &	performance para	meters.	
	UNIT-II		
V Propulsion- Electric Motor:			
			06 Hours
choice of electric propulsion system, block on notor and multi-motor configurations, fixed	& variable geared	transmission, In wheel motor	configuration
Choice of electric propulsion system, block on notor and multi-motor configurations, fixed classification of EV motors, Electric moto Comparison of Electirc Motors for EV application	& variable geared s used in currer	transmission, In wheel motor	Motors, sing
Choice of electric propulsion system, block on notor and multi-motor configurations, fixed classification of EV motors, Electric moto Comparison of Electirc Motors for EV applica Required Power Electronics & Control:	& variable geared rs used in currer tions	transmission, In wheel motor on the transmission of transmission of the transmission of the transmission of the transmission of the transmission of transmission of transmission of the transmission of transm	Motors, sing configuration t EV Motor 06 Hours
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Energy Sources & Charging:

10 Hours

Different Batteries and Ultra-capacitors, Battery characteristics (Discharging & Charging) Battery Chargers: Conductive (Basic charger circuits, microprocessor based charger circuit. Arrangement of an off-board conductive charger, Standard power levels of conductive chargers, Inductive (Principle of inductive charging, Soft-switching power converter for inductive charging), Battery indication Methods Charging Infrastructure: Domestic Charging Infrastructure, Public Charging Infrastructure, Normal Charging Station, Occasional Charging Station, Fast Charging Station, Battery Swapping Station, Move-and-charge zone.

Course Outcomes: At the end of the course student will be able to Identify EV concepts, EV configurations and various EV parameters for better understanding of the EV technology. Analyse the EV propulsion system and electric motors for vehicular applications & power electronics converters required for their control. Analyse DC motor & induction motor drives and discuss control methods. Elaborate various hybrid electric vehicle configurations and explain the power flow control in all HEV configurations Identify different energy sources used in EV and analyse the various methods used in charging these energy sources

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes \rightarrow	1	2	3	4	5	6	PS	O↓
↓ Course Outcomes							1	2
22EVT101.1			2	2				
22EVT101.2			2	3			2	
22EVT101.3			2	2				
22EVT101.4			2					
22EVT101.5			2					2

1: Low 2: Medium 3: High

REFERE	INCE BOOKS:
1.	C.C Chan, K.T Chau: Modern Electric Vehicle Technology, Oxford University Press Inc., New York 2001
2.	Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2003.
3.	Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel
	Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004.
4.	James Larminie, John Lowry, Electric Vehicle Technology Explained, Wiley, 2003.

	Veh	nicle Dynami	ics	
Course Co	de:	22EVT102	Course Type:	PCC
Teaching Hours/Week (L: T:	P):	4+0+0	Credits:	04
Total Teaching Hou	urs:	50+0+0	CIE + SEE Marks:	50+50
Teaching Departme	ent: E	lectrical and E	lectronics Engineering	
Course Objectives:				
1. Understand the dynamics of vehic	le rid	e under differen	t riding condition.	
2. Present a problem oriented in dep	oth kn	owledge of Vehi	icle Dynamics.	
3. address the underlying concepts a			-	
4. Calculate and refer the loads and t	forces	s associated to th	ne vehicles.	
5. Analyse the behaviour of the vehic	cles u	nder acceleratio	n, ride and braking	
		UNIT-I		
Basics of Vehicle Dynamics				10 Hours
History, vehicle classifications, fundamer	ntal a	pproaches to ve	ehicle dynamics modelling; SA	E Vehicle axis
system, Forces & moments affecting vehic	le, Ea	irth Fixed coordii	nate system, Dynamic axle loads	s, Equations o
motion, transmission characteristics, vehic	cle pe	erformance, Brak	e proportioning, braking efficie	ency.
		UNIT-II		
Acceleration Performance:				05 Hours
Braking Performance:			on; transverse weight shift; fro	05 Hours
Braking Performance:	nalysi		tion on braking performance; a	05 Hours
Braking Performance: Braking force analysis; brake design and ar	nalysi	y and maintenan	tion on braking performance; a	05 Hours
Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s	nalysi		tion on braking performance; a	05 Hours
Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s Road Loads	nalysi safety	y and maintenan	tion on braking performance; an ce issues in braking	05 Hours htilock braking 05 Hours
Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s Road Loads Wind drag and car body design, rolling re	nalysi safety	y and maintenan	tion on braking performance; an ce issues in braking	05 Hours ntilock braking 05 Hours e analysis and
Road Loads Wind drag and car body design, rolling re- driving styles; Aerodynamics Tire and Tire Dynamics	nalysi safety sistar	y and maintenan UNIT-III nce; breakdowns	tion on braking performance; an ce issues in braking of total road loads; gas mileag	05 Hours ntilock braking 05 Hours e analysis and 05 Hours
Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s Road Loads Wind drag and car body design, rolling re driving styles; Aerodynamics	nalysi safety sistar	y and maintenan UNIT-III nce; breakdowns	tion on braking performance; an ce issues in braking of total road loads; gas mileag	05 Hours ntilock braking 05 Hours e analysis and 05 Hours
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Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s Road Loads Wind drag and car body design, rolling re driving styles; Aerodynamics Tire and Tire Dynamics Tire specifications and constructions; tire vibration analysis; tire models Ride & Cornering/steering	nalysi safety sistar motio	y and maintenan UNIT-III nce; breakdowns on analysis; tire f UNIT-IV	tion on braking performance; an ce issues in braking of total road loads; gas mileag force analysis; tire contact stres	05 Hours ntilock braking 05 Hours e analysis and s analysis; tire 10 Hours
Braking Performance: Braking force analysis; brake design and ar system; wheel lock-up; tire/road friction; s Road Loads Wind drag and car body design, rolling re driving styles; Aerodynamics Tire and Tire Dynamics Tire specifications and constructions; tire vibration analysis; tire models Ride & Cornering/steering Riding comfort; perception of vibration; v	nalysi safety sistar motic	y and maintenan UNIT-III nce; breakdowns on analysis; tire f UNIT-IV ion sources; vibr	tion on braking performance; an ce issues in braking of total road loads; gas mileag force analysis; tire contact stres	05 Hours ntilock braking 05 Hours e analysis and 05 Hours s analysis; tire 10 Hours engers;: lowe
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Active. Choice of suspension spring rate, Calculation of effective spring rate, Vehicle suspension in fore and apt directions.

Course	Outcom	es: At the end of the course stude	ent v	vill b	e abl	e to					
1.	Analyse	the dynamics of vehicle under di	ffere	nt rio	ding	conc	litior	า.			
2.		acceleration and braking perform	nanc	e in e	elect	ric ve	ehicl	e to	understa	and the	vehicle
	dynamic	s under these conditions.									
3.		e road loads and tyre dynamics i									
4.	•	t riding comfort & vibrations, cor	nerir	ng an	nd ro	llove	er in	elec	tric vehi	cles to u	understand the
		r dynamics.									
5.	Infer on	the suspension kinematics and co	ontro	ollab	le su	sper	sion	eler	nents us	ed in el	ectric vehicles.
Course	Outcom	es Mapping with Program Outco	mes	Т	50	1	1	1	1		1
		Program Outcomes $ ightarrow$	1	2	3	4	5	6	PS	O↓	
		↓ Course Outcomes	-						1	2	-
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		22EVT102.1	2		2		2				1
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		22EVT102.5	2		3						-
		22201102.5	2		5						
	1: Low 2	2: Medium 3: High									-
REFERE	ENCE BOO										
1.		nentals of Vehicle Dynamics, Thor									
2.		Itibody systems Approach to Veh	icle	Dyna	mics	, Mi	ke Bl	und	ell and D	amian H	Harty, Elsevier,
	2004.										
3.		Dynamics, Theory and Applicatio	on, Re	eza N	I. Jaz	ar, S	prin	ger, i	2009 <i>,</i> ISE	3N 978-	0-387-74243-4,
		978-0-387-74244.									
4.		r Vehicle Dynamics, W.F. Milliker									1-526-9.
5.		II, Stoll and Betzler: The Automot					eerır	ng Pr	inciples.		
6.		cejka, Tire and Vehicle Dynamics	•								
7.		Rajamani, Vehicle Dynamics & co									
8.	K.V. Du	kkipati, Vehicle dynamics, Narsov	/a Pu	blica	tions	5.					

Course Code:	2	2EVT103	(Course	e Type		RETP
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Total Teaching	Hours	+0+52	(CIE			100
	Teaching) Departr	ment: /	Δnv			
ourse Obiectiv	es: The research purposes are	, Depui a					
•	ee future problems through purs	uit of trut	h as a "	ʻgloba	l centre	of excellenc	e for intellectu
-	ond to current social demands, a c technologies with the aim of re cy.						-
3. At the sa	ame time, the course aims to cre	ate excelle	ent edu	catior	nal resou	rces and an	excellent
	onal environment through frontli						
	erstand professional writing and				-		
data dise	covered by researching, and con	structing fi	inished	prote	ssional v	vorkplace do	ocuments.
ndividual PG St	tudents are to be allotted to the	e individu	ual facu	ultv m	embers	based on s	tudent's area
	st, specialization of faculty mem			-			
- () - 1		MODULE			6 4 6		
-	search problem – Selecting the	problem -	– Nece	-			
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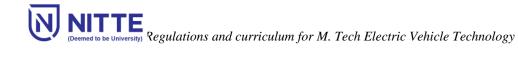


1. Gina Wisker, "The Undergraduate Research Hand book", 2018.

E Books / MOOCs/ NPTEL

1. <u>https://www</u>.classcentral.com/course/swayam-research-methodology7760

			Electric and H	ybrid	Ve	hicle	es L	abc	orat	ory		
			Course Code:	22EV	Г104					Coι	irse Type:	PCC Lab
		Теа	aching Hours/Week (L: T: P):	0:0:2							Credits:	01
			Total Teaching Hours:	0+0+2	26					CIE + S	EE Marks:	50+50
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1.	Тс	under	stand working of different ele	ctric m	otors	s driv	/es u	sed	in Ele	ectric Ve	hicles.	
2.	Тс	o study	off-grid solar inverters and inv	erter s	stack	conf	igur	atior	۱s.			
3.	Тс	o study	the concept of solar based EV	chargi	ng st	atior	۱.					
4.			fy components of electric and									
5.	Тс	under	stand the significance of BMS	in ma	nagir	ng en	ergy	stor	age.			
			Lis	t of Ex	peri	men	ts					
	1.	Electr	ic Rickshaw Motor kit									
	2.	BLDC	motor-based EV									
	3.	PMSN	A based Electric vehicle									
	4.	Induc	tion motor based electric vehi	cle.								
	5.	Study	of off-grid solar Inverter									
	6.	Study	of 4 Leg Semikron Stack									
	7.	Solar	based EV Charging station.									
	8.	Study	of electric vehicle system.									
	9.	Study	of hybrid electric vehicle syste	em.								
	10.	Demo	onstration of battery managem	ent Sy	stem	1						
Cours	se Ou	utcome	es: At the end of the course stu	dent v	vill b	e abl	e to					
1.	De	emonst	rate various electric motors dr	ives us	sed ii	n Ele	ctric	Veh	icles			
2.	Ar	nalyse o	off-grid solar inverters and inve	erter st	tack (confi	gura	tion	s.			
3.	De	emonst	rate use of solar based EV cha	rging s	tatio	n						
4.	Id	entify v	various components of electric	and h	ybrid	elec	tric	vehi	cle ai	nd analy	se its perfo	ormance.
5.	De	emonst	rate the use of BMS in managi	ng ene	ergy s	stora	ge d	evice	es of	EVs		
Cour	se Ou	utcome	es Mapping with Program Out	comes	& PS	50						
			Program Outcomes-	→ 1	2	3	4	5	6	PS	O↓	
			↓ Course Outcomes							1	2	
			22EVT104.1	1	2	2	3					
			22EVT104.2	1	2	2	3					
			22EVT104.3	1	2	2	3				2	



	22EVT104.4	1	2	2	3			
	22EVT104.5	1	2	2	3		3	
1: Low 2	Medium 3: High	•						

			Powe	ertrair	n Lal	bor	ato	ry			
			Course Code:	22EV1	۲105					Course Type:	PCC Lab
		Теа	ching Hours/Week (L: T: P):	0:0:2						Credits:	01
			Total Teaching Hours:	0+0+2	26					CIE + SEE Marks:	50+50
			Teaching Department:	Electri	cal a	nd l	Elect	tron	ics l	Engineering	
	1	ojective									
1.	-	-	conventional vehicle fuel eco	-							
2.			stand the working of transmis						licati		
3. 4.			hybrid electric vehicle (HEV) r stand hybrid electric vehicle (
4. 5.			Electric Vehicle reference app		· ·				lele		
<u> </u>	50	uuyori		st of Ex		-					
	1.	Studv	of Conventional Vehicle Spar		•			l Ecc	nom	nv and Emissions u	sing MATLAB
	2.		of Conventional Vehicle effici			-				.,	
	3.		of conventional vehicle refere					ptim	ize t	he transmission co	ontrol module
			shift schedules using MATLA								
	4.		of hybrid electric vehicle (HE							-	
	5.		of conventional vehicle refere	•	•		to o	ptim	ize t	he transmission co	ontrol module
	-		shift schedules to design con								
	6.	-	of conventional vehicle refere	•	•			•			
			shift schedules to assess the on performance, fuel econom	•	•			n cha	inge	s, such as an engir	e or gear
	7.		of hybrid electric vehicle (HE)	-				efer	ence	annlication using	ΜΔΤΙΔΒ
	8.		of HEV PO reference applicati					cici	crice		
	9.		of HEV P1 reference applicati								
	10.	-	of Electric Vehicle reference a		-			TLAE	3		
Cours			s: At the end of the course stu								
1.	-		1ATLAB as a tool to analyze th					nver	ntior	nal vehicle.	
2.	-		he working of TCM used in co								
3.			ransmission control module s								n changes.
4.			hybrid electric vehicle (HEV) i			_	t refe	eren	ce ap	plication.	
5.	Us	se Elect	ric Vehicle reference applicat	ion in T	VIAIL	AB					
Cours	 ب∩ م:	itcome	s Mapping with Program Out	romer	8, DC	0					
cours			Program Outcomes-		2	3	4	5	6	PSO↓	
					-	5		5	Ű		
			↓ Course Outcomes							1 2	
			22EVT105.1	1	2	2	3				
			22EVT105.2	1	2	2	3				
		F	22EVT105.3	1	2	2	3				
			22EVT105.4	1	2	2	3				



	22EVT105.5	1	2	2	3			
1: Low 2	: Medium 3: High							

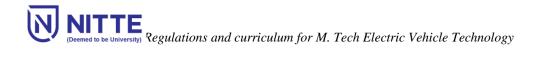
REFERENCE BOOKS:

1) <u>https://in.mathworks.com/help/autoblks/powertrain-reference-applications.html</u>

Advanced Battery Technology for Electrical Vehicles Course Code: 22EVT111 Course Type: PEC Teaching Hours/Week (L: T: P): 03 3:0:0 Credits: **Total Teaching Hours:** 40+0+0 CIE + SEE Marks: 50+50 **Teaching Department: Electrical and Electronics Engineering Course Objectives:** To understand electrical vehicle operation & battery basics 1. 2. To study the electric vehicle battery requirement and battery efficiency 3. To explain electric vehicle battery charging methods To understand electric vehicle fast charging & discharging behaviour 4. To understand electric vehicle battery performance 5. UNIT-I **ELECTRIC VEHICLE BATTERIES** 04 Hours Electric Vehicle Operation, Battery Basics, Introduction to Electric Vehicle Batteries, Fuel Cell Technology, Choice of a Battery Type for Electric Vehicles **ELECTRIC VEHICLE BATTERY EFFICIENCY** 06 Hours Effects of VRLA Battery Formation on Electric Vehicle Performance, Regenerative Braking, Electric Vehicle Body and Frame, Fluids, Lubricants, and Coolants, Effects of Current Density on Battery Formation, Effects of Excessive Heat on Battery Cycle Life, Battery Storage, The Lithium-ion Battery, Traction Battery Pack Design **ELECTRIC VEHICLE BATTERY CAPACITY** 05 Hours Battery Capacity, The Temperature Dependence of Battery Capacity, State of Charge of a VRLA Battery, Capacity Discharge Testing of VRLA Batteries, Battery Capacity Recovery, Definition of NiMH Battery Capacity, Li-ion Battery Capacity, Battery Capacity Tests, Energy Balances for the Electric Vehicle UNIT-II **ELECTRIC VEHICLE BATTERY CHARGING** 05 Hours Charging NiMH Batteries, Rate of Charge Effect on Charge Acceptance Efficiency of Traction, Battery Packs, Environmental Influences on Charging, Charging Methods for NiMH Batteries, Charging Technology, Battery Pack Corrective Actions **ELECTRIC VEHICLE BATTERY FAST CHARGING** 06 Hours On-board & off-board charging, The Fast Charging Process, Fast Charging Strategies, The Fast Charger Configuration, Using Equalizing/Leveling Chargers, Inductive Charging-Making Recharging Easier, Range Testing of Electric Vehicles Using Fast Charging, Electric Vehicle Speedometer Calibration. Wireless Charging **ELECTRIC VEHICLE BATTERY DISCHARGING** 04 Hours Definition of NiMH Battery Capacity, Discharge Capacity Behavior, Discharge Characteristics of Li-ion Battery, Discharge of an Electric Vehicle Battery Pack, Cold-Weather Impact on Electric Vehicle Battery Discharge



