Regulations and Curriculum for Bachelor of Technology (B.Tech.) in Robotics & Artificial Intelligence

Version 2022.03



(Established under Section 3 of UGC Act, 1956) Placed under Category 'A' by MHRD, GoI | Accredited with 'A+' Grade by NAAC

Regulations and Curriculum for

Bachelor of Technology (B. Tech.)

Choice Based Credit System (CBCS) Effective from AY 2022-23



(Deemed to be University under Section 3 of UGC Act, 1956) (Placed under Category 'A' by MHRD, Govt. of India, Accredited with 'A+' Grade by NAAC) University Enclave, Medical Sciences Complex, Deralakatte, Mangaluru – 575 018, Karnataka INDIA Tel: +91-824-2204300/01/02/03, Fax: 91-824-2204305 Website: www.nitte.edu.in E-mail: info@nitte.edu.in

VISION

To build a humane society through excellence in the education and healthcare

MISSION

To develop Nitte (Deemed to be University) As a center of excellence imparting quality education, Generating competent, skilled manpower to face the scientific and social challenges with a high degree of credibility, integrity, ethical standards and social concern Regulations and Curriculum B.Tech. Degree Programs Choice based Credit System (CBCS)

> Effective from Academic Year 2022 – 2023

Curriculum for Acquiring Professional Skills (CAPS)

With Scheme of Teaching & Examination

REGULATIONS: 2022

COMMON TO ALL B.Tech. DEGREE PROGRAMS CHOICE BASED CREDIT SYSTEM (CBCS)

Version 2022.03

Choice Based Credit System (CBCS)

- 1. Choice for the selection of courses during each semester
- 2. Choice in planning the academic activities by selecting desired number of courses per semester
- 3. Balanced curriculum with engineering, science, humanities, and management courses.
- 4. Project based learning (PBL) which focusses on experiential learning
- 5. Opportunities to study inter-disciplinary courses.
- 6. Enabling slow learners by offering important courses in all semesters.
- 7. Optional Summer semester
- 8. Opportunity to get associated in research projects to acquire research experience
- 9. Value addition with Honors / Minor credentials.

Curriculum for Acquiring Professional Skills (CAPS)

- 1. Practicing outcome-based education (OBE) where Courses made student-centric rather than teacher-centric
- 2. Provisions for courses integrated with Lab/ PBL component
- 3. Focus on experiential learning
- Ability enhancement and skill development courses as per National Education Policy (NEP) 2020
- 5. Focus on Industry Internship and Research Internship
- 6. Students to work on real world/interdisciplinary problems in major project
- 7. Importance is given to creativity, innovation, and development of entrepreneurship skills

Key Information

Program Title	Bachelor of Technology							
	Abbreviated as B.Tech.							
Short description	Four-year, eight semester Choice Based Credit System (CBCS) type							
	of Undergraduate Engineering Degree Program with English as							
	medium of instruction.							
Program Code	14ENGR11D2							
Revision version	2022.03							
	These regulations may be modified from time to time as mandated							
	by the policies of the University. Revisions are to be recommended							
	by the Board of Studies for Robotics & AI and approved by the							
	Academic Council.							
Effective from	09-03-2024							
Approvals	• Approved in the 51st meeting of Academic Council of NITTE							
	(Deemed to be University), held on 19-09-2022 and vide							
	Notification of NITTE (DU), N(DU)/REG/AC-							
	NMAMIT/2022-23/233 dated 12-10-2022.							
	• Notification of Nitte (DU), N(DU)/REG/AC/-SA/2022-23/909							
	dated 24-04-2023.							
	• Approved in the 54th Academic Council meeting of NITTE							
	(Deemed to be University), held on 24.06.2023 and vide							
	Notification of Ref: N(DU)/REG/AC-NMAMIT/2022-23/1264							
	dated 18.07.2023.							
	• Approved in the 56th Academic Council meeting of NITTE							
	(Deemed to be University), held on 23.02.2024 and vide							
	Notification Ref: N(DU)/REG/AC-NMAMIT/2023-24/925							
	dated 09.03.2024.							
Program offered at	NMAM Institute of Technology,							
	Off -Campus Centre, Nitte, 574110, Karkala Taluk							
Grievance and	All disputes arising from this set of regulations shall be addressed to							
dispute resolution	the Board of Management. The decision of the Board of							
	Management is final and binding on all parties concerned. Further,							
	any legal disputes arising out of this set of regulations shall be							
	limited to jurisdiction of Courts of Mangalore only							

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PREAMBLE

NMAM Institute of Technology (NMAMIT) was established in 1986 and is located at Nitte and off-campus center of NITTE (Deemed to be University), accredited by National Assessment & Accreditation Council (NAAC) with 'A+' grade. NMAMIT is recognized by the All-India Council for Technical Education (AICTE), New Delhi.

The Bachelor of Technology (B. Tech.) Programs focus on Pursuing Excellence, Empowering people, and Partnering in Community Development. Out of eleven UG Programs i.e., Artificial Intelligence & Machine Learning (AM), Artificial Intelligence & Data Science (AD), Biotechnology (BT), Computer & Communication Engineering (CC), Computer Science & Engineering(CS), Civil Engineering(CV), Electronics & Communication Engineering (EC), Electrical & Electronics Engineering (EE), Information Science & Engineering (IS), Mechanical Engineering(ME) and Robotics & Artificial Intelligence (RI), all seven eligible UG Programs i.e., BT, CS, CV, EC, EE, IS and ME are accredited by NBA, New Delhi under Tier - I category till 30th June 2025.

The curriculum is jointly approved by members of the Board of Studies (BoS) and Academic Council drawn from academia, Industry, Alumni, and working professionals from Industry, and has been designed to integrate hands-on practical training with the concepts of theory courses to enhance the learning experience.

The Curriculum focuses on students Acquiring Professional Skills (CAPS) through rigorous theoretical training using innovations in pedagogy, experiential learning, active learning, collaborative learning, critical thinking, project planning, Project Based Learning (PBL), Ability enhancement courses for skill-building, effective communication, professional practice, creativity & innovation and developing entrepreneurial skills.

The focus of the Institution is to impart Quality Education to generate competent, Skilled, and Humane Manpower to face emerging Scientific, Technological, Managerial and Social Challenges with Credibility, Integrity, Ethics, and Social Concern.

In the present scenario, students wish to make plans for a bright future. However, student aspirations and industry demands are highly diverse. Employers expect the graduates possess multi-disciplinary competency, Information and Communication Technology (ICT), and leadership skills. In this context, NMAMIT offers the opportunity to the students to select the courses of their choice and helps them in grooming to have well-rounded personalities and become industry ready.

Efforts have been made to make the syllabus compliant with international professional societies. As part of providing quality engineering education, at NMAMIT, Nitte, it has initiated the Choice Based Credit System (CBCS) into its academic curriculum. By this, the students can register for courses of their choice and alter the pace of learning within the broad framework of academic courses and credit requirements. CBCS allows students to plan for their academic load and alter it as they progress in learning. Students also have the option of choosing courses from a pool of courses within each classification. Ample options are given to choose interdisciplinary courses from other programs which will help the student to develop additional skills. Slow learners will also be benefitted since important courses are offered in all semesters. This arrangement helps the

students to re-register and clear the backlog courses in the subsequent semester. Suitable provisions are made for fast learners to associate them with research activities of faculty members and contribute to research beyond the working hours.

A faculty advisor helps the student in identifying the courses to be studied in each semester based on program requirements, course prerequisites, student's interest in various disciplines, past academic performance, and courses offered by the departments.

Learning becomes more 'experiential' by carrying out labs associated with theory, mini-projects, and Project Based Learning (PBL) as a part of many courses which enhances the capability of students in understanding and apply Engineering /Technology concepts to solve real life-problems. Hence students will develop the ability to apply the gained knowledge in multi-disciplinary projects and be able to take up major projects based on real-world problems and come up with better solutions while addressing social concerns.



REGULATIONS COMMON TO ALL B.Tech. (CBCS) DEGREE PROGRAMS OF

NITTE (Deemed to be University)

1. INTRODUCTION

- **1.1** The general regulations are common to all B.Tech.(CBCS) Degree Programs conducted at the NMAM Institute of Technology (NMAMIT), off-campus center of NITTE (Deemed to be University) and shall be called "B.Tech. Regulations".
- **1.2** The provisions contained in this set of regulations govern the policies and procedures on the Registration of students, imparting instructions of courses, the conduct of the examination & evaluation, certification of student performance, and all amendments related to the said Degree program(s).
- **1.3** This set of Regulations, on approval by the Academic Council and Governing Council, shall supersede all the corresponding earlier sets of regulations of the B. Tech Degree program of NITTE (Deemed to be University) along with all the amendments thereto, and shall be binding on all students undergoing the Graduate Degree Program(s) (Choice Based Credit System) conducted at the NMAMIT, Nitte with effect from its date of approval. This set of Regulations may evolve and get modified or changed through appropriate approvals from the Academic Council / Governing Council from time to time and shall be binding on all stakeholders (The Students, Faculty, Staff of Departments of NMAMIT, Nitte). The decisions of the Academic Council/ Governing Council shall be final and binding.
- **1.4** To guarantee fairness and justice to the parties concerned given the periodic evolutionary refinements, any specific issues or matters of concern shall be addressed separately, by the appropriate authorities, as and when found necessary.
- **1.5** The Academic Council may consider any issues or matters of Concern relating to any or all the academic activities of Engineering courses for appropriate action, irrespective of whether a reference is made here in this set of Regulations or otherwise.
- **1.6** The program shall be called **Bachelor of Technology**, abbreviated as B.Tech. (Program Specialization).



2. ELIGIBILITY FOR ADMISSION

S1.	Program	Duration	Eligibility
No			
1	B. Tech.	4 years	Passed 10+2 examination with Physics/ Mathematics / Chemistry/ Computer Science/ Electronics/ Information Technology/ Biology/ Informatics Practices/ Biotechnology/Technical Vocational subject as per Table-1 Obtained at least 45% marks (40% marks in case of candidates belonging to reserved category) in the above subjects taken together.
2	B.Tech. (Lateral Entry to Second year)	3 years	Passed Minimum THREE years / TWO years (Lateral Entry) Diploma examination with at least 45% marks (40% marks in case of candidates belonging to reserved category) in relevant branch of Engineering and Technology. (The University will offer suitable bridge courses such as Mathematics, Physics, Engineering drawing, etc., for the students coming from diverse backgrounds to prepare Level playing field and desired learning outcomes of the program)

	Table-1 Academic Level and Credit Framework for admission to Bachelor of Technology (B.Tech.) degree program										
Sl. No.	Academic Level	Desired Entry Qualifications at different levels.	NHEQF / NSQF Level at Exit	Unified Credit Level (UCF) at Exit							
1	12 th Std.	-	4	4							
2	First Year B.Tech. Degree	12 th Completed (NHEQF/UCF level 4 completed)	5	4.5							
3	Second Year B.Tech. Degree	A candidate with a Diploma in the appropriate branch of Engineering /Equivalent Vocational or Technical Program with NHEQF level 5/UCF level 4.5 completed	6	5							

2.1 Qualifications from foreign countries

Candidates with qualifications from educational institutions outside of India may be





admitted to the program(s) subject to the establishment of equivalence by the university. The Program Committee will evaluate and establish the eligibility of such candidates.

3. PROGRAM PATHS, EXIT OPTIONS, AND DURATION OF THE B. TECH. PROGRAM

<u>3.1 P</u>	rogram paths, exit o			
Sl. No	Academic Level	Entry Level Qualifications	Qualifications at Exit	NCrF Level
1	1 st yr. of UG Degree	A candidate completing 10+2 years with Diploma of Vocation or passed 12 th std. or equivalent vocational training with NCrF level 4	UG Certificate*	4.5
2	2 nd yr. of UG Degree	A candidate with Diploma in appropriate branch of Engineering/ UG Certificate/ Equivalent Vocational or Technical Program NCrF level 4.5	UG Diploma* (Engg.)	5.0
3	3rd yr. of UG Degree	A candidate with 10+3+1/12+2/ UG Diploma (Engg.) in appropriate domain with NCrF level 5	B. Sc (Engg.)*	5.5
	Final yr. of UG Degree	A candidate with 3 yrs. Bachelor degree in Vocation / B.Sc. (Engg.) with NCrF level 5.5	B. Tech (on completion of 160 credits with a minimum CGPA of 5)	6
4	Final yr. of UG Degree with Honours	A candidate with 3 yrs. Bachelor degree in Vocation / B.Sc. (Engg.) with NCrF level 5.5	B. Tech (Honors) 178 credits (Additional 18 credits over and above 160 credits in the same discipline	6
	Final yr. of UG Degree with a minor in (Other Discipline).	A candidate with 3 yrs. Bachelor degree in Vocation / B.Sc. (Engg.) with NCrF level 5.5	B. Tech with Minor 178 credits. Additional 18 credits over and above 160 credits in other disciplines	6

3.1 Program paths, exit options

*It is mandatory to earn 10 credits through Internship/Training/Specialised courses before the award of Qualifications at Exit.

3.2 Duration of the B. Tech. program

- (a) The B. Tech Program shall extend over a period of a total duration of 4 years for students admitted during the first year of the program.
- (b) The total duration shall be 3 years for students admitted to the second year under the lateral entry scheme.
- (c) The maximum period which a student can take to complete a full-time academic program is eight years / Six years for Lateral entry diploma students for B.Tech.
- (d) Each year shall have the following schedule with 5 $\frac{1}{2}$ days a week. Suggested break





down of Academic Year into Semesters

1.	No. of	There are three semesters in an academic year								
1.		-								
	Semesters	Two Main semesters (Odd, Even) followed b	•							
	/ Year	Normally the Odd Semester will be from August to December and								
			Even Semester from January to May during a calendar year.							
		The optional summer semester is offered du	uring the vacation period							
		of the even semester.								
		The summer semester is offered consideri	e .							
		courses of needy students, subject to the available								
		and other resources under a fast-track	mode as the available							
		instructional days during even semester va	acation periods are less.							
		However, the number of instructional hou	irs needed to cover the							
		syllabi shall be maintained (equivalent to tha	t in the regular semester)							
		with a greater number of instruction hours pe	er week.							
		(Note: The summer semester is primarily to	assist slow learners and/or							
		failed students in the main semesters. The	summer semester may be							
		used to arrange Add-On courses for other stu	udents and/or for deputing							
		them for practical training elsewhere)								
2.	Semester	Main semester (Odd, Even) each 20 Wee	eks; Summer Semester 8							
	Duration	Weeks								
3.	Academic	ODD / EVEN Semester								
	Activities	Registration of Courses & Course Work	(16)							
	(Weeks)	Examination Preparation and Examination	(04)							
		Total	(20)							
		Summer Semester								
		Registration of Courses & Course Work	(05)							
		Examination Preparation and Examination	(03)							
		Total	(08)							
		Declaration of results:	02 weeks from							
			the date of the							
			last							
			examination							
		Inter-Semester Recess:								
		After each Main Semester	(02)							
			1							
		Total Vacation: 10 weeks (for those who	-							
		summer semester) and 4 weeks (for those wh	no register for the summer							
		semester)								

(Note: In each semester, there will be provision for students to register for courses at the beginning, dropping of courses in the middle, and withdraw from courses towards the end, under the advice of a faculty member. These facilities are expected to enhance the learning capabilities of students, minimizing their chances of failure in courses registered and ensuring their better monitoring by Faculty Advisors).



A candidate shall be allowed a maximum duration of eight years from the first semester of admission to become eligible for the award of a Bachelor's degree.

The calendar of events in respect of the program shall be fixed by the Institution from time to time, but preferably in line with the suggested academic calendar of the NITTE (Deemed to be University).

4. DEGREE PROGRAMS

4.1 Undergraduate B. Tech. Degree Programs are offered in the following disciplines by the respective program hosting departments listed below:

respect	respective program nosting departments instea below.									
i)	Biotechnology Engineering	(BT)								
ii)	Computer Science & Engineering	(CS)								
iii)	Computer Science & Engineering (Cyber Security)	(CB)								
iv)	Civil Engineering	(CV)								
v)	Electronics & Communication Engineering	(EC)								
vi)	Electronics Engineering (VLSI Design and Technology)	(VT)								
vii)	Electrical & Electronics Engineering	(EE)								
viii)	Information Science & Engineering	(IS)								
ix)	Mechanical Engineering	(ME)								
x)	Artificial Intelligence and Machine Learning Engineering	(AM)								
xi)	Computer and Communication Engineering	(CC)								
xii)	Robotics and Artificial Intelligence Engineering	(RI)								
xiii)	Artificial Intelligence and Data Science	(AD)								
Other te	aching departments are –									
i)	Chemistry	(CY)								
ii)	Humanities	(HU)								
iii)	Management and Social Sciences	(MG)								
iv)	Mathematics	(MA)								
v)	Physics	(PH)								

4.2 The provisions of these regulations shall apply to any new discipline that may be introduced from time to time and appended to the above list.

5. CREDIT SYSTEM

In the Credit System, the course work of students is unitized, and each unit is assigned one credit after a student completes the teaching-learning process as prescribed for that unit and is successful in its assessment.

- **5.1 Credit Definition:** The following widely accepted definition for credit can provide good flexibility to the students and strengthens CBCS under the University. Here, one unit of course work and its corresponding one credit (while referring to the main semester) shall be equal to:
 - Four-credit theory courses shall be designed for 50 hours of the Teaching-Learning process.
 - Three-credit theory courses shall be designed for 40 hours of the Teaching-Learning process.
 - Two-credit theory courses shall be designed for 25 hours of the Teaching-Learning





process

• One credit theory course shall be designed for 15 hours of the Teaching-Learning process

The above figures shall also be applicable in the case of the summer semester. Other student activities which are not demanding intellectually, or which do not lend to effective assessment, like practical training, study tours, and attending guest lectures shall not carry any credit.

5.2 Credit Assignment and Lower & Upper Limits for Course Credits Registration in a Semester

All courses comprise of specific Lecture/Tutorial/Practical/Project (L-T-P-J) schedule. The course credits are fixed based on the following norms. Lecture / Tutorials / Practical:

- 1-hour Lecture per week is assigned 1.0 Credit.
- 2-hour Tutorial session per week is assigned 1.0 Credit.
- 2-hour Lab. Session/project work per week is assigned 1.0 credit. For example,
- A theory course with L-T-P schedule of 3-2-0 hours will be assigned 4.0 credits.
- A laboratory practical course with L-T-P schedule of 0-0-2 hours will be assigned 1.0 credit.
- Calculation of Contact Hours / Week A Typical Example *Example:*

An LTP-C of 2-2-2-4 means 2 instructional units based on classroom lecture (L), one instructional unit of the tutorial (T), and one laboratory (P) based instructional unit all delivered during a calendar week and repeated for the entire duration of the semester to earn 4 credits (C) after passing the course.

• As advised by the faculty advisor, a student may register, between a minimum of 16 credits and up to a maximum of 28 credits.

The maximum number of credits a student can register during a summer semester shall be 16. However, in special cases, the student may be permitted to register additional credits with the approval of the Department Undergraduate Committee (DUGC). There is no minimum number of credits fixed for course registration during the summer semester.

6 REGISTRATION

- **6.1** Every student after consulting his/ her Faculty Advisor in the parent department shall register for the approved courses (core and elective) to earn credits for meeting the requirements of a degree program at the commencement of each Semester on the days fixed for such registration and notified in the academic calendar. Students who fail to register on or before the specified date will be allowed to register within one week of the last date by paying a late fee. Such courses together with their grade and credits earned will be included in the grade card issued by the University at the end of each semester, like ODD, EVEN, and summer and it forms the basis for determining the student's performance in that semester.
- 6.1.1 Each course will be identified by a unique Course Code of seven alpha-numerals (two



alphabets followed by 5 digits). The alphabets reflect the discipline to which the course belongs. The first numeral (after the alphabet) indicates the learning level (based on prerequisites) of the course, and the rest of the three numerals indicate a running serial number. Each course also has its version to track the revisions carried out in its syllabus over time as represented by the last numerical separated by a hyphen (-). Example: EE1001-1 represents the course offered by EE Dept., Level-1, course serial number is 001 and the version is 1.

6.2 Mandatory Pre-Registration for higher semester

To facilitate proper planning of the academic activities of the Semester, the students must declare their intention to register for courses of higher semesters (3rd and above) at least two weeks before the end of the current semester choosing the courses offered by each department in the next higher semester which is displayed on the Department Notice Board at least 4 weeks before the last working day of the semester.

Registration to a higher semester is allowed only if the student fulfills the following conditions

- Satisfied all the academic requirements to continue with the program of studies
- Cleared all Institute, hostel, and library dues and fines, if any, of the previous semester
- Paid all required fees of the Institute and the hostel for the current semester
- Has not been debarred from registering on any specific grounds by the Institute.

6.3 Registering for Backlog Courses

- **6.3.1** Students who have not cleared a course (Theory/ Lab/ project) are shown with "F" grade. A course having an 'F' grade will be considered as a backlog and it has to be re-registered in the subsequent semesters. F-graded courses are eligible to register for the next level course (pre-requisite is met).
- **6.3.2** Re-registration fee will be as per the university norms existing at the time of re-registration. When a course is re-registered, the evaluation marks of that course shall be treated as canceled/ reset.
- **6.3.3** To provide an early opportunity for students to clear their backlog of courses, efforts will be made to offer as many courses as possible during Odd, Even and summer semesters.

7 ADD/DROP/AUDIT OPTIONS

7.1 Registration of courses

Each student shall have to register for course work at the beginning of a semester within 2 to 3 days of commencement after discussing with the course teacher and under faculty advice. The permissible course load is to be either average credits (20) or to be within the limits of minimum (16) and maximum (28) credits.

7.2 DROP-option

During a specified period in the middle of a semester student's performance in CIE is reviewed by the faculty advisor. Following a poor performance by a student, he/she can be facilitated to drop identified course(s) (up to the minimum credits specified for the



semester). Such course(s) will not be mentioned in the Grade card. Such courses are to be re-registered by these students and taken up for study at a later point in time.

7.3 Withdrawal from courses (Letter Grade "W")

During a specific period specified towards the end of the semester, a student's performance in CIE is reviewed by the faculty advisors. Following a poor performance by a student in the identified course (s) he/she is advised to withdraw from such course(s) (up to the minimum credits specified for the semester) with a mention in the Grade card (Grade "W"). Such courses to be re-registered by these students and taken up for study at a later point in time.

7.4 AUDIT-option (Letter Grade "U")

A student can register for courses for audit only, to supplement his/her knowledge and/or skills. The audit courses shall not be considered in determining the student's academic performance (SGPA and CGPA) in the semester. "U" grade is awarded to such courses and will be reflected in the grade card on satisfying the attendance requirements and CIE requirements. The candidate need not appear for SEE in such courses. However, CORE courses shall not be made available for audit.

8 COURSE STRUCTURE:

8.1 Types of courses

A "Course" is defined as a unit of learning that typically lasts one semester, led by one or more teachers, for a fixed roster of students. A course has identified course outcomes, modules/units of study, specified teaching-learning methods, and assessment schemes. A course may be designed to include lectures, tutorials, practical, laboratory work, field work, project work, internship experiences, seminars, self-study components, online learning modules, etc. in any combination

The following types of courses are included in the B. Tech. program:

- (a) **Humanities, Social Sciences, and Management Courses (HSMC):** These are common courses for all disciplines.
- (b) **Basic Science Courses (BSC):** Physics, Chemistry, and Mathematics: These are mandatory for all disciplines.
- (c) **Engineering Science Courses (ESC):** Basics of Electrical/ Electronics/ Civil/ Mechanical/ Computer Engineering, etc. These are mandatory for all disciplines.
- (e) **Professional Core Courses (PCC):** These are the professional Core Courses, relevant to the chosen specialization/ branch. The core courses shall be compulsorily studied by students, and it is mandatory to complete them to fulfill the requirements of a Program.
- (f) **Professional Elective Courses (PEC):** These are professional Electives, relevant to the chosen specialization/branch and can be chosen from the pool of courses. It shall be supportive to the discipline providing extended scope/enabling exposure to some other discipline /domain and nurturing student proficiency skills
- (g) **Open Elective Courses (OEC):** These are the Elective Courses from other technical areas and/ or emerging fields. Students of other departments shall opt for these courses for fulfilling the eligibility and prerequisites mentioned in the syllabus.
- (h) **Integrated Professional Core Courses (IPCC):** It refers to Professional Theory Core Course Integrated with Practical of the same course. Credit for IPCC shall be 04



considering L: T: P as 3:0:1 or L: T:P as 2:1:1, (where L, T, and P represent credits not hours per week)

- (i) **Holistic Education Courses (HEC):** These courses are designed to look into the emotional, social, ethical and academic needs of students in an integrated learning format. It helps in the engagement of all aspects of the learner including body, mind and spirit.
- (j) **Vocational Education Courses (VEC):** These courses are designed to prepare students for jobs that are based on manual or practical activities, traditionally non-academic related to a specific trade, occupation or vocation.
- (k) **Emerging Technology Courses (ETC):** These courses are designed to teach students about developing technologies that will be available within the next five to ten years and are expected to create significant social or economic effects.
- (1) **Programming Language Courses (PLC):** These courses are designed to teach students languages that can be used to communicate with computers for developing and working on different applications.
- (m) University Core Courses (UCC): These are compulsory core courses with common course codes across all the disciplines
 - i. **Project Work (PROJ):** Provide experiential learning opportunities for students. Students are required individually, or in a small group, to select and complete a project that may include review, design, development, curation, analysis, etc. with the application of skills and knowledge relevant to the area of study. Mini-project and Project work carried out at the parent Institution, or any university / Government recognized organization without affecting the regular class work
 - ii. **Internship (INT):** The internship (a form of experimental learning) program is a workplace-based professional learning experience that offers supervised exposure to real-life work experience in an area related to the field of study or career interest. An internship may be undertaken at a workplace such as an industry/R&D organization/Government organization, or any other reputed organization/ institution recognized for the purpose by the University. The internship program not only helps fresh pass-outs in gaining professional know-how but also benefits corporate sectors. The internship also enhances the employability skills of the student passing out from Technical Institutions
- (n) **Mandatory Non-Credit Courses (MNC):** These courses are mandatory, without the benefit of a grade or credit, passing each mandatory course is required to qualify for the award of a degree.
 - Assessment of these courses is conducted in the college and will include Continuous Internal Evaluation (CIE). University Semester End Evaluation (SEE) may not be necessary for these courses.
 - A minimum of 40% of the prescribed marks of CIE and SEE (If any) are required to secure a passing grade in these courses.
 - The 'PP' grade is awarded for a Pass in the course and the 'NP' grade is awarded for a Fail in the course. In case an 'NP' grade is awarded, the student has to reregister for the same course wherein he has no alternative options.
 - The "PP" and "NP" grades do not carry grade points and are hence not included in the Semester Grade Point Average (SGPA) and Cumulative Grade Point Average



(CGPA) computations. However, such non-credit mandatory courses are required to be included in the students' performance records (transcript) with Pass or Fail (PP or NP).

- Courses that come under this category are the following.
 - Engineering Visualization, Employability Skill Development, Environmental Science, Kannada etc.
- (o) **Ability Enhancement Courses (AEC)** These courses are designed to help students to enhance their skills in language, communication, personality development, etc. They also promote a deeper understanding of courses like social sciences, ethics, culture, human behavior human rights, and the law. Ability Enhancement Courses are based upon the content that leads to Knowledge enhancement.

Sl. No.	Course Category	Credit Range	Suggested Credits
1.	Basic Science Courses (BSC)	18-23	22
2.	Engineering Science Courses (ESC)	10-15	13
3.	Emerging Technology Courses (ETC)	03-05	03
4.	Programming Language Courses (PLC)	03-05	03
5.	Professional Core Courses (PCC)	52 - 58	55
6.	Professional Elective Courses (PEC)	12-18	15
7.	Open Elective Courses (OEC)	6	6
8.	Humanities, Social Sciences and Management courses (HSMC)	09-15	12
9.	Ability Enhancement Courses (AEC)	9	9
10.	Mandatory Non-credit Courses (MNC)	Non-Credit	0
11.	Holistic Education Courses (HEC)	2	1
12.	Vocational Education Courses (VEC)	1	1
13.	Project Work (PROJ) (UCC)	10-12	10
14.	Internship (INT) (UCC)	8-12	10
15.	Note: Student can register between 16 to 28 credits per semeste	er	160
	Total minimum Credits to be earned: 160		100

8.2 Typical Breakdown for the B.Tech. Degree Curriculum:

8.2.1 The Department Undergraduate Committee (DUGC) will discuss and recommend the exact credits offered for the program for the above components, the semester-wise distribution among them, as well as the syllabi of all undergraduate courses offered by the department from time to time before sending the same to the Board of Studies (BOS). The BOS will consider the proposals from the departments and make recommendations to the Academic Council for consideration and approval.