		UN	IT-III							
ELECTRIC VI	HICLE BATTERY PERFORMANC	CE								10 Hours
Control, High Spillage and E	erformance Management System, Voltage Cabling and Disconnects, ectric Shock, Charging Technology, ests, Building Standards, Ventilatior	Safe Elect	ty in	Bat	tery	Desi	ign,	Battery	Pack Safe	ety—Electrolyte
			•11 1.							
	mes: At the end of the course stude						مه: ما			
	be battery basics and its different t the capacity of different types of									
	e the impacts of rate of charge effe								ferent ba	ttery charging
4. Comp	are the fast charging and dischargir	ng be	havi	or of	diffe	erent	t typ	es of bat	teries.	
5. Analyz safety	ze battery performance manageme	nt sy	stem	is us	ed w	ith r	espe	ect to bat	tery oper	ration and
Course Outco	mes Mapping with Program Outco	mes	& PS	60						
	Program Outcomes→	1	2	3	4	5	6	PS	O↓	
	↓ Course Outcomes							1	2	
	22EVT111.1			2					3	
	22EVT111.2			2					3	
	22EVT111.3			2					3	
	22EVT111.4			2					3	
	22EVT111.5			2					3	
1: Lov	v 2: Medium 3: High		I	1	1	1	I	1		
Textbook:										





Energy Storage Systems for EV	
Course Code: 22EVT112 Course Typ	e: PEC
Teaching Hours/Week (L: T: P): 3:0:0 Credit	
Total Teaching Hours: 40+0+0 CIE + SEE Mark	s: 50+50
Teaching Department: Electrical and Electronics Engineering	L
Course Objectives:	
1. To understand working of different types of electric vehicles.	
2. To explain the battery parameters.	
3. To understand different types of batteries.	
4. To illustrate battery charging and modelling	
5. To introduce novel and alternate energy sources.	
UNIT-I	1
Types of Electric Vehicle	07 Hours
Battery electric vehicles, The IC engine/electric hybrid vehicle, fuelled electric vehicles, Elect	
supply lines, Solar powered vehicles, Electric vehicles which use flywheels or super ca	pacitors, Electric
Vehicles for the Future	
Battery Parameters	08 Hours
Electrochemical Batteries, Cell and battery voltages, Charge (or Amp hour) capacity, Energy	•
energy, Energy density, Specific power, Amp hour (or charge) efficiency, Energy efficiency. S	elf-discharge
rates, Battery geometry, Battery temperature, Battery life and number of deep cycles.	
UNIT-II	05 11
Types of Batteries	05 Hours
Lead Acid Batteries, Nickel-based Batteries: Introduction, Nickel cadmium, Nickel metal h	yariae batteries
Sodium-based Batteries, Lithium Batteries, Metal Air Batteries,	10 Hours
Battery Charging and Modelling	
Battery Charging, Battery chargers, Charge equalization, The Designer's Choice of Battery, U	
Hybrid Vehicles, Internal combustion/battery electric hybrids, Battery/battery electric hybri using flywheels, Complex hybrids, Battery Modelling, the purpose of battery modelling, B	
circuit, Modelling battery capacity, Simulation a battery at a set power, Calculating the Per	
Approximate battery sizing	
Approximate battery sizing	
UNIT-III	
Alternative and Novel Energy Sources and Stores:	10 Hours
Introduction, Solar Photovoltaic, Wind Power, Flywheels, Ultra capacitors, Super Capacito	
Hydrogen Fuel Cells: Basic Principles, Hydrogen Storage I: Storage as Hydrogen, Hydrogen Sto	
Methods	hage II. Chemica
methodo	
Course Outcomes: At the end of the course student will be able to	
 Identify various types of electric vehicles and their performance parameters. 	
 Analyse the battery parameters and their variations during charge and discharge cyclic data and their variations during charge and their variations during charge and their variating charge and their variating charge and their v	
 Analyse the battery parameters and their variations during charge and discharge cyl List different types of batteries and analyse their performance parameters. 	
 4. Examine the battery charging requirements and develop the complete battery mode 	
5. Identify novel and alternate energy sources which could be used in EVs.	-1.
Course Outcomes Manning with Program Outcomes & PSO	
Course Outcomes Mapping with Program Outcomes & PSO	

		Program Outcomes \rightarrow	1	2	3	4	5	6	PS	O↓	
		↓ Course Outcomes							1	2	
		22EVT112.1					2				-
		22EVT112.2					2			2	
		22EVT112.3					2			2	
		22EVT112.4					2			2	
		22EVT112.5					2				
	1: Low 2	: Medium 3: High									-
REFERE	NCE BOC	OKS:									
1.	James L	arminie Oxford Brookes Universit	ty, C	xfor	d, UK	Joh	n Lov	wry A	Acenti D	esigns Lt	td., UK, Electric
	Vehicle	Technology Explained									
2.	M. Bara	k (Ed.), T. Dickinson, U. Falk, J.L. S	Sudv	vorth	л <i>,</i> Н.F	₹. Thi	irsk,	F.L. 1	Гуе, "Ele	ctroche	mical Power
	Sources	: Primary & Secondary Batteries"	, IEE	Ene	rgy S	eries	51, A	. Wł	neaton 8	Co, Exe	ter, 1980.
3.	Mehrda	d Ehsani, Yimi Gao, Sebastian E. (Gay,	Ali E	mad	i, Mo	oderi	n Ele	ctric, Hy	brid Eleo	ctric and Fuel
	Cell Veh	icles: Fundamentals, Theory and	Des	ign, (CRC F	Press	, 200)4.			

Speci	al Electrical Mach	hines	
Course Code:	22EVT113	Course Type:	PEC
Teaching Hours/Week (L: T: P):	3+0+0	Credits:	03
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
Teaching Department:	Electrical and E	lectronics Engineering	
Course Objectives:		g	
1. To introduce new and advanced electr	ical machines like	e, Switched Reluctance Motor, S	ynchronous
Reluctance motor, Permanent Magnet			•
Motors & linear electrical machine the	ir modeling and o	control.	
	UNIT-I		
Permanent Magnet Synchronous Machi	ne and control	strategies	08 Hours
Real-Time Model of a Two-Phase PMSM, Tran			Phase to Two-
Phase Transformation Unbalanced Operation			
Electromagnetic Torque, Steady-State Torque	e Characteristics ,	, Models in Flux Linkages, Equiv	alent Circuits,
Per Unit Model, Dynamic Simulation, Small-Sig	•	-	
Magnet Synchronous Machine, Vector Control	, Derivation of Ve	ctor Control, Drive System Sche	matic, Control
Strategies			1
Permanent Magnet Brushless DC Machines a			07 Hours
PM Brushless DC Machine, Modelling of PM Br			
Drive Scheme, Commutation Torque Ripple			•••
Advancing, Dynamic Modelling, Machine Ed			eration of the
PMBDC Motor with the Split Supply Converter	, Operational Mo	des of the Converter	
Switched Reluctance Motor (SRM)	UNIT-II		05 Hours
Construction, Principle of working, Basic SRM a	nalysis constrair	ots on pole arc and tooth arc. Po	
Circuits, Control of SRM, Rotor Position sense	•	•	
Sensorless Control of SRM.			
Synchronous Reluctance Motor (SyRM)			03 Hours
Construction, Working, Control of SyRM, Adva	ntage Applicatio	ns	
Converters for SRM Drives			07 Hours
Converter Configurations, Single-Switch-per-	Phase Converter	rs. $(\alpha+1)$ Switch and Diode C	
Comparison of Some Power Converters, Two-S			-
SRM Drive, Control Principle, Closed-Loop, Spe	-		
	UNIT-III		40
Linear Electric Machines			10 Hours
Linear Induction Motor (LIM) – Construction	· ·		-
Certain design aspects, Control of LIM. Line	•		
equation, control, Application. DC Linear Mo		· · ·	•
current tubular electromagnetic launcher, indu EML. Linear Reluctance Motor (LRM) – Constr		•	
Levitation Machines (LLM) – Principle of Levita	-		
and stiffness. Course Outcomes: At the end of the course st	udent will he able	e to	
and stiffness. Course Outcomes: At the end of the course still 1. Examine control strategies of permane			





3.	Comprehend the construction and working	ng pr	incip	ole of	f SRN	/I and	d SyR	M mot	ors and t	their control.
4.	Analyze the converters for controlling of s	swite	ched	relu	ctand	ce m	otor.			
5.	Examine the basics, construction and wor	king	prin	ciple	e of v	ario	us lin	ear ele	ctric mo	tors.
Cour	rse Outcomes Mapping with Program Outco	ome	s & I	PSO		1				
	Program Outcomes→	1	2	3	4	5	6	PS	50↓	
	↓ Course Outcomes							1	2	
	22EVT113.1	2						2		
	22EVT113.2	2						2		
	22EVT113.3	2						2		
	22EVT113.4	2						2		
	22EVT113.5	2						2		
	1: Low 2: Medium 3: High	I	I			I				
REFE	RENCE BOOKS:									
1	R. Krishnan, "Permanent Magnet Synchro	nou	s and	d Bru	shle	ss D(C Mo	tor Driv	ves" CRC	press, 2010.
2	E. G Janardanan, 'Special Electrical Machin	nes'	PHI	Delhi	i, 201	14.				
3	T.J.E. Miller, 'Brushless magnet and Reluc	tanc	e mo	otor	drive	s', C	lared	on pres	ss, Londo	on, 1989.
4	R.Krishnan, 'Switched Reluctance motor	drive	es', (CRCp	oress	, 20	01.			

Automo	otive Electronic	s for EVs	
Course Code	e: 22EVT121	Course Type:	PEC

	Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03						
	Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50						
	Teaching Department:	Electrical and E	ectronics Engineering							
Course	Objectives:									
1.	Understand the electrical and electror	ic systems in vehi	cles							
2.										
3.										
4. Comprehend the lighting systems in vehicles										
5. Understand the auxiliaries and chassis electric systems in automobiles.										
UNIT-I										
Electr	ical And Electronic Systems in the	Vehicle:		06 Hours						
	iew, Motronic engine management onic stability program, Adaptive cruis	•	0 0	technology,						
	principles of networking		innent System.	03 Hours						
	rk topology, Network organization, OSI	reference model	Control mechanisms							
	notive networking	reference model,	control meenanisms.	05 Hours						
	system functions, Requirements for bu	is systems. Classi	fication of hus systems Appli							
	e, coupling of networks, Examples of net									
		UNIT-II		-						
Bus sy				11 Hours						
standa LIN bu MOST Blueto	 CAN bus: Applications, Topology , Data transmission system, CAN protocol , data transfer sequence, standardization, characteristics. LIN bus: Overview, Applications, Data transfer, Bus access, LIN protocol, network management, example. MOST bus: Introduction, features, data transfer, administrative functions, application layer Bluetooth: Overview, applications, Bluetooth versions, transmission technology, power classes, topology. 									
	al data channel, physical connections, A ng system	renneedure.		05 Hours						
	g fundamentals Lighting circuits, Gas	discharge and LE) lighting Case studies Diagn							
-	n faults, Advanced lighting technology, N	-		Using lighting						
		UNIT-III		.						
Auxili	aries in vehicles			05 Hours						
	creen washers and wipers, signalling circ	cuits, Other auxilia	ry systems, Case studies, Diagn	osing auxiliary						
system										
	ced auxiliary systems technology, new c	levelopments in a	uxiliary systems							
	is Electrical systems			06 Hours						
	ck brakes, Active suspension, Traction c									
	ns, Case studies, Diagnosing chassis elec	•	s, Advanced chassis systems tee	chnology,						
New d	evelopments in chassis electrical system	IS		1						
				1						
	Outcomes: At the end of the course st									
1.	Identify various electrical & electronic			3.						
2.	Discuss the basic principles of network	- ·	in an automotive.							
3.	Explain requirements and types of bus									
4.	Comprehend the lighting systems in ve									
5.	Understand the auxiliaries and chassis	electric systems i	n automobiles							



Course	Outcomes Mapping with Program Outc	omes	& P:	SO							
	Program Outcomes $ ightarrow$	1	2	3	4	5	6	PS	60↓		
	↓ Course Outcomes							1	2		
	22EVT121.1	2		2							
	22EVT121.2	2		2							
	22EVT121.3	2		2							
	22EVT121.4	2		2							
	22EVT121.5	2		2							
	1: Low 2: Medium 3: High										
REFERE	NCE BOOKS:										
1.	Robert Bosch GmbH, "Bosch Automotiv	e Eleo	ctrics	and	Aut	omo	tive	Electron	ics", 5th	Edition. Jo	hn
	Wiley & Sons Ltd, 2007.										
2.	William B. Ribbens, "Understanding Aut	tomo	tive E	Elect	ronic	:s", 6	6th Eo	dition, E	lsevier, 2	2003.	
3.	Tom Denton: "Automobile Electrical and Heinemann Publication, 2004.	d Elec	tron	ic Sy	sterr	ıs", 3	Brd E	dition, E	lsevier B	utterworth	1-

	Modeling and Analysis of Electrical Machines							
	Course Code: 22EVT122 Course Type: PEC							
	Teaching Hours/Week (L: T: P):	3+0+0	Credits:	03				
	Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50				
	Teaching Department: Electrical and Electronics Engineering							
Course	e Objectives:							
1.	To study the basic concepts of modelir	ng and reference	frame theory					
2.	To model various DC machine under tr	ansient and stead	ly state conditions					
3.	To understand the dynamic modeling of	of induction mach	ines					
4.	To model single-phase and three-phase	e transformers						
5.	To know synchronous machine modeli	ng.						
_		UNIT-I						

Basic Concepts of Modeling

Basic two pole machine representation of commutator machines, 3-phase synchronous machine with and without damper bar and 3-phase induction machine, Kron's primitive machine-voltage, current and torque equations.

Reference Frame Theory

Real time model of a two-phase induction machine, transformation to obtain constant matrices, three phase to two phase transformation, power equivalence.

DC Machine Modeling

Mathematical model of separately excited DC motor-steady state and transient state analysis, sudden application of inertia load, transfer function of separately excited DC motor, mathematical model of dc series motor, shunt motor, linearization techniques for small perturbations



05 Hours

04 Hours

06 Hours



					1						
Dynam	nic Mode	ing of Three Phase Induction Ma	-	<u> T- </u>							07 Hours
		odel in arbitrary frame, electron			tor	nue	deri	vatio	on of co	ommonly	
		stator reference frames model	•			•				-	
		es model, equations in flux link									
		Aodeling	- 9-	- ,		-		,			08 Hours
ntrodı	uction, si	ngle phase transformer model,	three	e ph	ase	trans	forr	ner	connec	tions, per	phase analysis
	•	, per unit normalization, per unit		•		•		•	•	⁵ base, per	r unit analysis o
norma	il system,	regulating transformers for voltage	ge ar	nd pł	nase	angl	e co	ntro			
Mada	ling of (washings	UN	IT-II							10 Hours
		Synchronous Machines Ditage equations and torque eq	uatio	nc i	n m	achir		ariah	nles sta	ator volta	
		tor reference frame variables, Par									
	•	between rotors, per unit system.									, ,
Course	e Outcom	es: At the end of the course stude	ent v	vill b	e ab	le to					
1.	1	e basic concepts of modeling of e								erence fra	ame theory
2.		he DC machine model under tran									
3. 4.		he dynamic model of 3phase indu he single-phase and three-phase									-
- .		ansformer	trans		ners	mou		ana	iyze the	e per unit i	nodel of the 5
5.		e the synchronous machine mode	eling	and	obta	in its	s per	unit	: equiva	lent.	
Course	-										
course	e Outcom	es Mapping with Program Outco	1	1	T	4			D	501	
	e Outcom	es Mapping with Program Outco Program Outcomes \rightarrow	mes 1	& P 9	50 3	4	5	6	Р	so↓	
	e Outcom		1	1	T	4	5	6	P 1	SO↓ 2	
200130	e Outcom	Program Outcomes→ ↓ Course Outcomes	1	1	T		5	6			
	e Outcom	Program Outcomes→	1	1	T	4	5	6			
	e Outcom	Program Outcomes→ ↓ Course Outcomes	1	1	T		5	6			
	e Outcom	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2	1 2 2	1	T	3	5	6			
	e Outcom	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3	1 2 2 2	1	T	3 3 3	5	6			
	e Outcom	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2	1 2 2	1	Т	3	5	6			
	e Outcom	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3	1 2 2 2	1	Т	3 3 3	5	6			
		Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.5	1 2 2 2 2 2	1	Т	3 3 3 3	5	6			
		Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4	1 2 2 2 2 2	1	Т	3 3 3 3	5	6			
	1: Low	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.5 2: Medium 3: High	1 2 2 2 2 2	1	Т	3 3 3 3	5	6			
REFERI	1: Low	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.5 2: Medium 3: High DKS:	1 2 2 2 2 2 2	2	3	3 3 3 3 3			1	2	/ate Ltd. 2009
	1: Low ENCE BOO R. Krish	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.5 2: Medium 3: High	1 2 2 2 2 2 2 2	2	3	3 3 3 3 3	Cont	rol",	1	2	
REFERI 1.	1: Low ENCE BOO R. Krish P.C.Kra	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.5 2: Medium 3: High DKS: nan, "Electric Motor Drives - Moo	1 2 2 2 2 2 2 2	2	3	3 3 3 3 3	Cont	rol",	1	2	
REFERI 1.	1: Low ENCE BOO R. Krish P.C.Kra 2ndEdit Arthur	Program Outcomes→ ↓ Course Outcomes 22EVT122.1 22EVT122.2 22EVT122.3 22EVT122.4 22EVT122.4 22EVT122.5 2: Medium 3: High DKS: nan, "Electric Motor Drives - Moc use, Oleg Wasynczuk, Scott D.Suc	1 2 2 2 2 2 2 2 2 2 2 3 4 boff	2 g, Ar , "Ar	3 nalys	3 3 3 3 3 3 3 is s of ysis",	Cont Elec	rrol",	1 PHI Lea I Machi	2 arning Priv nery and I arson, 200	Drive Systems", 09.