8.3 The earned Credit Requirements for the B.Tech. Degree is 160.

Degree is awarded by prescribing the total number of credits to be earned, rather than by using t h e program duration, giving flexibility to a student to plan their career.

8.4Program structure and suggested Course offerings



GL N				MESTER	T		/777 1			• ••		
Sl. No.		ourse and ourse code	Course Title		Теас	hing Ho	ours/Week		Exa	mination		
				Teaching Dept.	Theory Lecture	Tutorial	Practical/Dra wing	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
				Ē	L	Т	Р	Du	C	S	Tc	
1.	BSC	MA1001-1	Matrix Algebra & Calculus	MA	3	0	0	3	50	50	100	3
2.	BSC	PH1001-1	Engineering Physics	PH	3	0	2	3	50	50	100	4
3.	ESC	CV1001-1	Elements of Civil Engineering	CV	3	0	0	3	50	50	100	3
4.	ESC	EC1001-1	Basic Electronics	EC	3	0	0	3	50	50	100	3
5.	ESC	ME1001-1	Engineering Skill Development Practice	ME	0	0	2	2	50	50	100	1
б.	ESC	ME1002-1	Computer Aided Engineering Graphics	ME	0	2	2	3	50	50	100	2
7.	HSMC	HU1001-1	Technical English	HU	1	0	2	3	50	50	100	2
8.	HSMC	HU1002-1	Constitution of India and Professional Ethics	HU	1	0	0	1	50	50	100	1
9.	MNC	UM1001-1	Skill Development Lab Group- A	Any Dept.	0	0	4	0	0	0	0	0
				TOTAL	14	2	12	21	400	400	800	19



			II SE	MESTER	2							
Sl. No.		Course and	Course Title		Teaching Hours/Week			Exam	ination		_	
		Course code		Teaching Dept.	Theory Lecture Tutorial		Practical/ Drawing	Duration in hr	E Marks	E Marks	tal Marks	its
				Teac	L	Т	Р	Dur	CIE	SEE	Total	Credits
1.	BSC	MA1003-1	Differential Equations and Laplace Transforms	MA	3	0	0	3	50	50	100	3
2.	BSC	CY1001-1	Engineering Chemistry	СН	3	0	2	3	50	50	100	4
3.	ESC	CS1001-1	Problem-Solving through Programming	CS	3	0	2	3	50	50	100	4
4.	ESC	EE1001-1	Basic Electrical Engineering	EE	3	0	2	3	50	50	100	4
5.	ESC	ME1003-1	Elements of Mechanical Engineering	ME	3	0	0	3	50	50	100	3
6.	AEC	BT1001-1	Biology for Engineers	BT	1	0	0	1	50	50	100	1
7.	AEC	CS1002-1	IT Skills	CS	1	0	2	3	50	50	100	2
8.	MNC	CV1002-1	Environmental Science	CV	1	0	0	1	50	50	100	0
9.	MNC	UM1002-1	Skill Development Lab Group B	Any Dept.	0	0	4	0	0	0	0	0
	·	·		TOTAL	18	0	12	20	400	400	800	21

Mandat	Mandatory Internship-I*									
1.	INT	UC1001-1	Internship – I	Mandatory Intra Institutional Internship of duration (80 - 90 Hours) to be completed during I & II Semesters. *The grades will be included in the IV semester grade card (Refer 11.5.2 for details)	100		100	2		



			II	I SEMES	STER										
				Teaching Dept.	Teaching Hours/Week					Exam	ination				
SI. No.			Course and Course code Course Title		Course Title		Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J			U 1				
1.	BSC	MA2001-1	Statistics and Probability Theory	MA	3	0	0	0	03	50	50	100	3		
2.	IPCC	RI2006-1	Introduction to Robotics	RI	3	0	2	0	03	50	50	100	4		
3.	IPCC	RI2001-1	Analog and Digital Circuits	RI	3	0	2	0	03	50	50	100	4		
4.	PCC	RI2106-1	Drive Systems for Robot	RI	2	0	2	\checkmark	03	50	50	100	3		
5.	PCC	RI2105-1	Data Structures and Algorithms	RI	3	0	0	0	03	50	50	100	3		
6.	PCC	RI2603-1	Data Structures and Algorithms Lab	RI	0	0	2	0	03	50	50	100	1		
7.	HSMC	HU1004-1	Universal Human Values	HU	1	0	0	0	01	50	50	100	1		
8.	AEC	ME1654-1	Innovations and Design Thinking	ME	1	0	0	0	01	50	50	100	1		
9.	MNC	HU1003-1	Kannada (Balake / Samskrithika)	HU	1	0	0	0	-	50	00	50	0		
	TOTAL						8	-	20	450	400	850	20		

	Course prescribed to lateral entry Diploma holders admitted to III semester of Engineering programs													
1(м	4NC	MA1012 -1	Bridge course - Calculus & Differential	MA	S	0	0	0		100	0	100	0
10	101	and the	MA1012 -1	Equations	MA	5	0	0	0	-	100	0	100	0



			IV S	EMEST	ΓER								
				t.	Те	aching H	lours/Wee	ek		Exam	ination		
SI. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
				L ·	L	Т	Р	J	-		•	F	
1.	BSC	MA2005-1	Linear Algebra and its Applications	MA	3	0	0	0	03	50	50	100	3
2.	IPCC	RI2002-1	Design of Robotic Components	RI	3	0	2	0	03	50	50	100	4
3.	IPCC	RI2005-1	Introduction to Object-Oriented Programming	RI	3	0	2	0	03	50	50	100	4
4.	PCC	RI2111-1	Smart Mobile Robots	RI	2	0	2	\checkmark	03	50	50	100	3
5.	PCC	RI2109-1	Microcontroller and its Application	RI	3	0	0	0	03	50	50	100	3
6.	PCC	RI2604-1	Microcontroller Lab	RI	0	0	2	0	03	50	50	100	1
7.	HSMC	HU2001-1	Enhancing Self Competence	HU	2	0	0	0	03	50	50	100	2
8.	VEC	RI2551-1	Department specific Vocational Education Course (Motion Control using PLC)	RI	0	0	2	0	03	50	50	100	1
9.	HEC	HU1005-1	Essence of Indian Culture	HU	1	0	0	0	-	50	00	50	0
10.	UCC	UC1001-1	Internship – I (Activity based Internship)	RI	Mandatory Intra Institutional Activity based Internship of 2 weeks duration (80 - 90 h) to be completed during the vacations of I & II Semesters. Lateral entry students have to complete the Internship - I during the vacation of III semester					100	2		
			TOTAL		16	2	10	-	24	550	400	950	23

	Course prescribed to lateral entry Diploma holders admitted to III semester of Engineering programs												
11	MNC	MA1014-1	Bridge course - Discrete Mathematics & Numerical Methods	MA	3	0	0	0	-	100	0	100	0





			V S	SEMEST	ER								
				÷	Те	aching H	lours/Wee	k		Exam	ination		
Sl. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
		1		DI	L	T	P	J				L *	
1.	IPCC	RI2007-1	Kinematics and Dynamics of Robot	RI	2	2	2	0	3	50	50	100	4
2.	IPCC	RI2008-1	Image Processing and its Application	RI	3	0	2	0	3	50	50	100	4
3.	PCC	RI2101-1	Artificial Intelligence and Machine Learning	RI	2	2	0	0	3	50	50	100	3
4.	PCC	RI2601-1	AI and ML Lab	RI	0	0	2	0	3	50	50	100	1
5.	PEC	RI2XXX-1	Professional Elective-I	RI	3	0	0	0	3	50	50	100	3
6.	HSMC	HU1006-1	Introduction to IPR	Any Dept.	1	0	0	0	1	50	50	100	1
7		RIx6xx-1	Program Specific Ability Enhancement Course	RI	1	0	2	0	2	50	50	100	
7.	AEC	ME1659-1	Research Methodology	Any Dept.	2	0	0	0	3	50	50	100	2
8.	AEC	HU1007-1	Social Connect & Responsibility	Any Dept.	1	0	0	0	1	50	50	100	1
9.	AEC	UM1003-1	Employability Skill Development	RI	1	0	0	0	-	50	00	50	1
				14/15	6	8/6	-	20	450	400	850	20	



	VI SEMESTER												
				t.	Tea	aching H	Iours/Wee	ek		Exam	ination		
Sl. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J			•1		
1.	IPCC	RI2003-1	Micro Aerial Robots	RI	2	2	2	0	3	50	50	100	4
2.	PCC	RI2102-1	Control Engineering	RI	3	0	0	0	3	50	50	100	3
3.	PCC	RI2602-1	Control Engineering Lab	RI	0	0	2	0	3	50	50	100	1
4.	PEC	RIxxxx-1	Professional Elective – II [Group-1]	RI	3	0	0	0	3	50	50	100	3
5.	PEC	RIxxxx-1	Professional Elective -III [Group-2]	RI	3	0	0	0	3	50	50	100	3
6.	OEC	XXX5XX-1	Open Elective –I	Any Dept.	3	0	0	0	3	50	50	100	3
7.	HSMC	MG1003-1	Management & Entrepreneurship	Any Dept.	3	0	0	0	3	50	50	100	3
8.	AEC	HU1008-1	Life Skills for Engineers	Any Dept.	1	0	0	0	1	50	50	100	1
			TOTAL	17	4	4	-	22	400	400	800	21	





			VII S	EMESTI	ER								
				ц.	Те	aching H	Hours/We	ek		Exam	ination		
SI. No.		se and se code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J				L '	
1.	IPCC	RI2004-1	Industry 4.0 and IOT	RI	2	2	2	0	3	50	50	100	4
2.	PCC	RI2605-1	Robot Programming and Simulation Lab	RI	0	0	2	0	3	50	50	100	1
3.	PEC	RIXXXX-1	Professional Elective -IV [Group-1]	RI	3	0	0	0	3	50	50	100	3
4.	PEC	RIXXXX-1	Professional Elective – V [Group-2]	RI	3	0	0	0	3	50	50	100	3
5.	OEC	XXX5XX-1	Open Elective –II	Any Dept.	3	0	0	0	3	50	50	100	3
6.	HSMC	MG1002-1	Financial Management	Any Dept.	3	0	0	0	3	50	50	100	3
7.	HEC	HU1009-1	Indian Knowledge Systems	Any Dept.	1	0	0	0	-	50	00	50	1
8.	UCC	UC2002-1	Major Project Phase I	RI	-	-	4	-	-	100	00	100	2
		· · ·	TOTAL		15	02	8	-	18	450	300	750	20



			VII	I SEME	STER								
				÷	Те	aching H	lours/Wee	ek		Exam	ination		
SI. No.		ırse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
				_	L	Т	P	J					
1.	UCC	UC2001-1	Internship- II (Societal internship and Research/Industry Internship)		Mandatory Societal internship for 2 weeks (80 – 90 h) and Research Internship / Industry Internship of 6 weeks (240 – 270 h) or Research Internship / Industry internship for a total of 8 weeks (320 – 360 h)to be completed in one/two stretches during the vacation periods between IV to VII semesters				3	50	50	100	8
2.	UCC	UC3001-1	Major Project Phase II		researce institut Two interace	h institut e Canter contact h tion bety	arry out pro te/industry of Excelle ours /weel veen the pr l students.	/intra ences. c for	3	100	100	200	8
			TOTAL		-	-	-	-	6	150	150	300	16



	List of Vocational Education Courses (VEC)							
Code	ode Elective Course Title							
RI2551-1	Motion control using PLC							
RI2552-1	Metrology and Measurement							

	Open Electives offered to other branch students by the Department [OEC]									
Course Code	Course Code Course Title									
RI2501-1	RI2501-1 Autonomous Mobile Robots									
RI2502-1	Medical Robotics									
RI2503-1	PLC Control of Hydraulic and Pneumatic Circuits									

	Program Specific Ability Enhancement Course (AEC)								
Code	Title								
RI2651-1 Data Acquisition and Measurements									
RI2652-1	Engineering Economics								
RI2653-1	PLC Control of Hydraulic and Pneumatic Circuits								



	List of Professiona	l Elective C	ourses [PEC]						
	Group-1		Group-2						
	Automa	ation Strear	n						
Code	Elective Course Title	Code	Elective Course Title						
RI2201-1	Automation in Manufacturing Systems	RI2301-1	Digital Manufacturing						
RI2202-1	CNC Machining	RI2302-1	Intelligent Manufacturing						
RI2203-1	Industrial Automation and Control	RI2303-1	Mechatronics						
RI2204-1	Medical Robotics	RI2304-1	Robot Gripper Design						
RI2205-1	Micro-Electro-Mechanical Systems								
	Signal Processing a	nd Programming Stream							
Code	Elective Course Title	Code	Elective Course Title						
RI2211-1	Data Visualization	RI2311-1	Augmented Reality and Virtual Reality						
RI2212-1	Introduction to MATLAB Programming	RI2312-1	Computer Vision						
RI2213-1	Mobile Application Development	RI2313-1	PLC and SCADA						
RI2214-1	Virtual Instrumentation	RI2314-1	Signal Processing						
	Artificial Int	elligence S	tream						
Code	Elective Course Title	Code	Elective Course Title						
RI2221-1	Cloud Computing	RI2321-1	Autonomous Vehicles						
RI2222-1	Design and analysis of Algorithms	RI2322-1	Basics of Natural Language processing						
RI2223-1	Machine Learning with Python	RI2323-1	Business Analytics						
RI2224-1	Managing Information System								



8.5 Eligibility for submission of Project Work Report

- 8.5.1 Project work during the 8th semester shall be taken up batch-wise and report can be submitted for evaluation only on completion of a minimum of 122 credits and for Diploma lateral entry students (those who have joined the second year B.Tech.) the same is 88 credits.
- **8.5.2** Project work can be carried out as domain-specific /interdisciplinary under the guidance of faculty/ faculty members. They can also opt for an advanced Internship or research Internship in an Industry / Research Institution/Center of excellence.
- **8.5.3** Project viva-voce examination shall be conducted individually.

8.6 ELECTIVES

- **8.6.1** A candidate shall take electives in each semester from groups of electives, commencing from the 5th semester.
- **8.6.2** The minimum number of students to be registered for any Elective offered shall not be less than fifteen (15) and should not exceed forty (40).
- **8.6.3** A candidate shall opt for his/her choice of electives and register for the same at the beginning of each of the 5th to 7th semesters if pre-registration is not done. The candidate is permitted to opt for a change of elective within 15 days from the date of commencement of the semester as per the academic calendar of the college.

9 ATTENDANCE REQUIREMENT:

- **9.1** Each semester is considered as a unit and the candidate has to put in a minimum attendance of 85% in each subject with a provision of condoning 10% of the attendance by the Principal for reasons such as medical grounds, participation in University level sports, cultural activities, seminars, workshops, and paper presentation.
- **9.2** The basis for the calculation of the attendance shall be the term prescribed by the institution by its calendar of events. For the first semester students, the same is reckoned from the date of admission to the course.
- **9.3** The students shall be informed about their attendance position in the first week of every month by the College so that the students shall be cautioned to make up for the shortage.
- 9.4 A candidate having a shortage of attendance (<75%) in any course(s) registered shall not be allowed to appear for SEE of such course(s). Such students will be awarded an 'N' grade in these courses.
- **9.5** He/she shall have to repeat those course(s) with an 'N' grade and shall re-register for the same course(s) core or elective, as the case may be when the particular course is offered next either in a main (odd/even) or summer semester.

9.6 Attendance in CIE and SEE:

Attendance in all examinations both CIE and SEE of each course registered shall be compulsory and there shall not be any provision for re-examinations. Any student against whom any disciplinary action is pending shall not be permitted to attend any SEE in that semester.



10 WITHDRAWAL FROM THE PROGRAM

10.1 Temporary Withdrawal

- a) A student who has been admitted to a degree program of the college may be permitted once during the course to withdraw temporarily, for one semester, on the grounds of prolonged illness or grave calamity in the family, etc., provided –
- i. The student applies to the College within 6 weeks of the commencement of the college stating fully the reasons for withdrawal together with supporting documents and endorsement from his parent/guardian.
- ii. The College is satisfied with the genuineness of the case and that even by considering the expected period of withdrawal, the student can complete the program requirements (160 credits) within the time limits specified by the university.
- iii. The student does not have any dues or demands at the College / University including tuition and other fees as well as library material.
- iv. A student availing of temporary withdrawal shall be required to pay such fees and/or charges as may be fixed by the college until his/her name appears on the student's roll list. The fees/charges once paid shall not be refunded.
- v. A student will be entitled to avail of the temporary withdrawal facility only once during his/her studentship. However, any other concession for the concerned student shall have to be approved by the academic council.

10.2 Permanent Withdrawal

Any student who withdraws the admission before the closing date of admission for the Academic Session is eligible for the refund of the deposits only. Fees once paid will not be refunded on any account.

Once the admission for the year is closed, the following conditions govern withdrawal of admissions.

- i) A student who wants to leave the College for good will be permitted to do so (and take a Transfer Certificate from the College, if needed), only after clearing all other dues if any.
- ii) Those students who have received any scholarship, stipend, or other forms of assistance from the College shall repay all such amounts.
- iii) The decision of the Principal of the College regarding the withdrawal of a student is final and binding.

11 EVALUATION SYSTEM

- **11.1** The Academic Performance Evaluation of a student shall be according to a Letter Grading System, based on the Class Performance Distribution.
- **11.2** The Letter grades O, A+, A, B+, B, C, P, and F indicate the level of academic achievement, assessed on a decimal (0-10) scale.
- **11.3** The Letter grade awarded to a student in a course, for which he has registered shall be based on his performance in quizzes, tutorials, assignments, etc., as applicable, in addition to two mid-semester examinations and one semester-end examination. The distribution of weightage among these components may be as follows.



Sem	ester End Examination (SEE)	:	50% (50 marks)							
Con	tinuous Internal Evaluation (CIE)	:	50% (50 marks)							
CIE	CIE for Non-PBL Courses									
i)	i) Quizzes, Tutorials, Assignments, : 10 marks									
	Seminars, etc.									
ii)	Mid-semester Examinations	:	40 marks							
CIE	for PBL/IPCC Courses									
i)	Project Based Learning (PBL)	:	50 marks							
ii)	Mid-semester Examinations	:	40 marks							
iii) Quizzes, Tutorials, Assignments, Seminars, etc. : 10 marks										
60	60% weightage for theory + 40% weightage for PBL/Practical									

Any variation, other than the above distribution, requires the approval of the pertinent DUGC and Academic Council.

- **11.4** The letter grade awarded to a student in a 0-0-P (Practical) course, is based on an appropriate continuous evaluation scheme that the course instructor shall evolve, with the approval of the pertinent DUGC and the performance in SEE held on the specified period in a semester.
- **11.5 Evaluation Scheme** (*Refer to Appendix-B for detailed evaluation guidelines*): The course Instructor shall announce in the class and/or display at the Notice board/faculty door/website the details of the Evaluation Scheme, including the distribution of the weightage for each of the components and method of conversion from the raw scores to the letter-grades within the first week of the semester in which the course is offered so that there are no ambiguities in communicating the same to all the students concerned.
 - **11.5.1 Internship:** Mandatory Internship is in two parts. Internship-I (2 weeks) and Internship-II (8 weeks)

11.5.2 Internship-I

- 11.5.2.1 All the students admitted to the 1st semester of engineering programs shall have to undergo Internship-I of 02 weeks (or 80 to 90 hrs duration) during the first year. The internship shall include Inter / Intra Institutional activities. A viva voce examination (Presentation followed by question-answer session) shall be conducted during the 2nd semester (for lateral entry students, during the 3rd semester) and the prescribed credit shall be included in the 4th-semester grade card.
- 11.5.2.2 All the students admitted to the 3rd semester of Engineering programs (Lateral Entry Category) shall have to undergo a mandatory internship of 02 weeks (during the 3rd semester or the intervening period of the 3rd and 4th semesters). The internship shall include Inter/Intra Institutional activities.
- **11.5.2.3** The internship shall be considered as a head of passing and shall be considered for the award of a degree. Those, who do not take up / complete the internship shall be declared to fail and shall have to complete it during subsequent University examinations after satisfying the internship requirements. (The faculty coordinator or mentor has to monitor the student's internship progress and interact to guide them for the successful completion of the internship).



11.5.2.4 Procedure for the Evaluation of Internship-I

- a) Students should submit the reports immediately on completion of the Internship to the respective mentors
- b) The Examination of the internship will be carried out by the mentor
- c) The Internship-I shall be slated for 100 marks CIE only and will not have SEE.
- d) Internship-I marks are based on CIE marks (25 marks for the first presentation, 25 marks for the second presentation, and 50 marks for the report and final presentation).
- e) A Viva-Voce examination is conducted during I/II/III Semesters (Presentation followed by question-answer session) and the prescribed credit shall be included in the IV semester grade card.

11.5.3 Internship-II

- **11.5.3.1** All the students admitted to engineering programs shall have to undergo Internship-II of 08 weeks during the second and third year of their Engineering studies.
- **11.5.3.2** During the intervening period of the IV & V semesters and VI & VII semesters, students shall be ready for industrial experience. Therefore, they shall choose to undergo 8 weeks Internship involving Innovation / Entrepreneurship/ or short-term (about 2 weeks) societal-related activities and 6 weeks Industry Internship.
- **11.5.4 Project work evaluation:** The evaluation of CIE of the project work shall be based on the progress of the student in the work assigned by the project supervisor, periodically evaluated by him/her together with a department committee constituted for this purpose. Seminar presentation, project report, and final oral examination conducted by the project evaluation committee at the department level shall form the SEE of the project work.
- **11.5.5** In the case of other requirements, such as seminar, field work, or comprehensive viva voce, if any, the assessment shall be made as laid down by the DUGC/Academic council.
- **11.5.6** There shall be no re-examination for any course in the credit system. However, students
 - who have abstained from attending CIE or SEE without valid reasons ("N" grade), or
 - who have failed (F grade) to meet the minimum passing standards prescribed for CIE and/or SEE or
 - who have been detained for shortage of attendance or who have withdrawn (W grade) who have dropped any course shall be required to re-register for such course(s) and go through CIE and SEE again and obtain a grade equal to or better than "P" Grade in each case.
 - While such students should re-register for the same course(s) if core, they can re-register for the alternative course(s) from among the elective courses, as the case may be. The re-registration shall be possible when the particular course is offered again either in a main (Odd/Even) or summer semester.



11.6 Qualifying standards

Evaluation Method	Qualifying Standard
Sessional (CIE)	Score: ≥40% (≥20 marks)
Terminal (SEE)	Score: ≥40% (≥20 marks)
For securing a final Pass	Total 40 % of the Course maximum marks (100)
	i.e., the sum of the CIE and SEE marks prescribed for
	the Course is desired.

11.7 Grading System

The letter grade awarded to a student for his/her performance in a course is based on Absolute Grading.

11.7.1 Absolute Grading – Letter Grade and its range

The grade point scale for absolute grading

Marks Range (%)	Grade Point	Letter Grade	Descriptor		CGPA	Classification
90 & above	10	Ο	Outstanding		7.00-& above	First Class with Distinction
80-89	9	A+	Excellent			
70-79	8	А	Very Good			
60-69	7	B+	Good		6.00-6.99	First Class
55-59	6	В	Above Average		5.00-5.99	Second Class
50-54	5	С	Average			
40-49	4	Р	Pass		CGPA < 5.00*	Academic Probation / Non-compliance
00-39	0	F	Fails			
Absent	0	F	Absent			

* If a student secures CGPA< 5.0 at any point time during his/her studies, he/she will be on Academic Probation/Noncompliance (refer to sections 14.2 and 17.3 for more details.)

- i) Grade "N": A candidate having a shortage of attendance (<75%) in any course(s) or CIE marks less than 40% shall not be allowed to appear for SEE of such course(s). Such students will be awarded an 'N' grade in these courses with a grade point of 0.
- ii) The grade points are given above help in the evaluation of credit points earned by the student in a course as the credit points are equal to the number of credits assigned to the course multiplied by the grade points awarded to the student in that course. This



shall be used in Arriving at the credit index of the student for that semester, as it is the total of all the credit points earned by the student for all the courses registered in that semester.

11.8 Earning of Credits

A student shall be considered to have completed a course successfully and earned the credits if he/she secures an acceptable letter grade in the range of O-P. The letter grade "F" in any course implies the failure of the student in that course and no credits earned.

- **11.8.1** The Transitional Grades "I", "W" and "X" would be awarded by the teachers in the following cases. These would be converted into one or the other of the letter grades (O-F) after the student completes the course requirements.
- 11.8.2 Grade "I": To a student having attendance ≥85% and CIE ≥70%, in a course, but remained absent from SEE for valid & convincing reasons acceptable to the College, like:
 - i) Illness or accident, which disabled him/her from attending SEE.
 - ii) A calamity in the family at the time of SEE required the student to be away from the College.
 - iii) However, the committee chaired by the Principal is authorized to relax the requirement of $CIE \ge 70\%$ if the student is hospitalized or advised long-term rest after discharge from the hospital by the Doctor.
 - iv) Students who remain absent for Semester End Examinations due to valid reasons and those who are absent due to health reasons are required to submit the necessary documents along with their request to the Controller of Examinations to write Makeup Examinations within 2 working days of that examination for which he or she is absent, failing which they will not be given permission.
- **11.8.3 Grade "W":** To a student having satisfactory attendance at classes, but withdrawing from that course before the prescribed date in a semester under Faculty Advice
- 11.8.4 Grade "X": To a student having attendance ≥85% and CIE ≥70%, in a course but SEE performance could result in an F grade in the course. (No "F" grade will be awarded in this case, but the student's performance record is maintained separately).

11.9 Summer / Fast Track semester

- **11.9.1** The students who have satisfied CIE and Attendance requirements for the course/s and obtained an F grade in SEE are permitted to appear directly in ensuing examination/s as backlog paper/s. The students need not re-register for such course/s in the summer / fast track semester. In case the student wishes to improve CIE/ he/she has to re-register for the summer / regular semester as and when offered next.
- **11.9.2** The student who obtains required attendance and CIE in the summer semester, but obtains an 'F' grade in SEE; is permitted to appear for SEE subsequently as backlog course/s. The student need not repeat the course for Attendance and CIE.
- **11.9.3** The course/s for which the student does not possess satisfactory attendance and CIE score shall be marked as 'N' on the Grade sheet. Such students are not



permitted to SEE for the Courses marked as 'N' on the Grade sheet. The students have to re-register only for course/s marked as 'N' in the summer/ subsequent semester whenever that course is offered and obtain the required CIE and attendance. Subsequently, they are eligible to appear for SEE in such course/s.

- **11.9.4** Courses with Transitional Grades viz "W", "I", and "X" are also eligible to register in the summer semester in case they wish to improve their score in CIE.
- **11.9.5** All courses may not be offered in the summer semester. It is the discretion of the University to offer the courses based on the availability of resources. The Institutes shall notify timetable for the summer semester well in advance.
- **11.9.6** Summer Semester is optional; it is for the student to make the best use of the opportunity.
- **11.9.7** A student is permitted to register for a maximum of 16 credits in the Summer / fast track semester.
- **11.9.8** A student has to choose those courses which are offered by the Institution in a given summer Semester.
- **11.9.9** In the summer semester, each course needs to be offered for the required number of lectures/ tutorial/ laboratory hours as prescribed in the syllabus.

11.10 Grade Card

Each student shall be issued a Grade Card at the end of each semester. This will have a list of all the courses registered by a student in the semester, together with their credits, the letter grades with grade points awarded. Only those courses registered for credit and having grade points shall be included in the computation of the students' performance like SGPA and CGPA and the courses are taken for audit will not form part of this computation. The results of mandatory courses, which are of the non-credit type shall also be reflected in the Grade card as PP (for Passed) or NP (for not passed). **Each UG student shall have to obtain the grade PP in each mandatory course to qualify for the Degree awarded by the university.**

11.11 Re-evaluation and paper seeing.

Re-evaluation is permitted only for theory papers. The University, on receiving application within the stipulated time and remittance of a prescribed fee for re-evaluation, shall permit re-evaluation for the course/s applied. The marks obtained after re-evaluation shall be the final marks awarded.

11.12 The Make-Up Examination

The Make-Up Examination facility would be available to students who may have missed attending the SEE of one or more course(s) in a semester for valid reasons and given the "I" grade; Also, students having the "X" grade shall be eligible to take advantage of this facility. **The makeup examination would be held as per dates notified in the Academic Calendar during the summer semester.** However, it would be possible to hold a makeup examination at any other time in the semester with the permission of the Academic Council of the College. In all these cases, the standard of makeup examinations shall be the same as the regular SEE for the course(s).



- a) All the "I" and "X" grades awarded to the students would be converted to appropriate letter grades after the make-up examinations. Any outstanding "I" and "X" grades after the last scheduled make-up examinations shall be automatically converted to "F" grades.
- b) All the "W" grades awarded to the students would be eligible for conversion to the appropriate letter grades only after the concerned students re-register for these courses in a main/ Summer semester and fulfill the passing standards for their CIE and (CIE+SEE).

11.13 Rules for grace marks

- **11.13.1** Grace marks up to 1% of the maximum total marks of the courses for which he/she is eligible and have registered (non-credit courses excluded) in the examination or 10 marks whichever is less shall be awarded to the failed course(s), (with a restriction of a maximum of 5 marks per course) provided on the award of such grace marks the candidate passes in that course(s).
- **11.13.2** No grace marks for change of grade point.

12 EVALUATION OF PERFORMANCE

The overall performance of a student will be indicated by two indices:

SGPA; which is the Semester Grade Point Average, and CGPA which is the Cumulative Grade Point Average.

SGPA for a semester is computed as follows.

$$SGPA = \frac{\sum[(Course \ Credits) \times (Grade \ Point)] \ (for all \ courses \ in \ that \ semester)}{\sum[Course \ Credits]}$$

CGPA is computed as follows:

 $CGPA = \frac{\sum[(Course \ Credits) \times (Grade \ Point)]}{\sum[Course \ Credits]}$ (for all courses excluding those with F grades until that semester)
(for all courses excluding those with F grades until that semester)

13 COMMUNICATION OF GRADES

The SGPA and CGPA respectively, facilitates the declaration of academic performance of a student at the end of a semester and the end of successive semesters. Both would be normally calculated to the second decimal position.

14 REQUIREMENTS FOR VERTICAL PROGRESSION (PROMOTION / ELIGIBILITY TO HIGHER SEMESTERS)

- **14.1** All students are promoted to the next semester or year of their program, irrespective of their academic performance.
- **14.2** However, at any stage of his/her study, if a student reaches a CGPA below 5.00, the student will be on Academic Probation and is permitted to register for a maximum of 16 credits during odd semester of an academic year. However, the student has the choice to re-register for the courses/courses in which he/she has obtained an 'F'/ 'N' grade.





14.3 A Student shall be declared fail if he/she

- (i) Has not satisfied the CIE requirements of any Course/s.
- (ii) Has not appeared for the SEE even after satisfying the attendance and CIE requirements.
- 14.4 Vertical Progression for regular students who have taken admission to the first year: Normally a student is expected to complete a minimum of 85% of credits by the end of the 7th semester. However, for submission of B.Tech. Major Project in 8th semester, the student should have completed at least 122 credits.
- **14.5** Vertical Progression in case of Diploma students admitted to Second year (lateral entry):
 - 14.5.1 Lateral entry students should complete at least 85% of credits by the end of the 7th semester. However, for submission of B.Tech. Major Project in 8th semester, the student should have completed at least 88 credits.
 - **14.5.2** Diploma students should register for mandatory non-credit Mathematics Courses Bridge Courses (i) Calculus and Laplace Transforms and (ii) Probability and Differential Equations prescribed during III and IV semesters respectively. They shall attend these bridge course classes during the respective semesters to satisfy attendance and CIE requirements.
 - **14.5.3** Completion of Mathematics Courses Bridge Courses (i) Calculus and Laplace Transforms and (ii) Probability and Differential Equations shall be mandatory for the award of the degree.

14.6 Termination from the program

A student shall be required to withdraw (discontinue) from the program and leave the college on the following grounds.

- i) Failure to secure a minimum CGPA of 5.0 at the end of the 8 years (6 years for lateral entry students).
- **ii)** Failure to earn 160 credits (120 for lateral entry students) in 8 years (6 years for lateral entry students) of duration from the year of admission including the duration of temporary withdrawal (leave of absence).
- iii) Absence from classes for more than **six weeks at a time** in a semester without leave of absence being granted by competent authorities.
- iv) Failure to meet the standards of discipline as prescribed by the college from time to time.

15 AWARD OF CLASS

Sometimes, it would be necessary to provide equivalence of these averages, viz., SGPA and CGPA with the percentages and/or classes awarded as in the conventional system of declaring the results of university examinations. This can be done by prescribing certain specific thresholds in these averages for Distinction, First Class and Second Class. This can be seen in the following Table.





Grade Point	Percentage of Marks*	Class
≥ 7.00	≥70%	First class with
		Distinction
≥ 6.00	$\geq 60\%$	First Class
$5.0 \ge CGPA < 6.00$	$50 \ge Percentage < 60\%$	Second Class

Percentage Equivalence of Grade Points (For a 10-Point Scale)

Percentage * = (CGPA) x 10

16 APPEAL FOR REVIEW OF GRADES

- a. The entire process of evaluation shall be made transparent and the course instructor shall explain to a student why he/she gets whatever grade he/she is awarded, if and when required. A mechanism for the review of grades is incorporated into the evaluation system. However, before appealing for such review, a student shall first approach the concerned course Instructor and then the concerned DUGC, with the request to do the needful; and only in situations where satisfactory remedial measures have not been taken, the student may then appeal to the Department Academic Appeals Boards (DAAB) before the date specified in Academic Calendar, by paying the prescribed fees.
- b. The fee for such an appeal will be decided by the Senate from time to time. If the appeal is upheld by DAAB, then the fee amount will be refunded to the student.

17 AWARD OF DEGREE

17.1 (1) **B.Tech. Degree**

- a) Students shall be declared to have completed the Program of B.Tech. degree and is eligible for the award of degree provided the students have undergone the stipulated Course work of all the semesters under the Scheme of Teaching and Examinations and have earned the prescribed number of credits (160 credits for regular students registered for 4-year degree programs & 120 for lateral entry students).
- b) For the award of a degree, a CGPA \geq 5.00 at the end of the Program shall be mandatory.
- c) Completion of Additional Mathematics I and II shall be mandatory for the award of degree to lateral entry diploma students.
- d) Earning of Activity Points:
 - i. Every student entering 4-year degree program should earn 100 activity points & every student entering 4-year degree program through Lateral Entry should earn 75 activity points as per the AICTE Activity Point Program for the award of an Engineering degree
 - ii. The activities can be spread over the years (duration of the program) at any time during the semester weekends and holidays, as per the interest & convenience of the students from the year of entry to the program.
 - iii. The Activity Points earned shall be reflected on the student's eighth-semester Grade Card.
- iv. Activity Points (non-credit) do not affect SGPA/CGPA and shall not be considered for vertical progression.
- v. In case students fail to earn the prescribed activity Points before the commencement of 8th-semester examinations, the eighth-semester Grade Card shall be issued only after earning the required activity Points. Students shall be admitted for the award



of a degree only after the release of the Eighth semester Grade Card.

17.2 Honours/ Minors Degree

17.2.1 B.Tech. (Honours) Degree

- i. Students must earn a minimum of 18 additional credits in his/her major program discipline entitles a student to get an 'Honours' credential.
- ii. Students have to pay additional fees for all the courses registered for 'Honours'
- iii. Students with a minimum of 7.5 CGPA and no backlog at the end of the 4th semester will qualify for registering for courses under the 'Honours credential.
- iv. Students shall register for 'Honours' courses from the 5th semester onwards.
- v. Students should register for additional courses and plan to take courses that are prescribed under that 'Honours' list as per 'pre-requisite' courses to earn the 'Honours' credential.
- vi. Students who wish to acquire an 'Honours' credential need to carry out 'Honours' course registration along with their regular semester course registration.
- vii. He/she accumulates credits by registering for the required courses, and if the requirements for 'Honours' are met within the prescribed minimum time limit of the program, the 'Honours' will be awarded along with the degree.
- viii. Also, the student should meet the following requirements to become eligible for the 'Honours award.
 - Minimum CGPA of 7.5 in this major discipline at the end of the 8th semester
 - Minimum CGPA of 7.0 in the registered 'Honours' courses
- ix. In case a student withdraws from the 'Honours' registration in the middle of the program, the 'Honours' courses completed will be converted to 'Audit' courses and indicated accordingly in subsequent Grade Sheets and Consolidated Grade Sheets.
- x. It must be noted that the 'Honours' award will be mentioned in the Degree Certificate as **"Bachelor of Technology in (specialization) with Honours".**
- xi. This fact will also be reflected in the Consolidated Grade Sheet under a separate heading 'Honours' with similar details shown for other credited courses and the CGPA for 'Honours' will be indicated at the end of the list of courses under 'Honours'.
- xii. The grades obtained in the courses credited towards the 'Honours' award are not counted and shall not influence the GPA/ CGPA of the 'program' student has registered.

17.2.2 Minor Degree

- i. Students have to earn a min of 18 additional credits from the courses focused on discipline other than his/her major program discipline entitles a student to get a 'Minor' credential.
- ii. Students have to pay additional fees for all the courses registered for 'Minor'.
- iii. Students with a minimum of 5.0 CGPA and no backlog at the end of the 3rd semester will only qualify for registering for the course under the 'Minor' credential.
- iv. Students shall register for 'Minor' degree courses from the 4th semester onwards.
- v. All Departments will offer 'Minors' in their varied disciplines and will prescribe



what set of courses and/or projects is necessary for earning a minor in that discipline.

- vi. Students should register for additional courses and plan to take courses that are prescribed under that 'Minors' list as per 'pre-requisite' courses to earn the 'Minor' credential
- vii. If any of the courses listed under the 'minor' option is a course listed under his/her curriculum as PCC then the student cannot opt for that 'Minor', since all minor courses need to be earned as additional courses to his/her program curriculum and depts decision is final and binding
- viii. Students who wish to acquire a 'Minor' can register for 'Minor' courses along with their regular semester course registration.
- ix. Also, the student should have a minimum CGPA of 5.0 in the 'Minor' courses registered to become eligible for the Minor credential. This fact will also be reflected in the Consolidated Grade Sheet under a separate heading 'Minor in (specialization)'.
- x. If the course requirements for a particular 'Minor' are met within the prescribed minimum time limit of the program, the minor will be awarded along with the degree, and it will be mentioned in the **Degree Certificate as "Bachelor of Technology in (Major discipline) with Minor in (specialization)."**
- xi. In case a student withdraws from the 'Minor', the 'Minor' courses completed, will be converted to 'Audit' courses and indicated accordingly in subsequent Grade Sheets and Consolidated Grade Sheets.
- xii. The grades obtained in the courses credited towards the 'Minor' award are not counted and shall not influence the GPA/ CGPA of the program the student has registered for.

17.2.3 Additional norms for Honours/Minors

- i. Students shall register for additional courses to earn Honours/Minors in consultation with their Class Advisor from the list of courses suggested by the DUGC.
- DUGC may recommend Massive Open Online Courses (MOOCs)/SWAYAM/NPTEL courses to students who wish to register for Honours/Minors after justifying and establishing the equivalence of the curriculum. The decision of DUGC should be communicated to the Dean of Academics and Controller of Examinations for seeking approval.
- iii. A maximum of 40% credits prescribed for Honors/Minors may be earned through MOOCs/SWAYAM/NPTEL
- iv. Students may choose to take up additional course work, from the MOOCs courses list suggested by various departments (which can be from SWAYAM/NPTEL) with proctored examinations as approved by the University and complete the same before the last working day of the VIII semester with a final score (online assignments: 25 % + Proctored examination: 75 %) leading to the following certificates: Completed the course (40-59)– ELITE (60 to 75 %) or ELITE + SILVER (76 to 89 %) or ELITE + GOLD (\geq 90 %)
- v. In case, in MOOCs (ex: Coursera), there is no proctored examination, the University will conduct a SEE as deemed to be fit for the award of Credits



- vi. The Credit equivalence for online courses shall be as follows -
 - 4 weeks of online course duration 1 credit (approx. 13-14 hours)
 - 8 weeks of online course duration 2 credits (approx. 26-28 hours) and
 - 12 weeks of online course duration 3 credits (approx. 39-42 Hours)

17.3 Noncompliance

17.3.1 Noncompliance of CGPA \geq 5.00 at the end of the Program

- a) Students, who have completed all the courses of the Program but do not have a $CGPA \ge 5.00$ at the end of the Program, shall not be eligible for the award of the degree.
- b) In the cases of 17.3 (1), a student shall be permitted to appear again for SEE in course/s (other than Internship, Technical seminar, Project (Mini and Major), and Laboratories) of any Semester/s without the rejection of CIE marks for any number of times, subject to the provision of a maximum duration of the Program to make up the CGPA equal to or greater than 5.00 for the award of the Degree.
- c) Students shall obtain written permission from the Controller of Examinations to reappear in SEE to make up the CGPA equal to or greater than 5.00.
- d) In case, the students earn improved grade/s in all the reappeared course/s, the CGPA shall be calculated considering the improved grade/s. If it is \geq 5.00, the students shall become eligible for the award of the degree. If CGPA <5.00, the students shall follow the procedure laid in 17.3.1 (b).
- e) In case, the students earn improved grade/s in some course/s and the same or lesser than the previously earned pass grade/s in the other reappeared course/s, the CGPA shall be calculated considering the improved grade/s and the pass grades earned before the reappearance. If it is ≥5.00, the students shall become eligible for the award of the degree. If CGPA<5.00, the students shall follow the procedure laid in 17.3.1 (b).
- f) In case, the students earn improved grade/s in some courses and fail in the other reappeared course/s, the CGPA shall be calculated by considering the improved grade/s and the previously earned pass grade/s of the reappeared course/s in which the students have failed. If it is≥5.00, the students shall become eligible for the award of the degree. If CGPA <5.00, the students shall follow the procedure laid in 17.3.1 (b).</p>
- g) In case, the students fail (i.e., earns an F grade) in all the reappeared course/s, pass grade/s of the course/s earned by the students before reappearance shall be retained. In such cases, the students shall follow the procedure laid in 17.3.1 (b).

17.3.2 Noncompliance with Project/ Mini project

The project/mini project shall be considered as a head of passing and shall be considered for the award of degree. Those, who do not take up/complete the mini-project shall be declared to fail in that course and shall have to complete the same during subsequent University examinations after satisfying the Mini-project requirements.

17.3.3 Noncompliance of Internship

All the students of B. Tech shall have to undergo mandatory Internship-I and Internship-II for a total of 10 weeks to earn a total of 10 credits in parts during the vacations at the end of the 1/2/3 academic year. The evaluation of Internship shall



be during IV and VIII semesters. The internship shall be considered mandatory for the award of a degree. Those, who do not take up/complete the internship shall be declared to fail in that Course and shall have to complete the same during subsequent University examinations after satisfying the internship requirements. The maximum duration for a student for complying with the Degree requirements is 16 - semesters from the date of first registration for his/ her first semester (8 years from the date of admission to the first year, (12 semesters / 6 years from the date of admission for lateral entry student)).

18 GRADUATION REQUIREMENTS AND CONVOCATION

- 18.1 A student shall be declared to be eligible for the award of the degree if he/she has
 - a) Fulfilled "Award of Degree" Requirements
 - b) No Dues to the College, Departments, Hostels, Library, Central Computer Centre and any other centers
 - c) No disciplinary action is pending against him/her.
- 18.2 The award of the degree must be recommended by the Governing council
- **18.3 Convocation:** Degree will be awarded to the students who have graduated during the preceding academic year. Students are required to apply for the Convocation along with the prescribed fees, after having satisfactorily completed all the degree requirements (refer to "Award of Degree") within the specified date to arrange for the award of the degree during convocation.

19 AWARD OF PRIZES, MEDALS, CLASS & RANKS

- **19.1** For the award of Prizes and Medals, the conditions stipulated by the Donor may be considered as per the statutes framed by the University for such awards. Sometimes, it would be necessary to provide equivalence of these averages, viz., SGPA and CGPA with the percentages and/or Class awarded as in the conventional system of declaring the results of University examinations. This can be done by prescribing certain specific thresholds in these averages for Distinction, First Class, and Second Class as described in Section 15.
- **19.2** An attempt means the appearance/registration of a candidate for an examination in one or more courses either in part or failing a particular examination.
 - **19.2.1** A candidate who fails/remains absent (after submitting exam application) in the main examination and passes one or more subjects/courses or all subjects/courses in the supplementary/Make-up examination such candidates shall be considered as taken more than an attempt.
- **19.3** Merit Certificates and University Medals/ will be awarded based on overall CGPA, governed by the specific selection criteria that may be formulated by the University for such Medals / Awards
 - **19.3.1** Only those candidates who have completed the Program and fulfilled all the requirements in the minimum number of years prescribed (i.e., 3 years for Diploma lateral entry students or 4 years for students who joined after the 12th standard) and who have passed each semester in the **first attempt** are eligible for the award of Merit Certificates and /or University Medals.
 - **19.3.2** Candidates with W, N, I, X & F grades and who passes the courses in the subsequent/supplementary/make up examinations are not eligible for the award of



Gold Medal or Merit Certificate.

20 CONDUCT AND DISCIPLINE

- **20.1** Students shall conduct themselves within and outside the premises of the College in a manner befitting the students of an Institution of National Importance.
- 20.2 As per the order of the Honorable Supreme Court of India, ragging in any form is considered a criminal offense and is banned. Any form of ragging will be severely dealt with.
- **20.3** The following acts of omission/ or commission shall constitute a gross violation of the Code of Conduct and are liable to invoke disciplinary measures:
 - i. Ragging.
 - ii. Lack of courtesy and decorum; indecent behavior anywhere within or outside the campus.
 - iii. Willful damage or stealthy removal of any property/belongings of the College/Hostel or fellow students/citizens.
 - iv. Possession, consumption, or distribution of alcoholic drinks or any kind of hallucinogenic drugs.
 - v. Mutilation or unauthorized possession of Library books.
 - vi. Noisy and unseemly behavior, disturbing studies of fellow students.
 - vii. Hacking in computer systems (such as entering into another Person's area without prior permission, manipulation and/or Damage of computer hardware and software, or any other Cybercrime, etc.).
 - viii. Plagiarism of any nature.
 - ix. Any other act of gross indiscipline as decided by the Senate from time to time.
 - x. Use of Mobile in the college Academic area.
 - xi. Smoking in College Campus and supari chewing.
 - xii. Unauthorized fundraising and promoting sales.
 - xiii. Commensurate with the gravity of the offense the punishment may be: reprimand, expulsion from the hostel, debarring from an examination, disallowing the use of certain facilities of the College, rustication for a specified period or even outright expulsion from the College, or even handing over the case to appropriate law enforcement authorities or the judiciary, as required by the circumstances.
- **20.4** For an offense committed in (i) a hostel (ii) a department or a classroom and (iii) elsewhere, the Chief Warden, the Head of the Department, and the Dean (Academics), respectively, shall have the authority to reprimand or impose fine.
- **20.5** All cases involving punishment other than reprimand shall be reported to the principal.
- **20.6** Cases of adoption of unfair means and/or any malpractice in an examination shall be reported to the Controller of Examinations for taking appropriate action.
- **20.7** Note: Students are required to be inside the examination hall 20 minutes before the commencement of the examination. This is applicable for all examinations (Semester end/Supplementary/makeup) henceforth. Students will not be allowed inside the examination hall after the commencement, under any circumstances.



APPENDIX - A

Definitions, terminology, and abbreviations

1. Nitte DU / University

a. Refers to Nitte (Deemed to be University)

2. BoM

a. Refers to Board of Management of Nitte (Deemed to be University)

3. BoS

a. Refers to the Board of Studies in Mechanical Engineering

4. Institute/Institution

a. Refers to NMAM Institute of Technology, Nitte

5. Program

a. A range of learning experiences over a specified period, leading to the award of a degree/diploma/certificate. A program is completed when the courses that make up the program are completed, and other requirements as specified in the program regulations are met.

6. Course

a. A unit of learning that typically lasts one semester, led by one or more teachers, for a fixed roster of students. Often referred to as a "subject". A course has identified course outcomes, modules/units of study, specified teaching-learning methods, and assessment schemes. A course may be designed to include lectures, tutorials, practical, laboratory work fieldwork, project work, internship experiences, seminars, self-study components, online learning modules, etc. in any combination.

7. Semester

- a. An academic session, usually of 16 weeks duration, with a minimum of 90 working days during which coursework and assessments are to be completed. Typically, two semesters make up an academic year, with the first of these referred to as the Odd Semester and the second as the Even Semester.
- b. An additional short semester (usually 8 weeks) may be offered between an even semester and subsequent odd semester (in the interval between two academic years) and is termed a summer semester. The summer semester is offered to enable students to register for:
 - i. Fast-tracked courses required for clearing backlog courses
 - ii. Fast-tracked courses for earning additional credit / completing non-credit mandatory requirement
 - iii. Value added courses
 - iv. The courses offered in summer semesters are bound by the same regulations as that of regular semesters, except that they are run at an accelerated pace to provide the required contact hours and conduct assessments within the 8 weeks.



8. Credit

a. A unit by which the course work is measured. It determines the number of hours of formal learning (contact hours) required per week. Credits are calculated based on the concept of "notional learning time". Notional learning time is the number of hours that a learner is expected to spend, on average, to achieve the specified learning outcomes of the course. This may comprise a variable combination of scheduled learning activities, (lectures, seminars, labs, etc.) and self-directed learning time (reading required before classes, working on assignments, examination preparation, and completion of assessments).

9. Credit equivalence of notional learning time for different types of activities

a. The credit values assigned to various teaching-learning activities are as follows:

Type of teaching- learning	Nature of activity	No. of contact hours per week equivalent to one credit	The total number of contact hours over a 16-week semester is equivalent to one credit
Lectures / Seminars / synchronous virtual classes / synchronous webinars	Scheduled instruction	1:1	16
Tutorials	Scheduled instruction	2:1	32
Supervised Demonstrations /Laboratory sessions / Studio / Workshops / Workplace simulation / Skill Practice Sessions	Scheduled instruction	2:1	32
Supervised Field visits/community visits/Internships	Scheduled instruction	3:1	48
Scheduled self- directed study (individual or group)	Scheduled instruction	2:1	32
Asynchronous E- Learning modules (structured self- directed study	Independent learning	2:1	32
Student Seminar	Independent /small group learning	2:1	32
Project work/dissertation	Independent /small group learning	3:1	48
Internship for credit	Industry placement/ Research Internship	3:1	48



10. Choice-based credit system (CBCS)

A program structure for higher education requires students to earn a minimum of credits by completing various types of courses, including electives, which facilitate a student to have some freedom in selecting his/her own choices, within as well as across disciplines.

11. Course Registration

Refers to formal registration of the Courses in the study every semester (Credits and Audit) by every student under the supervision of a faculty advisor. The institution will maintain records of the same and communicate them to the University.

12. Learning outcomes

- a. Program Outcomes (PO) Statements defining the skills, knowledge, and attitude that graduates of a program will be able to demonstrate upon completing the program
- b. Course Outcomes (CO) Statements defining the skills, knowledge, and attitude that students will be able to demonstrate upon completing the course. COs are mapped to the POs such that attaining the course outcomes leads to the attainment of program outcomes.
- c. Attainment of POs-COs is mapped to the POs such that attaining the course outcomes leads to the attainment of program outcomes.

13. Evaluation

For all courses, the evaluation will be based on both formative assessment (Continuous Internal Evaluation, CIE) and summative assessment (Semester End Evaluation, SEE). Weightage for CIE and SEE will be 50% each

13.1 Continuous Internal Evaluation (CIE)

Refers to the periodic and continuous *formative assessment* of students' performance during the semester by the teacher(s) of the course to provide timely feedback to students and for guiding "course corrections" by the teachers. The assessment methods may include tests, quizzes, assignments, project evaluations, portfolio evaluations, seminar assessments, etc. CIE will have a weightage of 50% in the determination of the final grading of the course.

13.2 Semester End Evaluation (SEE)

Refers to a *summative assessment* that covers the entire course syllabus, conducted by the University, at the end of the semester. Appropriate assessment methods aligned with the learning domain and teaching-learning methods are to be used. CIE will have a weightage of 50% in the determination of the final grading of the course.

14. Grading

Course Grade refers to a qualitative measure of performance of a student in each course, based on the percentage of marks secured in Continuous Internal Evaluation (CIE) and Semester End Evaluation (SEE). A Letter grade is awarded for each course.

15. Semester Grade Point Average (SGPA)

Refers to the measure of a student's academic performance in a semester. It is calculated based on the credits and the grades obtained in the courses offered in the semester.



16. Cumulative Grade Point Average (CGPA)

Refers to the measure of the cumulative performance of a student in all the previous semesters and is computed from the 2nd semester onwards. It is calculated based on the credits and the grades obtained in all the courses taken.

17. Academic Bank of Credits (ABC)

The Academic Bank of Credits is a national-level facility for "credit transfer". It is provided by the Ministry of Education, Govt. of India, to promote the flexibility of the curriculum framework and interdisciplinary/multidisciplinary academic mobility of students across the Higher Education Institutions in the country. The banking and redemption of credits through ABC will be governed by the University's guidelines.



APPENDIX-B

Evaluation Guidelines

CIE and SEE details for various types of courses

1. Theory: PCC/IPCC/PEC/OEC

1.1. Scheme of examinations: CIE+SEE =50+50=100 marks

1.2. Continuous internal evaluation (CIE):

1.2.1. CIE (PCC/PEC/OEC)

Type of Questions	Questions to be set (Can have sub- questions a and b)	Questions to Be answered	Marks per question	Total marks				
	Mid Sem Exam-1							
40%	of the total syllabus (Unit-1) (15 Teac	hing hours)					
Descriptive Part-1	2	1	10	10				
Descriptive Part-2	2	1	10	10				
	Mid Sen	n Exam-2						
40%	of the total syllabus (Unit-2) (15 Teac	hing hours)					
Descriptive Part-1	2	1	10	10				
Descriptive Part-1	2	1	10	10				
	TA	SKS						
TASKThe task comprises 5 class tests/quizzes/assignments conducted for each unit for a max mark of 10. All tests/quizzes/Assignments are compulsory								
Maximum Marks	-			50				

1.2.2 CIE (IPCC/PBL)

Type of Questions	Questions to be set (Can have sub- questions a and b)	Questions to be answered	Marks per question	Total marks		
	Mid Sem E	xam-1				
40%	of the total syllabus (Uni	t-1) (15 Teac	hing hours)			
Descriptive Part-1	2	1	10	10		
Descriptive Part-2	2	1	10	10		
	Mid Sem Exam-2					
40%	of the total syllabus (Uni	t-2) (15 Teac	hing hours)			
Descriptive Part-1	2	1	10	10		
Descriptive Part-1	2	1	10	10		
Task	The task comprises 5 class conducted for each unit tests/quizzes/Assignments	for a max m	ark of 10. All	10		
	Maximum Marks	•	2	50		
	60% weightage, conve	erted to 30 ma	urks			
	Practical/Project Base	d Learning (l	PBL)			
Practical/PBL Practical/PBL (comprises of implementation of theoretical concepts through projects/problem solving)						
	40% weightage, conve	erted to 20 ma	urks			
Maximum Marks [3	30 (Theory)+ 20 (Practica	l/PBL)]		50		





Type of Questions	Module & Teaching hours	Questions to be set (Can have sub-questions a, b, and c)	Questions to be answered	Marks per question	Total marks
MCQ	Entire Syllabus	10 or 20	All Questions	2 or 1	20
Descriptive	Unit-115 teaching hours	3	2	16	32
Descriptive	Unit-215 teaching hours	3	2	16	32
Descriptive	Unit-310 teaching hours	2	1	16	16
Maximum Marks					
SEE Marks	with 50% Weightage				50

1.2.3 Semester End Evaluation (SEE): 3 Hours Duration

1.2.4 CIE & SEE for various types of courses

	Evaluation scheme				n scheme	
			CIE	5	SEE	
			(Minimun	0 7		m Passing
				0% of Max		0 % of Max
			marks		marks)	
S1.	Cour	1 000	Max	Min	Max	Minimum
No.	Cour	1303	Marks	eligibility	Marks	passing
				marks		marks
				required		required
	Integrated	Theory	30	12	50	20
1	Professional Core	Practical	20	08		
	Course (IPCC)	Total	50	20	50	20
	PCC with PBL	Theory	30	12	50	20
2	component	PBL component	20	08		
	-	Total	50	20	50	20
3	PCC/PEC/OEC		50	20	50	20
4	Laboratory		50	20	50	20
5	Drafting		50	20	50	20
6	Mini Project		100	40		
7	Inter/Intra Institutio (2 weeks)	onal Internship	100	40		
Q	Industrial/Govt./ NGO/MSME/ Rural Internship/ Innovation / Entrepreneurship (In single or two stretches =Total of 8 weeks)		100	40	100	40
9	Research Internship/ Advanced Industry Internship/Project work		100	40	100	40
10	Seminar		100	40		

All university examinations (SEE) shall be conducted for a maximum of 100 marks. For assigning





the letter grade the university examination marks secured by a student, except in the case of serial no. 06, 07, and 10 shall be reduced to 50 marks and added to CIE marks. If the total marks result in a fraction during reduction, it shall be rounded off to the nearest higher value.