		22EVT123		DEC
	Course Code:		Course Type:	PEC
	Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03
	Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
	Teaching Department:	Electrical and E	ectronics Engineering	
	e Objectives:			
1.	To identify various power semicondu application.			
2.	To understand the static and dynam semiconductor devices			
3.	To enable the students, the knowled applications		· · · · · · · · · · · · · · · · · · ·	r electronics
4.	To understand the control and Gate Dr	•	for different power devices.	
		UNIT-I		
	er Diodes			05 Hours
	ate losses, switching characteristics-turn-			
	tky diodes, series and parallel connectior r BJT'S	is of diodes, shub	ber requirements for diodes, di	
	ate losses, switching characteristics, res			05 Hours
	fications, turn-on transient, turn-off trans	ciont ctorago tim		itching losses
device	e protection- snubber requirements for B	-	•	-
device Gate		UT'S and snubber	design - switching aids.	05 Hours
device Gate Basic minim	e protection- snubber requirements for B Turnoff Thyristor (GTO)	UT'S and snubber	design - switching aids. O turn-on transient, GTO turn	05 Hours -off transient
device Gate Basic minim	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching on num on and off state times, gate drive req	UT'S and snubber	design - switching aids. O turn-on transient, GTO turn	05 Hours -off transient
device Gate Basic minim protec Powe	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching o num on and off state times, gate drive req ction of GTO'S.	BJT'S and snubber characteristics, GT juirements, maxir UNIT-II	design - switching aids. O turn-on transient, GTO turn num controllable anode current	05 Hours -off transient t, over current 07 Hours
device Gate Basic minim protee Basic charae transi transi MOSF protee	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching on hum on and off state times, gate drive required ction of GTO'S. r MOSFET'S structure, V-I characteristics, turn-on cteristics, resistive switching specificat ent and di/dt limitations, turn-off transic ents on switching stresses and losses - d ET'S, FBSOA and RBSOA curves, device ction, Miller region.	BJT'S and snubber characteristics, GT juirements, maxin UNIT-II process, on sta ions, clamped ir ent, turn off time lv/dt limitations, g ce protection —sr	design - switching aids. O turn-on transient, GTO turn num controllable anode current ate operation, turn-off proce iductive switching specificatio , switching losses, effect of rev gating requirements, gate char	05 Hours -off transient t, over current 07 Hours ess, switching ons - turn-or verse recovery ge - ratings of T drivers and
device Gate Basic minim protee Basic charae transi transi MOSF protee Insula	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching on hum on and off state times, gate drive required ction of GTO'S. r MOSFET'S structure, V-I characteristics, turn-on cteristics, resistive switching specificat ent and di/dt limitations, turn-off transide ents on switching stresses and losses - d ET'S, FBSOA and RBSOA curves, device ction, Miller region. ated Gate Bipolar Transistors (IGBT'	BJT'S and snubber characteristics, GT juirements, maxin UNIT-II process, on sta ions, clamped ir ent, turn off time lv/dt limitations, p ce protection —sr	design - switching aids. O turn-on transient, GTO turn num controllable anode current ate operation, turn-off proce iductive switching specification , switching losses, effect of rev gating requirements, gate char nubber requirements, MOSFE	05 Hours -off transient t, over curren 07 Hours ess, switching ons - turn-or rerse recovery ge - ratings o T drivers and 08 Hours
device Gate Basic minim protec Basic charac transi transi transi mOSF protec Insula Basic clamp gating times	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching on hum on and off state times, gate drive required ction of GTO'S. r MOSFET'S structure, V-I characteristics, turn-on cteristics, resistive switching specificat ent and di/dt limitations, turn-off transic ents on switching stresses and losses - d ET'S, FBSOA and RBSOA curves, device ction, Miller region.	UNIT-II UNIT-II process, on sta ions, clamped in ent, turn off time lv/dt limitations, g ce protection —sr S) c, switching chara GBT turn-on trans and RBSOA curves current protection	design - switching aids. O turn-on transient, GTO turn num controllable anode current ate operation, turn-off proce iductive switching specification , switching losses, effect of rev gating requirements, gate charged nubber requirements, MOSFE int, IGBT turn off transient- cu , switching losses - minimum of n of IGBT'S, short circuit protect	O5 Hours -off transient t, over current O7 Hours ess, switching ons - turn-or rerse recovery ge - ratings o T drivers and O8 Hours specifications urrent tailing n and off state
device Gate Basic minim protec Powe Basic charac transi transi transi MOSF protec Insula Basic clamp gating times	e protection- snubber requirements for B Turnoff Thyristor (GTO) structure and operation, GTO switching on hum on and off state times, gate drive required ction of GTO'S. r MOSFET'S structure, V-I characteristics, turn-on cteristics, resistive switching specificat ent and di/dt limitations, turn-off transitions ents on switching stresses and losses - di ET'S, FBSOA and RBSOA curves, device ction, Miller region. ated Gate Bipolar Transistors (IGBT' structure and operation, latch up IGBT bed inductive switching specifications - IC grequirements -ratings of IGBT'S, FBSOA a	BJT'S and snubber characteristics, GT juirements, maxin UNIT-II process, on sta ions, clamped in ent, turn off time lv/dt limitations, g ce protection —sr S) , switching chara GBT turn-on trans and RBSOA curves current protection, s and protection,	design - switching aids. O turn-on transient, GTO turn num controllable anode current ate operation, turn-off proce iductive switching specification , switching losses, effect of rev gating requirements, gate charged nubber requirements, MOSFE int, IGBT turn off transient- cu , switching losses - minimum of n of IGBT'S, short circuit protect	05 Hours -off transient t, over curren 07 Hours ess, switching ons - turn-or rerse recovery ge - ratings o T drivers and 08 Hours specifications urrent tailing n and off state
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(Deemed to be University) Regulations and curriculum for M. Tech Electric Vehicle Technology

Cours	Course Outcomes: At the end of the course student will be able to						
1.	Comprehend the types, characteristics, protection and modeling of Power Diodes, Power BJT's and						
	Thyristors.						
2.	Analyze the structure, characteristics, gate drive requirements and modeling of GTO's and TRIACS.						
3.	Explain the principle of operation of MOSFET with their characteristics and effect of reverse						
	recovery transients on switching stresses & losses						
4.	Explain the principle of operation of IGBT with their characteristics and protection against over-						
	current & short-circuit.						
5.	Illustrate the construction and features of the emerging power electronic devices						

Course Outcomes Mapping with Program Outcomes & PSO

	-		r					
Program Outcomes→	1	2	3	4	5	6	PS	O↓
↓ Course Outcomes							1	2
22EVT123.1			2				1	
22EVT123.2			2				1	
22EVT123.3			2				1	
22EVT123.4			2				1	
22EVT123.5			2				1	

1: Low 2: Medium 3: High

REFERE	REFERENCE BOOKS:						
1.	Ned Mohan, Tore M. Undeland, William P. Robbins, "Power Electronics Converters, Applications,						
	and Design", 3rdEdition. Wiley India Pvt Ltd, 2011.						
2.	G. Massobrio, P. Antognetti, "Semiconductor Device Modeling with Spice", McGraw-Hill, 2nd						
	Edition, 2010.						
3.	B. Jayant Baliga, "Power Semiconductor Devices", 1 st Edition, International Thompson Computer						
	Press, 1995.						
4.	V. Benda, J. Gowar, and D. A. Grant, "Discrete and Integrated Power Semiconductor Devices:						
	Theory and Applications", John Wiley & Sons, 1999.						
5.	Joseph Vaithiyathil, "Power Electronics Principles and Applications" Mc Graw Hill Education, 2010.						

		Emt	bedde	d Syste	ems					
		Course Code:	22EVT	131				Cour	rse Type:	PEC
	Те	aching Hours/Week (L: T: P):	3:0:0						Credits:	03
		Total Teaching Hours:	40+0+	0				CIE + SE	E Marks:	50+50
		Teaching Department: I	lectric	al and E	lect	ron	ics I	inginee	ring	
Cour	se Objectiv	es:								
1.	To famil	iarize the concept of embedde	d syster	n						
2.	To ident	ify various processing element	s of em	bedded s	yster	n an	nd th	eir struct	ture	
3.	To intro	duce various memory elements	s used i	n embed	ded s	syste	ems			
4.	To unde	rstand various interfacing devi	ces used	d with en	nbedo	ded	syst	ems		
5.	To intro	duce the concept of Real Time	Operati	ing Systei	ms					
			UN	IIT-I						-
Intro	oduction									03 Hours
Embe	edded syste	ems overview-design challenge	-optimi	zing metr	rics-p	roce	esso	technolo	ogy-IC tec	hnology
Proc	essing Elem	ients								12 Hours
view	and develo	pment environment – ASIPs - s	electin	g a micro	proce	esso	r - g	eneral pu	irpose pro	cessor desigr
			UN	IT-II						
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	· · ·									06 Hours
Intro	duction-me	mory write-ability and storag	e perm	anence, (comn	non	mei	nory typ	es-compo	
mem	duction-me ory hierarc	emory write-ability and storag hy and caches-advanced RAM.	e perm	anence, (comn	non	mei	nory typ	es-compo	1
Intro mem Inte i	duction-me ory hierarc r facing									sing memory
Intro mem Inte i Intro	duction-me ory hierarc r facing duction-cor	hy and caches-advanced RAM.	essor in	terfacing	: I/O	add	ress	ing, inter	rupts, DM	sing memory 09 Hours A-Arbitration
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	22EVT131.4	2	3				-
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	22EVT131.5	2	3				
	1: Low 2: Medium 3: High						1
REFERE	NCE BOOKS:						
1.	Frank Vahid and Tony Givargis, Embe	dded syster	n design: A	\ unifi	ed hardv	vare/Softw	vare
	introduction, Third edition, John Wile	ey & sons, 2	010				
2.	Embedded System Premier, David E S	imon, Addi	son Wesley	y			
3.	Embedded System 2nd Edition by Raj	Kamal, Tat	ta McGraw	-Hill E	ducatior	า	
4.	Wayne Wolf, Computers as Compone	ents: Princip	les of Emb	edded	l Compu	ting Syster	n Design,
	Morgan Kaufman Publishers, 2008.						
5.	Santanu Chattopadhyay, Embedded s	system Desi	gn, PHI Lea	arning	Pvt. Ltd	., 2010	
6.	Steave Heath, Embedded system Des	ign, Second	edition, 20	003			
7.	Daniel D. Gajski, Samar. Abdi, Andrea	s. Gerstlaue	er Embedd	ed sys	tem des	ign: Mode	ling, synthesis
	and verification, Springer, 2009						
8.	Jonathan.W.Valvano, Embedded Mic	rocomputer	systems: I	Real T	ime Inte	rfacing, Th	ird edition,
	Cengage learning,2012						

		Applied Mathen	natics	
Cou	rse Code:	22EVT132	Course Type:	PEC
Теа	ching Hours/Week (L: T: P):	3:0:0	Credits:	03
Tota	al Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
Теас	hing Department: Electrical an	d Electronics Engi	neering	
Cour	se Objectives:			
1.	To introduce numerical methods	for the solution of a	Igebraic and transcendenta	
2.	To understand various technique	es to get Numerical S	olution of Partial Differentia	al Equations
3.	To solve the problems pertaining value	g to linear algebra, s	ystem of linear algebraic e	quations and Eigen
4.	To introduce linear programm pertaining to graph theory.	ing technique for c	optimizing the solution ar	nd solve problems
UNIT	-1			
Num	erical Methods			08 Hours
Mulle	ion of algebraic and transcendenta er method (no derivation) Chebysh ergence, system of non-linear equ	nev method, general ations and complex	iteration method (first or	der), acceleration o
equa	tions – Birge - Vieta method and Ba	irstow's method.		

Classification of second order equations, parabolic equations- solution of one dimensional heat equation, explicit method, Crank-Nicolson method and Du Fort-Frankel method, hyperbolic equations- solution of one dimensional wave equation, Numerical solution of differential equations – Numerov method.

UNIT-II

Linear Algebra

08 Hours

Vector spaces, linear dependence, independence, basis and dimension, elementary properties.

System of Linear Algebraic Equations and Eigenvalue Problems: Iterative methods - Gauss-Seidal method, SOR method, Eigenvalue problems – Gerschgorian circle, Eigenvalues and Eigenvectors of real symmetric matrices -Jacobi method, Givens method. Conditions/Tests for- positive definite, semi-definite and indefinite Matrices and comment on stability

Optimization and Graph Theory

07 Hours

09 Hours

Optimization

Linear programming- formulation of the problem, graphical method, general linear programming problem, simplex method, artificial variable technique -M-method.

Graph Theory: Basic terminologies, types of graphs, sub graphs, graphs isomorphism, connected graphswalks, paths, circuits, connected and disconnected graphs, operations on graphs, Eulerian paths and circuits, Hamiltonian paths and circuits, applications of graphs.

UNIT-III

Interpolation and Linear Transformations

Interpolation: Hermit interpolation, spline interpolation.

Linear Transformations: Definition, properties, range and null space, rank and nullity, algebra of linear transformations- invertible, singular and nonsingular transformations, representation of transformations by matrices.

Course	e Outcomes: At the end of the course student will be able to
1.	Apply numerical methods for the solution of algebraic and transcendental
2.	Use various techniques to get Numerical Solution of Partial Differential Equations
3.	Analyze the problems pertaining to linear algebra and solve system of linear algebraic equations and
	Eigen value problems
4.	Apply linear programming technique for optimizing the solution and analyze problems pertaining to
	graph theory
5.	Comprehend interpolation problems and apply linear transformations techniques.

Course Outcomes Mapping with Program Outcomes & PSO

	Program Outcomes $ ightarrow$	1	2	3	4	5	6	PSO↓		
	↓ Course Outcomes							1	2	
	22EVT132.1			2		2				
	22EVT132.2			2		2				
	22EVT132.3			2		2				
	22EVT132.4			2		2				
	22EVT132.5			2		2				
1: Low 2: Mediu	ım 3: High		1	1	1	1	1	1	1	





REFERE	ENCE BOOKS:
1.	M K Jain, S R K Iyengar and R K Jain, "Numerical Methods for Scientific and Engineering
	Computations", New Age International, 2004.
2.	M K Jain, "Numerical Solution of Differential Equations", 2nd Edition, New Age International, 2008.
3.	Dr. B.S. Grewal, "Numerical Methods in Engineering and Science", Khanna Publishers, 1999.
4.	Dr. B.S. Grewal, "Higher Engineering Mathematics", 41st Edition, Khanna Publishers, 2011.
5.	Narsingh Deo, "Graph Theory with Applications to Engineering and Computer Science", PHI, 2012.
6.	Kenneth Hoffman and Ray Kunze, "Linear Algebra", 2nd Edition, PHI, 2011.

Digital Controller

			250
Course Code:	22EV1133	Course Type:	PEC
Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50

	Teaching Department: Electrical and Electronics Engineering	
Cour	se Objectives:	
1.	Analyse the overview of dsPIC33CH512MP508 family digital signal controller	
2.	Understand the peripherals interrupt and DMA controllers.	
3.	Analyse ADC and timer modules of dsPIC33CH512MP508 family controllers.	
4.	Analyse PWM and I/O modules of dsPIC33CH512MP508 family controllers.	
5.	Analyse I2C,SPI and CAN protocols used in the DSP.	
	UNIT-I	
Intro	duction to the dsPIC33C family digital signal controller	07 Hours
Block	diagram of dsPIC33/PIC24 Enhanced CPU, On chip memory and Peripherals, Applications	and Features
of ds	PIC Family, Data memory, Modulo Addressing	
Inter	rupt Controller	08 Hours
Intro	duction, Interrupt Vector Table (IVT), interrupt control and status registers, non-maskable	traps interrupt
proce	essing timing, interrupt setup procedures	
	UNIT-II	
Analo	og to Digital Converter	05 Hours
Intro	duction, Registers, Register Map, Conversion Sequence, ADC Operation, Application Examp	les, Operation
Durir	g Power-Saving Modes, Effects of Reset	
Confi	gurable Logic Cell (CLC): Overview and Features	
Time	er 1 Module	03 Hours
Intro	duction, Control Registers, Modes of Operation, Interrupts, Operation in Power-Saving Mo	odes

High resolution PWM with Fine Edge Placement

Registers, Register Maps, Common Functions Register Map, PWM Generator Register Map, Architecture Overview Operation, PWM Clocking, PWM Generator (PG) Features, Common Features, Lock and Write Restrictions, Application Examples.

UNIT-III

10 Hours

07 Hours

Queued Serial Peripheral Interface: Overview, Block Diagram, Signal Description, Memory map Registers, Operating Modes

Inter-Integrated Circuit (I2C): Features, modes of Operation, Block Diagram, Memory Map and Registers, Functional Description.



CAN Flexible Data-Rate (FD) Protocol Module: Introduction, CAN FD Message Frames, Registers, Modes of Operation, Configuration

Cours		es: At the end of the course stude									 	
1.	Analyse	the overview of dsPIC33CH512N	1P50	8 far	nily o	digita	al sig	nal c	ontrolle	r		
2.	Underst	and the peripherals interrupt and	l DM	А со	ntrol	lers.					 	
3.	Analyse	ADC and timer modules of dsPIC	33C⊦	1512	MP5	08 fa	mily	con	trollers.		 	
4.	Analyse	PWM and I/O modules of dsPIC3	3CH	512N	1P50	8 far	nily	cont	rollers.		 	
5.	Analyse	I2C, SPI and CAN protocols used i	n th	e DSI	Ρ.							
Cours	se Outcom	es Mapping with Program Outco	mes	& PS	50	1		1			 	
		Program Outcomes $ ightarrow$	1	2	3	4	5	6	PS	C↓		
		↓ Course Outcomes							1	2		
									T	Z		
		22EVT133.1		2			2		2	2		
		22EVT133.2		2			2		2	2		
		22EVT133.3		2			2		2	2		
		22EVT133.4		2			2		2	2		
		22EVT133.5		2			2		2	2		
	1: Low	2: Medium 3: High									 	
REFE	RENCE BO	OKS:									 	
1	dsPIC3	3Cxxx Reference manual.									 	
2	dsPIC3	3CH512MP508-Family-Data-Sheet	t-DS7	7000	5371	D					 	

		Programming	Dig	ital	Sig	nal	Cor	itro	ller		
		Course Code:	22EV	TAU	J 11				Cou	rse Type:	AUDIT
	Teac	ching Hours/Week (L: T: P):	0:0:2							Credits:	-
		Total Teaching Hours:	0+0+	26				C	E + SE	E Marks:	-
		Teaching Department: I	lectri	cal a	and	Elect	tron	ics I	Ingine	ering	
		on Programming a DSC.							-	_	
Topics c											
•		chitectural features of 16-bit DSC									
•		gisters / peripherals available									
•		ogramming of DSC	1 1	ODI	0	DC	<u>л</u> .		1 DWD		. 1 1
•		nple experiments to use the perip ntroller	oherals,	GPI	U, A	ADC,	Tim	ier ar	nd PWM	t using16 bi	t dıgıtal sıgnal
Course	Outcom	nes: At the end of the course stu	ident v	vill b	e abl	e to					
1.	Descrik	be the architecture and pin co	nfigu	atio	n of	DSC	•				
2.	Illustra	te different control and data	registe	ers.							
3.	Develo	p programs for the functionir	ng of (GPIO	and	l Tim	ners				
4.	Develo	p programs for the functionir	ng of I	PWI∕	1 mo	dule)				
5.	Analyz	e and Develop program DSC	for sca	alar o	contr	o lo	f mo	otor.			
Course	Outcor	nes Mapping with Program O	1	1			1	1			
		Program Outcomes-	→ 1	2	3	4	5	6	PS	O↓	
		↓ Course Outcomes							1	2	
		22EVTAU11.1				2	3				
							5				
		22EVTAU11.2				2	3				
		22EVTAU11.3		1		2	3				
		22EVTAU11.4		-		2	3		2	3	
							5			5	
		22EVTAU11.5				2	3		3		
	1: Lov	v 2: Medium 3: High	I	1	1	1					
	1, 10,										

	Power E	lectronic Con	iverters	
	Course Code:	22EVT201	Course Type:	PCC
	Teaching Hours/Week (L: T: P):	4:0:0	Credits:	04
	Total Teaching Hours:	50+0+0	CIE + SEE Marks:	50+50
	Teaching Department:	Electrical and E	lectronics Engineering	
Course	Objectives:			
1.	Understand the essentials of power co	nversion		
2.	Design practical non isolated converter	rs		
3.	Design practical offline converters			
4.	Design practical isolated converters			
5.	Bidirectional converter topologies for I	Electric Vehicles		
		UNIT-I		1
Power	Semiconductor Devices			05 Hours
[deal a	and Typical Power Switching Wave	eforms, Ideal a	nd Typical Power Device Ch	naracteristics
Unipol	ar Power Devices, bipolar Power Dev	vices, MOS-Bipo	lar Power Devices.	<u>.</u>
Introdu	uction to Power Conversion			06 Hours
	ting power with resistors, Converting po			converter,
boost c	converter, buck-boost Converter, Input	filtering, RLC filte	r.	
		UNIT-II		
Non-is	olated converters			09 Hours
	onverter, Boost converter, Buck-Boost c	onverter, analysi	s design and simulation.	00 110010
	,			
		UNIT-III		1
Offlin	e Converters—the front end			11 Hours
Rectifie	er Bridge: Capacitor selection, Diode Co , Input Power Factor, Hold-Up Time, In-		Rms current in the Capacitor, C	Jurrent in the
Diodes <u></u> Power Power The Va	Factor Correction : Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power	leed for Storage, Factor Correction	Passive PFC, Improving the Harm on, Constant on-time borderline	nonic Content
Diodes <u></u> Power Power The Va	Factor Correction : Definition of Power Factor Correction? Harmonic Limits, A N	leed for Storage, Factor Correction	Passive PFC, Improving the Harm on, Constant on-time borderline	nonic Content
Diodes <u></u> Power Power The Va	Factor Correction : Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power	leed for Storage, Factor Correction	Passive PFC, Improving the Harm on, Constant on-time borderline	nonic Content
Diodes Power Power The Va fixed- f	Factor Correction: Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power requency continuous mode (CCM), Ana	leed for Storage, I Factor Correctic lytical control lav UNIT-IV	Passive PFC, Improving the Harm on, Constant on-time borderline v.	nonic Content mode (BCM)
Diodes, Power Power The Va fixed- f Isolate Simulat parasit clampin	Factor Correction: Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power requency continuous mode (CCM), Ana ed Converters tions and practical designs of flyback co ic elements, flyback waveforms with pa ng network, two-switch flyback, simula onverter, need for a complete core res	leed for Storage, Factor Correction lytical control lav UNIT-IV Donverters, an ison arasitic elements tions and practic	Passive PFC, Improving the Harm on, Constant on-time borderline v. lated buck-boost, flyback wavef , clamping the drain excursion, cal designs of forward converter	onic Content mode (BCM) 09 Hours forms withou designing the rs, an isolated
Diodes Power Power The Va fixed- f Isolate Simulat parasit clampin buck co	Factor Correction: Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power requency continuous mode (CCM), Ana ed Converters tions and practical designs of flyback co ic elements, flyback waveforms with pa ng network, two-switch flyback, simula onverter, need for a complete core res	leed for Storage, Factor Correction lytical control lav UNIT-IV Donverters, an ison arasitic elements tions and practic	Passive PFC, Improving the Harm on, Constant on-time borderline v. lated buck-boost, flyback wavef , clamping the drain excursion, cal designs of forward converter	onic Content mode (BCM) 09 Hours forms withou designing the rs, an isolated
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Diodes, Power Power The Va fixed- f Isolate Simulat parasit clampin buck co bridge Bidirec Introdu Reduce	Factor Correction: Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power requency continuous mode (CCM), Ana ed Converters tions and practical designs of flyback co ic elements, flyback waveforms with pa ng network, two-switch flyback, simula onverter, need for a complete core res driver etional Converter Topologies for Plug-In action, Literature Survey, Bidirectional C	UNIT-IV UNIT-IV UNIT-IV UNIT-IV UNIT-IV UNIT-V UNIT-V Electric Vehicles Converters, Bidire anation, Plug-In	Passive PFC, Improving the Harm on, Constant on-time borderline v. lated buck-boost, flyback wavef , clamping the drain excursion, cal designs of forward converter a configuration, two-switch forw s ectional AC/DC Converters for Pl Charging Mode, Propulsion	onic Content mode (BCM) 09 Hours forms withou designing the s, an isolated vard and half 08 Hours lug-In EV wit
Diodes, Power Power The Va fixed- f Isolate Simulat parasiti clampin buck co bridge Bidirec Introdu Reduce	Factor Correction: Definition of Power Factor Correction? Harmonic Limits, A N Iley-Fill Passive Corrector, Active Power requency continuous mode (CCM), Ana ed Converters tions and practical designs of flyback co ic elements, flyback waveforms with pa ng network, two-switch flyback, simula onverter, need for a complete core res driver tional Converter Topologies for Plug-In action, Literature Survey, Bidirectional Converter	UNIT-IV UNIT-IV UNIT-IV UNIT-IV UNIT-IV UNIT-V UNIT-V Electric Vehicles Converters, Bidire anation, Plug-In	Passive PFC, Improving the Harm on, Constant on-time borderline v. lated buck-boost, flyback wavef , clamping the drain excursion, cal designs of forward converter a configuration, two-switch forw s ectional AC/DC Converters for Pl Charging Mode, Propulsion	onic Content mode (BCM) 09 Hours forms withou designing th rs, an isolated vard and half vard and half 08 Hours lug-In EV wit



Decemed to be University Regulations and curriculum for M. Tech Electric Vehicle Technology

Course	1	es: At the end of the course stude				e to					
1.	,	the operation of different power									
2.	-	f non-isolated converters used in			vehio	cles					
3.	•	ront end for practical offline conv									
4.		the operation of practical isolated									
5.	Analyze	the Bidirectional converter topol	ogies	s use	d in	Elect	ric V	/ehic	les		
Course	e Outcom	es Mapping with Program Outco	mes	& PS	60	1	-	-	n		
		Program Outcomes $ ightarrow$	1	2	3	4	5	6	PS	50↓	
		↓ Course Outcomes							1	2	_
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		22201201.1	T	2					5		
		22EVT201.2	1	2					2		
		22EVT201.3	1	2					2		-
		22EVT201.4	1	2					2		
		22EVT201.5	1	2					2		-
	1: Low 2	2: Medium 3: High							l		
		<u> </u>									
REFER	ENCE BOO	DKS:									
1.	B. Jayar	t Baliga, "Power Semiconductor I	Devi	ces",	1 st E	ditio	on, Ir	nterr	ational	Thomps	on Computer
	Press, 1	995.									
2.		bhe Basso, "Switch Mode Power S v-Hill,2008.	Supp	lies :	SPIC	CE Si	mula	tion	s and Pr	actical D	esigns",
3.	L. Asho	Kumar, S. Albert Alexander, "Po Group, 2021	wer	Conv	/erte	rs fo	r Ele	ectric	Vehicle	s", CRC	Press, Taylor &

EV Moto	or drives and	control	
Course Code:	22EVT202	Course Type:	PCC
Teaching Hours/Week (L: T: P):	4:0:0	Credits:	04
Total Teaching Hours:	50+0+0	CIE + SEE Marks:	50+50
Teaching Department: I	Electrical and E	lectronics Engineering	
Course Objectives:			
1. Understand requirement of EV motors			
2. Understand suitability of electric motor	r & their control		
3. Understand speed control of Induction	motor		
4. Understand PWM techniques of Invert	er for Induction r	notor	
5. Understand different sensors and sens	orless operation	of motor	
	UNIT-I		
EV Motors Characteristics			03 Hours
Requirement of EV motors, Comparison of EV	motors		
DC Motor			06 Hours
Basics of DC Motor, Torque speed characteristi	ics, DC Motor dyr	namics, Field Weakening Contro	l, Four
quadrant operation			
	UNIT-II		
DC Motor Dynamics & Control			03 Hours
Current Loop Control, Speed Control Loop			
Dynamical System Control			00.11
Cain & Dhace Margins DD Controller DI Con	trollor Colocting	DI Cain for Speed Controller	09 Hours
Gain & Phase Margins, PD Controller, PI Con Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical	mparison of conv nternal Model	ventional PI Controller with PI co	PI Controller ontroller with
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I	mparison of conv nternal Model	ventional PI Controller with PI co	PI Controller ontroller with
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical (mparison of conv nternal Model	ventional PI Controller with PI co	PI Controller ontroller with er, Feedback
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor	omparison of conv nternal Model Current Loop UNIT-III	ventional PI Controller with PI co Control, Load Torque Observ	PI Controller ontroller with er, Feedback
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical (Induction Motor Rotating Magnetic Field, Basics of Induction mo	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c	PI Controller ontroller with er, Feedback
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c	PI Controller ontroller with er, Feedback 04 Hours ircle diagram,
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic ted Control, Field	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours 'oltage 03 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic ted Control, Field	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours 'oltage 03 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic ted Control, Field	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours 'oltage 03 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmon	omparison of conv nternal Model Current Loop UNIT-III otor, Speed-Torq starting, Dynamic ted Control, Fielc	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, c c modelling of Induction motor	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours 'oltage 03 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmon Permanent magnet ac motors	UNIT-III OUNIT-III OUNIT-III OTOR, Speed-Torq Starting, Dynamic ted Control, Field Onics, Space Vect	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, co c modelling of Induction motor I Weakening Control, Variable V or Modulation, Dead time & con	PI Controller ontroller with er, Feedback 04 Hours circle diagram, 05 Hours 'oltage 03 Hours mpensation 08 Hours
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmon	UNIT-III OUNIT-III OUNIT-III OTOR, Speed-Torq Starting, Dynamic ted Control, Field Onics, Space Vect UNIT-IV PMSM torque e	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, co c modelling of Induction motor I Weakening Control, Variable V or Modulation, Dead time & con	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours foltage 03 Hours mpensation 08 Hours ods, machine
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmon PMSM and BLDC, PMSM dynamic modelling,	UNIT-III OUNIT-III OUNIT-III OTOR, Speed-Torq Starting, Dynamic ted Control, Field Onics, Space Vect UNIT-IV PMSM torque e	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, co c modelling of Induction motor I Weakening Control, Variable V or Modulation, Dead time & con	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours oltage 03 Hours mpensation 08 Hours ods, machine
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmo Permanent magnet ac motors PMSM and BLDC, PMSM dynamic modelling,	UNIT-III OUNIT-III OUNIT-III OTOR, Speed-Torq Starting, Dynamic ted Control, Field Onics, Space Vect UNIT-IV PMSM torque e	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, co c modelling of Induction motor I Weakening Control, Variable V or Modulation, Dead time & con	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours foltage 03 Hours mpensation 08 Hours ods, machine
Design, PI Controller with Reference model, Co Reference Model, 2 DOF Controller with I Linearization, Simplified Modeling of Practical of Induction Motor Rotating Magnetic Field, Basics of Induction mo current displacement (double cage rotor), line Induction Motor Speed Control Rotor Field oriented control, Stator Field Orien Variable Frequency Control PWM and Inverter Sinusoidal PWM, Injection of third order harmo Permanent magnet ac motors PMSM and BLDC, PMSM dynamic modelling,	UNIT-III OUNIT-III OUNIT-III OTOR, Speed-Torq Starting, Dynamic ted Control, Field OUNIT-IV UNIT-IV PMSM torque eding constant pov	ventional PI Controller with PI co Control, Load Torque Observ ue Curve Leakage inductance, co c modelling of Induction motor I Weakening Control, Variable V or Modulation, Dead time & con	PI Controller ontroller with er, Feedback 04 Hours ircle diagram, 05 Hours oltage 03 Hours mpensation 08 Hours ods, machine



Sensor	less cont	trol of ac motors									05 Hours
Voltage	e Model E	Estimator, Current Model Estimat	or, C	lose	d-loo	p M	RAS	obse	rver, PN	/ISM sens	sor less control
		es: At the end of the course stude				e to					
1.		e the characteristics of the motors									
2.		dynamics of DC motor and different									
3.		e the speed control and PWM tec							of Indu	ction mo	otor
4.		the operation and control of perr			nagn	et ac	: mo	tors.			
5.	Analyze	sensor-less control of 3-phase ac	mot	ors.							
Course	Outcom	es Mapping with Program Outco	1	1	1		_				
		Program Outcomes→	1	2	3	4	5	6	PS	o↓	
		↓ Course Outcomes							1	2	
		+							-	-	
		22EVT202.1			2		2				
		22EVT202.2			2		2				
		22EVT202.3			2		2		2		
		22EVT202.4			2		2		2		
		22EVT202.5			2		2		2		
	1: Low 2	2: Medium 3: High								1	
REFERI	ENCE BOO	DKS:									
1.	K Wang	Hee Nam: AC Motor Control & E	lectr	ical \	/ehic	le Al	oplic	atior	n, CR Pre	ess, Taylo	or & Francis
	Group,										
2.	C.C Cha 2001	n, K.T Chau: Modern Electric Veh	icle T	Fech	nolog	gy, O	xfor	d Un	iversity	Press Inc	., New York
3.		ussein, Electric and Hybrid Vehicle	es: D	esigi	า Fur	dam	nenta	als, C	RC Pres	s, 2003.	
4.		arminie, John Lowry, Electric Veh									