2 Laboratory/Practical Course

2.1 Split-up of Marks for evaluation of Practical for 50 CIE marks and 50 SEE marks.

2.2 Split-up of Marks for evaluation of Laboratory work:

- **2.2.1** Laboratory in-charge faculty will follow rubrics given in the Tables below for an evaluation of laboratory courses
- **2.2.2** In the case of Practical, the IA marks shall be based on laboratory observation, records, viva, and at least one practical test.
- **2.2.3** Continuous Evaluation in every lab session will be done using the format mentioned in the Table to evaluate PO9 (Individual and teamwork) and PO10 (Communication).
- 2.2.4 Rubrics used for continuous Evaluation of **laboratory courses involving experiments** with hardware

Lab	conduction an	d Record	Lab Int	ternal Assessme	ent
 Split-up: 60% (30 Marks) of Maximum CIE marks (50). Each experiment is to be evaluated for conduction with an observation book and record write-up (30 marks per experiment). The final marks for conduction and record are the average of all the specified experiments in the syllabus. 			Split-up: 40% (20 Marks) of Maximum CIE marks (50). One test of 20 Marks In the test, conduction of the experiment and acceptable result with viva-voce will carry a weightage of 60% per experiment, with the rest 40% for procedural knowledge and regularity of the student.		
Rubrics	Marks			Marks	
per experiment	Distribution	Remarks	Rubrics	distribution	Remarks
Circuit	02		Write-up	04	
Design	02	Evaluation of	Conduction	10	
Procedure	02	Record write-up			
Conduction	06	to include			
Viva	06	weightage for			
Record write-up	12	submission on time, neatness,	Results	06	
Total Marks	30	etc.	Total Marks	20	



2.2.5 Split-up of Marks used for continuous Evaluation of laboratory involving experiments with software

Rubrics for Split up of Marks	Methodology / Process Steps per Experiment	Marks
#R1	Observation, Write up of Procedure / Algorithm/ Program execution, and Conduction of experiment	12
#R2	Viva – Voce	06
#R3	Record writing	12
	Total Marks for each experiment	30
	Internal Test: Lab Internal Assessment	
	(i)Write-up of Procedure/Program/Algorithm	04
#R4	(ii) Conduction/Execution	10
	(iii) Viva-Voce	06
	Total Marks	20

3. Internship and Evaluation

3.1 Introduction

The rise in global competition has prompted organizations to devise strategies to have a talented and innovative workforce to gain a competitive edge. Developing an internship policy is an impactful strategy for creating a future talent pool for the industry. The internship (a form of experiential learning) program not only helps fresh pass–outs in gaining professional know-how but also benefits corporate sectors. The internship also enhances the employability skills of the student passing out from Technical Institutions.

The following list provides a brief illustrative overview of the knowledge, skills, work habits, and

character traits commonly associated with 21st-century skills and to be acquired by graduates:

- Critical thinking, problem solving, reasoning, analysis, interpretation, and synthesizing information.
- Scientific literacy and reasoning, the scientific method.
- Research skills and practices, interrogative questioning.
- Creativity, artistry, curiosity, imagination, innovation, and personal expression.
- Information and communication technology (ICT) literacy, media and internet literacy, data interpretation and analysis, and computer programing.
- Oral and written communication, public speaking and presenting, listening.
- Economic and financial literacy, entrepreneurial skills.
- Global awareness, multicultural literacy, humanitarianism.
- Environmental and conservation literacy, ecosystems understanding.





- Civic, ethical, and social-justice literacy.
- Leadership, teamwork, collaboration, cooperation, and facility in using virtual workspaces.
- Perseverance, self-direction, planning, self-discipline, adaptability, initiative.
- Health and wellness literacy, including nutrition, diet, exercise, and public health and safety.

The internship experience will augment the outcome-based learning process and inculcate various attributes mentioned above in a student in line with the graduate attributes defined by the NBA as well as NEP 2020

Following are the intended objectives of internship training.

- (i) Expose Technical students to the industrial environment, which cannot be simulated in the classroom, and hence create competent professionals in the industry.
- (ii) Provide possible opportunities to learn, understand and sharpen the real-time technical/managerial skills required at the job.
- (iii) Expose to the current technological developments relevant to the subject area of training.
- (iv) Use the experience gained from the industrial internship in discussions held in the classrooms.
- (v) Create conditions conducive to the quest for knowledge and its applicability on the job.
- (vi) Learn to apply technical knowledge in real industrial situations.
- (vii) Gain experience in writing reports on technical works/projects.
- (viii) Expose students to the engineer's responsibilities and ethics.
- (ix) Familiarize with various materials, processes, products, and their applications along with relevant aspects of quality control and safety measures.
- (x) Promote academic, career, and/or personal development.
- (xi) Expose the students to future employers.
- (xii) Make students available to the industry for employment.
- (xiii) Understand the psychology of the workers and their habits, attitudes, and approach to problem-solving.
- (xiv) Understand the social, economic, and administrative considerations that influence the working environment of industrial organizations.
- **3.2 Academic credit framework for the internship and project work** undergone as part of the B.Tech. program.
 - A minimum of 20 credits of Internship/ Entrepreneurial activities / Project work/ Seminar and Inter/ Intra Institutional Training may be counted towards B. Tech. degree program
 - Here, 1 credit is equivalent to a minimum of 40-45 hours of work. Therefore, a full-time intern is expected to spend 40 45 hours per week on Internship, Training, Project work, Seminar activities, etc. This will result in about 800 to 900 hours of total internship and project duration for the B. Tech program.
 - To derive the benefits of an internship, it is introduced in two/ three stages of the B.Tech. program.
 - Internships may be full-time or part-time; they are full-time during the summer vacation and





part-time during the academic session. The curriculum is flexible to adjust internship duration. Therefore, opportunities must be provided for experiences that cannot be anticipated when planning the course.

• The departments have the flexibility to schedule internships, Project work, Seminars, etc. according to the availability of the opportunities. However, the suggested minimum requirement regarding Internship duration and credits are as given in Table -B1.

Sl. No.	Title	Schedule	Duration	Activities	Credits
1	Internship-I	Ongoing First-year academic session/ Summer vacation after 2nd Semester/ vacation during 3 rd semester (for lateral entry students	02 weeks	Inter/ Intra Institutional Activities (Evaluation in 4 th semester)	02
2	Internship- II	a) Summer vacation after 4th Semester	02-04 weeks	Industrial/Govt./ NGO/ MSME/ Rural Internship/ Innovation / Entrepreneurship/ social internship	
		b) Summer vacation after 6th Semester	04-06 weeks	Industrial/Govt./ NGO/ MSME/ Rural Internship/ Innovation / Entrepreneurship	
		c) Total of a) and b) at the beginning of the 8th semester	08 weeks	Evaluation in 8 th Semester	08
3	Project work	6 th Semester	6 hours/week	Mini -Project	02
		8th Semester	16 weeks	Extended Industry Internship /Research Internship/ Project work	10
				Report preparation and writing	
				Seminar	01
		Total Cre	edits		23

Table-B1 Suggested Credit Framework for Internship and Project work

Table-1 states that during the ongoing/ summer vacations after the 2nd Semester, students are required to be involved in Inter/ Intra Institutional Activities viz; Training with higher Institutions; Soft skill training organized by Training and Placement Cell of the respective institutions; contribution at incubation/ innovation /entrepreneurship cell of the institute; participation in conferences/ workshops/ competitions, etc.; Learning at Departmental Lab/ Tinkering Lab/ Institutional workshop; Working for consultancy/ research project within the institutes and Participation in all the activities of Institute's Innovation Council for eg: IPR workshop/Leadership Talks/ Idea/ Design/ Innovation/ Business Completion/ Technical Expos, etc.





During the summer vacation after the 4th/ 6th semester, students are ready for industrial experience. Therefore, they may choose to undergo Internship / Innovation / Entrepreneurship related activities. Students may choose either to work on innovation or entrepreneurial activities resulting in start-up or undergo internship with industry/NGO/ Government organizations/ Micro/ Small/ Medium enterprises to make themselves ready for the industry.

3.3 Internship Supervision

- i) The internship shall be carried out under the supervision of a faculty mentor. The faculty mentor/guide should,
- ii) Serve as a teacher, mentor, trainer, critic, leader, and boss.
- iii) Provide sufficient time to guide the interns. (Interns are students or a trainee who does a job to gain work experience)
- iv) Play a vital role, along with the Training and Placement Officer, in providing internship opportunities for the students.
- v) Exhibit qualities such as leadership, strong communication skills, and patience.
- vi) Provide a letter of recommendation in due consultation with students and the industrial organization (if possible) where the internship is intended to be carried out, endorsed by the authority (Principal/Institution Internship Coordinator).
- 3.3.1 Each faculty mentor shall supervise the students/Student batches allotted to them. Often, the supervision may be by an external expert. In such cases, the faculty mentor shall jointly guide the student/s without causing miscommunications/embarrassment to either side.
- 3.3.2 Depending on the activity taken up by the students, the internship shall be carried out individually or in batches having not more than three students.
- 3.3.3 Faculty Mentor, along with the external expert, shall scrupulously evaluate the work of an individual student or students of a batch and maintain the relevant documents.
- 3.3.4 For allotment of CIE marks, the institutions shall prepare the rubrics for each activity offered by the institution as given in Table B2. The marks shall be allotted by the Internship committee designated by HOD in consultation with the mentors.
- 3.3.5 For all activities conducted by the institution, the attendance of the students shall be maintained by the faculty and maintained in their respective departments.

3.4 Internship-I (Activity based Internship)

While intra-activities are within the institution, inter-activities shall be between the concerned institution and neighboring institutions. Intra and Inter activities are the activities that are the impetus to learning techniques. It adds to the comprehensive growth of the mind and associated activities.

As the students are on the verge of learning technical aspects and have a limited period of internship, it is preferable to expose students to polygonal activities instead of one type of activity. Therefore, activities completed by the students shall not be one type of activity but can be few within the period of the internship. In this regard, Intra and Inter-Institutional activities shall be completed under the supervision of a faculty on a self-learning basis.

The faculty have to kindle the latent abilities of the students, encourage, guide, supervise and shape them to achieve the desired result. Therefore, a learning agenda in the form of specific learning objectives and outcomes shall be prepared before the start of the internship.



Whatever the activity/activities that are/are done under Intra and Inter-Institutional activities, should ignite the inquisitiveness to learn, enhance the knowledge, thinking ability and imagination, planning, application of mind, execution ability, innovation attitude, listening and understanding, vocabulary, personal expression, public speaking, written communication, oral presentation of the subject matter, acquire leadership qualities and teamwork requirements, responsiveness, ethics, etc.

3.4.1 List of proposed activities

- a. Activities concerned with the works of Indian scholars like Charaka and Susruta, Aryabhata, Bhaskaracharya, Chanakya, Madhava, Patanjali, Panini, and Thiruvalluvar, among numerous others
- b. Activities such as training with higher Institutions or Soft skill training
- c. Contribution at incubation/ innovation /entrepreneurship cell of the institute.
- d. Learning at Departmental Lab/Tinkering Lab/ Institutional workshop.
- e. Working for consultancy/ research projects within the institute.
- f. Learning MS Word, Excel, Microsoft equations, MS drawing tools, MS Powerpoint, etc.
- g. Coding.
- h. Mini projects using commercially available assembled electronic products.
- i. Debates, quizzes, and group discussions: On technical topics already studied (both in Kannada and English).
- j. Essay competitions: Both in Kannada and English on technical topics already studied.
- k. Survey and study of published literature on the assigned topic: Technical paper survey, Preparation of synopsis. Exposure to technical paper publications.
- l. Photography.
- m. Short film production: Contemporary aspects, technical aspects, etc.
- n. Internship in Disaster Management.
- o. Solar energy connected activities that help the common man.
- p. Working with Smart City Administration.
- q. Hackathon (it is a design sprint-like event in which computer programs and others involved in software development, including graphic designers, interface designers, project managers, and others, often including domain experts collaborate intensively on software projects).
- r. Industrial Safety, Fire Safety, Electrical Safety, Chemical Process Safety, Food Safety, etc.
- s. Internship and project work in Indian Knowledge System related Areas/Topics.
- t. Industrial visits to Small Scale Industries/ Factories/ Cottage Industries/substation visits etc., and submission of the report.

3.5 Documents to be submitted by Students for Internship Evaluation

3.5.1 Student's Diary

The main purpose of writing a daily diary is to cultivate the habit of documenting and to encourage the students to search for details. It develops the student's thought process and reasoning abilities. The students shall record in the daily training diary the day-to-day account of the observations, impressions, information gathered, suggestions given, if any, and activities carried out. It should contain sketches and drawings related to the observations made by the students. The daily training diary should be signed after every day or at least twice a week by the faculty/ in charge of the section (external expert) where the student has been working.





Student's Diary should be submitted by the students along with attendance records. It shall be evaluated based on the following criteria:

- i) Regularity in the maintenance of the diary.
- ii) Adequacy and quality of information recorded.
- iii) Drawings, sketches, and data were recorded.
- iv) Thought processes and recording techniques were used.
- v) Organization of the information

3.5.2 Internship report

After completion of the Internship, the student shall prepare, with a daily diary as a reference, a comprehensive report in consultation with the mentor/s to indicate what he/she has observed and learned in the training period along with the internship outcomes. The training report should be signed by the mentor. The Internship report shall be evaluated based on the following criteria and/or other relevant criteria about the activity completed.

- i) Originality.
- ii) Adequacy and purposeful write-up.
- iii) Organization, format, drawings, sketches, style, language, etc.
- iv) Practical applications, relationships with basic theory, and concepts taught in the appropriate course.
- v) Variety and relevance of learning experience.

Procedure for the Evaluation of Internship-I

- a) Students should submit the reports immediately on completion of the Internship to the respective mentors
- b) The Examination of the internship will be carried out by the mentor
- c) The Internship-I shall be slated for 100 marks CIE only and will not have SEE.
- d) Internship-I marks are based on CIE marks (25 marks for the first presentation, 25 marks for the second presentation, and 50 marks for the report and final presentation).
- e) A Viva-Voce examination conducted during the I/II/III Semesters (Presentation followed by question-answer session) and the prescribed credit shall be included in the IV semester grade card.

3.5.3 Assessment Rubrics for evaluation of Internship-I (Intra and Inter-Institutional Activities)

S	Table – B2 Internship-I Assessment RubricsScheduled during the first year (Prescribed Period 02 weeks and Prescribed credits:02)						
SI No	Sub Activity Head	Performance/ Appraisal	Assessment Rubrics (Allotted marks decide the letter	Proposed Document as Evidence	Evaluated by		
1	Inter/ Intra	Excellent	80 to 100				
	Institutional Workshop/Training.	Good	60 to 79	(i) Student's Diary and			
	workshop/ framing.	Satisfactory	40 to 59	(ii) Internship			
		Unsatisfactory and fail	< 39	- Report along			
2	Working for	Excellent	80 to 100		Institute		





	consultancy/	Good	60 to 79	with the	Faculty
	Research project.	Satisfactory	40 to 59	certificate	(mentor)
		Unsatisfactory and fail	< 39	issued from	together
3	Festival (Technical /	Excellent	80 to 100	the relevant	with
	Business / Others)	Good	60 to 79	authorized	External
	Events.	Satisfactory	40 to 59	Authority	Expert, if
		Unsatisfactory and fail	< 39	-	any.
4	Contribution in	Excellent	80 to 100]	-
	Incubation/	Good	60 to 79		
	Innovation/	Satisfactory	40 to 59	-	
		Unsatisfactory and fail	< 39		
	Entrepreneurship				
	Cell.				
5	Learning at	Excellent	80 to 100]	
	Departmental	Good	60 to 79		
		Satisfactory	40 to 59		
	Lab/Tinkering		•	-	
	Lab/Institutional	Unsatisfactory and fail	< 39		
	workshop.				
6	Other than the	Excellent	80 to 100		
	above five	Good	60 to 79		
		Satisfactory	40 to 59		
	activities	Unsatisfactory and fail	< 39		
Note stude		shall be the sum of mark	ts allotted to co	ompleted activit	ies by the

3.6 Internship-II: (Societal internship and Research/Industry Internship) (08 weeks) [Scheduled during the intervening period of IV & V semester and VI & VII semester]

During the intervening period of the IV & V semesters and VI & VII semesters, students shall be ready for industrial experience. Therefore, they shall choose to undergo an Internship involving Innovation / Entrepreneurship/short-term (about 2 weeks) societal-related activities. Students may choose to work on innovation or entrepreneurial activities, or both resulting in start-up or undergo internship with industry/NGO/ Government organizations/ Micro/ Small/ Medium enterprises to make themselves ready for the industry.

3.6.1 Innovation

Innovation refers to a new or improved product or process or a combination thereof that differs marginally or significantly from the unit's previous product. An innovation center is a place where students are encouraged to implement the innovative ideas formed through imagination, brainstorming sessions, design thinking, and associated activities to bring them to reality. It is a place, where creative minds are shaped.

3.6.2 Entrepreneurship

Entrepreneurship refers to setting up a new business or business and taking on financial risks in the hope of profit. It involves investment to undertake production along with arranging inputs like land, labour, material, and capital, introducing new techniques and products, identifying new sources for the enterprise, etc.

3.6.3 Incubation Center



An organized unit designed for innovation as well as to accelerate the growth and success of new entrepreneurial companies through mentorship and an array of business support resources and services that could include physical space, capital, coaching, common services, and networking connections.

3.6.4 Startup

An entity that develops a business model based on either product innovation or service innovation and makes it scalable, replicable, and self-reliant.

An entity shall be considered a Startup

- i) Up to ten years from the date of incorporation/registration, if it is incorporated as a private limited company (as defined in the Companies Act, 2013) or registered as a partnership firm (registered under section 59 of the Partnership Act, 1932) or a limited liability partnership (under the Limited Liability Partnership Act, 2008) in India.
- ii) Turnover of the entity for any of the financial years since incorporation/ registration has not exceeded one hundred crore rupees.
- iii) The entity is working towards innovation, development, or improvement of products or processes, or services, or if it is a scalable business model with a high potential for employment generation or wealth creation.
- iv) Provided that an entity formed by splitting up or reconstruction of an existing business shall not be considered a Startup.

3.6.5 Societal (Social) related activities

Short-term internships (about 2 weeks) in villages, slums, or urban areas can be under social internship. The internship will be more fruitful if students work in teams. The teams can select one or more fields to do their best in the field of agriculture, watershed management, wastelands development, non-conventional energy, low-cost housing, sanitation, nutrition and personal hygiene, schemes for skill development, income generation, blood bank, government schemes such as

- i) (Swachch Bharat: Swachh Bharat Mission, Swachh Bharat Abhiyan, or Clean India Mission is a country-wide campaign to eliminate open defecation and improve solid waste management.
- ii) Accessible India: Accessible India Campaign or Sugamya Bharat Abhiyan is a program to serve the differently able community of the country.
- iii) Digital India: A campaign to ensure the Government's services are made available to citizens electronically by improved online infrastructure and by increasing Internet connectivity or making the country digitally empowered in the field of technology.
- iv) Beti Bachao and Beti Padhao: A campaign of the Government of India that aims to generate awareness and improve the efficiency of welfare services intended for girls in India.
- v) Environment and Energy Conservation and Education, legal aid, consumer protection, and allied field including Indian Red Cross Society, National Cadet Corps, Bharat Scouts, and Guides.

Societal activities are one of the NBA graduate attributes that are part of PO6 and PO7, which are reproduced below.

vi) PO-6: The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal, and cultural issues and the consequent responsibilities relevant to the professional engineering practice.



vii) PO-7: Environment and Sustainability: Understand the impact of the professional engineering solution in societal and environmental contexts and demonstrate the knowledge of and need for sustainable development. The long-term goal under Societal (social work) related activities, particularly in a rural area, results in a rural internship. In urban areas, the student may adopt slum/ economically weaker section areas for short duration social internship to uplift the living conditions.

Given the above, internship coordinators should encourage students to take up a societal internship as far as possible.

3.6.6 Places for Innovation/Entrepreneurial Activities

Students shall carry out Innovation or Entrepreneurial activities or both at the Incubation Center and Entrepreneurship Cell of the parent institution or elsewhere such as ATAL Incubation Centers [A flagship of Atal Innovation Mission (AIM), NITI Aayog for promoting the culture of innovation and entrepreneurship in India], institutes of national importance, public sector units, IT companies, government organizations, and non-governmental organizations, industries including MSME, etc.

• Institutes should deter students to opt for internships at places established for commercial benefits.

3.6.7 Industrial Internships

The gap between the theoretical knowledge obtained in the classrooms and the practical skills required in the actual workplace scenarios is fast growing. This has put forth varied challenges to graduating students when it comes to job placements. As institutes cannot have a relevant facility to expose students to a real-time industrial environment, an industrial internship is an appropriate solution.

The main objective of the industry internship is to ensure that the intern is exposed to a real job world environment and gains practical experience. Often, it may be a practical exposure to the theory that has been learned during the academic period. The industry internship helps students understand analytical concepts and tools, hone their skills in real-life situations, and build confidence in applying the skills learned.

3.6.7.1 Industry Internship Benefits

- i) Have ample opportunities to attend seminars, symposiums, workshops, etc. This in turn provides an opportunity to establish rapports with professionals and pioneers in their respective fields for further growth.
- ii) Have wide scope to publish paper/s in journals.
- iii) Good recommendation letter/s that increase the prospectus for further internships, higher studies, and placements.
- iv) Helps to acquire team spirit, motivated acts, techniques to resolve conflicts, etc.
- v) Helps to develop a lot of leadership skills.
- vi) Increases the prospect of placement in the same concern, provided the intern has exhibited a clear understanding of basics and completed the internship.
- vii) Fosters to substantiate the issues with facts and figures.
 For AICTE Internship opportunities refer to <u>https://internship.aicte-india.org/</u>
- **3.6.8** Assessment Rubrics for Innovation / entrepreneurship/ Societal Internship Activities Once the internship begins, the students are required to maintain a diary/journal and submit a report regularly to the guide. These reports should summarize the activities in which the

student was involved during the previous week's period. At the end of the internship, each student is required to submit a hard copy of the consolidated diary/journal and report for evaluation. The report should indicate the learning and achievements of the internship.

Table – B3 Innovation/entrepreneurship/ Societal Internship Activities and Assessment Rubrics Scheduled during the intervening period of IV & V semester and VI & VII Sem (Prescribed Period 08 weeks: Credits 08)							
Sub Activity Head	Appiaisai	Assessment Rubrics	Proposed Document as Evidence	Evaluate d by			
(1) Development of new product/	Excellent Good Satisfactory	80 to 100 60 to 79 40 to 59	(i) Student's Diary and (ii)				
Business Plan/ registration of start- up/societal internship	Unsatisfactory and fail	< 39	from relevant Authorized	(i)Institute Faculty (mentor)			
(2) Internship with	Excellent	80 to 100	Authority. Wherever only	together with			
Industry/ Govt. /	Good Satisfactory	60 to 79 40 to 59	Certificate is issued, Assessment shall be at the	External			
NGO/ PSU/ Any Micro/ Small/Medium Enterprise.	Unsatisfactory and fail	< 39	Assessment shall be at the institute as per (i) and (ii) to decide the letter grade.	Expert if any.			
Note: (i) The total CIE mark the student.	s shall be the sum of	f marks allotte	d to successfully completed	activities by			

3.7 Research Internships / Extended Industry Internships

- 3.7.1 Research Internship /Extended Industry Internship of sufficient duration encourages students early on in their careers. Its main goal is to allow improving their analytical and technical skills in an international environment. An internship can be in an industry or at an appropriate workplace.
- 3.7.2 Research internships and industrial internships have different purposes and come with a set of benefits. A prior experience in any field is always preferred over a fresh start. Therefore, one of them can be selected depending on the interest the students have. Internships pose unexpected challenges and make students think appropriately, tackle difficulties with ease, and act in a scholarly way to get past the hurdles and practical constraints. An internship is always beneficial however good or bad it is.
- 3.7.3 Internships not only enhance one's learning but also identifies him/her as someone who commits to approaching a project and completing it with or without guidance. Internship learning is an impetus for professional development.
- 3.7.4 While a research internship is a stepping stone to higher studies, an industry internship is a pathway to a placement. Those who are self-motivated and interested in searching for new things that are original and unique can choose a research internship. Those who are interested in real industry- experience and aspire to get a job soon after graduation can choose an industry internship.



- 3.7.5 Research Internships (Also known as dissertation internships) are focused research projects that push students' intellectual abilities beyond those driven by the classroom. Often, a research internship typically helps solve problems that are usually part of major research projects. It involves a short theoretical or experimental research project supervised by a researcher.
- 3.7.6 The research internships, under the advice of a faculty supervisor, can be one's own selected project or a project on which a Researcher is researching, or a new project/real-world project offered by an organization. The research area may be about single or multidisciplinary fields such as science, technology, engineering, mathematics, management, and business studies. Research internships can be carried out either individually or in teams (not exceeding 3 or 4 students).
- 3.7.7 Research internship opportunities, before graduation, maybe in a laboratory of college, a research institute, or a company's R & D department. Apart from fixed working hours of the day of an organization, the researcher can devote sufficient time to other research-related activities for early and successful completion of the Research Internship.

3.7.8 Necessary Skills for Research Internship and Industrial Internship

- For the internships to progress without hurdles and for successful completion, the Researchers should maintain a harmonious relationship with the guide/s, administrators, co-workers, and others, and strictly adhere to the rules and regulations of the workplace. The other skills required or acquirable during the Internship are,
 - 1. Good Communication skills.
 - 2. Attention to detail.
 - 3. Planning and scheduling.
 - 4. Documentation.
 - 5. Critical thinking.
 - 6. Data collection.
 - 7. Data analysis.
 - 8. Ability to maintain quality, safety, and/or infection control standards.
 - 9. Appreciating and practicing ethical issues.

3.7.9 Responsibilities of an Intern

Interns,

- 1. If working with a researcher, shall assist the researcher in an ongoing research project or work collaboratively in designing a new project of mutual interest.
- 2. Shall engage in literature survey and get an insight of the research work at the initial stages.
- 3. Shall compile data, sort, file, implement ideas with minimal guidance and assist write papers.
- 4. Shall become familiar with several tools [meters (Electrical and Electronics, mechanical, computer, etc.)] used in data collection, software, graphic software, Statistical Package for the Social Sciences (SPSS) software [IBM's statistical software platform], etc.
- 5. Shall attain skills with Microsoft Word Office, Excel, PowerPoint, Outlook, etc.
- 6. Shall give a mid-term oral presentation to a committee for review and feedback.
- 7. Shall attend discussions, meetings, symposiums, classroom lectures, etc., to learn new



scientific techniques, design experiments, analyze results, and formulate different hypotheses.

- 8. Shall learn to write reports and be able to correspond independently.
- 9. Shall manage time effectively.
- 10. Shall keep a track of the progress of the project.
- 11. Shall develop integrative thinking.

3.7.10 Research internship Outcomes

- 1. Generating technical paper/s and publishing in refereed journal/s.
- 2. Possibility of acquiring intellectual ownership and patent.
- 3. Build a prototype for an idea on which the research was carried out.
- 4. File patent/s.
- 5. Add academic knowledge to the field.
- 6. Enhanced ability in arranging meetings, presentations, seminars, training, etc.
- 7. Improved conscientiousness and ethics.

3.7.11 Research internships Benefits

- 1. Are a great way to pursue an academic career in teaching and research, as a Research Scientist at a Research Organization, Company, Industry sector, etc.
- 2. Establish professional networks for a future career.
- 3. Pave the way to join a research team and work alongside leading experts in the field.
- 4. Introduced to new ideas through interaction with like-minded students and others.
- 5. Develop research skills and knowledge in a specific area of interest.
- 6. Provide opportunities for growth, achievement, and personal development. Offer an opportunity to publish a research paper that will boost the resume while applying for Post Graduate Studies

4. Evaluation Procedure of UC3001-1 Research Internship /Extended Industry Project/Internship/Project work (16 weeks)

- **4.1** The students pursuing the course UC3001-1 shall submit the diary recordings of day-to-day activities to the concerned guide, reporting progress achieved in the course and seeking guidance to proceed with the internship. The interns should provide all the details to the guide so that he/she can discuss with the employer to make the internship successful.
- **4.2** The intern should constantly update the guide about the progress of the internship. The guide should know the intern's internship tasks, duties, responsibilities, and potential projects. The evaluation of interns and their internship progress should be honest and constructive.
- **4.3** The hardcopy or softcopy of the diary maintained by the interns must be signed at regular intervals by the guide.
- **4.4** Regarding the intern's feedback, the guides should propose changes in internship activities so that they are helpful to the internship.
- **4.5** Illustrations, drawings, photos, forms, samples, classified materials, etc., are to be included in the report only after obtaining the consent of the concerned authorities and should indicate the source of all such material. The final report should also be submitted to the place where the internship was carried out. The report should avoid a tone that is predominantly cynical or unduly critical of the employer or of those with whom the student intern has worked. The content of the report must be based on interns' own work.





4.6 Continuous Internal Evaluation (CIE)

The guides should evaluate the interns using the following as well as any other appropriate methods;

- a) Punctuality of intern.
- b) Conduct and character.
- c) Tactfulness and politeness with colleagues and the public.
- d) Attitude regarding professionalism.
- e) Inquisitiveness and eagerness to learn.
- f) Research attitude.
- g) Problem-solving techniques.
- h) Innovation mindset.
- i) Time management and meeting deadlines.
- j) Receptiveness to feedback and critiques.
- k) Ability to work in a team as a member.
- 1) Ability to work without supervision.
- m) Supervisory skills and leadership skills.
- n) Judgment and decision-making skills.
- o) Writing skills, oral communication skills, technical communication skills, computer skills, analysis skills, and business writing skills.
- p) Appropriateness of technical skills.
- q) Familiarization with writing technical papers, standards, codes, etc.
- r) Reading Behavioural attitude.
- s) Outcomes.
- t) Successes and failures experienced

4.7 Recommendation letter

The guide must state whether the intern,

- a) Exceeded the expectations of the internship.
- b) Met the expectations of the internship.
- c) Did not meet the expectations of the internship.
- d) Did work to a satisfactory level.
- e) Did an unsatisfactory internship.

In the end, the guide should issue a recommendation letter.

4.8 Assessment of CIE marks

- 4.8.1 **Single discipline:** The CIE marks shall be awarded by a committee consisting of the Head of the concerned Department and two faculty members of the Department, one of whom shall be the Guide. The CIE marks awarded for the internship, shall be based on the evaluation of the diary, presentation skill, and viva-voce in the ratio of 50:25:25.
- 4.8.2 **Interdisciplinary:** The CIE marks awarded for the internship, shall be group-wise at the institution level with the participation of all guides of the internship. Participation of external guide/s, if any, is desirable.
- **4.8.3** The CIE marks awarded for the internship, shall be based on the evaluation of the diary, presentation skill, and viva-voce in the ratio of 50:25:25.

4.9 Assessment of SEE marks





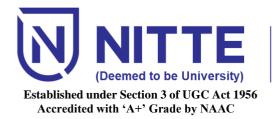
- 4.9.1 Single discipline: Contribution to the internship and the performance of each group member shall be assessed individually in the semester-end examination (SEE) conducted at the department. Marks shall be awarded based on the evaluation of the report, presentation skill, and viva-voce in the ratio of 50:25:25.
- 4.9.2 Interdisciplinary: Contribution to the internship and the performance of each group member shall be assessed individually in the semester-end examination (SEE) conducted separately at the departments to which the student/s belongs. Marks shall be awarded based on the evaluation of the report, presentation skill, and viva-voce in the ratio of 50:25:25.

4.10 Evaluation of research Internship/Extended Industry Internship/Project Work:

Split-up of marks for evaluation of Project work for 100 CIE marks and 100 SEE marks

Split up		Rubrics	Marks
		Abstract/ Synopsis Write-up	10
	Content Development	Selection of Topic/ Relevance of the subject to the concerned discipline	05
		Problem Identification	05
Report (50 Marks)		Objectives and Methodology	05
		Literature Survey (Papers/Sites/Sources Surveyed)	10
	Problem-Oriented Exposition	Documentation/ Systematic Approach	10
		Results (with inferences, Conclusions, etc.)	05
Project		Quality of preparation of presentation	05
Presentatio n Skill		Communication Skills	05
(25 Marks)		Technical knowledge and awareness	05
		Individual involvement	10
Viva- Voce		The clarity in answering questions relating to fundamentals and concepts	10
(25 Marks)		The clarity in answering the questions related to the project	05
		The understanding ability of the questions asked	05
		The confidence in answering the questions asked.	05
		Total Marks	100







B.Tech. Syllabus

Effective from Academic Year 2022 – 2023

Curriculum for Acquiring Professional Skills (CAPS)

With Scheme of Teaching & Examination



Course Numbering Scheme

Branch	Code	Course Level		Course Code	e	Separator	Version						
Letter	Letter	Number	Number	Number	Number	-	Number						
Branch Code	RI is 2 L	etter code for the l	Department	of Robotics &	zAI								
Course Level	prerequis L L L	Course Level is a 1-digit number that can have a value between 1-4 and indicates the prerequisite of a course. Level-1 courses are basic courses with no courses as pre-requisites. Level-2 course(s) have Level-1 course(s) as prerequisites. Level-3 course(s) have Level-2 course(s) as prerequisites. Level-4 course(s) have Level-3 course(s) as prerequisites.											
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B. Tech. (RI): Scheme of Teaching and Examinations 2022-26 Outcome Based Education (OBE) and Choice Based Credit System (CBCS) (Effective from the academic year 2022 - 23) GROUP - I												
			I SEMESTER (AI&DS, A	AI&ML, C	CC, CS, IS, 1	RI)						
	Teaching hours/Week Examination											
SI No.		urse and ırse code	Course Title	Teaching Department	Theory Lecture	L Tutorial	d Practical/ Drawing	Duration in hours	CIE	SEE	Total Marks	Credits
1	BSC	MA1001-1	Matrix Algebra & Calculus	MA	3	0	0	3	50	50	100	3
2	BSC	PH1001-1	Engineering Physics	PH	3	0	2	3	50	50	100	4
3	ESC	CV1001-1	Elements of Civil Engineering	CV	3	0	0	3	50	50	100	3
4	ESC	EC1001-1	Basic Electronics	EC	3	0	0	3	50	50	100	3
5	ESC	ME1001-1	Engineering Skill Development Practice	ME	0	0	2	2	50	50	100	1
6	ESC	ME1002-1	Computer Aided Engineering Graphics	ME	0	2	2	3	50	50	100	2
7	HSMC	HU1001-1	Technical English	HU	1	0	2	3	50	50	100	2
8	HSMC	HU1002-1	Constitution of India and Professional Ethics	HU	1	0	0	1	50	50	100	1
9	MNC	UM1001-1	Skill Development Lab Group- A	Any Dept.	0	0	4	0	0	0	0	0
			TOTAL		TOTAL	14	2	12	21	400	800	19



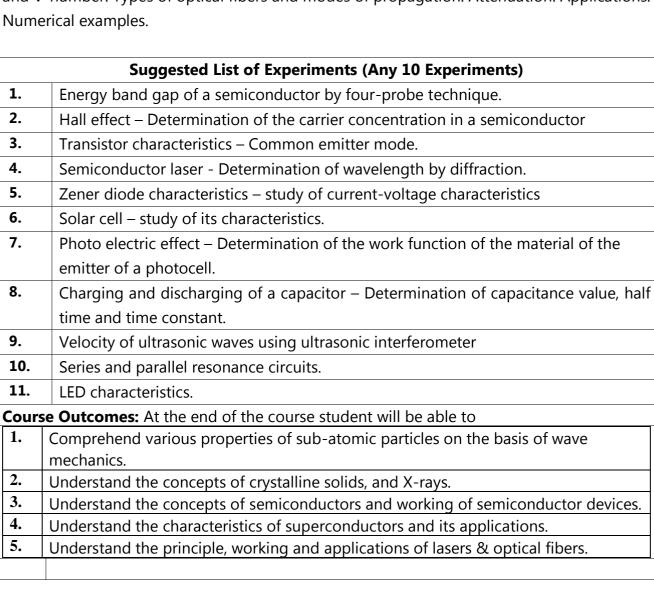
	Algebra & C		
Course Code:	MA1001-1	Course Type	BSC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	39	CIE + SEE Marks	50+50
Teaching I	Department: M	lathematics	
Course Objectives:			
1. This course will enable the studen series, elementary linear algebra, p skilled for solving problems in sci	partial differentia ence and enginee	tion, multiple integration	,
MATRICES	UNIT-I		07 Hours
	Chalon form	and rank of a matrix (
Elementary transformation of a matrix solution of system of linear equations			
by Gauss Seidel method. Eigen values			
method to find the largest eigen value	-	•	
SEQUENCES AND SERIES	es and eigen ver	ciors of square matrice	07 Hours
Convergence and divergence of infinit	to corios. Tosts f	or convergence of posi	
theorem for a function of single va functions into Taylor's and Maclaurin's		nainder (without proot	f), expansion of
DIFFERENTIAL CALCULUS			07 Hours
Polar curves, angle between the radiu curves. derivatives of arcs, radius of cu Theorem (without proof), mean value	irvature - cartes	ian, parametric and pol	ar forms. Rolle's
PARTIAL DIFFERENTIATION			07 Hours
Partial derivatives of simple functions,	total differentia	ation - differentiation o	
implicit functions, Jacobians. Taylor's minima for functions of two variables, one subsidiary condition).	theorem for fu	inctions of two variabl	es, maxima and
,	UNIT-III		
MULTIPLE INTEGRALS			11 Hours
Double integrals and triple integrals, e		0	ation, change of
Double integrals and triple integrals, e variables and applications to area	and volume. B	eta and Gamma func	ation, change of
Double integrals and triple integrals, e variables and applications to area properties.	and volume. B	eta and Gamma func	ation, change of tions and their
Double integrals and triple integrals, evariables and applications to area properties. Course Outcomes: At the end of the Solve the system of linear equa	and volume. B course student tions and find e e given functior	eta and Gamma func will be able to eigen values and eigen	ation, change of tions and their vectors of the

Independent variables, apply them to solve engineering problems and examine the given function for its extrema. 5. Apply the notion of multiple integrals to find areas and volumes. Course Outcomes Mapping with Program Outcomes & PSO Program Outcomes→ 1 2 3 4 5 6 7 8 9 10 11 12 PSO↓ ↓ Course Outcomes 1 2 3 4 5 6 7 8 9 10 11 12 9SO↓ ↓ Course Outcomes 1 2 3 4 5 6 7 8 9 10 11 12 9SO↓ ↓ Course Outcomes 1 2 2 1 1 1 2 3 MA1001-1.1 3 2 1	4.			1 -1.			1	- (- (· (] (
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Course Code: PH1001-1 Course Type: IPCC Teaching Hours/Week (L: T: P: S): 30:2:0 Credits: 04 Total Teaching Hours: 39+0+26 CIE + SEE Marks: 50+50 Teaching Department: Physics Course Objectives: 1. To introduce the concepts of wave mechanics to study the properties of sub-atomic particles. 2. To explain the concepts of semiconductors and their applications. 3. To explain the properties of superconductors and their applications. 5. To explain the properties of superconductors and their applications. Introduction to wave mechanics. Matter waves – de Broglie's relation, characteristics of matter waves. Wave function, properties and physical significance of a wave function, probability density and normalization of wave function, Schrödinger wave equation (time dependent). Application of Schrödinger wave equation –particle in a potential well of infinite depth, Eigen functions, probability densities and energy Eigen values for a particle in an infinite potential well. Numerical examples. Crystallography & X-rays 07 Hours Crystallography & X-rays 0. 7 Hours Crystallography & X-rays 0. 7 Hours Crys		LINGIN										
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Semiconductor devices: light emitting diode, photodiode, and solar cell.												
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ENGINEERING PHYSICS





Optical fibers

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semiconductor laser. Applications.

Optical fibers: Introduction to optical fibers. Propagation mechanism in optical fibers - angle of acceptance, acceptance cone and numerical aperture – derivation. Fractional index change and V-number. Types of optical fibers and modes of propagation. Attenuation. Applications.

Lasers: Introduction to lasers. Absorption and emission of radiation, Einstein's coefficients. Condition for laser action, population inversion and metastable states. Requisites of a laser system – active medium, pumping mechanism and optical resonant cavity. Three level and four level lasers. Principle, construction and working of Nd:YAG laser, He-Ne laser and

Introduction to superconductors, characteristic properties. Type-I and Type-II superconductors. BCS theory (qualitative). Applications of superconductors. Numerical examples.

UNIT-III

Superconductors

Lasers

04 Hours

05 Hours

04 Hours

F	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	PSO	\checkmark
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	RENCE BOOKS:	•		•	-			-				011				
1.	V. Rajendran, Engine		-	•												
2.	M. R. Srinivasan , Phy	SICS	tor I	ngi	nee	rs, ቦ	lew	Ag	e In	tern	atior	nal Pu	Jplist	ners,	Ban	galor
	2 nd Edition, 2009.															
3.	Kenneth Krane, Mod															
4.	S. O. Pillai, Solid State					-						ition	, 201	5		
5	A.Ghatak, Optics, Tat	a Mo	cGra	w F	Hill P	ub.,	5 th	edit	ion,	201	.2					
	A. J. Dekker, Electric	al E	İngi	neer	ring	Ma	teri	als,	Pre	ntic	e Ha	ll In	dia F	ub.,	New	Delh
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Cou	ırse Code:	CV1001-1	Course Type	ESC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	39	CIE + SEE Marks	50+50
	-	nartment: Civ	il Engineering	I
°0111	rse Objectives:			
<u>1.</u>	Understand the importance of	Civil Engineeri	ng and develon the an	alytical skills to
	solve coplanar concurrent force	-	ng and develop the an	
2.	Solve non – concurrent force sy		vze cylinders and string	as usina
	equilibrium conditions.		, ,	<u> </u>
3.	Identify different types of supp	orts, loadings	and analyze determina	te beams
4.	Understand static friction and a			
5.	Understand centroid and mom			
		UNIT-I		
				06 Hours
Cons Vate Ingir ntro	e and importance of different fie struction Technology, Geotechni er Resources and Irrigation Engi neering oduction to Engineering Mec acteristics of a force, Force sys	cal Engineerin ineering, Trans hanics: Basic	ig, Structural Engineer sportation Engineering idealizations -; Defir	, Environmenta
Cons Wate Ingir ntro Char Reso Conc Mom /arig Equil orce	etruction Technology, Geotechni er Resources and Irrigation Engi oduction to Engineering Mec acteristics of a force, Force sys- lution of forces, Composition of to urrent force system. ment of a force, couple, character gnon's theorem, Resultant of copla ibrium of forces - *Definition of Ec e systems. Particle equilibrium in 2	cal Engineering ineering, Trans hanics: Basic tems and clas forces - Definit eristics of coup anar - non-con quilibrant; Cone	ig, Structural Engineer sportation Engineering idealizations -; Defir sification; Principle of tion of Resultant; Resul ole, Equivalent force - icurrent force system. ditions of static equilibr	, Environmentanition of force transmissibility tant of coplana 09 Hour couple system
Cons Wate Engir Intro Char Reso Conc Conc Mom Varig Equil	struction Technology, Geotechni er Resources and Irrigation Engi poduction to Engineering Mec acteristics of a force, Force sys- lution of forces, Composition of to urrent force system. ment of a force, couple, character gnon's theorem, Resultant of copla ibrium of forces - *Definition of Ec	cal Engineering ineering, Trans hanics: Basic tems and clas forces - Definit eristics of coup anar - non-con quilibrant; Cone	ig, Structural Engineer sportation Engineering idealizations -; Defir sification; Principle of tion of Resultant; Resul ole, Equivalent force - icurrent force system. ditions of static equilibr	, Environmentanition of force transmissibility tant of coplana 09 Hours couple system
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Cons Wate Engir Intro Char Reso Conc Conc Varig Equil force of co	etruction Technology, Geotechni er Resources and Irrigation Engineering oduction to Engineering Mec acteristics of a force, Force sys- lution of forces, Composition of to urrent force system. nent of a force, couple, character gnon's theorem, Resultant of copla ibrium of forces - *Definition of Ec e systems. Particle equilibrium in 2 oplanar concurrent force system.	cal Engineerin ineering, Trans hanics: Basic tems and clas forces - Definit eristics of coup anar - non-con quilibrant; Con 2-D & 3-D, Cor UNIT-II types of load rt reactions for	ig, Structural Engineer sportation Engineering idealizations -; Defir sification; Principle of tion of Resultant; Resul ole, Equivalent force - icurrent force system. ditions of static equilibr neept of free body diago	, Environmentanition of force transmissibility tant of coplana 09 Hours couple system ium for differen ram, Equilibrium 07 Hours ally determinate eams with poin ds and moment
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Moment of inertia of an area, polar moment of inertia, Radius of gyration, Perpendicular axis



05 Hours

	BAS	IC ELECTRON		
Cou	irse Code:	EC1001-1	Course Type:	ESC
Теа	ching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03
Tota	al Teaching Hours:	39+0+0+0	CIE + SEE Marks:	50+50
	Teaching Department: Ele	ectronics & Con	nmunication Engineering	J
Cour	se Objectives:			
1.	To familiarize the student with	Semiconductor	devices like Diodes, Trans	sistors and
	their applications			
2.	To analyze the working of simp	ole electronic ci	rcuits involving Op-amps,	555 Timer
2	and Linear Regulator ICs.	c of Modorn cor	munication system	
3. 4.	To understand the fundamental To introduce the fundamentals			
4. 5.	To familiarize the student with	3		sistors and
5.	their applications	Semiconductor	devices like blodes, frans	
<u> </u>		UNIT-I		
Diod	es and their Applications			06 Hour
Semi	conductor Diode, Diode Equivaler	nt circuits, Load	Line analysis, Half Wave R	ectifier, Fu
	Bridge Rectifier, capacitor and o		uit (only qualitative appro	ach). Zene
Diod	a and its use in Valtage Degulatio			
Diou	e and its use in Voltage Regulatio	n		
Tran	sistors and their Applications			09 Hour
Tran Bipo	sistors and their Applications lar Junction Transistor: Constru	ction and opera		d Commo
Tran Bipo Base	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a	ction and opera nalysis, RC cou	upled amplifier (frequenc	d Commo
Tran Bipo Base exclu	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to	ction and opera nalysis, RC cou o switch ON/OF	upled amplifier (frequenc F an LED	d Commo y respons
Tran Bipo Base exclu Field	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction	ction and opera nalysis, RC cou o switch ON/OF and Characteri	upled amplifier (frequenc F an LED stics of JFET, Transfer Cha	d Commo y respons
Tran Bipo Base exclu Field	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to	ction and opera nalysis, RC cou o switch ON/OF and Characteri DSFETs, CMOS Ir	upled amplifier (frequenc F an LED stics of JFET, Transfer Cha	d Commo y respons
Tran Bipo Base exclu Field Deple	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction etion and Enhancement mode MC	ction and opera nalysis, RC cou o switch ON/OF and Characteri	upled amplifier (frequenc F an LED stics of JFET, Transfer Cha	d Commo y respons aracteristic
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Tran Bipo Base exclu Field Deple Op- <i>I</i> Intro	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction etion and Enhancement mode MC Amp & Linear IC Applications duction, Op-Amp Specifications,	ction and opera nalysis, RC cou o switch ON/OF and Characteri DSFETs, CMOS Ir UNIT-II Differential &	upled amplifier (frequenc F an LED stics of JFET, Transfer Cha nverter. Common-Mode operatio	d Commo y respons aracteristic 11 Hour n, Op-Am
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Tran Bipo Base exclu Field Deplo Op- <i>I</i> Intro appli Com Feed Conc Oscil Fund Mode	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction etion and Enhancement mode MC Amp & Linear IC Applications duction, Op-Amp Specifications, cations: Inverting/Non-Inverting parator. 555 Timer IC in Astable m back and Oscillator Circuits back– Principle and advantages of cept of positive feedback, Op-Am lator	ction and opera nalysis, RC cou o switch ON/OF and Characteri OSFETs, CMOS Ir UNIT-II Differential & Amplifier, S node. 78XX serie negative feedb p Oscillators – UNIT-III d Embedded S heme (Block s	upled amplifier (frequence F an LED stics of JFET, Transfer Chanverter. Common-Mode operatio umming, Integrator, Dires IC Voltage Regulators. ack, Voltage series feedbace RC phase shift, Hartley an scheme), Information sou	d Commo y respons aracteristic 11 Hour n, Op-Am fferentiato 05 Hour ck amplifie d Colpitts 08 Hour urce, Inpu
Tran Bipo Base exclu Field Deplo Op- <i>I</i> Intro appli Com Feed Conc Oscil Fund Mode	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction etion and Enhancement mode MC Amp & Linear IC Applications duction, Op-Amp Specifications, cations: Inverting/Non-Inverting parator. 555 Timer IC in Astable m back and Oscillator Circuits back– Principle and advantages of cept of positive feedback, Op-Am lator	ction and opera nalysis, RC cou o switch ON/OF and Characteri OSFETs, CMOS Ir UNIT-II Differential & Amplifier, S node. 78XX serie negative feedb p Oscillators – UNIT-III d Embedded S heme (Block s	upled amplifier (frequence F an LED stics of JFET, Transfer Chanverter. Common-Mode operatio umming, Integrator, Dires IC Voltage Regulators. ack, Voltage series feedbace RC phase shift, Hartley an scheme), Information sou	d Commo y respons aracteristic 11 Hour n, Op-Am fferentiato 05 Hour ck amplifie d Colpitts 08 Hour urce, Inpu
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Tran Bipo Base exclu Field Deplo Op- <i>I</i> Intro appli Com Feed Conc Oscil Feed Conc Oscil Mode Trans comr Embe Class syste	sistors and their Applications lar Junction Transistor: Constru Characteristics, DC load line a ided), BJT as a switch, BJT circuit to Effect Transistor: Construction etion and Enhancement mode MC Amp & Linear IC Applications duction, Op-Amp Specifications, cations: Inverting/Non-Inverting parator. 555 Timer IC in Astable m back and Oscillator Circuits back– Principle and advantages of tept of positive feedback, Op-Am lator lamentals of Communication an ern communication system scl sducers, Transmitter, Channels munication. edded system definition, Embo	ction and opera nalysis, RC cou o switch ON/OF and Characteri OSFETs, CMOS Ir UNIT-II Differential & Margative feedb p Oscillators – UNIT-III d Embedded S heme (Block s s, Receivers, edded System Elements of Em htroller, RISC v/	upled amplifier (frequence F an LED stics of JFET, Transfer Chanverter. Common-Mode operatio umming, Integrator, Dires IC Voltage Regulators. ack, Voltage series feedbace RC phase shift, Hartley an ystems scheme), Information sour Noise, Fundamentals of V/s General Computing bedded systems, Core of	d Commo y respons aracteristic 11 Hour n, Op-Am fferentiato 05 Hour ck amplifie d Colpitts 08 Hour urce, Inpu of Cellula g Systems Embedde