		2EVT203	C	Course Ty	pe		RETP
eaching Hours/	Week (L: T: P)	0:0:4	c	credits			2
otal Teaching H	ours	0+0+52	c	CIE			100
	Teaching Department: E	lectrical a	nd Elec	ctronics	Engin	eering	
urse Objectives	The research purposes are						
	e future problems through pu	ursuit of tru	uth as a	"global o	entre d	of excellence	ce for
intellectu	al creativity".						
2. To respor	nd to current social demands,	and to cor	ntribute	to the c	eation	and develo	opment
	fic technologies with the aim	of realizing	g an afflu	uent soci	ety and	l natural	
	ent for humanity.						
	me time, the course aims to c				resour	ces and an)
	educational environment thr	-			o		aina
	stand professional writing an ble data discovered by resear				•	•	•
•	e documents.	ching, and	construc	cung nin	sneu p	UIESSIUIIdI	
	c accuments.						
athematical mo rried out during e research pape	second semester, students a delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor	computer	simulat ut by the	ions/Pre e PG Stud	liminar lent is d	y experimevaluated f	entation/test
athematical mo rried out during e research pape minutes presen aminers.	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor	/computer < carried ou k carried o	simulat ut by the out will	ions/Pre PG Stud be eval	liminar lent is d	y experimevaluated f	entation/test
athematical mo rried out during e research pape minutes prese aminers. purse Outcomes:	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor At the end of the course stud	/computer < carried ou k carried o dent will be	simulat ut by the out will e able to	ions/Pre PG Stud be eval	liminar lent is o uated f	y experim evaluated f or 50mark	entation/test for 50 marks as jointly by
athematical mo rried out during e research pape minutes prese aminers. ourse Outcomes: Create a m	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor <u>At the end of the course stuc</u> nodel/prototype through fab	/computer < carried ou k carried o dent will be	simulat ut by the out will e able to	ions/Pre PG Stud be eval	liminar lent is o uated f	y experim evaluated f or 50mark	entation/test for 50 marks as jointly by
athematical mo rried out during le research pape minutes preser aminers. Durse Outcomes: . Create a m proposed p	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor At the end of the course stud nodel/prototype through fabi problem.	/computer < carried ou k carried o dent will be rication, sin	simulat ut by the out will e able to	ions/Pre PG Stud be eval	liminar lent is o uated f	y experim evaluated f or 50mark	entation/test for 50 marks as jointly by
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athematical mo rried out during e research pape minutes presen aminers. urse Outcomes: Create a m proposed p Analyse an	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor At the end of the course stud nodel/prototype through fabi problem.	/computer < carried ou k carried o dent will be rication, sin	simulat ut by the out will e able to mulatior	ions/Pre PG Stud be eval	liminar lent is o uated f	y experim evaluated f or 50mark	entation/test for 50 marks as jointly by
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athematical mo rried out during le research pape aminers. Durse Outcomes: Create a m proposed p Analyse an Compose a	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor At the end of the course stud nodel/prototype through fabi problem. d validate the results obtaine technical paper as per the gi	/computer < carried out k carried out dent will be rication, sin d. ven format omes & PS	simulat ut by the out will <u>e able to</u> mulatior t.	ions/Pre PG Stud be eval	liminar lent is o uated f	y experim evaluated f or 50mark	entation/test for 50 marks as jointly by
athematical mo rried out during le research pape aminers. Durse Outcomes: Create a m proposed p Analyse an Compose a	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fabi problem. d validate the results obtaine technical paper as per the gi	/computer < carried out k carried out dent will be rication, sin d. ven format omes & PS	simulat ut by the out will <u>e able to</u> mulatior t. O	ions/Pre e PG Stud be eval n, data a	liminar lent is o uated f nalysis	y experim evaluated f or 50mark , Experime	entation/test for 50 marks as jointly by
athematical mo rried out during le research pape aminers. Durse Outcomes: Create a m proposed p Analyse an Compose a	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research wor At the end of the course stud nodel/prototype through fabi problem. d validate the results obtaine technical paper as per the gi Mapping with Program Outcome	/computer < carried out k carried out dent will be rication, sin d. ven format omes & PS	simulat ut by the out will <u>e able to</u> mulatior t. O	ions/Pre e PG Stud be eval n, data a	liminar lent is o uated f nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by
athematical mo rried out during le research pape aminers. Durse Outcomes: Create a m proposed p Analyse an Compose a	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fability oroblem. d validate the results obtaine technical paper as per the gin Mapping with Program Outcome Program Outcomes	$\langle \text{computer} \rangle$ $\langle \text{carried out} \rangle$	simulat ut by the out will e able to mulation t. 2 3	e PG Stud be eval n, data a	liminar lent is o uated 1 nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by
athematical mo rried out during e research pape minutes preser aminers. Durse Outcomes: Create a m proposed p Analyse an Compose a	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fability oroblem. d validate the results obtaine technical paper as per the gin Mapping with Program Outcome Program Outcomes 22EVT203.1 22EVT203.2 22EVT203.3	$\langle \text{computer} \rangle$ $\langle \text{carried out} \rangle$	simulat ut by the out will a able to mulation t. 2 3 3 3 3 3 3 3	e PG Stud be eval n, data a 4 5 3 3 3	liminar lent is o uated 1 nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by
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athematical mo rried out during he research pape o minutes presen caminers. Durse Outcomes: Analyse an Compose a Durse Outcomes	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fability oroblem. d validate the results obtaine technical paper as per the gi Mapping with Program Outcome ↓ Course Outcomes 22EVT203.1 22EVT203.2 22EVT203.3 1: Low	$\langle \text{computer} \rangle$ $\langle \text{carried out} \rangle$	simulat ut by the out will a able to mulation t. 2 3 3 3 3 3 3 3	e PG Stud be eval n, data a 4 5 3 3 3	liminar lent is o uated 1 nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by
athematical mo rried out during e research pape minutes preser aminers. Ourse Outcomes Analyse an Compose a Outcomes	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fability oroblem. d validate the results obtaine technical paper as per the gin Mapping with Program Outcome ↓ Course Outcomes 22EVT203.1 22EVT203.2 22EVT203.3 1: Low	$\langle computer \rangle$ $\langle carried outher \rangle$	simulat ut by the out will a able to mulation t. 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	e PG Stud be eval n, data a 3 3 h	liminar lent is o uated 1 nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by
arried out during ne research pape D minutes preser caminers. Durse Outcomes: 1. Create a m proposed p 2. Analyse an 3. Compose a Durse Outcomes	delling/ Design calculations/ second semester. r prepared based on the work ntation on the research work At the end of the course stud nodel/prototype through fability oroblem. d validate the results obtaine technical paper as per the gi Mapping with Program Outcome ↓ Course Outcomes 22EVT203.1 22EVT203.2 22EVT203.3 1: Low	$\langle computer \rangle$ $\langle carried outher \rangle$	simulat ut by the out will a able to mulation t. 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	e PG Stud be eval n, data a 3 3 h	liminar lent is o uated 1 nalysis	y experim evaluated f or 50mark , Experime PSO↓	entation/test for 50 marks as jointly by

	Power Electro	nic Co	onver	rters	Labo	orat	ory				
	Course Code:	22EV	Г204				Cou	rse Type:	PCC Lab		
	Teaching Hours/Week (L: T: P):	0:0:2						Credits:	01		
	Total Teaching Hours:	0+0+2	26				CIE + SE	E Marks:	50+50		
	Teaching Department:	Electri	cal an	d Elec	tron	ics I	Enginee	ring			
Course Ob	•										
	nderstand the design and operation of										
		nd buck-boost converter powered by car battery. of rectifier with PFC.									
	nderstand the design and operation of						+				
	nderstand the design and operation on Inderstand the operation of non-isola	-						invortor			
5. 01		st of Ex			JUart		rger anu	inverter.			
1.	Design and simulate a voltage mode				d ctu	dy th	o offort (of ESR of fi	lter canacito		
1.	used on the performance of the cor				J Stu	ay th	e enecti				
2.				ter for	car ł	batte	rv.				
3.		n and simulate a current mode buck converter for car battery. n and simulate synchronous buck converter and compare its efficiency with buck conve									
4.	Design and simulate a buck-boost c							,			
5.	Design a 100 W rectifier operated o							e starting	inrush		
	current.			·	-			5			
6.	Design and simulate the passive PFG	C for a ı	rectifie	er circu	it.						
7.	7. Design and simulate flyback converter without parasitic elements.										
8.	Design and simulate a two-switch for	orward	conve	rter us	ing tv	vo N	1OSFETs	and a coup	ole of diodes		
	to recycle the magnetizing energy.										
9.	Design and simulate non-isolated b	idirecti	onal or	nboarc	l char	ger					
10.	Design and simulate DC- AC convert	ter usin	ig IGBT								
	tcomes: At the end of the course stu					م ما ا					
	alyze the effect ESR of filter capacito										
	mpare the performance of synchron					-		er.			
	esign rectifier operated on universal esign flyback and forward converter.			e leatt	iie oi	PFC	•				
	alyze non-isolated bidirectional onb	oard ch	arger	and in	verte	r					
J. 7.1			larger		vence						
Course Ou	tcomes Mapping with Program Out	comes	& PSO)							
	Program Outcomes-		1 1	3 4	5	6	PSO	C↓			
	↓ Course Outcomes						1	2			
	22EVT204.1	2					2				
	22EVT204.2	2					2				
	22EVT204.3	2					2				
	22EVT204.4	2					3				
	22EVT204.5	2					3				
1:	Low 2: Medium 3: High		· I		•	-	I	1			



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toph	ophe	e Ba	isso,	"Sw	itch I	Mod	le Po	owe	r Sup	plie	es : S	PICE	Simu	latio	ns and	d Prac	tical	Desi	gns",	
aw-	aw-H	Hill,2	2008																	
aw-	aw-H	Hill,2	2008	•																

Course Code: 22EVT205 Course Type: PCC Lab Teaching Hours/Week (L: T: P): 0:0:2 Credits: 01 Total Teaching Hours: 0+0+26 CIE + SEE Marks: 50+50 Teaching Department: Electrical and Electronics Engineering Course Objectives: 1. To study the effect of field weakening in DC motor control												
Total Teaching Hours:0+0+26CIE + SEE Marks:50+50Teaching Department: Electrical and Electronics EngineeringCourse Objectives:1.To study the effect of field weakening in DC motor control2.To understand the open loop and closed loop control of DC motor.3.To study PWM generation and control of 3-phase induction motor.4.To understand the significance of dead time in PWM generation.5.To study the control of BLDC and PMSM motorList of Experiments1.Model the DC motor and study the effect of field weakening on the speed.2.For a DC motor design suitable current PI gains so that current control bandwidth is 150 Hz and the damping coefficient is 0.7.3.For a DC motor, demonstrate four quadrant operation.												
Total Teaching Hours:0+0+26CIE + SEE Marks:50+50Teaching Department: Electrical and Electronics EngineeringCourse Objectives:1.To study the effect of field weakening in DC motor control2.To understand the open loop and closed loop control of DC motor.3.To study PWM generation and control of 3-phase induction motor.4.To understand the significance of dead time in PWM generation.5.To study the control of BLDC and PMSM motorList of Experiments1.Model the DC motor and study the effect of field weakening on the speed.2.For a DC motor design suitable current PI gains so that current control bandwidth is 150 Hz and the damping coefficient is 0.7.3.For a DC motor, demonstrate four quadrant operation.												
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 To understand the significance of dead time in PWM generation. To study the control of BLDC and PMSM motor List of Experiments Model the DC motor and study the effect of field weakening on the speed. For a DC motor design suitable current PI gains so that current control bandwidth is 150 Hz and the damping coefficient is 0.7. For a DC motor, demonstrate four quadrant operation. 												
 5. To study the control of BLDC and PMSM motor List of Experiments 1. Model the DC motor and study the effect of field weakening on the speed. 2. For a DC motor design suitable current PI gains so that current control bandwidth is 150 Hz and the damping coefficient is 0.7. 3. For a DC motor, demonstrate four quadrant operation. 												
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the damping coefficient is 0.7.3.For a DC motor, demonstrate four quadrant operation.												
3. For a DC motor, demonstrate four quadrant operation.												
4. Study the stability of the DC motor using bode plot for open loop and closed loop cases.												
 5. Design and simulate Variable Voltage Variable Frequency Control for 3 phase induction motor. 6. Generate sinusoidal PWM for single phase inverter. 												
6. Generate sinusoidal PWM for single phase inverter.												
7. Generate PWM signals for H bridge inverter incorporating dead time.												
8. Simulate space vector PWM technique												
9. Study of BLDC motor drives.												
10. Study of PMSM drives.												
Course Outcomes: At the end of the course student will be able to												
1. Demonstrate the effect of field weakening in DC motor control.												
2. Design open loop and closed loop control of DC motor.												
3. Analyse the control of 3 phase induction motor.												
4. Demonstrate the significance of dead time in PWM generation.												
5. Develop controllers for BLDC and PMSM drives.												
Course Outcomes Mapping with Program Outcomes & PSO												
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↓ Course Outcomes 1 2												
22EVT205.1 2 3												
22EVT205.2 2 3												
22EVT205.3 2 3												
22EVT205.4 2 3												
22EVT205.5 2 3												
1: Low 2: Medium 3: High												
1: Low 2: Medium 3: High												

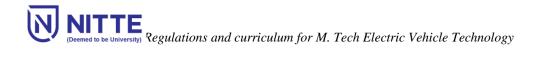
1	K Wang Hee Nam: AC Motor Control & Electrical Vehicle Application, CR Press, Taylor & Francis	
	Group, 2019	

Battery Management System											
	22EVT211	-	DEC								
Course Code:		Course Type:	PEC								
Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03								
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50								
Teaching Department:	Electrical and	Electronics Engineering									
Course Objectives:											
1. To introduce the various Battery Mana	agement System	parts									
2. To understand basic information abou	t batteries										
3. To measure different battery paramet	ers										
4. To estimate state of charge of the batt	tery										
5. To estimate state of health of the batt	ery										
UNIT-I											
Battery Management System parts			05 Hours								
The Power Module (PM), The battery, The I Battery Management Systems, Comparison of two types of cellular phones			ison of BMS in								
Basic information on batteries			06 Hours								
Battery systems, Definitions Battery design, batteries, Basic thermodynamics, Kinetic and voltage	•	•									
Lithium-Ion Battery Fundamentals			04 Hours								
Battery Operation, Battery Construction, Batter	ery Chemistry, Sa	afety Longevity, Performance, Int	tegration								
	UNIT-II										
Measurement of battery parameters			05 Hours								
Cell Voltage Measurement, Current Meas	urement, Curre	ent Sensors Current Sense Mo	easurements,								
Synchronization of Current and Voltage, T	emperature Me	easurement, Measurement Un	certainty and								
Battery Management, System Performance	<u> </u>										
Battery Management System Functional	lity		03 Hours								
Charging, Strategies, CC/CV Charging Method Management, Operational Modes	l, Target Voltage	e Method, Constant Current Met	thod, Thermal								



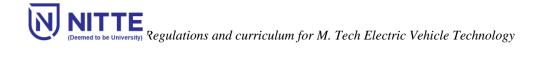


Charg	e Balanc	ing									04 Hours
		gies, Balancing Optimization, Ch	arge	Trar	nsfer	Bala	ancir	ıg <i>,</i> Fl	ying Cap	pacitor, In	ductive Charge
		ng, Transformer Charge Balancin									0
State-	of-Charc	e Estimation Algorithms	-	-							03 Hours
		finitions, Coulomb Counting,	SO	с с	orre	ctior	IS,	ocv	Measu	irements,	Temperature
	-	Kalman Filtering, Other Observer									·
			UN	IT-II	l						
State-	of-Healt	h Estimation Algorithms									05 Hours
State o	f Health, I	Mechanisms of Failure, Predictive	SO⊦	l Mo	dels	Impe	edan	ce De	etection	, Passive N	/lethods, Active
Metho	ds, Capac	ity Estimation, Self-Discharge Det	tectio	on Pa	aram	eter	Estii	matio	on, Dual	-Loop Syst	tem, Remaining
Useful	Life Estim	ation									
Fault I	Detectio	n									05 Hours
Overvie	ew, Failur	e Detection, Overcharge/Overvo	Itage	e, Ov	er-Te	empe	eratu	ire, C	Dvercurr	ent Batte	ry
	-	ssive Self-Discharge, Internal Sho			Dete	ectio	n, De	etect	ion of Li	thium Pla	ting, Venting
Detecti	ion, Exces	sive Capacity Loss, Reaction Stra	tegie	es							
Course	Outcom	es: At the end of the course stude	ent v	vill b	e abl	e to					T
1.		various Battery Management Syst									
2.		ne basic information about batter									
3.		e different battery parameters an	id an	alyze	e bat	tery	perf	orma	ance to i	dentify Ba	attery
	-	ment System Functionality		6							
4.		e need of Charge Balancing and s							-	-	rithms
5.	Estimate	the state of health of the batter	y an	d dis	cuss	batt	ery f	ault	detectio	n.	
Courses	Outeen	A Manuain a with Dragware Outag		0 00	<u>```</u>						
Course	Outcom	es Mapping with Program Outco	1	1	I	4	-	6			
		Program Outcomes $ ightarrow$	1	2	3	4	5	6	P3	O↓	
		↓ Course Outcomes							1	2	
		·									
		22EVT211.1	2		3					3	
		22EVT211.2	2		3					3	
			_		-						
		22EVT211.3	2		3					3	
		22EVT211.4	2		3					3	
		22201211.4	2		5					5	
		22EVT211.5	2		3					3	
	1: Low 2	2: Medium 3: High									
	ENCE BOC		•			1.					E. Mar
1.		gveld, "Battery management sys	tems	s:de	esign	by n	node	elling	" Univer	sity Press	Facilities,
2		ven,2001	1.141-1			-++-				ا ماه د ماه	2014
2.		Veicker, "A Systems Approach to									
3.	• •	L. Plett, "Battery Management S									
4.		k (Ed.), T. Dickinson, U. Falk, J.L.							•		
	Sources	: Primary & Secondary Batteries"	, IEE	Ene	rgy S	eries	s ⊥, A	ι.vvr	ieaton &	LCO, EXETE	er, 1980.





Thermal Ma	nager	nent o	f EV	' sys	sten	ns		
Course Code:	22EV	Γ212				Coui	se Type:	PEC
Teaching Hours/Week (L: T: P):	3:0:0						Credits:	03
Total Teaching Hours:	40+0+	+0				CIE + SE	E Marks:	50+50
Teaching Department	: Electri	ical and I	Electr	onic	s En	gineering		
Course Objectives:								
1. To understand thermal management of	of electr	onics						
2. To understand the importance of them	mal resi	istance n	etwo	ork				
3. To understand thermal management of	of micro	electron	ic pa	ckag	es			
4. To comprehend the concepts of coolir								
5. To explain thermal management syste	-							
		NIT-I						
Introduction to thermal management of	f Electr	onics						07 Hours
Semiconductor Technology Trends, Tempera			t Fai	ilure	s Te	mperatur	e-Depend	
Failures Importance of Heat Transfer in Electro		•				1	-1-0.14	
Thermal Resistance Network	, .							08 Hours
Thermal Resistance Concept, Series Thermal	Lavers.	Parallel	Ther	mal	Lave	ers Gener	al Resista	
Thermal Contact Resistance, Interface Materia	•							
Circuit Boards (PCBs)								
	UN	NIT-II						
Fins and Heat Sinks	_							05 Hours
Fin Equation, Infinitely Long Fin, Adiabatic	Fin Tir	o Conve	ction	and	d Ra	diation f	rom Fin	
Temperature Fin Tip Fin Thermal Resistance								•
Heat Sink Thermal Resistance, Effectiveness						-		
Advanced Cooling Technologies	5, ana 1	Linciene	y, 110	ut J		vianaiac	tuning i r	10 Hours
Pipes, Capillary Limit, Boiling Limit. Sonic Limit	Entrai	nmontli	mit (Otho	r Ho	at Dino D	orformon	
Pipe Applications in Electronic Cooling, Therm					i ne	at ripe r		Le Linnis, near
The Applications in Electronic Cooling, Thermis	osypho	ns, Liqui		mg				
		IIT-III						
The second Care of the second second second								10 Hours
Thermal Specification of Microelectronic			<u> </u>					
Importance of Packaging, Packaging Types,	•							unction-to-Air
Thermal Resistance, Junction-to-Case and								kage inermai
Characterization Parameters, Parameters Affe	cting ir	iermai C	narac	teris	STICS	от а Раска	age	
			1					
Course Outcomes: At the end of the course stu								1
1. Describe different types of temperatur							tems.	
2. Describe series and parallel thermal la	-					n PCB.		
	ملم مرمين	ectronic a	applic	atio	n.			
3. Use suitable fins and heat sinks for a g								
 Use suitable fins and heat sinks for a gi Compare different advanced cooling te 	echnolo	ogies.					_	
 Use suitable fins and heat sinks for a git Compare different advanced cooling te Analyse thermal specifications of micro 	echnolo	ogies.			parai	neters af	fecting th	ermal
 Use suitable fins and heat sinks for a git Compare different advanced cooling te 	echnolo	ogies.			baraı	neters af	fecting th	ermal
 Use suitable fins and heat sinks for a git Compare different advanced cooling te Analyse thermal specifications of micro characteristics of a package. 	echnolo oelectro	ogies. onic pack			baraı	meters af	fecting th	ermal
 Use suitable fins and heat sinks for a gi Compare different advanced cooling te Analyse thermal specifications of micro characteristics of a package. Course Outcomes Mapping with Program Out	echnolo oelectro tcomes	ogies. onic pack & PSO	age a	and p			1	ermal
 Use suitable fins and heat sinks for a git Compare different advanced cooling te Analyse thermal specifications of micro characteristics of a package. 	echnolo oelectro tcomes	ogies. onic pack			baraı 6	meters af	1	ermal
 Use suitable fins and heat sinks for a gi Compare different advanced cooling te Analyse thermal specifications of micro characteristics of a package. Course Outcomes Mapping with Program Out	echnolo oelectro tcomes	ogies. onic pack & PSO	age a	and p			1	ermal



	22EVT212.1	1	2						
		-	2						
	22EVT212.2	1	2						
	22EVT212.3	1	2						
	22EVT212.4	1	2						
	22EVT212.5	1	2						
	1: Low 2: Medium 3: High								
REFERE	NCE BOOKS:								
1.	Younes Shabany," Heat Transfer: Ther	mal Ma	inagem	ent o	f Elec	tron	ics" 20	10 , CRC	Press.
2.	Jerry Sergent, Al Krum, "Thermal Man	agemer	nt Hand	book	: For	Elec	tronic A	ssembli	es Hardcover",
	1998, Mc Graw- Hill.								
3. "Vehicle thermal Management Systems Conference Proceedings", 1st Edition; 2013, Coventry									
Techno centre, UK									
4.	T. Yomi Obidi, "Thermal Management	in Auto	motive	appl	icatio	ons",	2015, 9	SAE Inter	rnational.

	Vehicle	e Body Engine	eering							
	Course Code:	22EVT213	Course Type:	PEC						
	Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03						
	Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50						
	Teaching Department:	Electrical and E	lectronics Engineering							
Course	e Objectives:									
1.	Understand different aspects of car bo	dy and bus body	types							
2.	Understand different types and dimen	sions of commerc	ial vehicle.							
3.										
4.	Know the role of various aerodynamic	forces and mom	ents, measuring instruments							
5.	Know body optimization techniques fo	r minimum drag.								
		UNIT-I								
CAR I	BODY DETAILS			07 Hours						
regula	of Car body – Saloon, convertibles, ations, driver's visibility, improvement construction-Various panels in car bo	in visibility and	tests for visibility. Driver sea	-						
	ODY DETAILS			08 Hours						
variou	Types of bus body: based on capacity, distance travelled and based on construction. – Bus body layout for various types, Types of metal sections used – Regulations – Constructional details: Conventional and integral. driver seat design- Safety aspect of bus body.									
COMN	UNIT-II COMMERCIAL VEHICLE DETAILS 15 Hours									



Types of commercial vehicle bodies – Light commercial vehicle body. Construction details of commercial vehicle body – Flat platform body, Trailer, Tipper body and Tanker body – Dimensions of driver's seat in relation to controls – Drivers cab design – Regulations.

			UN	IT-III	I						
VEHI	CLE AERO	DDYNAMICS									10 Hours
Object	tives, Vehi	cle drag and types. Various types	of fo	rces	and	mon	nents	s. Eff	ects of fo	orces an	d moments. Side
wind e	effects on	forces and moments. Various boo	dy op	timi	zatio	n teo	chnic	ques	for mini	mum dra	ag. Wind tunnels
– Prir	nciple of	operation, Types. Wind tunnel	test	ting	such	as:	Flo	w v	isualizat	ion tecł	nniques, Airflow
manag	gement te	st – measurement of various forc	es ar	nd m	ome	nts k	y us	ing v	vind tun	nel.	
Cours	e Outcom	es: At the end of the course stude	ent w	/ill b	e abl	e to					
1.	Describe	e different aspects of car body and	d bus	s boc	dy ty	pes.					
2.	Illustrate	e different types and dimensions	of cc	mm	ercia	l veh	icle.				
3.	Design o	lriver's cab in relation to controls.									
4.	Illustrate	e the role of various aerodynamic	forc	es ai	nd m	ome	nts,	mea	suring in	strumer	nts
5.	Analyse	various body optimization techni	ques	for	minii	mum	l dra	g.			
	•		-					-			
Cours	e Outcom	es Mapping with Program Outco	mes	& PS	50						
		Program Outcomes→	1	2	3	4	5	6	PS	0↓	
		_									
		↓ Course Outcomes							1	2	
		22EVT213.1					2				
		22EVT213.2					2				

REFERE	ENCE BOOKS:
1.	Powloski, J., "Vehicle Body Engineering", Business Books Ltd., 1998.
2.	James E Duffy, "Body Repair Technology for 4-Wheelers", Cengage Learning, 2009.
3.	Miles, G.J., "Body construction and design", Illiffe Books Butterworth & Co., 1991.
4.	John Fenton, "Vehicle Body layout and analysis", Mechanical Engg. Publication Ltd., London, 1992.
5.	Braithwaite, J.B., "Vehicle Body building and drawing", Heinemann Educational Books Ltd., London,
	1997.
6.	Dieler Anselm., The passenger car body, SAE International, 2000.

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2

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22EVT213.3

22EVT213.4

22EVT213.5

1: Low 2: Medium 3: High

PWM Controlled	Power Electr	onic Converters	
Course Code:	22EVT221	Course Type:	PEC
Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
Teaching Department:	Electrical and E	lectronics Engineering	
Course Objectives:			
1. To introduce the concept of PWM and	their application	to power electronics control	
2. To study various PWM Techniques and	I their modeling.		
3. To know the various switching and con	nduction losses as	sociated with power devices	
4. To study the concept of converters wit	h compensation.		
	UNIT-I		1
PWM DC/DC Converters			08 Hours
Analysis of Galvanically Isolated Forwarc	d Converter, Bo	oost Converter, Push – Pull	(Symmetrie
Converters - Analysis of Idealized Circuit i	in Continuous N	lode, Output Characteristics,	Selection of
Components, DC Pre-magnetization of the	e Core, Half-Brid	ge Converter, Bridge Convert	er, Hamilto
Circuit, Ćuk Converters - Elimination of the	Current Ripple,	Ćuk Converters with Galvanic	Isolation.
Control Modules	· · ·		06 Hours
Basic Principles and Characteristics of PWM	Control Module	es - Circuit Analysis, Simple PV	WM, Voltage
Controlled PWM, Current-Controlled PWM- Co	ompensated PWN	1.	
	UNIT-II		I
DC/AC Converters – Inverters			08 Hours
Single-Phase Voltage Inverters - Pulse-Cor	ntrolled Output	Voltage, Pulse-Width Modula	ted Inverte
- Unipolar PWM, Three-Phase Inverters-Ov		-	•
Modulation - Space Vector Modulation: E	Basic Principles,	Application of Space Vector	Modulatio
Technique, Direct and Inverse Sequencing,	Real Drive Influ	ence. PWM techniques for cu	irrent sourc
inverter.			
AC/DC Converters – Rectifiers			07 Hours
Rectifiers with Circuit for Power Factor Correc	ction , Active Recti	fier - Active Rectifier with Hyste	eresis Currei
Controller, PWM Rectifiers - Advanced Contro	ol Techniques of I	PWM Rectifiers , PWM Rectifier	with Curre
Output, PWM Rectifiers in Active Filters, Some	Topologies of PW	/M Rectifiers, Applications of PV	VM Rectifier
	UNIT-III		
AC/AC Converters			06 Hours
Single-Phase AC/AC Voltage Converters	- Time Propo	rtional Control, Three-Phase	Converter
Frequency Converters, Direct Frequency Co	onverters, Introd	uction to AC/AC Matrix Conv	erters - Bas
Characteristics, Bidirectional Switches, Real	ization of Input	Filter, Current Commutation,	Protection of
	nverter.		
Matrix Converter, Application of Matrix Con	nverter.		04 Hours
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters		al: nT< t <nt +="" 1,="" 2,="" dt,="" n="0," td="" tir<=""><td></td></nt>	
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters Basic Characteristics -Multilevel DC/DC Conver	rters, Time Interva		ne Interval:
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters Basic Characteristics -Multilevel DC/DC Conver nT + DT < t < (n + 1)T, Multilevel Inverters - Ca	rters, Time Interva		ne Interval:
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters Basic Characteristics -Multilevel DC/DC Conver nT + DT < t < (n + 1)T, Multilevel Inverters - Ca Inverters, Flying Capacitor Multilevel Inverter.	rters, Time Interva Iscaded H-Bridge	Inverters, Diode-Clamped Multi	ne Interval:
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters Basic Characteristics -Multilevel DC/DC Conver nT + DT < t < (n + 1)T, Multilevel Inverters - Ca Inverters, Flying Capacitor Multilevel Inverter. Course Outcomes: At the end of the course str 1. Use the knowledge of PWM technique	rters, Time Interva iscaded H-Bridge udent will be able	Inverters, Diode-Clamped Multi	ne Interval: level
Matrix Converter, Application of Matrix Con Introduction to Multilevel Converters Basic Characteristics -Multilevel DC/DC Conver nT + DT < t < (n + 1)T, Multilevel Inverters - Ca Inverters, Flying Capacitor Multilevel Inverter. Course Outcomes: At the end of the course stu	rters, Time Interva iscaded H-Bridge udent will be able is in controlling di	Inverters, Diode-Clamped Multi to fferent power electronic conver	ne Interval: level ters.
Matrix Converter, Application of Matrix ConIntroduction to Multilevel ConvertersBasic Characteristics -Multilevel DC/DC ConvernT + DT < t < (n + 1)T , Multilevel Inverters - Ca	rters, Time Interva iscaded H-Bridge udent will be able is in controlling di nics in design and	Inverters, Diode-Clamped Multi e to fferent power electronic conver l analysis of DC –DC PWM conve	ne Interval: level ters. erters.