L.	Explain the operation of Red	tifiers	s; De	esigr	nar	ecti	fier	circ	uit,	give	en th	e spo	ecific	ation
	for output Voltage, PIV, and	rippl	e fa	ctor;	De	sign	a Z	Zene	r vc	ltag	ge re	gula	tor fo	or the
	given specification of output	t volt	age	and	Ρον	ver;								
2.	Explain the construction and	d ope	ratic	on of	f Bip	ola	r tra	nsis	tor	in C	E or	CB N	Mode	;
	Explain the use of BJT in Am	-							-	•			-	
	construction and operation	of JFE	Τo	r MC	DSF	et; e	xpl	ain t	he	ope	ratio	n of	a CN	10S
	Inverter;													
3.	List the ideal and practical p					•		•			•	•		
	Specifications; Explain the u		•				-					-	-	
	Differentiation and compari			-		stab	Ie N	/lulti	VID	rato	r, us	ing 5	55 H	mer
A	IC, for the given frequency a									<u>а Г</u> .		م طلع م	:	at of
4.	List the advantages and disa										•		•	
	negative feedback on Ampl Voltage Negative feedback;	-		-										
	Hartley, and Colpitts Oscilla				per			Οþ	-A11	ip c	asec	INC	rnas	e-sinit
5.	Explain the scheme of a Mo		Com	mu	nica	tion	SV	sterr	n: Li	st tk	ne di	ffere	nces	
-•	between a general computi						-							
	differences between Harvar							-						ectures
our	rse Outcomes Mapping with	Prog	ram	n Ou	itco	mes	s &	PSC)					
	Program Outcomes-	→ 1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
	EC1001-1.1	3												
	EC1001-1.2	3												
	EC1001-1.3	3												
	EC1001-1.4	3												
	EC1001-1.5	3												
	1: Low 2: Medium 3: Hig	Jh												
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EXT			1 - 1	// = 1		nic	De	vice	s ar	nd C	ircui	t The	eory",	11 th
EX1	Robert L. Boylestad, Louis N Edition, PHI, 2016	lashe	ISKY	, "Ele	ectro	JIIC								
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Cou	rse Code:	ME1001-1	Course Type	ESC
Теа	ching Hours/Week (L: T: P: S)	0:0:2:0	Credits	01
Tota	al Teaching Hours	26	CIE + SEE Marks	50+50
	Teaching Depart	tment: Mechai	nical Engineering	
Cour	se Objectives:			
	ents belonging to all branches o			
-	s related to mechanical engineeri		will have a minimum u	Inderstanding c
	anical systems, equipment and p			
1.	Prepare fitting models by using	•	. .	according to
	the given dimensions using diff			_
2.	Prepare sheet metal models usi			rocess. Prepare
2	carpentry joints using importan			
3.	Calculate velocity ratio in a V be			mple machine
	parts such as machine vice and			
Cittin	g Shop	UNIT-I		09 Hours
	and use of engineering steel i	rule height ga	uge caliper micromet	
				σε τίμος εριςδιά
-		ale, neight ga	uge, canper, micromet	ter, files, chisels
hacks	saw, hammers, drill bit, taps etc.			
hacks		by making use		
hacks Mode	aw, hammers, drill bit, taps etc. els: Preparation of fitting models	by making use UNIT-II		nipping.
hacks Mode Carpe	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde	by making use UNIT-II ring	of filing, sawing and ch	nipping. 09 Hours
hacks Mode Carpe Study	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde of the use of carpentry sheet meta	by making use UNIT-II ring I work and sold	of filing, sawing and ch lering tools. Study the	nipping. 09 Hours
hacks Mode Carpe Study surfac	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde	by making use UNIT-II ring I work and solc linder and cone	of filing, sawing and ch lering tools. Study the e.	nipping. 09 Hour s development o
hacks Mode Carpe Study surfac Mode	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde of the use of carpentry sheet meta ces of simple solids like prism, cy	by making use UNIT-II ring I work and solc linder and cone	of filing, sawing and ch lering tools. Study the e.	nipping. 09 Hour s development o
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hacks Mode Study Surfac Mode and c Activ 1. Ca	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde withe use of carpentry sheet meta ces of simple solids like prism, cyl els: Preparation of a carpentry an cylinder. e learning lculation of speed/ velocity ration	by making use UNIT-II ring I work and solc linder and cone d two sheet me UNIT-III	of filing, sawing and ch lering tools. Study the e. etal models (square/ re a drilling machine	nipping. 09 Hours development o ectangular prisn 08 Hours
hacks Mode Study surfac Mode and c Activ 1. Ca 2. As	aw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde withe use of carpentry sheet meta ces of simple solids like prism, cyl els: Preparation of a carpentry an cylinder. elearning lculation of speed/ velocity ration sembly/ Disassembly of a machir	by making use UNIT-II ring I work and sold linder and cone d two sheet me UNIT-III n of a V belt of he part such as	of filing, sawing and ch lering tools. Study the e. etal models (square/ re a drilling machine machine vice and tailst	oripping. 09 Hour s development of ectangular prism 08 Hour s tock of a lathe.
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hacks Mode Study surfac Mode and c Activ 1. Ca 2. As 3. Fa too	saw, hammers, drill bit, taps etc. els: Preparation of fitting models entry, Sheetmetal Work and Solde withe use of carpentry sheet meta ces of simple solids like prism, cyl els: Preparation of a carpentry an eylinder. e learning lculation of speed/ velocity ration sembly/ Disassembly of a machin brication/ Assembly of Automat ols such as magnetic drill/ power se Outcomes: At the end of the of Prepare fitting models by using the given dimensions. Draw the development and pre frustum of a cone using the req joints using carpentry tools. Cal and actual velocity ratios in a V	by making use UNIT-II ring I work and sold inder and cone d two sheet me UNIT-III n of a V belt of he part such as ic Linear actua tool kit) course student required tools pare sheet met uired tools and culate the perc belt drive. Asse	of filing, sawing and ch lering tools. Study the e. etal models (square/ re machine vice and tailst ator (Fabrication of ho will be able to and fitting operations al models of prisms, cy soldering process. Pre entage error between te mble and disassemble	09 Hours development o ectangular prism 08 Hours tock of a lathe. les using Powe according to linder and epare carpentry the theoretical simple
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	ME1001-1.2	3	1	-	-	-	-	-	2	3	2	-	-	-	-	-
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1.	K.R.Gopalkrishna, "A te	ext E	300	k of	Elei	nen	ts o	of N	lecł	nani	cal E	Ingir	neeri	ng″	Sub	has
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Coι	urse Code:	ME1002-1	Course Type	ESC
	ching Hours/Week (L: T: P: S)	1:0:2:0	Credits	02
	al Teaching Hours	60	CIE + SEE Marks	50+50
C		tment: Mecha	nical Engineering	
<u>Lou</u> 1.	rse Objectives:	tonding of the	the own of projection on	
1.	To impart and inculcate underst	-		•
	dimensioning, conventions and of projection system.	projection of p		ent quadrants
2.	To know and understand the pr	ojection of diff	erent plane surfaces	
3.	To impart the knowledge on un	•		solid objects
	in different positions.	derstanding af		solid objects
4.	To develop the lateral surfaces	of solid objects	and its use in sheet me	etal
	development			
		UNIT-I		
Orth	ographic Projection			10 Hours
Orth	ographic Projection: Planes of	Projection, Fi	irst angle projection,	reference line
	ventions employed for drawing, F	•	• • •	
	th quadrants, Projection of Lines (F	•		
true	and apparent inclinations.		-	
		UNIT-II		
Proj	ection of Plane surfaces	UNIT-II		12 Hours
	ection of Plane surfaces ection of plane surface: Triangle,		ngle, Pentagon, Hexago	
Proje			ngle, Pentagon, Hexago	
Proje diffe	ection of plane surface: Triangle, rent positions.		ngle, Pentagon, Hexago	
Proje diffe Proj	ection of plane surface: Triangle, rent positions. ection of Solids	Square, Rectar UNIT-III		on and Circle in 16 Hours
Proje diffe Proj	ection of plane surface: Triangle, rent positions.	Square, Rectar UNIT-III Is, Pyramids, Co		on and Circle in 16 Hours
Proje diffe Proj Proje	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV		on and Circle in 16 Hours ferent positions
Proje diffe Proj Proje	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of a	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids	nes and Cylinders in dif	on and Circle in 16 Hours ferent positions 12 Hours
Proje diffe Proje Proje Deve	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of a	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids	nes and Cylinders in dif	on and Circle in 16 Hours ferent positions 12 Hours
Proje diffe Proje Proje Deve their	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids ght regular Pris	nes and Cylinders in dif	on and Circle in 16 Hours ferent positions 12 Hours s and cones and
Proje diffe Proje Proje Deve their	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig frustums. netric projection and Isometric v	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids ght regular Pris <i>v</i> iew	ones and Cylinders in dif sms, Pyramids, Cylinders	on and Circle in 16 Hours ferent positions 12 Hours s and cones and 10 Hours
Proje diffe Proje Proje Deve their Isom	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig frustums. hetric projection and Isometric v hetric scale, Difference between	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids ght regular Pris <i>v</i> iew Isometric pro	ines and Cylinders in dif ms, Pyramids, Cylinders	on and Circle in 16 Hours ferent positions 12 Hours s and cones and 10 Hours view: To draw
Proje diffe Proje Proje Deve their Isom	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig frustums. hetric projection and Isometric v netric scale, Difference between netric views of simple solids an	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids ght regular Pris <i>v</i> iew Isometric pro	ines and Cylinders in dif ms, Pyramids, Cylinders	on and Circle in 16 Hours ferent positions 12 Hours s and cones and 10 Hours view: To draw
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Proje diffe Proje Proje Deve their Isom Isom	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig frustums. hetric projection and Isometric v hetric scale, Difference between hetric views of simple solids an ections.	Square, Rectar UNIT-III Is, Pyramids, Co UNIT-IV solids ght regular Pris <i>v</i> iew Isometric pro- nd machine c	mes and Cylinders in dif ms, Pyramids, Cylinders jection and isometric omponents using the will be able to	If Hours ferent positions 12 Hours and cones and 10 Hours view: To draw ir orthographic
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Proje diffe Proje Proje Deve their Isom Isom Isom Isom Isom Isom	ection of plane surface: Triangle, rent positions. ection of Solids ection of right regular solids: Prism elopment of Lateral surfaces of elopment of lateral surfaces of: Rig frustums. hetric projection and Isometric views hetric scale, Difference between hetric views of simple solids an ections. rse Outcomes: At the end of the of Identify a coordinate system in projections of a point and a line Draw the orthographic projection pentagonal, hexagonal and circ	Square, Rectar UNIT-III s, Pyramids, Co UNIT-IV solids ght regular Pris view Isometric pro- nd machine c course student which a point of sular) for a give	mes and Cylinders in dif mes and Cylinders in dif ms, Pyramids, Cylinders jection and isometric omponents using the will be able to element exists. Draw th urface (Triangular, squa	If Hours ferent positions 12 Hours and cones and 10 Hours view: To draw ir orthographic e orthographic re, rectangular,
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	ME1002-1.3	3	1	0	0	3	0	0	0	1	1	0	2	2	1	2
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2.	A Text book of Engineering						nan	& K	anna	iah I	P. Rad	iant P	Publisł	nina F	louse	
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<u>3.</u> 4.	A Primer on computer aider Engineering Drawing and C	omp	uter	Grap	hics,	Shah	, Pea	arsor	n, 20	010.				tion,	2011	
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SCHEME OF EXAMINATION

- 1. Question paper consists of 4 units with two questions in each unit.
- 2. Students are expected to answer Four full questions choosing at least ONE question from each unit.

Cou	ırse Code:	HU1001-1	Course Type	HSMC
Теа	ching Hours/Week (L: T: P: S)	1:0:2:0	Credits	01
Tot	al Teaching Hours	39	CIE + SEE Marks	50+50
	Teaching	Department: H	lumanities	
Cour	se Objectives:			
<u>1.</u>	Identify the nuances of Phoneti	cs. Intonation a	and enhance pronunciat	tion skills
2.	Understand Technical Commun			
	effective Interpersonal Commu	5		
3.	Enhance basic English gramma		of language skills	
4.	Improve sentence structure wit		2 2	
5.	Develop spoken and writing ski	I		
		UNIT-I		
				16 Hour
Phor	netics & Pronunciation			
Intro	duction to Phonetics; Word Stres	s, Rhythm and I	Intonation; Weak Forms	and
	ng Forms, Role of IPA in past ten	,		
Acce	5			
Com	munication Skills			
		ting and Introd	ucing, Making Requests	s, asking for an
Intro	munication Skills duction to Communication, Greet og Permission, Offering Help	ting and Introd	ucing, Making Requests	s, asking for an
Intro Givin	duction to Communication, Green og Permission, Offering Help	5		J
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	HU1001-1.2	2					2				3		3			
	HU1001-1.3		2					3	2		3		3			
	HU1001-1.4		2				2			2	2		2			
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1.	Subhashini, A Textbook	c of	Eng	lish	Lang	gua	ge 8	k Co	mm	nuni	catio	n Ski	ills, F	l Vic	tor	et al.
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Cοι	ırse Code:	HU1002-1	Course Type	HSMC
Теа	ching Hours/Week (L: T: P: S)	1:0:0:0	Credits	01
Tot	al Teaching Hours	13	CIE + SEE Marks	50+50
	Teaching	Department: H	lumanities	
Coui	rse Objectives:			
1.	Inculcate Social and Political co	nsciousness of	the Indian Polity.	
2.	Understand their Obligations, R			Duties and the
	Role that they have to play in d			
3.	Develop National and Patriotic		, , , , , , , , , , , , , , , , , , ,	y
4.	Understand the nature and cha		ons between union and	state
	governments.			
5.	Divulge the students about the	statutory instit	utions and policies.	
		UNIT-I		
Evol	ution of the Indian Constitution			06 Hours
1909	Act, 1919 Act, 1935 Govt of	India Act, Cor	nstituent Assembly: Co	omposition and
Func	tions, Basic structure of Indian	Constitution,	Fundamental features	of the Indiar
Cons	stitution, Salient Features of Indiar	n Constitution		
		UNIT-II		
	cture of Government			05 Hours
Unio	n Government: Legislature; Execu		Prime Minister, Council	
Unio Judio	n Government: Legislature; Execu ciary, Judicial Review and activism	tive-President,		
Unio Judio State	n Government: Legislature; Execu iary, Judicial Review and activism Government: Executive: Governo	tive-President, or, Chief Ministe	er, Council of Ministers	
Unio Judio State	n Government: Legislature; Execu ciary, Judicial Review and activism	tive-President, r, Chief Ministe tutions, Urban	er, Council of Ministers	
Unio Judio State Loca	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo l Government: Panchayat Raj Insti	tive-President, or, Chief Ministe	er, Council of Ministers	of Ministers;
Unio Judio State Loca Stat	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo l Government: Panchayat Raj Insti utory Institutions	tive-President, r, Chief Ministe tutions, Urban UNIT-III	er, Council of Ministers Governance	of Ministers; 02 Hours
Unio Judic State Loca Stat e Elect	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I	tive-President, r, Chief Ministe tutions, Urban UNIT-III	er, Council of Ministers Governance	of Ministers; 02 Hours
Unio Judio State Loca Stat e Elect	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo l Government: Panchayat Raj Insti utory Institutions	tive-President, r, Chief Ministe tutions, Urban UNIT-III	er, Council of Ministers Governance	of Ministers; 02 Hours
Unio Judic State Loca Stat Elect Com	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women.	tive-President, r, Chief Ministe tutions, Urban UNIT-III ndia, National	er, Council of Ministers Governance Human Rights Comm	of Ministers; 02 Hours
Unio Judio State Loca Statu Elect Com	n Government: Legislature; Execu ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women.	tive-President, or, Chief Ministe tutions, Urban UNIT-III ndia, National	er, Council of Ministers Governance Human Rights Comm will be able to	of Ministers; 02 Hours ission, Nationa
Unio Judic State Loca Stat Elect Com	n Government: Legislature; Execu- ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women. rse Outcomes: At the end of the o Analyze the legalities and relate	tive-President, or, Chief Ministe tutions, Urban UNIT-III ndia, National	er, Council of Ministers Governance Human Rights Comm will be able to fting, adoption, and ent	of Ministers; 02 Hours ission, Nationa
Unio Judic State Loca Stat Elect Com	n Government: Legislature; Execu- ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women. rse Outcomes: At the end of the o Analyze the legalities and relate the Indian Constitution as a fun	tive-President, or, Chief Ministe tutions, Urban UNIT-III ndia, National	er, Council of Ministers Governance Human Rights Comm will be able to fting, adoption, and ent	of Ministers; 02 Hours ission, Nationa
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Unio Judic State Loca Stat Elect Com	n Government: Legislature; Execu- ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women. rse Outcomes: At the end of the o Analyze the legalities and relate the Indian Constitution as a fun privileges of Indian Citizenship Understand and judiciously use	tive-President, or, Chief Ministe tutions, Urban UNIT-III ndia, National course student dissues of dra damental law of the fundamen	er, Council of Ministers Governance Human Rights Comm will be able to fting, adoption, and ent of the nation and the pr tal rights, fundamental	of Ministers; 02 Hours ission, Nationa forcement of ovisions and duties and
Unio Judio State Loca State Elect Com 1.	n Government: Legislature; Execu- ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women. rse Outcomes: At the end of the of Analyze the legalities and relate the Indian Constitution as a fun privileges of Indian Citizenship Understand and judiciously use privileges envisaged in the cons	tive-President, or, Chief Minister tutions, Urban UNIT-III ndia, National course student ed issues of dra damental law of the fundament	er, Council of Ministers Governance Human Rights Comm will be able to fting, adoption, and ent of the nation and the pr tal rights, fundamental gating social harmony a	of Ministers; 02 Hours ission, Nationa forcement of ovisions and duties and
Unio Judio State Loca State Elect Com 1. 2.	n Government: Legislature; Execu- ciary, Judicial Review and activism e Government: Executive: Governo I Government: Panchayat Raj Insti utory Institutions ions - Election Commission of I mission for Women. rse Outcomes: At the end of the of Analyze the legalities and relate the Indian Constitution as a fun privileges of Indian Citizenship Understand and judiciously use privileges envisaged in the cons and respecting the rights and li	tive-President, or, Chief Minister tutions, Urban UNIT-III ndia, National course student d issues of dra damental law of the fundament stitution propag	er, Council of Ministers Governance Human Rights Comm will be able to fting, adoption, and ent of the nation and the pr tal rights, fundamental gating social harmony a r people.	of Ministers; 02 Hours ission, Nationa forcement of ovisions and duties and ind equality
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	Program Outcomes →	1	2	3	4	5	6	7	8	9	10	11	12		PSO	\downarrow
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	HU1002-1.1								3			1	1			
	HU1002-1.2								2			1	1			
	HU1002-1.3			2				1	2			1	1			
	HU1002-1.4								1							
	HU1002-1.5			1					3			1	1			
	1: Low 2: Medium 3: H	ligh														
2. 3.	Introduction to Constit Publishing House Pvt. I Introduction to Constit	<u>.td.,</u> utio	<u>Nev</u> n of	v De Ind	elhi. ia; B	srij K	-									
	Duanting Hall of India D	. 														
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			B. Tech. (RI): Scheme of Teachir Outcome Based Education (OBE) and C (Effective from the acac GROU II SEMESTER (AI&DS, A	Choice B lemic ye P - I	ased Cree ar 2022 -	dit Syst 23)))				
				ent	Teach	ing hour	s/Week		Exam	ination		
SI No.		urse and urse code	Course Title	Teaching Department	T Lecture	L Tutorial	d Drawing	Duration in hours	CIE	SEE	Total Marks	Credits
1	BSC	MA1003-1	Differential Equations and Laplace Transforms	MA	3	0	0	3	50	50	100	3
2	BSC	CY1001-1	Engineering Chemistry	СН	3	0	2	3	50	50	100	4
3	ESC	CS1001-1	Problem-Solving through Programming	CS	3	0	2	3	50	50	100	4
4	ESC	EE1001-1	Basic Electrical Engineering	EE	3	0	2	3	50	50	100	4
5	ESC	ME1003-1	Elements of Mechanical Engineering	ME	3	0	0	3	50	50	100	3
6	AEC	BT1001-1	Biology for Engineers	BT	1	0	0	1	50	50	100	1
7	AEC	CS1002-1	IT Skills	CS	1	0	2	3	50	50	100	2
8	MNC	CV1002-1	Environmental Science	CV	1	0	0	1	50	50	100	0
9	MNC	UM1002-1	Skill Development Lab Group B	Any Dept.	0	0	4	0	0	0	0	0
			TOTAL		TOTAL	18	0	12	20	400	800	21

Mandat	tory Intern	ship-I*					
1.	INT	UC1001-1	Internship – I	Mandatory Intra Institutional Internship of duration (80 - 90 Hours) to be completed during I & II Semesters. *The grades will be included in the IV semester grade card (Refer 11.5.2 for details)	100	 100	2

	Differential Equat			
Car		O BT\CV\EC		BSC
	urse Code:	3:0:0:0	Course Type Credits	03
	ching Hours/Week (L: T: P: S)	39	CIE + SEE Marks	50+50
101	al Teaching Hours			50+50
		epartment: M	athematics	
<u>Cou</u> 1.	rse Objectives:			
1.	This course will enable the stude		•	
	differential equations, partial dif		ons and become skill	ed for solving
	problems in science and enginee	UNIT-I		
		UNIT-I		15 Hours
FIRS	T ORDER ORDINARY DIFFERENT		NS	15 110015
equa ORD Seco inver	order and higher degree) equa ations solvable for x, general and si DINARY DIFFERENTIAL EQUATION and higher order linear differe rse differential operator, method o	ingular solutior NS OF HIGHER ntial equation	ns of Clairaut's equations of Clairaut's equations of ORDER with constant coeffic	ons.
	variable coefficients- Cauchy's line lems.	ear differential		•
prob	-	•		ns to engineering
prob LAPL Defir prop Inver	lems.	ear differential UNIT-II functions, tran functions and onvolution the	equation. Application	ns to engineering 15 Hours es and integrals- ns.
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prob LAPL Defir prop Inver Appl First equa dime meth	ACE TRANSFORMS nitions, transforms of elementary perties. Periodic functions, unit step rse Transforms and properties, co	ear differential UNIT-II functions, trans functions and onvolution the UNIT-III ential equation constants/arb Solution of PDE Lagrange's Ma	equation. Application nsforms of derivative unit impulse function orem, initial & final itrary functions. D i's by direct integratio ethod. Solution of p	ns to engineering 15 Hours es and integrals- ns. value theorems 09 Hours artial differentia perivation of one on method, by the
prob LAPL Defir prop Inver Appl First equa dime meth equa	ACE TRANSFORMS nitions, transforms of elementary perties. Periodic functions, unit step rse Transforms and properties, co lications to engineering problems. TIAL DIFFERENTIAL EQUATIONS and higher order partial different ations by elimination of arbitrary ensional heat and wave equations, so hod of separation of variables, by	ear differential UNIT-II functions, trans of functions and onvolution the UNIT-III ential equation constants/arb Solution of PDE Lagrange's Ma one independe	equation. Application nsforms of derivative unit impulse function orem, initial & final itrary functions. D i's by direct integratio ethod. Solution of p ent variable.	15 Hours and integrals value theorems 09 Hours artial differentia perivation of one on method, by the
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prob LAPL Defir prop Inver Appl PAR First equa dime meth equa Cour 1. 2.	ACE TRANSFORMS nitions, transforms of elementary perties. Periodic functions, unit step rse Transforms and properties, co lications to engineering problems. TIAL DIFFERENTIAL EQUATIONS and higher order partial differential ations by elimination of arbitrary ensional heat and wave equations, so nod of separation of variables, by ations of derivatives involving only rse Outcomes: At the end of the co Solve first order ordinary differential	ear differential UNIT-II functions, tran o functions and onvolution the UNIT-III ential equation constants/arb Solution of PDE Lagrange's Ma one independent ourse student v ntial equations. equations of h	equation. Application nsforms of derivative unit impulse function orem, initial & final is. Formation of p itrary functions. D i's by direct integratio ethod. Solution of p ent variable. will be able to	15 Hours and integrals s and integrals value theorems 09 Hours artial differentia perivation of one on method, by the partial differentia

	equations with consta	nt c	oef	ficie	nts											
5.	Understand the derivati	on d	of o	ne d	lime	nsic	nal	hea	t an	d w	ave e	equa	tions	anc	solv	/e
	partial differential equa	tior	۱S.													
Cours	se Outcomes Mapping v	vith	Pro	ogra	am (Dute	:om	es 8	<u> </u>	SO			_			
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	MA1003-1.2	3	2													
	MA1003-1.3	2	2													
	MA1003-1.4	2	2													
	MA1003-1.5	3	2													
	1: Low 2: Medium 3: H	ligh														
EXT	BOOKS:															
1.	B.S. Grewal, "Higher Eng	gine	erir	ng M	1ath	ema	tics	", Kł	nanr	na P	ublic	atior	ns, 43	3 rd E	ditio	n,
	2015.															
2.		ced	Eng	inee	ering	j Ma	the	mat	ics",	Joł	n W	iley a	and S	Sons	, 10 ^{tł}	۱
	Edition (Reprint), 2016.															
	RENCE BOOKS:															
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2.	,,	Ingi	nee	ring	Ma	ther	nati	cs",	Tata	a Mo	c Gra	w –ŀ	Hill, I	New		
2	Delhi,2010.															
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1	Publications, 2010.	<u>.</u>	_ //	-1.			<u></u>			F .			-1 -2			1-1
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6.	G.F. Simmons and S.G.	Krar	ntz,	"Dif	tere	ntial	Εqι	latio	ons"	, Mo	cGrav	<i>N</i> Hil	I, 200)7.		
	oks / MOOCs/ NPTEL															
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(corrosion	-
v	ve coatings	;
а	nd Tinning	J,
	4Hour	S
v	ver-voltage	2.

	Engine	eering Chem	istry	
Cou	rse Code:	CY1001-1	Course Type:	IPCC
Теа	ching Hours/Week (L:T:P: S):	3:0:2:0	Credits:	04
Tota	al Teaching Hours:	39+0+26	CIE + SEE Marks:	50+50
	Teaching I	Department: C	hemistry	
Cour	se Objectives:			
1.	a) Know the basics of electroche	emistry and its u	isage in the working of fue	el cells and
	modern-day batteries.			
	b) Gain knowledge of the harmfu		rosion on metal and techn	iques used
	in preventing it, including metal			
2.	a) Get acquainted with the diffe		idustrially important polyr	ners along
	with their characteristic properti			
-	b) Know the requirements of bo			
3.	a) Get the knowledge on the dif		fuels and related paramet	ters.
	b) Know the basics of liquid crys		'al a sub-sa'a	
	c) Understand the different rout	es of nonmater	iai synthesis.	
4.	To provide students with practi	cal knowledge	of quantitative analysis o	f materials
	by classical methods.			
5.	Familiarize with the practica	l knowledge	of chemistry enabling	their skill
	development by instrumental m	ethods of analy	/sis.	
		UNIT-I		
	TROCHEMICAL CELLS & BATTE			08 Hours
[ntro	duction, Derivation of Nernst equ	ation for single	electrode potential. EMF	of the cell,
Num	erical problems. Construction an	d working of	calomel electrode, Measu	rement of
	- ala atua da una taustial. Taun sala atiu			

Numerical problems. Construction and working of calomel electrode, Measurement of single electrode potential. Ion-selective electrode- definition, construction, and working of the glass electrode. Determination of pH using a glass electrode. 4 Hours

Introduction to battery, battery characteristics, Classification of batteries–primary, secondary, and reserve batteries. Construction, working, and applications of Lithium-ion battery, and Flow batteries- Construction, working and applications of Vanadium flow battery. Fuel cells- Introduction, construction, working, and uses of Methanol-Oxygen fuel cells. 4 Hours

CORROSION SCIENCE & METAL FINISHING

Corrosion - definition, Electro-chemical theory of corrosion, Factors affecting the rate corrosion. Differential metal corrosion- galvanic series, Differential aeration corrosion Waterline and pitting corrosion. Stress corrosion. Corrosion Control: Protective coating Inorganic coating - Anodizing and Phosphating. Metal coating - Galvanization and Tinnin cathodic protection. 4Hou

Introduction to metal finishing, Polarization, decomposition potential, and over-voltage.



Electroplating, effect of plating variables on the nature of electrodeposit, Electroplating of Chromium, Electroless plating - advantages, Electroless plating of copper on PCB.

3Hours

UNIT-II	
POLYMERS	07 Hours
Definition, Classification, free radical mechanism of polymerization of ving	yl chloride.
Emulsion polymerization. Glass transition temperature. Structure and property re	elationship.
Synthesis, properties, and applications of PMMA, Polycarbonate	
Elastomers – Definition, Synthesis, and applications of Butyl rubber and Silicone	rubbers.
Adhesives- Synthesis and applications of Epoxy resins. Polymer Composites: In	troduction,
synthesis, properties, and applications of carbon fiber.	
Conducting polymers-definition, applications. Mechanism of conduction in poly	
WATER CHEMISTRY	06 Hours
Impurities in water, Water analysis - Determination of Hardness, determination c	
Oxygen by Winkler's method, Boiler feed water, and boiler problems – scales a	0
boiler corrosion. External treatment - hot lime soda process, Ion-exchange meth	od. Internal
treatment -phosphate conditioning, colloidal conditioning, Calgon co	onditioning.
Desalination of seawater - Electro dialysis and reverse osmosis. Sewage treatme	nt: Primary,
secondary, and tertiary treatment.	
NANOMATERIALS	02 Hours
Introduction, classification of nanomaterials. Synthesis of nanomaterials by	
combustion, chemical vapour deposition, and sol-gel methods. Appli nanomaterials.	cations of
UNIT-III	
CHEMICAL FUELS	06 Hours
Introduction, definition, classification of fuels. Calorific value-definition, Gros	s, and Net
calorific values. Determination of calorific value of a solid/liquid fuel usin	
calorimeter. Numerical problems. Petroleum cracking-fluidized bed catalyti	-
Reformation of petrol. Knocking and its harmful effects. Prevention of knock	king, power
alcohol and biodiesel.	5 1
LIQUID CRYSTALS	03 Hours
Introduction, classification- Thermotropic, and Lyotropic with examples.	Types of
mesophases - nematic, chiral nematic, smectic, and columnar. The chemical co	nstitution
of liquid crystals. Electro-optic effect of liquid crystals. Applications of liquid	
display systems.	-
Suggested List of Experiments	
1 Determination of Total Hardness of a sample of water using disodium salt	

3.	Determination of nitro hydrochloric acid soluti	-	am	nmo	nia	in e	each	ו sa	mpl	e o	f fer	tilize	r usi	ngas	standa	rd
4.	Determination of ma	nga	nese	e d	ioxi	de	in	Pyre	olus	ite	usin	g st	anda	rd po	otassiu	m
5.	permanganate solution Determination of Iron in dichromate crystals by	n th	-			•				te c	ore s	oluti	on us	ing po	otassiu	m
6.	Determination of Chem sample.									f the	e giv	en in	dustr	ial wa	stewat	er
7.	Potentiometric estimati	on	of F	AS ι	usino	g sta	and	ard	K ₂ C	r ₂ 07	solu	tion.				
8.	Colorimetric determina					, 										
9.	Conductometric estima	tion	of	an A	Acid	mix	ture	e us	ing	stan	darc	l Na	DH so	lutior	۱.	
10.	Determination of pKa o															
11.	Determination of the vis	scos	ity o	coef	ficie	nt c	of a	give	en lio	quic	l usir	ng Os	stwald	d's vise	comete	er.
12.	Flame photometric esti							-				-				
								J			-					
	rse Outcomes: At the er	nd o	f th	e cc	urse	e stu	Ider	nt w	ill b	e ak	ole to)				
1.	a) Understand the basi	ic cc	omp	one	nts	ofe	lect	rocł	nem	ical	cells	and	there	by rel	ate the	eir
	principles to modern b	oatt	erie	s an	d fu	el c	ells.									
	b) Identify the differ	ent	typ	bes	of	corr	osio	on;	tecl	nniq	lues	gen	erally	used	l for i	ts
	prevention, and unc	lers	tanc	d tl	ne	met	al	surf	ace	m	odifi	catio	n te	chniqu	ues lik	ke
	electroplating and electroplatin			•	-											
2.	a) Analyze the differer	nt ty	pes	of	ooly	mer	s, tł	neir	syn	thet	ic ro	utes,	and	applic	ations.	
	b) Understand the prin	me	proł	blen	ns fa	iced	l in	boil	er f	eed	wate	er, su	ıbseq	uent r	emedi	al
	measures undertaken			,				,								
	c) Identify the syntheti															
3.	Identify the methodol	0				-					•			nemica	al fuels.	•
	Understand the applic															
4.	Understand the diffe		-	•					c ti	trati	ions	for	the	estima	ation o	of
	composition in materi															
5.	Handling different ty	•								lysis	s of	mat	erials	usin	g sma	
	quantities involved for	r qu	ick a	and	acci	urat	e re	sult	S.							
Cou	rse Outcomes Mapping												40			-
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS I	501	-
	Course Outcomes CY1001-1.1	Н	L													-
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	CY1001-1.2 CY1001-1.3	H	H													-
	CY1001-1.4	M	L					1	1							1
	CY1001-1.5	Μ	L		1		1	1	1	1		1				