4. 5.		nd analyze single phase and 3-ph ifferent topologies of multilevel				01170		5.			
Ј.	Design u	merent topologies of multilever	COTIV	erter	5.						
ourso	Outcome	es Mapping with Program Outco	mac	8. DQ	50						
Jourse	outcom	Program Outcomes \rightarrow	1	2	3	4	5	6	PS	50↓	
		↓ Course Outcomes							1	2	-
		22EVT221.1	1		3				3		
		22EVT221.2	1		3				3]
		22EVT221.3	1		3				3		1
		22EVT221.4	1		3				3]
		22EVT221.5	1		3				3		
	1: Low 2	: Medium 3: High									
EFERE	NCE BOC	DKS:									
1.	Branko	L. Doki ć BrankoBlanu, "Power El	ectro	nics	Con	verte	ers a	nd Re	egulator	rs", Sprir	ıger
	(Interna	tional Publishing, Switzerland) 3	rd Ed	ition	n, 201	L5					
2.	Mohan, India, 20	Undeland and Robbins, "Power D11.	Elect	roni	cs: Co	onve	rter,	Арр	lication	s and De	sign", Wiley
3.		ame Holmes and Thomas A. Lipo ctice" IEEE Press 2003	"Pul	se W	/idth	Mod	dulat	ion F	or Pow	er Conve	erters Principles
4.		nganathan, Course Notes on Elec	tric [Drive	s, In	dian	Insti	tute	of Scien	ice, Bang	zalore 2004
5.		ion notes and datasheets from P									-
6.		yanan, NPTEL https://nptel.ac.ir	,		11.00	14.00			/		

Solar Battery Charging System									
Course Code: 22EVT222 Course Type: PEC									
Teaching Hours/Week (L: T: P): 3:0:0 Credits: 03									
	Total Teaching Hours: 40+0+0 CIE + SEE Marks								
Teaching Department: Electrical and Electronics Engineering									
Cours	se Objectives:								
1.	To understand the functioning of solar	photovoltaic ce	ells and know the ratings						
2.	To know the solar array connection an	d estimate solar	r module power						
3.	To understand function of charge cont	roller and MPPT	techniques						
4.	To know the concept of solar PV system	m design and int	tegration						
5.	To explain the installation, trouble sho	oting and safety	requirement of solar system						
	•	UNIT-I							
Sola	r Photovoltaic			08 Hours					

Solar Cell and its function, Solar Technologies, Solar Cell Parameters, Efficiency of Solar Cell, Solar PVModule, Rating of Solar PV Module, PV Module Parameters, Efficiency of PV Module, MeasuringModule ParameterSolar Photovoltaic Module06 Hours



Array	Connectio	n of PV Module in Series and Para	امالد	Ectir	nati		nd M	0201	rement	of BV/ Mo	dula Power	
	on of PV N		ancı,	Lotin	natio	Jii ai		casu	irement		uule rower,	
Jereetti												
			UN	IIT-II								
Charge Controller, MPPT and Inverter											08 Hours	
	Power MOSFET and IGBT, Opto coupler, Buck and Boost Converter, Fly back Converter, Full Bridge Inverter,											
Voltage and Current Feedback, DC to DC power converter, DC to AC Converter, AC to DC Converter, Battery												
Charge controller, Maximum Power Point Tracking, Specification of Inverter and charger.												
Solar PV System Design and Integration 08 Hours												
Solar Radiation, Energy Measurements, Estimating Energy requirement, Types of Solar PV System, Design												
metho	dology fo	SPV system, Design of Off Grid	Sola	ar Po	wer	Plan	t, Ca	se st	udies of	f 3KWp Of	ff grid Solar PV	
Power	Plant, Des	sign and Development of Solar St	reet	Ligh	t and	l Sola	ar La	nteri	n, Off Gr	id Solar p	ower Plant.	
			UN	IT-III								
Install	ation, Tr	ouble Shooting and Safety									09 Hours	
Installa	tion and [•]	Trouble shooting of Standalone S	Solar	PVS	Syste	m, N	/lain ⁻	tenai	nce of So	olar PV Sy	stem, Safety in	
installa	ntion of So	lar PV System, Maintenance of S	olar	PV S	yster	n.						
Course	Outcome	es: At the end of the course stude	ent v	vill be	e abl	e to						
1.	Describe	the functioning of solar photovo	ltaic	cells	and	cell	para	met	ers.			
2.	Design th	ne solar array connections and he	ence	sola	r mo	dule	fora	a give	en applio	cation.		
3.	Analyse	the function of charge controller	and	need	l for	MPF	PT te	chnic	lues.			
4.	Design o	f off grid solar photo voltaic syste	em.									
5.	Describe	the installation, trouble shooting	g and	d safe	ety r	equi	reme	ent o	f solar sy	/stem		
Course	Outcome	es Mapping with Program Outco		1		1	1	1				
		Program Outcomes $ ightarrow$	1	2	3	4	5	6	PS	O↓		
		↓ Course Outcomes							1	2		
									Ŧ	2		
		22EVT222.1			2					3		
		2251/7222 2			2							
		22EVT222.2			2					3		
		22EVT222.3			2					3		
		22EVT222.4			2					3		
		22EVT222.5			2					3		
	1: Low 2	: Medium 3: High										
REFERE	ENCE BOC											
1.		Singh Solanki, Solar Photovoltaic	Tech	nolc	gy a	nd S	ystei	ns A	Manual	for Techn	icians,	
	Trainers	and Engineers, PHI, 2013										

		andards & T	Couris					
	Course Code:	22EVT223	Course Type:	PEC				
	Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03				
	Total Teaching Hours:40+0+0CIE + SEE Marks:50+50							
	Teaching Department:	Electrical and	Electronics Engineering					
Course	Objectives:							
1.	To introduce Understand different star	ndards related t	to electric vehicles					
2.	Understand charger an HEV standards							
3.	Understand type testing of electric veh	icle						
4.	Understand retro fitment standards							
5.	Know government policies related to E	Vs						
		UNIT-I						
EV Sta	ndards			06 Hours				
ninute	consumption, Method of measuring t power, CMVR type approval for electric		-	-				
	r Standard			04 Hours				
	Vehicle Conductive AC Charging System	n, Electric Venic	cie Conductive DC Charging System					
	andard Type Approval for Hybrid Electric Vehicl		Approval for Hybrid Electric Vah	05 Hours				
	gory with GVW > 3500 kg	les, Civivk Type	Approvalior Hybrid Electric Ven					
N Caleg								
		UNIT-II						
Retro fi	itment Standards			08 Hours				
CMVR 1	Type Approval of Hybrid Electric System	n Intended for I	Retro fitment on Vehicles of M ar	nd N Categor				
naving	GVW <= 3500 kg and GVW > 3500 kg.							
CMVR	Type Approval of Electric Propulsion	n Kit Intended	for Conversion of Vehicles for	Pure Electri				
Operat	tion							
Safety	Requirement of Traction Battery			08 Hours				
Introdu	iction to Vehicle safety standards, R	ules and Regu	lations, Environmental impuritie	es and safet				
require	ments, Battery Operated Vehicles -Sa	fety Requirem	ents of Traction Batteries, Auto	motive safet				
compor	nents certification by various organizati	ons (ARAI, SIAN	И, SAE, ASME, FMVSS).					
		UNIT-III						
	nment Policies			09 Hours				
	al Electric Mobility Mission Plan 2020 (N	EN4N4D2020) E	aster Adoption and Manufacture	of (Hybrid and				
	Vehicles) – FAME, Niti Aayog Report or		•	or (riybrid dri				





Course	Course Outcomes: At the end of the course student will be able to							
1.	Illustrate different standards related construction and safety in electric vehicles							
2.	Describe central motor vehicles rules (CMVR) type of standards for electric and hybrid electric vehicles.							
3.	Describe CMVR types of standards for retro fitment of existing IC engine driven vehicles.							
4.	Illustrate safety standards of traction batteries.							
5.	Describe government policies like national electronic mobility plan related to EVs							

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	PS	O↓
↓ Course Outcomes							1	2
22EVT223.1					2	3		
22EVT223.2					2	3		
22EVT223.3					2	3		
22EVT223.4					2	3		
22EVT223.5					2	3		

1: Low 2: Medium 3: High

REFERENCE BOOKS:

1.	Automotive Industry	Standards Ind	ia 2015-2016
T .	Automotive maustry	/ Stanuarus, Inu	Id, 2013-2010

Other References

1. https://araiindia.com

2. https://emobility.araiindia.com

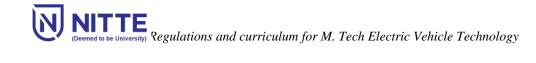
- 3. https://dhi.nic.in/writereaddata/Content/NEMMP2020.pdf
- **4.** https://niti.gov.in/content/national-mission-transformative-mobility-and-battery-storage
- 5. https://niti.gov.in/writereaddata/files/document_publication/NITI-RMI_India_Report_web-v2.pdf

EV	's in Smart Gri	d								
Course Code:	22EVT224	Course Type:	PEC							
Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03							
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50							
Teaching Department: Electrical and Electronics Engineering										
Course Objectives:										
• To understand the fundamentals of Plug	g in Electric Vehicl	e technologies								
• To understand the cyber security of Plu	g in Electric Vehic	le technologies in Smart Grid								
• To understand the impact of plug in elec	ctric vehicles on p	ower system								
• To understand the PEV Load and Its Imp	pact on Static Volt	age Stability								
• To study the response of large-scale EV	charging loads to	frequency								
	UNIT-I									
Overview of Plug-in Electric Vehicle Tec	hnologies		04 Hours							
PEV Technologies, PEV Systems, impacts, Sma	ort Charging Infras	tructure, Integration of PEVs to	o Electric Grid							
Promotional Programs on PEVs										
Wireless Power Transfer (WPT) for Electric Ve	ehicles (EVs)		05 Hours							
Wireless Energy Transfer Methods, Inductive	Coupling Versus N	Aagnetic Resonance Coupling,	Modelling the							
WPT System, WPT for EV Charging, Stationary	WPT for EV Charg	ing, Dynamic WPT for EV Charg	ing							
Cyber Security of Plug-in Electric Vehicles in S			06 Hours							
Detection Methods, Smart Grids with PEVs, Co										
Security Challenges, Data Attacks and Intrus			ion Methods,							
Application to the Detection of Malicious PEV	Penetration Level									
	UNIT-II		1							
Impact Evaluation of Plug-in Electric Vehicles			05 Hours							
Probabilistic PEV Charging Demand, Fast Cha		babilistic Arrivals, Probabilistic	PEV Charging							
			Demand, Probabilistic Grid Impact of Fast Chargers.							
PEV Load and Its Impact on Static Voltage Sta	hility		1							
			09 Hours							
Modeling of PEV Charging Load, Introduction	to Power System		ng of the PEV							
Charging Load, Effects of Charger Resistances	to Power System on Load Model Pa	rameters, Newton Raphson Pov	ng of the PEV wer Flow with							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S	to Power Systen on Load Model Pa ystem Static Volta	rameters, Newton Raphson Porage Stability	ng of the PEV wer Flow with Theory, Static							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Charg	to Power Systen on Load Model Pa ystem Static Volta	rameters, Newton Raphson Porage Stability	ng of the PEN wer Flow with Theory, Statio							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Charg	to Power Systen on Load Model Pa ystem Static Volta	rameters, Newton Raphson Porage Stability	ng of the PEN wer Flow with Theory, Statio							
Charging Load, Effects of Charger Resistances	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu	rameters, Newton Raphson Porage Stability	ng of the PEV wer Flow with Theory, Static							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Char Impact through Proper Planning	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating	ng of the PEV wer Flow with Theory, Static PEV Charging							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Char Impact through Proper Planning The Response of Large-Scale EV Chargin	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III g Loads to Freq	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating u uency	ng of the PEN wer Flow with Theory, Static PEV Charging 11 Hours							
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Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Char Impact through Proper Planning The Response of Large-Scale EV Chargin Introduction Characteristics of EV Charging Lo in FR ,The Current Related Research of FR Bas FR Resources ,Traditional FR Resources ,Li	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III Ig Loads to Freq bads, Current Rela ads, Current Rela	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating uency Ited Research of EVs on FR , EV nation Among EVs, AGC, BESSs y Storage Devices ,EV/BESS	ng of the PEN wer Flow with Theory, Static PEV Charging 11 Hours s' Advantages Properties of FR Resource							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Charging Impact through Proper Planning The Response of Large-Scale EV Charging Introduction Characteristics of EV Charging Lo in FR ,The Current Related Research of FR Bas FR Resources ,Traditional FR Resources ,Li Coordinated Control Strategy for EVs/BESSs ,Co	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III g Loads to Freq Dads, Current Rela ded on the Coordin arge-Scale Energe Dordination Princi	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating uency Ited Research of EVs on FR , EV nation Among EVs, AGC, BESSs y Storage Devices ,EV/BESS ple ,Implementation Method fo	ng of the PEN wer Flow with Theory, Static PEV Charging 11 Hours s' Advantages Properties of FR Resource r Coordinated							
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Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Char Impact through Proper Planning The Response of Large-Scale EV Charging Introduction Characteristics of EV Charging Lo in FR ,The Current Related Research of FR Bas FR Resources ,Traditional FR Resources ,Li Coordinated Control Strategy for EVs/BESSs ,Co FR, Case Study and Results , Simulation Mo Asynchronous Response of Small-Scale Charg	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III g Loads to Freq Dads, Current Rela ded on the Coordin arge-Scale Energy Dordination Princi odel and Parame ing Facilities to G	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating uency Ited Research of EVs on FR , EV nation Among EVs, AGC, BESSs y Storage Devices ,EV/BESS ple ,Implementation Method fo ters, Simulations of Power Sy rid Frequency, Formulation of	ng of the PEN wer Flow with Theory, Statio PEV Charging 11 Hours s' Advantages Properties o FR Resource r Coordinateo rstem FR The							
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Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Charging Impact through Proper Planning The Response of Large-Scale EV Charging Log Introduction Characteristics of EV Charging Log in FR ,The Current Related Research of FR Bas FR Resources ,Traditional FR Resources ,Li Coordinated Control Strategy for EVs/BESSs ,Co FR, Case Study and Results , Simulation Mo Asynchronous Response of Small-Scale Charg Control Method . Demonstration of coordinated	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III g Loads to Freq bads, Current Rela bads, Curren	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating uted Research of EVs on FR , EV nation Among EVs, AGC, BESSs y Storage Devices ,EV/BESS ple ,Implementation Method fo ters, Simulations of Power Sy rid Frequency, Formulation of n of equality	ng of the PEN wer Flow with Theory, Static PEV Charging 11 Hours s' Advantages Properties of FR Resource r Coordinated vstem FR The							
Charging Load, Effects of Charger Resistances of PEV Load, Impact of PEV Charging Load on S Voltage Stability Analysis, Mitigating PEV Charging Impact through Proper Planning The Response of Large-Scale EV Charging Introduction Characteristics of EV Charging Lo in FR ,The Current Related Research of FR Bas FR Resources ,Traditional FR Resources ,Li Coordinated Control Strategy for EVs/BESSs ,Co FR, Case Study and Results , Simulation Mo Asynchronous Response of Small-Scale Charg	to Power Systen on Load Model Pa ystem Static Volta ging Impacts throu UNIT-III Ig Loads to Freq bads, Current Rela ed on the Coordin arge-Scale Energy bordination Princi odel and Parame ing Facilities to G ion, Demonstratio	rameters, Newton Raphson Por age Stability, Voltage Stability ugh Voltage Control, Mitigating uency Ited Research of EVs on FR , EV nation Among EVs, AGC, BESSs y Storage Devices ,EV/BESS ple ,Implementation Method fo ters, Simulations of Power Sy rid Frequency, Formulation of n of equality to	ng of the PEN wer Flow with Theory, Static PEV Charging 11 Hours s' Advantage Properties o FR Resource r Coordinated stem FR The the Proposed							



	<u> </u>											<u> </u>
3.		Analyse the impact of plug in electric vehicles on power system										
4.	Describe the PEV Load and Its Impact on Static Voltage Stability											
5.	Describe the impact of large-scale EV charging loads to grid frequency											
Course	Outcomes M	apping with Program Outco	mes	& PS	50							
		Program Outcomes \rightarrow	1	2	3	4	5	6	PS	SO↓		
	↓ C	ourse Outcomes							1	2		
		22EVT224.1			2		2					
	22EVT224.2 2 2											
		22EVT224.3			2		2					
		22EVT224.4			2		2	2				
		22EVT224.5			2		2	2				
	1: Low 2: M	edium 3: High			1							
REFERE	NCE BOOKS:											
1.		jakaruna, FarhadShahnia and Fechniques", Springer Scienc						•				irids-
2.		'ijia Cao, YonghongKuang and Key Technologies of Vehicle-										
3.	Qiuwei Wu, Ltd, 2013.	"Grid Integration Of Electric	Vehi	icles	In O	oen I	Elect	ricity	/ Marke	ts", Johr	n Wiley & So	ns,

Automotive	Computer Con	trolled Systems							
Course Code:	22EVT231	Course Type:	PEC						
Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03						
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50						
Teaching Department: Electrical and Electronics Engineering									
Course Objectives:									
 To study and analyze various vision systems for vehicles. To understand the architecture for autonomous vehicles and study the overview of the architecture. 									
3. To study the fundamentals about Automatical States and the fundamental states about Automatical States about A	onomous vehicle v	vith case study.							
	UNIT-I								
Introduction of common technology			08 Hours						
Engine related systems. Ignition system, management systems, Anti-lock braking conditioning, computer-controlled diesel	systems, Tractior		ontrol system, air						
Computer ECM			06 Hours						
Fundamental parts of computer, Principles memories, Adaptive operating strategy of the	•	omputer data, Computer inte	erfaces, Computer						
	UNIT-II								
Sensors	UNIT-II		06 Hours						
Introduction of sensors and transducers Ele	ectromagnetic Se	nsors Ontical sensors variab							
sensors, temperature sensors, Pressure se	•	•							
sensors, Oxygen Sensor, Practical Importa									
Actuators			04 Hours						
Introduction of Actuators, Actuators operation ABS actuators.	n, Injectors, Exhau	ist gas recirculation actuators,	motors, Solenoids,						
Diagnostic tools, equipments and techn	iques		05 Hours						
Diagnostic tools that connect to ECM, Digital Fault and error Codes, OBD II (On board diagn		oscope, Circuit testing, Ignition	system tests,						
	UNIT-III								
Communication protocols			06 Hours						
Overview of automotive communication protocols, CAN, LIN, Flex Ray, MOST, Ethernet, D2B and DSI, Communication interface with ECUs, Interfacing techniques and Interfacing with infotainment gadgets, Relevance of Protocols such as TCP/IP for automotive applications, Wireless LAN standards such as Bluetooth, IEEE 802.11x communication protocols for automotive applications.									
Infotainment Systems			05 Hours						
Application of telematics in automotive doma (GPRS).	in, Global positioni	ng systems (GPS) and General p	acket radio service						
Course Outcomes: At the end of the course st	udent will be able	to							
1. Describe different technologies used									
2. Illustrate the different features of em			(ECM)						
3. Describe different sensors and actuate	ors used in vehicle	S.							