1: Low 2: Medium 3: High

TE	KTBOOKS:
1.	Engineering Chemistry by P.C. Jain & Monica Jain., DhanpatRai Publications, New Delhi.2015
2.	Engineering chemistry by R V Gadag & A Nityananda Shetty., IK
	International Publishing House Private Ltd. New Delhi.2016.
3.	Physical Chemistry, by P. W. Atkins, Oxford Publications (Eighthedition-2006)
RE	FERENCE BOOKS:
1.	Chemistry for Engineering Students by B.S. Jai Prakash, R.Venugopal, Sivakumaraiah
	& Pushpa Iyengar., Subhash Publications, Bangalore.2016.
2.	Principles of Physical Chemistry by B.R.Puri, L.R.Sharma& M.S. Pathania., S.Chand &
	Co. Pvt. Ltd. NewDelhi.1998.
3.	Liquid crystals and plastic crystals, Vol-I, edited by G.W.Gray and P.A.Winsor, Ellis
	Horwood Series in Physical Chemistry, New York. 2010, (p.No.106-142).
4.	Corrosion Engineering by M.G. Fontana, Mc Graw HillPublications.2006.
5.	Vogel's textbook of quantitative inorganic analysis, revised by J.Bassett, R.C. Denny, G.H. Jeffery, 4thEd.
6.	Laboratory manual in Engineering Chemistry Sudharani, Dhanpatrai Publishing Company, New Delhi.
ΕB	ooks / MOOCs/ NPTEL
1.	http://bcs.whfreeman.com/vollhardtschore5e/default.asp.
2.	https://www.ttu.ee/public/m/Mehaanikateaduskond/Instituudid/Materjaliteh
	nika_instituut/MTX9100/
	Lecture11_Synthesis.pdf.
3.	http://nptel.ac.in/courses/113108051/module1/lecture1.pdf

	Total Teaching Hours:39+0+26CIE + SEE Marks:50+50Teaching Department: Computer Science & EngineeringCourse Objectives:1.Make students learn basics of Computer System, Principles of Problem solving, and the basics of C programming language including the basic structure, data types an keywords used to design & develop programming skills.2.Outline the usage of Input Output statements, Operators and Evaluating expressions in C.3.Apply the concepts of decision making and looping in problem solving to demonstrate its usage using simple programs.4.Apply the concepts of Arrays, User-defined functions and code reusability in problem solving along with parameter passing and returning with the help of user defined functions.5.Demonstrate the usage of Strings, Structures, Pointers and File handling that are	Cοι	urse Code:	CS1001-1	Course Type:	BSC
 Teaching Department: Computer Science & Engineering Course Objectives: Make students learn basics of Computer System, Principles of Problem solving, and the basics of C programming language including the basic structure, data types an keywords used to design & develop programming skills. Outline the usage of Input Output statements, Operators and Evaluating expressions in C. Apply the concepts of decision making and looping in problem solving to demonstrate its usage using simple programs. Apply the concepts of Arrays, User-defined functions and code reusability in problem solving along with parameter passing and returning with the help of user defined functions. Demonstrate the usage of Strings, Structures, Pointers and File handling that are 	 Teaching Department: Computer Science & Engineering Course Objectives: Make students learn basics of Computer System, Principles of Problem solving, and the basics of C programming language including the basic structure, data types an keywords used to design & develop programming skills. Outline the usage of Input Output statements, Operators and Evaluating expressions in C. Apply the concepts of decision making and looping in problem solving to demonstrate its usage using simple programs. Apply the concepts of Arrays, User-defined functions and code reusability in problem solving along with parameter passing and returning with the help of user defined functions. Demonstrate the usage of Strings, Structures, Pointers and File handling that are essential for understanding the concepts with simple examples. 	Теа	aching Hours/Week (L: T: P: S):	3:0:2:0 Credit: 39+0+26 CIE + SEE Marks t: Computer Science & Engineering omputer System, Principles of Problem nguage including the basic structure, da elop programming skills. out statements, Operators and Evaluation making and looping in problem solving nple programs.		04
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Demonstrate the usage of Damigs, Datactares, Forniters and The handling that are	essential for understanding the concepts with simple examples.	4.	problem solving along with para			
	UNIT-I	5.		-		hat are

INTRODUCTION TO COMPUTER SYSTEM:

Introduction to Computer generations and types, CPU, Primary Memory, Secondary Memory, Ports and Connections.

Problem solving, Program Development steps, Introduction to Algorithms and Flowcharts.

INTRODUCTION TO C PROGRAMMING LANGUAGE:

Evolution & Characteristics of C Language, Structure of a C Program, C Compilation Model. Characters set, C tokens, Keywords and identifiers, Constants, Data Types and Variables. OPERATORS AND EXPRESSIONS:

Arithmetic operators, Relational operators, Logical operators, Assignment operators, Increment and Decrement operators, conditional operator, Bitwise operators, Special Operators.

Arithmetic expressions, Operator precedence and associativity, Type conversions in expressions, Evaluation of expressions.

MANAGING INPUT AND OUTPUT OPERATIONS:

Formatted Input and Output functions, Unformatted Input and Output functions.

UNIT-II

15 Hours

DECISION MAKING AND BRANCHING:

Decision making with if statement, Simple *if* Statement, the *if...else* statement, *Nesting of if...else* statements, The *else...if* ladder, The *switch* statement, The *goto* statement, break and continue statements.



DECISION MAKING AND LOOPING:

The *while* statement, the *do...while* statement, the *for* statement, Jumps in Loops.

ARRAYS:

Arrays (1-D, 2-D) Initialization and Declaration.

USER-DEFINED FUNCTIONS:

Need for the User-defined Functions, Element of User-defined Functions, Argument Passing – call by value, call by reference, Category of Functions.

Examples: Linear Search, Binary Search, Bubble sort, Selection Sort, Trace and Transpose, Matrix Multiplication.

UNIT-III

09 Hours

STRINGS:

Declaring and Initializing strings, String manipulation functions.

STRUCTURES:

Defining a Structure, Declaration and Accessing the Structured Variable.

POINTERS AND FILE HANDLING:

Introduction, Declaration, accessing of variables using Pointers, Basic file operations: Open, Close, Read, Write.

	Suggested List of Experiments
	Part A
1.	Write a C program to find the roots of a quadratic equation ax2+bx+c=0.
2.	Write a C program to find the sum of all the digits and occurrence of a digit in the number.
3.	Write a C program to find the GCD and LCM of given two numbers using Euclid's method.
4.	Write a C program to print the prime numbers in a given range.
5.	Write a C program to find if a given string is a palindrome or not.
6.	Write a C program to input N real numbers in 1-D array. Compute mean, variance and Standard Deviation. [Mean= sum/N, Variance = Σ (Xi-mean) 2 /N, STDDeviation= $\sqrt{variance}$.]
7.	Write a C program to read N integers into an array A and find the sum of elements using pointers.
8.	Write a C program to copy contents of one file to another file.
	Part B
9.	Write a C program to perform a binary search for a given key integer in a single dimensional array of numbers in ascending order and report success or failure in the form of a suitable message.
10.	Write a C program to input N integer numbers into a single dimension array, sort



	them in to ascending given array and the s			-								nd tł	nen t	o pri	int b	oth the
11.	Write a C program t resultant matrix.									-		and f	ind	the t	race	of the
12.	Write a C program u to compute the proc	-														
13. 14.	Write a C program u printmat() to read th elements of a row, su elements of the two Write a C program	ne va um c dime	lue: of al ensi	s int I the ona	o a e ele I arr	two me ay A	din nts (an	nens of a d pr	sion col int	al a umr the	rray n, fino resul	A, fir d the lts.	nd th e tota	e su al su	m of m of	all the all the
	dimensional array of message using funct	nun ions	nbei	rs ar	nd re	еро	rt su	icce	SS C	or fa	ilure	in th	ne fo	rm c	of a s	uitable
15.	Write a C program to 6subjects of N stude grade based on aver	ents	into	an	arra	iy o	f str					-				
			A	٩ver	age			Grad	de							
				80-	100			Dist	inct	ion						
				60-	79			First	t Clá	ass						
				40-	59			Seco	ond	Cla	SS					
				<4()			Fail								
16.	Write a C program,	to in	nple	mer	nt a	buk	oble	sor	t te	chn	ique	usin	g a	func	tion	to sort
	given N integers in a	scer	din	g/ d	esce	endi	ing	orde	er as	s pe	r use	er's p	refe	rence	Э.	
_	•															
	rse Outcomes: At the er															
1.	Describe the basics of		•		-							•	ess	of pr	oble	m-
2.	solving aspects using															
4.	Apply the knowledge									ate s	simp	ie ex	pres	sion	s and	1
3.	input/output statemer									ch a	c bro	nch		ndl		n a
5.	Develop the C progra constructs for a given		-		itroi	Sld	tem	ents	s su	CII d	IS DIC	anch	ing a	inu i	oopi	ng
4.	Apply the knowledge	•			icał	vilit.	/ na	ram	noto	r na	ccina	n and	l rot	urnir		عمدا
	to develop a maintair					-	•			-	-				-	
	functions.			nog	Turr		''g					nera	ang	unu	ys ai	
5.	Identify and describe	the	use	e of	strir	nas.	stru	ctur	res.	poir	nters	and	file	hanc	dina	
	mechanisms in a C pro					. <u> </u>			,							
		J														
Cour	rse Outcomes Mapping	wit	h P	rogi	ram	Ou	tco	mes	8	PSC)					
	Program Outcomes→		2	3	4	5	6	7	8	9	10	11	12		PSO-	\downarrow
↓ (Course Outcomes													1	2	3
	CS1001-1.1	3	1	1	1								l		2	
		2	3	İ	İ	1	1						İ		3	
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	CS1001-1.2 CS1001-1.3	2	3												3	



	CS1001-1.5 2 3 3
	1: Low 2: Medium 3: High
TEXTE	BOOKS:
1.	E. Balaguruswamy, Programming in ANSI C, Tata McGraw Hill, 3rd Edition, 2004.
2.	Jacqueline A. Jones & Keith Harrow, C Programming with Problem Solving, Pearson,
	Pap/Dskt edition, 1996
REFER	ENCE BOOKS:
1.	Kernighan & Ritchie, The C Programming (ANSI C), Prentice Hall; 2ndEdition, 1998.
2.	Rajiv Khanna, Computer Concepts and C Programming, New Age International Pvt
	Ltd Publishers, 1st Edition, 2006.
3.	Yashwant Kanetkar, Let Us C, 5th Edition, BPB Publications, New Delhi, 2004.
E Boo	ks / MOOCs/ NPTEL
1.	http://www.lysator.liu.se/c/bwk-tutor.html#introduction
2.	http://www.acm.uiuc.edu/webmonkeys/book/c_guide/
3.	C programming Tutorial by Mark Burgers <u>http://markburgess.org/CTutorial/C-Tut-</u>
	02.pdf
4.	http://nptel.ac.in/courses/106105085/4
5	https://www.lynda.com/C-training-tutorials/1249-0.html

Course Code:	EE1001-1	Course Type:	ESC
Teaching Hours/Week (L: T: P:S):	3:0:2:0	Credits:	04
Total Teaching Hours:	39+0+26	CIE + SEE Marks:	50+50
Teaching Department	t: Electrical & E	lectronics Engineering	L
Course Objectives:			
1. To familiarize the student with	the DC circuit ar	nalyses.	
2. To analyze single and three-ph	ase AC circuits.		
3. To understand the working prin	nciple of electric	al machines.	
4. To introduce the concept of ele	ectrical wiring pr	otective devices and safety	^v measures
	UNIT-I		
Circuit Fundamentals			07 Hour
asic nodal and mesh analysis excited	by independent	DC voltage sources, Power	and Energy
Generation of sinusoidal voltage, free	quency of gener	ated voltage, definition an	d numerica
alues of average value, root mean sc	quare value, form	n factor and peak factor of	sinusoidall
varying voltage and current, phasor re	epresentation of	alternating quantities.	
A.C. Circuits			09 Hour
nalysis of R, L, C, R-L, R-C and R-L-C s	eries and paralle	Circuits Phasor Diagrams	ROJINOWA
eactive power, apparent power and and current relations in star and delta	power factor.	Three-phase balanced circu	uits, voltag
eactive power, apparent power and and current relations in star and delta	power factor.	Three-phase balanced circu	uits, voltag
eactive power, apparent power and and current relations in star and delta wo wattmeters	power factor. T connections. Me	Three-phase balanced circu	uits, voltag
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and Three-way control. Elementary discussion on Circuit protective devices: Fuse and Miniature Circuit Breaker (MCB's). Electric shock, precautions against shock. Earthing: Pipe and Plate earthing.

and	Plate earthing.														
			gge					peri	me	nts					
1.	Verification of KVL ar														
2.	Measurement of curr		ро	ver	and	ро	wer	fact	or c	of in	cand	esce	nt la	mp, flı	lorescer
	lamp, CFL and LED la														
3.	Sinusoidal steady stat	te re	espc	nse	of I	R-L,	and	1 R-(C ci	rcui	ts- in	nped	ance	calcu	lation
	and verification.														
4.	Load test on a single-	-pha	ase -	Tran	sfor	me	r.								
5.	Voltage and Current	relat	tion	ship	s of	thr	ee p	bhas	e st	ar/c	lelta	circu	uits.		
6.	Measurement of thre	e-pl	hase	e po	wer	usi	ng t	wo	wat	tme	ter n	netho	od.		
7.	Speed load character	istic	ofa	a 3-	pha	se Ir	ndu	ctio	n M	oto	r.				
8.	Two-way and Three-w	way	Cor	ntrol	of	am	p ar	nd fo	orm	atio	n of	truth	tabl	е	
		D	emo	onst	rati	on	Ехр	erin	nen	ts					
1.	Demonstration of fus	e, N	1CB	by o	crea	ting	a f	ault.							
2.	Demonstration of cut	out	t seo	tior	ns o	f ele	ectri	cal ı	mac	hin	es (D	C ma	achin	es, Inc	duction
	machines and Synchr	ono	ous r	nac	hine	es).									
Cou	rse Outcomes: At the en	d of	fthe	e col	urse	stu	den	t wi	ll be	e ab	le to				
1.	Analyze the DC Circuit	s us	ing	mes	h &	no	de r	neth	nod	s an	d de	scrib	e AC		
	fundamentals.														
2.	Analyze voltage & curr	rent	pha	sor	rela	tior	nshi	ps ir	n sir	ngle	phas	se &	three	e phas	e AC
	circuits and compute c	om	plex	ро\	ver.										
3.	Summarize the fundan	nent	als	of e	lect	rom	agr	etis	m a	nd a	apply	/ prir	nciple	e of sir	ngle-
	phase transformer to c	om	pute	e tra	nsfo	orm	er e	fficie	ency	/.					
4.	Describe the construct	ion,	оре	erati	ng j	orin	cipl	e of	DC	& s	ynch	ronc	ous m	nachin	es and
	analyze their performa	nce	cha	ract	eris	tics.									
5.	Describe the working p	orino	ciple	e, sta	artir	g p	roce	ess,	per	form	nance	e cha	racte	eristics	8
	applications of Induction	on r	noto	or ai	nd c	lom	esti	c wi	ring	8	orote	ective	e sch	emes.	
Cou	rse Outcomes Mapping	wit	h P	rogi	ram	Ou	tco	mes	8	PSC)				
	Program Outcomes →	1	2	3	4	5	6	7	8	9	10	11	12	PS	50↓
\downarrow (Course Outcomes													1	2
	EE1001-1.1	2	3												
	EE1001-1.2	2	3												
	EE1001-1.3	2	3												
	EE1001-1.4	2	3											1	
	EE1001-1.5	2	3		1			1						1	
	1: Low 2: Medium 3:			I	1	1	I	I	I	1		1	1	_	1

TEXTBOOKS:

1. Electrical Technology, Hughes, Edward, Pearson Education Publications, 10th Edition, 2010.



2.	
	Edition 2009.
3.	Lecture Notes on Basic Electrical Engineering, Department of E&E, NMAMIT, Nitte
REFER	RENCE BOOKS:
1.	Electrical Engineering Fundamentals, Vincent Del Toro, 2nd Edition, Pearson, 2015
2.	Electrical Technology, H. Cotton, CBS; 7 th Edition, 2005.
3.	Basic Electrical Engineering by A. Mittle and V. N. Mittle, Tata McGraw Hill, 2005
4.	Basic Electrical Engineering, Dr. Debashisha Jena, Wiley India Private Limited, 2012
E Boo	ks / MOOCs/ NPTEL
1.	http://nptel.ac.in/courses/108105053/
	Basic Electrical Technology Lectures by Dr. L Umanand Department of Power
	Electronics Group, CEDT IISC Bangalore available at
2.	http://www.nptelvideos.in/2012/11/basic-electrical-technology.html

	Elements of	Mechanical	Engineering	
Course		ME1003-1	Course Type	PCC
Teachi	ng Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total T	eaching Hours	39	CIE + SEE Marks	50+50
	Teaching Depart	ment: Mecha	nical Engineering	
Course	Objectives:			
Students	belonging to all branches of Engine	0		•
	al engineering so that they will have	e a minimum und	lerstanding of mechanical sy	ystems, equipment
and proce		ray courcos f	ormation of staam and	hailars
	nderstand the principles of ene			Dollers.
	now the working principles of J			itioning
-	nderstand basic principles of I.	<u> </u>		<u> </u>
	nderstand the basic principles			<u> </u>
5. U	nderstand the different machir		s, automation, and robo	otics.
		UNIT-I		00 11
-	· · · · · · · ·			09 Hours
	of energy: Introduction to Fo		sification of different so	urces of energy.
	tional & Non-conventional) wi			
-	ies of Steam: Formation of ste	am, States of S	Steam and Steam prope	rties, Numerical
Problem				
	Definition and Functions of boi			
Babcock	& Wilcox boiler. Boiler mount	ings and acces	sories – Meaning and F	
				06 Hours
-	and compressors: Introduction	n, Working pri	nciples of Centrifugal P	ump and Single
-	eciprocating Compressor.			
	s: Working principles of Impuls			
), Water turbines (Pelton whee	el, Kaplan, anc	l Francis turbines), Gas	turbines (Open
and Clos	sed cycles).			
		UNIT-II		
				09 Hours
Internal	Combustion Engines: I. C. Er	ngines parts, W	/orking of 2-Stroke and	4-stroke Petrol
and dies	el engines. Numerical Problen	ns on Indicate	d Power, Brake power,	mechanical and
thermal	efficiencies.			
Refrige	ration and Air conditioning:	Properties of	refrigerants, Refrigerat	ion – Meaning,
Uses an	d Definitions (COP, Tons of F	Refrigeration, I	Refrigerating Effect). Co	onstruction and
working	Principle of Vapor Compressi	on, Vapor Abs	sorption refrigeration s	ystem, and Air-
conditio	ners (Window A.C.)			
				06 Hours
Power 1	ransmission: Belt drives - App	olications, Ope	n and Crossed belt driv	es, Length of
	Velocity ratio, Ratio of belt ter	•		-
	ons). Gear drives - Introduction		-	
	k & Pinion. Simple and compo	•	-	
	al problems (No derivations)			
	g and Soldering: Basic princip	les of Arc weld	ding, Gas welding, Solde	ering, and



Brazing.

UNIT-III

09 Hours

Machine Tools: Introduction, Types of machine tools and Applications.

Lathe operations - Turning, facing, Taper Turning using swiveling compound rest and Thread cutting.

Drilling operations - Drilling and Tapping

Milling operations - Plane milling (Up and Down milling), End milling.

Grinding operations - Surface grinding, cylindrical grinding and Centerless grinding.

Mechatronics and Automation: Meaning, Need for automation, Types - Fixed, Programmable & Flexible automation. Elements of automated systems, Open and Closed loop control systems.

Robotics: Introduction, Robot Anatomy, Classification based on Robot Configuration, Applications of Robots.

Course Outcomes: At the end of the course student will be able to

1. Explain the principles of energy sources, formation of steam and boilers.

2. Discuss the working principles of pumps, compressors, and turbines.

3. Explain basic principles of I. C. Engines, Refrigeration and Airconditioning.

4. Discuss the basic principles of power transmission and metal joining processes.

5. Explain the different machining operations, automation, and robotics.

Course Outcomes Mapping with Program Outcomes & PSO

			9												
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	P	SO \	\boldsymbol{k}
↓ Course Outcomes													1	2	3
ME1001-1.1	3	1	-	-	-	1	-	1	-	1	-	-	-	-	-
ME1001-1.2	3	1	-	-	-	-	-	-	1	1	-	-	1	-	-
ME1001-1.3	3	2	-	-	-	-	-	-	-	1	-	-	-	-	-
ME1001-1.4	3	2	-	-	-	-	-	-	1	1	-	-	1	-	-
ME1001-1.5	3	2	-	-	-	-	-	1	1	1	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

- K.R.Gopalkrishna, "A text Book of Elements of Mechanical Engineering" Subhash Publishers, Bangalore. 2010
- 2. Mikell P. Groover, "Automation, Production Systems & CIM", 3rd Edition, PHI, 2012

3. V.K. Manglik, "Elements of Mechanical Engineering", PHI Publications, 2013.

REFERENCE BOOKS:

- 1. S. Trymbaka Murthy, **"A Text Book of Elements of Mechanical Engineering"**, 4th Edition 2006, Universities Press (India) Pvt. Ltd, Hyderabad.
 - 2. K.P. Roy, S.K. Hajra Choudhury, Nirjhar Roy, "Elements of Mechanical

Engineering", Media Promoters & Publishers Pvt Ltd, Mumbai,7thEdition,2012.

3. Pravin Kumar, "Basic Mechanical Engineering", 2013 Edition, Pearson.

E Books / MOOCs/ NPTEL

1. https://nidm.gov.in/iec.asp (Study material of National Institute of Disaster management)



Co	urse Code:		BT	1001-1	C	ourse 1	уре		Α	EC
Теа	aching Hours/Week (L: T: P	: S)	1:0):0:0	C	redits			0	1
Tot	tal Teaching Hours		13		C	ie + se	E Marks		5	0+50
	Teaching De	partn	nent:	Biotec	hnolo	gy Eng	ineering			
	rse Objectives:									
1.	To learn the types of cells,	biom	nolecu	ules and	l life p	rocesse	S			
2.	To know the applications i	nspir	ed by	v nature	in var	ious str	eams			
3.	To be updated application	of bi	iology	y in real	life sc	enarios	5.			
			l	JNIT-I						
	RODUCTION FOR BIOLOGY)5 Hour
-	Biology for Engineers? Cell T			-		-				nd Fung
uka	aryotes - Plant and Animal Ce	ells, Bi			Life Pr	ocesse	s at Cellu	lar Le	vel.	
			l	JNIT-II						
PP	LICATIONS INSPIRED BY NAT	URE							()5 Hour
Com	posites in Construction, Terr	nite N	Moun	d archit	tecture	e, Coun	ter curre	nt hea	t ex	changer
Desi	gn of aeroplane, helicopter	and	subm	narine, I	nform	ation T	heory an	d Bio	logy	, sona
	lical Devices.									
/led										
/led			U	NIT-III						
	L LIFE SCENARIOS		U	INIT-III					()3 Houi
REA		Agrie			Лedica	l Techr	ology.		()3 Houi
REA	L LIFE SCENARIOS	Agrie			Лedica	l Techr	ology.		()3 Hour
REA Rece	L LIFE SCENARIOS	-	cultu	re and N					()3 Houi
REA Rece	L LIFE SCENARIOS ent scenarios in Environment,	the o	cultur cours	re and N e stude	nt will	be able	e to	eerin		
REA Rece Cou 1.	L LIFE SCENARIOS ent scenarios in Environment, rse Outcomes: At the end of	the of Bio	cultur cours ology	re and N e stude to be aj	nt will oplied	be able	e to	eerin		
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REA Rece Cou 1. 2. 3. 4.	L LIFE SCENARIOS ent scenarios in Environment, rse Outcomes: At the end of Ascertain the importance of Interpret the basics of cell Draw inspiration nature in Analyse the significance of	the of Bio and I desig	cultui cours logy life pr gn of nicry c	re and M e stude to be aj rocesses machin of natur	nt will oplied ery and e in de	be able in vario d const esign of	e to ous engir ruction electrica	l, elec	g str	eams ic and
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1.	Suraishkumar, G.K. Biology for Engineers, Oxford University Press India, 2019.
2.	Chakraborty, T, Akthar, N Biology for Engineers, PHI learning Print Book ISBN :
	9789391818142 eBook ISBN : 9789391818197
REFER	RENCE BOOKS:
1.	Rao C.V., <i>Biology for Engineers</i> , 2021
2.	Raven, P. H. and Johnson, G. B. <i>Biology</i> . 4th Ed. WCB publishers, 2010.
3.	Ethier, R. S. and Simmons, C. A. Introductory biomechanics- From cells to organisms.
	Cambridge University Press, 2012

Теа	ırse Code:	IS1001-1	Course Type	AEC
	ching Hours/Week (L: T: P: S)	1:0:2:0	Credits	02
Tot	al Teaching Hours	39	CIE + SEE Marks	50+50
	Teaching Departmer	nt: Informatio	on Science Engineering	I
Cour	se Objectives:			
1.	Demonstrate the basics of Android Pr	ogramming.		
2.	Design and develop web pages that in	clude static and	dynamic content.	
3.	Describe the basic concepts of Cloud.			
4.	Discuss the basic concepts of IoT.			
5.	Recognize the best practices of Cyber	•	rity.	
		UNIT-I		
intro	duction to Application develop	oment		05 Hours
Simp	le android application developr	ment (No kno	owledge of programmi	ing language is
requi	ired).			
Note	:			
1.	The purpose of application deve	elopment is to	ignite and promote pro	aramming skills
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6.			he android applicatio	
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- Inline CSS, Internal CSS, Classes, and IDs
- div, Color, Floating, Positioning
- Margins, Padding, Borders
- Fonts, Aligning Text, Styling Links

Creating a web page dynamic using JavaScript

- Dynamic web page and Introduction to JS
- Basic syntax
- Functions
- Events

Creating dashboards in websites

Activity: Personal website design and launch with a free platform or Create a Blogging website.

	UNIT-II	
Introducti	ion To Cloud, IoT Concepts and Cyber Security	05 Hours
Fundame	ntals of cloud	
Cloud ser	vice models	
•	IaaS (Infrastructure-as-a-Service)	
•	PaaS (Platform-as-a-Service)	
•	SaaS (Software-as-a-Service)	
Cloud dep	ployment types	

- Public
- Private
- Hybrid

Community Cloud Cloud services:

• Google Drive - file storage and synchronisation service developed by Google;

• Google docs, sheets and slides - bring your documents to life with smart editing and styling tools to help you easily format text and paragraphs;

• GoogleCo-lab (Usage ofJupyter Notebook): Colab notebooks allow you to combine executable code and rich text in a single document, along with images, HTML,LaTeX, and more.

Working of IoT and IoT components (Only brief introduction and demonstration through videos) Explain concept of Internet of Things with examples

- Smart home
- Smart city
- Smart Farming

Activity: Create your cloud service account and demonstrate using cloud services. Identify cloud service providers with respect to service models and deployment types. Identify areas where the Internet of Things could bring positive changes.