4.	Use diagnostic tools such as digital multimet				•			-		ng ECM.
5.	Illustrate communication protocols and info	tain	ment	t syst	ems	use	d in v	/ehicles	•	
our	se Outcomes Mapping with Program Outcome			1	r –	r —	1			
	Program Outcomes $ ightarrow$	1	2	3	4	5	6	P:	50↓	
	↓ Course Outcomes							1	2	-
	22EVT231.1			2						_
	22EVT231.2			2						-
	22EVT231.3			2						-
	22EVT231.4			2						-
	22EVT231.5			2			3			-
	1: Low 2: Medium 3: High		1	1	1					
EFE	RENCE BOOKS:									
1.	Ronald K Jurgen, "Navigation and Intelligent T	rans	sport	atior	ו Sys	tem	s — P	rogress	in Techr	nology",
	Automotive Electronics Series, SAE, USA, 1998	3. 2.	Willi	am E	8 Rib	bens	s, "Ui	ndersta	nding Au	utomotive
	Electronics", 7th edition, Butter worth Heinen	nanr	n Wo	burn	-20	12.				
2.	References 1. Dennis Foy, Automotive Telema	atics	, Red	Hat,	200	2.2.	Yilir	Zhao,	Vehicle L	ocation and
	Navigation Systems, Artech House, 1997. 3. Ja	ay Fa	rrell	and	Mat	thew	/ Bar	th, The	Global P	ositioning Sys
	and Inertial Navigation, McGraw- Hill, 1999.	•								0 /



Course Code:	22EVT232	Course Type:	PCC
Feaching Hours/Week (L: T: P):	3:0:0	Credits:	03
Fotal Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
U	tment: Electrical and Electr	0 0	
ourse Objectives:			
ourse Objectives:			

3.	To understand the network security issues in automotive network
4.	To understand the requirement of firmware resiliency in automotive application.
5.	

UNIT-I

Cryptography Introduction:

Introduction to cryptography, Classical Cryptosystem, Block Cipher Data Encryption Standard (DES), Triple DES, Modes of Operation, Stream Cipher. Advanced Encryption Standard (AES), Introduction to Public Key Cryptosystem, Diffie-Hellman Key Exchange, Knapsack Cryptosystem, RSA Cryptosystem. Embedded Security: Introduction 08 Hours

Authentication, Integrity and Confidentiality, Properties of secure system Security elements(JIL), importance of keys in security, customization challenges, distribution of keys, tools and examples.(cryptoAuthlib)

UNIT-II

Protecting IP in cloud connected world:

Protection of IP, CODE isolation, encryption, hardware security, trustonic expertise tool for IP protection.

Automotive Network security:

Motivation for automotive network security, Automotive security, message authentication, Automotive security IC attributes, security challenges.

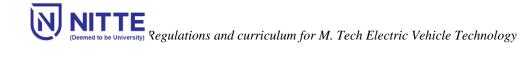
UNIT-III	
Firmware Resiliency in Automotive application:	10 Hours
Automotive growth drivers, Firmware Vulnerabilities in automotive, Simplified protection, Platform firmware protection (secure boot controller).	Automotive



07 Hours

07 Hours

08 Hours



Firmv	vare Vulnerabilities in data centre.
Cours	e Outcomes: At the end of the course student will be able to
1.	Comprehend the algorithms of cryptography for data and network security
2.	Analyze the importance of key security and customization challenges for embedded security
3.	Explain the importance of Protection of IP in cloud connected network
4.	Describe the importance of message authentication and security challenges and solutions for automotive network.
5.	Analyze the importance of firmware resiliency in automotive applications.
Cours	e Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	PS	O↓
↓ Course Outcomes							1	2
22EVT232.1	3	2						
22EVT232.2	3	2						
22EVT232.3	3	2						
22EVT232.4	3	2						
22EVT232.5	3	2						

1: Low 2: Medium 3: High

TEXTBOOKS:

 Wiiliam Stallings, "Cryptography and Network security Principles and practices", 4th Edition, prentice hall, November 16,2015.

E-Resources:

1.	https://onlinecourses.nptel.ac.in/noc21_cs16/preview
2.	https://www.microchip.com/en-us/solutions/embedded-security
3.	https://vimeo.com/371395354
4.	https://vimeo.com/391579350?aliId=eyJpIjoiK1V6Z1M0VTRIdVR3SmlPaCIsInQiOiJMbWxYM1prT2Z QNXhTemVoWEFkRVRBPT0ifQ%253D%253D
5.	https://vimeo.com/400991351?aliId=eyJpIjoiN2I1Z2N2c0pBNUlodmFsZyIsInQiOiJ5bFlzT3IVUnVkRjN RSIpXd0xJNmRBPT0ifQ%253D%253D
6.	SHIELDS UP! Webinar #27: Platform Firmware Resiliency in Automotive Applications (2822370) (on24.com)
7.	https://page.microchip.com/FY21Q2-ShieldsUP-HardGates_LP-ShieldsUp-Webinar3.html
8.	SHIELDS UP! Webinar #33: Data Center Security Solutions (2977322) (on24.com)



VEHICLE MANAGEMENT AND CONTROL

Course Code:	22EVT233	Course Type:	PCC
Teaching Hours/Week (L: T: P):	3+0+0	Credits:	03
Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50

Teaching Department: Electrical and Electronics Engineering

Course Objectives:

1.	To understand the basic control systems in power train
2.	To recognize the electronically controlled system
3.	To understand the body electronics and lighting in electrical vehicle
4.	To identify the motor and control systems in EV
5.	To know the requirement for infotainment and display

UNIT-I

EV,HEV and Power Train

1 phase and 3 phase AC analog control, 1 phase and 3 phase AC digital control, battery pack passive balancing, DC-DC converter, automatic transmission, Battery control unit, DC fast charging, drive line components, electric power steering, fuel cell control unit, sensors in power train, Block diagram of VCU, Virtual engine sound system.

Advanced driver assistant systems(ADAS):

ADAS domain controller, automotive thermal camera, camera module without processing, conditionally automated drive controller, drive assist ECU, Drive monitoring, LiDAR.

UNIT-II

Body Electronics and Lighting :

Automotive HVAC compressor Module, Automotive HVAC control module, Automotive HVAC sensors, Automotive gateway, heater module, Body control module, DC/AC inverter, door handle module, gesturing, headlight, Interior Light, Obstacle detection sensor, power distribution box, rear light, wiper module, sliding door module, smart glass module, seat comfort module, passive entry passive start.

Motor control and Drive:

07Hours

08 Hours

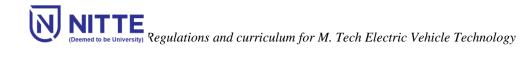
07 Hours

08Hours

Motor types: ACIM control, Brushed DC motor Control, PMSM control, Stepper Motor control, Switched reluctance Motor control.



			UN	IT-II							·
Infota	inment an	d cluster:									04 Hours
Head	unit, audio	amplifiers, telematics, USB medi	ia Hu	ıb, w	irele	ss ch	argiı	ng			
Displa	ıy:										04 Hours
Graph	ical user ir	nterface, Human machine interfac	ce fo	r dia	gnos	tic to	ools				
Timin	g and Sync	hronization:									02 Hours
Navig	ation, secu	re position and synchronization									L
Cours	e Outcome	es: At the end of the course stude	ent v	vill b	e abl	e to					
1.	Compret	nend the basics of power train mo	odul	es in	EV a	nd H	IEV				
2.	Recogniz	e the electronically controlled sy	sten	n use	ed in	adva	ncec	l driv	ver assis	tance sys	tem
3.	Identify	the body electronics and lighting	g rec	luire	men	t for	EV				
4.	Select th	e type of motors and control syst	tem	for E	V ap	plica	tion				
5.	Recogniz system.	ze the need of infotainment, disp	lay a	nd s	ynch	roniz	atio	n for	effectiv	e automa	ated transport
Cours	e Outcome	es Mapping with Program Outco	mes	& PS	60						
		Program Outcomes \rightarrow	1	2	3	4	5	6	PS	O↓	
		↓ Course Outcomes							1	2	
		22EVT233.1	2	3			3				
		22EVT233.2	2	3			3				
		22EVT233.3	2	3			3		3		
		22EVT233.4	2	3			3		3		
		22EVT233.5	2	3			3				
	1: Lov	v 2: Medium 3: High	1	1	1	1	<u> </u>				



EFERE	NCE BOOKS:
1.	https://www.ti.com/applications/automotive/overview.html
2.	https://www.microchip.com/en-us/solutions/automotive-and-transportation
3.	https://www.microchip.com/en-us/solutions/motor-control-and-drive
4.	https://www.microchip.com/en-us/solutions/power-management-and-conversion
5.	https://www.microchip.com/en-us/solutions/displays
6.	Bosch Automotive Handbook, Sixth edition,2004.

	Fundament	tals of Automo	tive Systems		
	Course Code:	22EVT234	Course Type:	PEC	
	Teaching Hours/Week (L: T: P):	3:0:0	Credits:	03	_
	Total Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50	
	Teaching Departmen	t: Electrical and E	Electronics Engineering		
Cours	se Objectives:				
1.	To study two stroke and four stroke en	gines			
2.	To study automotive transmission brak	king and steering			
3.	To study the suspensions and tyres of a	automotives.			
		UNIT-I			
Auto	omotive Engines			15 Hours	
Classi	ification of Internal Combustion Engine	es, Engine Compo	onents, Operation of Four St	roke Engines	s Two
				- ·.· -	
Strok	e Engines, Engine Cycles Engine Perfo	rmance, Supercha	arging, Combustion in Spark	lgnition Eng	gines,
	5 5 7 5	-	5 5	5	
Comb	bustion in Compression Ignition Engir	nes, Carburetion, I	5 5	5	
Comb	5 5 7 5	nes, Carburetion, I	5 5	5	
Comb	bustion in Compression Ignition Engir	nes, Carburetion, I	5 5	5	
Comb Emiss	bustion in Compression Ignition Engir	nes, Carburetion, I vertrain. UNIT-II	5 5	5	0
Comb Emiss Autor	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow	nes, Carburetion, I vertrain. UNIT-II Ig	Fuel Introduction Systems,	Engine Emis	sions,
Comb Emiss Autor Autor	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin	nes, Carburetion, I vertrain. UNIT-II vg in Analysis, Trans	Fuel Introduction Systems, mission Matching and Intro	Engine Emiss 15 Hours oduction to	sions, Brake
Comb Emiss Autor Autor Syste	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra	nes, Carburction, I vertrain. UNIT-II B B in Analysis, Trans raulic Brake, Air Br	Fuel Introduction Systems, mission Matching and Intro	Engine Emiss 15 Hours oduction to	sions, Brake
Comb Emiss Autor Autor Syste	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra em, Components of Brake System, Hyd	nes, Carburction, I vertrain. UNIT-II B B in Analysis, Trans raulic Brake, Air Br	Fuel Introduction Systems, mission Matching and Intro	Engine Emiss 15 Hours oduction to	sions, Brake
Comb Emiss Autor Autor Syste	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra em, Components of Brake System, Hyd	nes, Carburction, I vertrain. UNIT-II B B in Analysis, Trans raulic Brake, Air Br	Fuel Introduction Systems, mission Matching and Intro	Engine Emiss 15 Hours oduction to	sions, Brake
Comb Emisss Autor Autor Syste Introd	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra em, Components of Brake System, Hyd	nes, Carburction, I vertrain. UNIT-II B In Analysis, Trans raulic Brake, Air Br seering System	Fuel Introduction Systems, mission Matching and Intro	Engine Emiss 15 Hours oduction to	sions, Brake
Comb Emiss Autor Autor Syste Introd	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra em, Components of Brake System, Hyde duction to Steering System, Manual St ension and hybrid powertrain	nes, Carburetion, I vertrain. UNIT-II ng in Analysis, Trans raulic Brake, Air Br seering System UNIT-III	Fuel Introduction Systems, mission Matching and Intro rake, Antilock Brake System,	15 Hours oduction to Braking Ana 10 Hours	Brake alysis,
Comb Emiss Autor Autor Syste Introd Susp Powe	bustion in Compression Ignition Engir sion Control Systems, Automotive Pow motive transmission, braking and steerin motive Clutch, Transmission, Powertra em, Components of Brake System, Hyde duction to Steering System, Manual St ension and hybrid powertrain er Steering System, Wheel Alignment, In	unit-iii Unit-ii Unit-ii Ma Manalysis, Trans raulic Brake, Air Br ceering System UNIT-III unitroduction to Sus	Fuel Introduction Systems, mission Matching and Intro rake, Antilock Brake System, spension System, Compone	15 Hours oduction to Braking Ana 10 Hours nts of Suspe	Brake alysis, nsion
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5.	Describe su	ispansion and turos used in	automoti	100							
	Describe st	uspension and tyres used in	automotiv	ves.							
Cour	se Outcomes	Mapping with Program Out	comes &	PSO							
		Program Outcome		2	3	4	5	6	PS	50↓	
		_							4		
		↓ Course Outcomes							1	2	
		22EVT234.1			2		2				
		22EVT234.2					2				
		22EVT234.3					2				
		22EVT234.4			2		2				
		22EVT234.5					2				
	1: Low 2: I	Medium 3: High						1			
REFE	RENCE BOOKS										
1.		E. Foster, T. Kobayashi and I	N. Vaugha	n (Ec	litor	s-in-	Chie	f), Er	cyclope	edia of Au	utomotive
	0	Parts 1-6, Wiley, 2015.								-	
2.		J. K. Ball, Automotive Engin	_								
3.		K. Newton, and W. Steeds,									
4.	D. B. Astow, 2004	G. Howard and J. P. Whiteh	ead, Car S	uspe	nsio	n an	d Ha	ndlir	ng, 4th I	Edition, SA	AE International
5.		rake Design and Safety, SAE									
6.		Internal Combustion Engine									
7.		. Gao and A. Emadi, Modern		Hybri	d Ele	ectrio	c and	l Fue	l Cell V	ehicles: F	undamentals,
	Theory and I	Design, 2nd Edition, CRC Pre									
			PCB DE	SIGI	N						
		Course Code:	22EVTA	J21					Cours	se Type:	AUDIT
	Teac	hing Hours/Week (L: T: P):	0:0:2							Credits:	-
		Total Teaching Hours:	0+0+26					С	IE + SEE	Marks:	-
		Teaching Department:	Electrical	and	l Ele	ectro	onics	s En	aineeri	na	II
	UNIT-I										
			UNIT-I								Hours
		nted circuit board: fundame	ental of ele	ectro			one	nts,	basic el	06 ectronic o	circuits, Basics
of pr	rinted circuit	board designing: Layout	ental of ele planning,	ectro gene	eral		one	nts,	basic el	06 ectronic o	circuits, Basics
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of pr	rinted circuit	board designing: Layout	ental of ele planning, ection of a	ectro gene artwo	eral		one	nts,	basic el	06 ectronic o ers, groui	circuits, Basics nd conductor
of pr consi	rinted circuit iderations, the	board designing: Layout ermal issues, check and insp	ental of ele planning, ection of a UNIT-I	ectro gene artwo	eral ork.	rule	oone s an	nts, d pa	basic el aramete	06 ectronic d ers, groun 06	circuits, Basics nd conductor Hours
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Course	Out	tcome	s: At the end of the course stude	ent v	vill b	e abl	e to					
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1.		Describe layout planning and general rules of PCB design.										
2.		esign rules for digital circuit PCB										
3.		Design rules for analog circuit PCB										
4.		Describe electronic design automation tools for PCB designing.										
5.	Ana	alyze	and Develop program PCB for	r a g	jiven	арр	olicat	ion.				
Course	e Ou	itcom	es Mapping with Program Outo					1	1			
		Program Outcomes→		1	2	3	4	5	6	PSO↓		
			↓ Course Outcomes	-						1 2		-
			•							-	_	
			22EVTAU21.1				2	3				
		-	22EVTAU21.2				2	3				-
			22EVTAU21.3				2	3				
			22EVTAU21.4				2	3				-
			222.4 111021.4				2	5				
			22EVTAU21.5				2	3				
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ГЕХТВО			2. Medium 5. Trign									
			ed circuit board design fabricati	on a	ssem	hlv a	and t	estir	og Rv	RSKh	andnur	Tata McGraw
		 Printed circuit board design ,fabrication assembly and testing By R. S. Khandpur, Tata McGra Hill 2006 										
REFERE												
 Printed Circuits Handbook, Sixth Edition, by Clyde F. Coombs, Jr, Happy 								Нарру Т	. Holder	,Publisher:		
			Graw-Hill Education Year: 2016									
	3. Complete PCB Design Using OrCAD Capture and PCB Editor, Kraig Mitzner Bob									r Bob Do	be Alexander	
		Akuli	n Anton Suponin Dirk Müller, 2n	d Ed	ition	200	Э.					
	4.	Intro	duction to System-on-Package, F	lao F	R Tun	nmal	a&N	1adh	avan	Swamin	athan, N	AcGraw Hill,
		2008			<u>.</u>							
	5.	EMC	and Printed circuit board ,Desigr	the	eory a	and I	ayou	t, M	ark I	Montro	se IEEE o	compatibility
		socie	•									
	6.	Flexib	le Printed circuit board Design a	nd r	nanu	Ifact	uring	,Вy	Robe	ert torzv	vell	