	Brief awareness on cyber safety measures
	• Identification of basic security issues in mobile phones and personal compute
	Installation of Antivirus software
	Firewall concepts
	Browser settings
	 Importance of privacy and Password policy (Best practices).
rogr	ams 26 Hou
1.	
2.	Design and create simple android application
3.	Design and create web page for displaying your article (Title, header, paragrap
	formatting tags)
4	Design and create a webpage for your wishlist (What you want to do). Also I
	challenges and opportunities along with images to present your dreams (List order
	and unordered, Image, table)
5	Design and create webpage using HTML and CSS about an awesome animal (U
Э.	
6	necessary CSS tags)
0.	Design and create web page for a travelbook /recipe book with more than 3 page
-	table to list places /recipes (iframe, hyperlink)
7.	Design and create web page with JavaScript to design a simple calculator to perfor
_	the following operations: sum, product, difference and quotient
8.	Design and create a personal webpage with dashboard
9.	Design and create web page about advantages of business process automation wi
	respect to your branch of engineering
10	. Create user account and demonstrate use of Google drive, Google docs, GoogleCola
	(Usage of Jupyter Notebook)
11	. Demonstrate Internet of Things using examples a. Smart home b. Smart city c. Sma
	farming
12	. Demonstration and hands on browser settings, privacy settings and password polic
13	. Demonstration of common security threats (using videos) a. Phishing b. DoS attack
	Man in the middle attack d. Spamming e. Virus
ours	e Outcomes: At the end of the course student will be able to
1.	Understand the basics of Android Programming.
2.	Develop web pages that include static and dynamic content.
3.	Analyze the basic concepts of Cloud.
4.	Comprehend the basic concepts of IoT.
5.	Illustrate the best practices of Cyber Safety and security

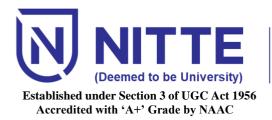


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		ENVIRC	DNMENTAL	SCIENCE	
Cours	se Code:		CV1002-1	Course Type	MNC
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Total	Teaching Ho	ours	13	CIE + SEE Marks	50+50
		Teaching De	partment: Civ	il Engineering	
Course	e Objectives:				
1.	To raise consciou	usness about environ	mental condition	s and to imbibe environme	ntally appropriate
	behaviour.				
			-	significance of environmen	tal practice in their
		the engineering pra			
3.	To make them c	onscious of understa		onment where we live and a	act up on.
			UNIT-I		
Title				ntal studies- current scenar	03 Hours
Eco sys		components; ecolo producers, consum Habitat, range of li ecological pyramid he Anthropogenic Sy	ogical balance; ers and decomp fe, Biome, balanc s stem- human ac for economy and	ced eco- system, food chai ctivities like growing food, d social security. Soil erosion	biotic, abiotic; n, food web and building shelter
Natura	al resources				03 Hours
Water domes Qualit value, Minera petrole Forest enviror objecti Mater	resources - stic and indust y aspects - total hardness al resources- eum Wealth - nmental effect ives ial cycles	Global water restrial purposes in In Water quality pa s, iron, fluoride, lea Metallic minerals, Components of ts of deforestation Carbon, nitrogen	sources: distribudia. rameters, drinl ad, arsenic, nitr non-metallic r the forest, ke n and remedie <u>and sulphur cy</u> UNIT-II	minerals Fossil fuels ey benefits of forests es Sustainable develop vcles.	for turbidity, pH - Coal and . Deforestation- ment- definition,
Enviro health	•	ution: Definition	, harmful effe	cts related to public	03 Hours
nealth					
	er pollution:	Definition, types	and sources –	· agriculture (pesticide	



		induced diseases- definition, common diseases and their of Fluoride problem in drinking water	causatives,
Land	pollution:	Definition, sources_ agriculture, housing, industry, transportation. Types of municipal Solid waste Disposal landfills, composting, incineration (in brief) and effects	J .
Air Po	Ilution:	Definition, types and sources: industry, mining, agriculture, tran and effects	sportation
Noise	pollution:	Definition, sources, mining, industries, rail-roads, aviation, e control measures	effects and
Energ	ly ent types of er		02 Hours
		gy; fossil fuels- coal, oil and natural gas- brief description only. Nuclear ener	rav- nuclear
	plants,	y, lossi lucis cou, on and llatural gas bher description only. Nuclear cher	igy nuclear
Renewa	•	lar energy- Photovoltaic systems for street and domestic lighting, solar water h	eating-brief
	,	on, merits and demerits, Hydro power- definition, merits and demerits.	
Biomas	ss energy- def	inition, sources of bioenergy, biogas, biofuels, India's position in renewable	energy
Hydrog	gen as an alter	rnative future source of energy- brief scope, fuel cells. UNIT-III	
Curre			
		mental issues of importance	02 Hours
Popul	ation growt	mental issues of importance h- Definition, growth rate, effects, remedies Urbanization -	02 Hours Definition,
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HOLISTIC COMPONENTS

HUMANITIES

Holistic education is not only about teaching the basic subjects, but it is more about redefining the way a student should be taught. The purpose of holistic language teaching is the development of the learners' ability to handle both their language oral skills as well as maximizing their life skills. The department contributes to educational life and work spaces that are creative and meaningful. Multidisciplinary and holistic learning is an ancient method used in Indian education system as well as the other parts of the world. This is the reason that such type of education system was advocated by scholars like Kautilya, Banabhatta, Plato, and Aristotle among many others. Holistic approach is essentially a student centered strategy rather than a teacher centered one.

Holistic education through courses allied to Humanities is created within the inclusive connections of social and human experience. A curriculum built around such stages is considered holistic if they involve the practices that integrates language acquisition and fills multiple cognitive demands in interlocking activities that spiral learning. Through the applied learning style of a person--mind, body and spirit students will learn more effectively the nuances of language, responsibilities towards social fabrics and ethics.

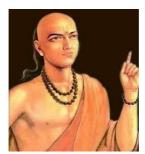
The approach strives to make a learner construct his own understanding of the text he/she interacts with and converses with others according his understanding. Intensive experiential and group sessions, a co-created learning ambience and hands-on engagement through real-life cases, field trips and internships to make learning exciting, rigorous and transformative. As a part of the holistic approach and its philosophy, a student is educated beyond core academics providing him/her virtuous and holistic education. This helps the students to discover their individuality and comprehend the significance of life purposefully, creatively, and morally in a complex world. Krishnamurti writes If the unity of life and the oneness of its purpose could be clearly taught to the young, how much brighter would be our hopes for the future! (Krishnamurti, J. 1974).

MATHEMATICS

INDIAN MATHEMATICIANS

It is essential to know about the ancient, medieval and modern time Indian mathematicians and their contribution to Science and Mathematics. Ancient Indian mathematicians have contributed immensely to the field of mathematics. The invention of zero is attributed to Indians and this contribution outweighs all other made by any other nation since it is the basis of the decimal number system, without which no advancement in mathematics would have been possible. The number system used today was invented by Indians and it is still called Indo-Arabic numerals because Indians invented them and the Arab merchants took them to the western world.

Here we are introducing some of the important Indian mathematicians from ancient times.



<u>Aryabhata</u>: (500 A. D.) - Studied at the University of <u>Nalanda</u>, which was considered as a great centre of learning. Aryabhata was a <u>great Indian mathematician</u>. He gave the value of " $\underline{\pi}$ " as 3.1416, claiming for the 1st time, that it was approximation. Aryabhata also dealt with other aspects of mathematics and Astronomical calculations, namely <u>Geometry</u>, <u>Mensuration</u>, <u>Square root</u>, <u>Cube root</u>, <u>Progression</u> and <u>Celestial sphere</u>. He presented a method to solve an intermediate equation of certain type that are important in astronomy and computer science.



Bhaskara: (1100 A. D.) - was a great <u>Mathematician</u> and <u>Astrologer</u>. He was the first Mathematician to declare confidently that any term divided by ZERO is infinity and the sum of any term and infinity is infinity. His concept of "<u>Tatkalikagati</u>", which means <u>instantaneous motion</u>, used by astronomers to determine the motion of the planet accurately brought credit to him. He explained the solutions of quadratic and cubic equations. He stated the Rolle's theorems in analysis, the mean value theorem.



Srinivas Ramanujan was an Indian Mathematician who made significant contributions to mathematical analysis, Number theory and continued fractions. He made many important contributions in the field of mathematics with his wonderful and unique knowledge. That's why his birthday is celebrated as Mathematics Day.

PHYSICS

The ancient world had considered Physical Sciences, Chemical Sciences, Earth Sciences, Biological Sciences, Mathematical Sciences etc. as study of nature, which were all studied under the banner of Philosophy. Even today, the philosophers are studying Metaphysics which connects physical attributes to mind. Physics is a branch of science which deals with the study of matter and energy. The Physical Science was a matter of interest for all the civilizations including Vedic era of India dating back to over 3000 years. The physical science in ancient India was majorly restricted to Astronomy and Astrology. It was Kanada(600 B.C.) who presented holistic approach of physics, by blending science, philosophy and religion through 'Vaisesika Sutra'. Their essence is the atomic theory of matter. He gave the name 'Paramanu' (Atom), to be the indivisible entity of matter. The idea of chemical change was also put forward by Kanada. Bharadwaja is credited with teaching missile technology. Aryabhata(500 A.D.) was a great astronomer. He was the first to state that the earth is round and it rotates on its own axis, creating day and night. He declared that the moon is dark and shines only because of sunlight. Aryabhatta contributed greatly to the field of science particularly astronomy. Varaha mihira (500 A.D.) studied astrology and astronomy and declared that the earth was spherical. He also proposed that the moon and planets are lustrous not because of their own light but due to sunlight. Bhaskra (1100 A. D.) was a great scientist his concept of "Tatkalikagati", which means instantaneous motion, used by astronomers to determine the motion of the planet accurately brought credit to him. Brahmagupta(598 A.D.) calculated the instantaneous motion of a planet, gave correct equations for parallax, and some information related to the computation of eclipses and is widely regarded as one of the most accomplished of the ancient Indian astronomers.

"If you wish to make an apple pie from scratch, you must first invent the universe."So said astronomer Carl Sagan in an episode of his landmark television series, Cosmos. Embedded in Sagan's memorable quip is a certain holistic understanding of the universe — a notion that the existence of any one thing is intimately tied to the existence of everything else. There are no apple pies without apples; there are no apples without the proper climate for growing apple trees; there is no proper climate for growing apple trees without a planet on which the apple trees can grow and so on, all the way back to the Big Bang.Pythagoras and his followers held mathematics in an almost holy regard, and they saw numbers as a basic form of matter. According to their view, all things had numbers, and the objects of the universe — including human societies — were arranged in harmonious mathematical relationships with one another.

All sciences were originated from philosophy. Physics was called natural philosophy until the 19th century, but once it was proven to be correct it was no longer philosophy and became a science. Physics is the science of the natural world, more specifically dealing with the matter, energy, space-time, and fundamental forces that govern the physical world. In physics we study a wide range of physical phenomena from subatomic particles to large galaxies of the material universe, and use empirical data and mathematics to find results and conclusions. Physics is also deeply concerned with arriving at knowledge about the ultimate nature of reality. Since we cannot know whether we have discovered everything which would affect our theories of the universe, all such theories are perpetually subject to modification or change. Mathematics is a language and a tool that we use in physics to explain the universe. Quantum physics is a mathematical description that rules the tiny world of atoms and subatomic particles in our universe. Without quantum physics, much of the information technology that we rely on, from microcircuits to lasers, would not exist. Today many scientists argue that metaphysics plays an important role in quantum mechanics at a deeper level; the nature of reality is all mathematical. This could be an example of how metaphysical assumptions can get in the way of our understanding the paradoxical nature of quantum mechanics. But even when quantum mechanics appears a mystical science of metaphysics, it is not metaphysics but productive science.

Thus, the Physics though has many branches and uses many other branches of science and philosophy, in the past and the present, its aim is to understand the whole universe which is nothing but matter and energy which is seen or unseen.

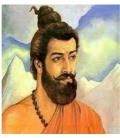


CHEMISTRY

ANCIENT SEERS OF INDIA – CHEMISTRY

In ancient India, chemistry was called **Rasayan Shastra**, **Rasa-Vidya**, **Rasatantra and Rasakriya** all of which roughly mean '*Science of Liquids*'. There also existed chemical laboratories which were called **Rasakriya**-nagaram/Rasakriya-shala, which literally mean '*School where liquids are activated*'. Rigveda (earlier than 1500 BCE) mentions many fermented drinks and methods of fermentation, apart from various metals. Soma juice from the stems of the soma plant was considered a divine drink. The Vedic Indians were acquainted with the art of dyeing with certain natural vegetable colouring matters. A type of pottery, now known as 'Painted Grey Ware', is also associated with the Vedic period.

Ancient chemistry in India grew out of the early efforts to develop an elixir; to turn base metals into gold and on metallurgy. Chemical techniques in India can be traced back all the way to the Indus valley or Harappan civilisation (3rd millennium BCE). Pre-Harappan Indians were acquainted with the art of making baked or burnt clay pottery as well as painting the same with two or more colours (by addition of iron oxide, manganese oxide, etc.). Kautilya's Arthashaastra (3rd or 4th century BCE) has a lot of information on prevailing chemical practices. Apart from mines and minerals, it discusses the details of precious stones (pearl, ruby, beryl, etc.); preparation of fermented juices (sugarcane, jaggery, honey, jambu, jackfruit, mango, etc.) and oil extraction.



It is said that **Maharshi Kanada** was the first to propound that the *Parmanu* (atom) was an indestructible particle of matter and that Universe is made up of *Kana*. When matter is divided and sudivided, we reach a stage beyond which no division is possible, the undivisible element of matter is *Parmanu*. Kanada explained that this indivisible, indestructible y cannot be sensed through any human organ.



Nagarjuna (931 A.D.) from Somnath in Gujarat was a chemist/alchemist, who concentrated his efforts in transforming the base metals into gold. His reputation was such that people believed Nagarjuna to be in communion with gods and goddesses who had blessed him with the power of changing base metals into gold and extracting the 'elixir of life'.



Prafulla Chandra Ray (1861-1944), an Indian chemist, is often referred to as the Father of Chemistry in India. He received his BS in 1882 and his PhD in 1887 from University of Edinburgh. In 1896, he announced a major discovery of a new compound, mercurous nitrite.

Today's Science and Technology has been greatly inspired by the contributions of these wise seers. Indians have continued to show their global impact in the Field of Science.



In the 21st century, biochemist **Har Gobind Khorana** won the Nobel Prize (1968) for demonstrating how the nucleotides in nucleic acids control the synthesis of proteins. Thus, the seers of ancient India have contributed significantly in the development of Modern Chemistry.

BIOTECHNOLOGY

Biology for Engineers

Science deals with matter. It is based on starting from scratch with what a human can observe, test, and rationalize. Ancient sages have worked hard to be seen as the only reliable providers of knowledge to the world. In 1875, the Vymaanika Shaastra, a 4th Century BC text written by Sage Bharadwaj was discovered in a temple in India. It contains 3000 shlokas in 8 chapters which was physically delivered by the ancient Hindu Sage Bharadwaj. The book greatly deals with the operation of ancient vimanas and included information on steering, precautions for long flights, protection of the airships from storms and lightning and how to switch the drive of solar energy or some other form of energy. One of the chapter will reveal the secrets of constructing aeroplanes that cannot be broken or cut, that is indestructible, that is fire resistant. It also deals with the secret of making planes motionless and invisible. It also describes how to defeat the enemy planes etc. as per the Sage Bharadwaj the vimanas were classifies as per the Yugas. During the period of Krita Yuga, Dharma was establishes firmly. The pushpak Vimana which was used by Ravan was an Aerial vehicle. He used this vehicle to kidnap Sita from jungle and took him to his Kingdom Srilanka. Ramayana was during the Treta Yug in which the Vimanas were highly discovered. During this period "Laghima" gave them the power to lighten their vehicle do they can travel freely in the air.

COMPUTER, INFORMATION SCIENCE & ENGINEERING

The Indians (**Aryabhata**, 476 BC - 550 BC) contributed **Zero** (**0**) to the number system. So that numeric system and computing world found an ease in solving numerical problems using computer programs.

Acharya **Pingala** was an ancient Indian mathematician who lived around 300 BCE. He wrote the Chandaḥśāstra, where he analysed **Sanskrit poetry mathematically**. It also contained the first known explanations of **digit zero**, **binary numbers**, **Fibonacci numbers and Pascal's triangle**.

Baudhayana (8th century BCE) composed the Baudhayana Sulba Sutra, which contains examples of Pythagorean triples, such as: (3,4,5), (5,12,13), (8,15,17), (7,24,25) and (12,35,37) as well as a statement of the Pythagorean theorem for the sides of a square: "The rope which is stretched across the diagonal of a square produces an area double the size of the original square."

In Indian astronomy, the study of **trigonometric functions** flourished in the Gupta period, especially due to **Aryabhata** (sixth century CE), who discovered the sine function.

Quadratic equation of the form $ax^2 + bx + c = 0$, $a \neq 0$ and is given by $x = (-b \pm \sqrt{b^2 - 4ac}) / 2a$. was discovered by Sridharacharya in the 11th century.

The largest numbers the Greeks and Romans used were 106. In 5000 BC Indians used numbers as big as 10^{53} (10 to the power 53) with specific names. The largest used number today is **Tera 10**¹².

Kaṭapayadi numerical notation is an ancient Indian system to depict letters to numbers for easy remembrance of numbers as words or verses.

For example: $\overline{\mathfrak{m}}(Ka)=1$ $\overline{\mathfrak{m}}(Ka)=2$ $\overline{\mathfrak{n}}(Ga)=3$ $\overline{\mathfrak{n}}(Ga)=4$ $\overline{\mathfrak{m}}(Ga)=5$ $\overline{\mathfrak{m}}(Ca)=6$ $\overline{\mathfrak{m}}(Ca)=7$ $\overline{\mathfrak{m}}(Ja)=8$ $\overline{\mathfrak{m}}(Ja)=9$ $\overline{\mathfrak{m}}(Nya)=0$. The modern **Hasing technique in computing system** which is resembling was then being used in the **Indian Katapayadi** system. For example, the hashing number based on Katapayadi system would be as follows for '**Gurudey**'

Gu=Ga(is the consonant)=3, Ru=Ra(is the consonant)=2, De=Da(is the consonant)=8Va=Va(is the consonant)=4, So Gurudeva = 4823.

In the recent decades, following are the few of the major contributors to the computing world:

- 1. In 1996 the USB port invented by the **Ajay Bhatt**, an Indian at Intel Oregon which involved low level **programs delt with embedded C Language** to perform flexible IO transfer and opened up an area to use plug-and-play devices efficiently.
- 2. The Pentium chip invented by Vinod Dham, that made C compiler to speed up the program execution and do well with GUI applications (both System and User Level) that are wiritten in C language.
- 3. Amit Singhal is an Indian who rewrote (search engine in 2001) the google algorithm (C language coding embedded with Assembly Language service routins in Windows and Unix/Linux). Then on the Google processes over 40,000 search queries every second on average which translates to over 3.5 billion searches per day and 1.2 trillion searches per year worldwide.

Few of the contribution as Auther of CP and Educators of C language:

- 1. Yashavant Kanetkar is an Indian computer science author, known for his varieties of C Programming books.
- 2. E. Balagurusamy : An Computer scientist known for Programming in ANSI C.

ELECTRONICS AND COMMUNICATION ENGINEERING

The idea of a holistic approach to engineering design and education has been envisioned to meet the perceived and emerging needs for innovation in the 21st century. Many engineering educators, practicing engineers and engineering students have already recognized the gaps and areas of potential improvements in the knowledge acquisition process implemented in current engineering degree programs when compared to current societal and technological issues and developments.

Society and humanity have progressed drastically over the past few generations. Engineers as a network of professional problem solvers have been heavily involved in these global communities and the engineering profession is evolving from one that focuses on targeted, isolated issues, to one that embraces challenges that incorporate physical, economic, environmental, and humanitarian aspects.

Currently, engineering students are required to take classes on ethics, liberal studies and technology and society courses, however engineering students are not prefaced with the importance of rounding out their education with these topics, and while social issues are discussed, they are not related to engineering specifically. That being said, explicitly linking the technical aspects of engineering to society is paramount in training effective problem solvers for the 21st century. With some exposure to multi-disciplinary, inter-disciplinary and trans-disciplinary approaches to engineering and design, students will be better prepared for their future careers in industry or research fields.

The functional requirements for the perceived solution were determined by the expected outcomes and what students should take away after experiencing the new educational product. Some of them are:

• students will be inspired and driven to seek opportunities in engineering for environmental, social, medical, and human development/poverty issues.

• students will be able to identify the issues that are emerging from new technology, how to mitigate the negative aspects and reduce the amount of impact, while leveraging the positive outcomes.

• students will have respect and knowledge of the importance of ethics and policy matters in the field of engineering and be able to determine between unethical and an ethical situation in a proactive manner.

The courses should overcome the challenges of the current engineering educational system. Approaching the degree from a holistic perspective. The integrated system that fosters collaboration among faculty and students. A new organizational and pedagogical model, which emphasizes knowledge integration and interweaves thematic content threads throughout the curriculum should be proposed.

- Foundations thread (math and science) Key mathematical concepts lay the foundation for understanding the anchoring concepts in courses throughout the ECE curriculum. The foundations thread unpacks mathematics and physics concepts to help students learn fundamentals in ECE topics like circuits, signals and systems, and electromagnetics. The foundations thread champion spearheads the collaboration between the math and ECE departments to introduce and promote the value and utility of mathematics in ECE courses, as well as the importance of mathematical thinking.
- Creativity thread (research, design, and optimization tools) The creativity thread is intended to integrate research and design throughout the undergraduate experience. By showing the impact of research, students will see the practical applications and potential breakthroughs of fundamental ECE concepts. Likewise, exposing students to design at every level of the undergraduate experience allows them to experience the excitement of engineering by applying their foundational knowledge to a tangible product.
- Professional formation thread (communications, cultural adaptability, ethics, leadership, and teamwork) Partnering with faculty and industry leaders to ensure students develop professional skills meaningfully and effectively to enhance student-industry interactions.

ELECTRICAL AND ELECTRONICS ENGINEERING

Agastya Samshita available at Prince's Library of Ujjain in India, dates back to the first millennium BC, contains a detailed description construction of an electric battery/cell along with way to utilize the battery to 'split' water into its constituent gasses. The method of generating electricity using modern battery cell resembles Agastya's method. The materials used by Sage Agastya for generating electricity were an earthen pot, copper plate, copper sulphate, wet saw dust, zinc amalgam. As quoted in Agastya Samhita the open circuit voltage and short circuit current of the prepared cell are 1.138 volts and 23 mA respectively. He articulates 100 earthen pots on water, has the power to change the form of water to oxygen and hydrogen. If hydrogen is contained in an air tight cloth, it can be used in aerodynamics, i.e. it will fly in air. In an iron vessel and in a strong acidic medium, gold or silver nitrate covers copper with a layer of gold or silver. The copper that is covered by gold is called Shatakumbha or artificial gold.

Rao Saheb Krishnaji Vajhe, an engineer from Pune while reading books related to science found the pages of Agastya Samhita with Damodar Tryambak Joshi of Ujjain. Dr. M. C. Sahastrabuddhe, the Head of the Sanskrit Department in Nagpur, when reading Agastya Samhita found the similarity of it with of Daniel Cell. He requested P.P. Hole, the Professor of Engineering at Nagpur to investigate on the same.

On the basis of the descriptions in Agastya Samhita Mr. Hole and his friend started preparing the apparatus for the experiment. While preparing the set up they could not understand the meaning of shikhigreeva and while checking the Sanskrit dictionary, they understood that it meant the neck of a peacock. They went to Maharaja Park and asked the chief when a peacock would die. The chief was very angry and asked them to give in an application. After few days during a conversation with an Ayurveda expert he confirmed that shikhigreeva is copper sulphate, which solved their problem. Thus, a cell was formed and it had an open circuit voltage of 1.38 volts and short circuit current of 23 milli amperes. The results of the experimentation were communicated to Dr. M.C. Sahastryabuddhe. It was exhibited fourth general meeting at the Swadeshi Vigyan Sanshodhan Sanstha, Nagpur on August 7, 1990 to the scholars. It was concluded that the description was of an electric cell

On the basis on Agastya Samhita and other scriptures, Rao Saheb Vajhe, who spent his life in rummaging the Indian scientific scriptures, gave different names to electricity. The six ancient terminologies for electricity are:

- Tadit—produced by friction from leather or silk,
- Saudamini—produced by friction from gems or glass,
- Vidyut— from clouds or steam,
- Shatakoti alias Shatakumbhi—produced from a battery of hundreds of cells,
- Hradini—obtained from storage cells,
- Ashani—the one emanating from a magnetic rod.

MECHANICAL ENGINEERING

Mechanical engineering is one of the oldest disciplines of engineering, which requires the knowledge of mathematics, materials, physics and other engineering technologies. It is concerned with materials, processes and machines and requires the concepts of forces, moments, energy, entropy, work etc. The developments that are visible in all spheres of life have connection to mechanical engineering. Engineering has made a significant contribution in the development of civilizations and contribution of mechanical engineering in areas like construction of large scale structures including for irrigation, architecture, military etc. is significant. Difficult problems of the society have been solved using simple concepts of mechanical engineering, say for eg. use of lever principle to move heavy objects. In fact, mechanical engineering made a significant contribution to the first cycle of industrial revolution, i.e., industrial revolution 1.0 during the 18th century. James Watt is often called the 'Father of Mechanical Engineering', as his invention of steam engine led to significant developments during the industrial revolution and beyond. The earliest computers were mechanical devices with electronics.

Significant contributions have been made during the Vedic ages and the first ever mechanical device that was invented was wheel and potter. Surmyam Suiramiva identified metals like Fe, Cu, Ag, Au etc., during the Vedic times. People knew about materials and material processing during those times and identified terminologies for the same in Sanskrit and produced gold and silver coins.

Seers like Tritala, Jalayan, Karaa, Vayurathaa and Vidyutrathaa discovered about aerodynamics during Rig Veda period, much before Wright Brothers discovered about aero planes. Computational Fluid Dynamics (CFD) analysis, which we are talking about today for different analysis, was there in the Vimana Shastra slokas.

Mechanical and manufacturing technology of ancient India ensured processing of natural products and their transformation into goods of trade, commerce and export.

Many scientists have made significant contributions to this domain. Leonardo da Vinci (16th century) studied and designed many mechanical systems that were related to transportation and warfare. In 17th century, Isaac Newton contributed the Laws of Motion used in several applications. Rudolf Diesel (18th century) was a German inventor, who created the first successful diesel engine and today diesel engines play a very important role in the transport and power sector in the world. Carl Frederich Benz (18th century) was a German automotive engineer, who developed the first practical automobile.

Mechanical engineering has evolved over the years and today the advent of computer and IT tools has facilitated better mechanical engineering in terms of design, analysis, and manufacturing. A mechanical engineer needs to work in multiple domains and needs to possess multiple skills like design, redesign, analyze, test, manufacture etc. It has been one of the founding disciplines of engineering and has contributed and will keep contributing to the growth and developments in this physical world.

CIVIL ENGINEERING

Indian civilization was the oldest civilization in the world and has a strong tradition of science and technology. It was the land of sages, seers, scholars, and scientists. Hinduism is a knowledge-based civilization, the Vedic texts should not be ignored dismissed as mythologies or as the work of imagination or just containing some moral stories. The Veda means knowledge and they contain relevant knowledge otherwise these texts would not have survived the millennia years of the historic storm. Let us know some of the great work done in ancient times.

Ancient India not only practised scientific methods of design and construction but also documented them for future generations. Here are some tips given by ancient sages on selection of site and construction

(1) Vishwakarma Vastu Shastra- Vishwakarma explains the first point of construction in the ancient book Vastu Shastra – 'पूर्व भूमिं परिक्ष्येत पश्चात् वास्तु प्रकल्पयेत्', This means that before construction one should test the land. Vishwakarma

further says that construction should not be done on the land which is very mountainous or on land with large cracks. Vastu shastra literally "science of architecture" are texts on the traditional Indian system of architecture. These texts describe principles of design, layout, measurements, ground preparation, space arrangement, and spatial geometry. The designs aim to integrate architecture with nature, the relative functions of various parts of the structure, and ancient beliefs utilising geometric patterns (yantra), symmetry, and directional alignments.

(2) Kashyap Shilpa (Craft) – In this ancient book, Kashyap Rishi has said that the foundation should be dug until water is seen because this way you would ensure that you have reached the rock level and the foundation would be strong.

(3) Bhrigu Samhita – In this scripture saint Bhrigu says that before buying land, one should test it for form, colour, juice, smell and touch. Rishi Bhrigu also explains its methods in his book.

Ancient cities of India found on the basis of archaeological discoveries:

- Rama was the world's first king to build a bridge across the sea. But he did not do it on his own. He sought the help of a great engineer called Nala according to Valmiki Ramayana. Any wise man will seek local knowledge when he ventures into new places. Nala knew the shallow areas across the sea in and around Tamilnadu. American space agency NASA also confirmed that there was a bridge through the satellite pictures. Any wise engineer will use such naturally elevated areas instead of deep waters to build a bridge.
- Bageeratha changed the course of the mighty river Ganges. The vast forest areas of modern Bihar, Uttar Pradesh, and West Bengal were made into fertile lands by his marvelous engineering feat. In those days very few people lived in those jungles. Puranas say that Bageeratha did penance for several thousand years to do this that too 'standing in one foot'. This is a phrase Indians use very often. Even the great Tamil poet Tiruvalluvar uses the simile of Stork that stands in one foot to catch a fish. This is the hidden language to say that he tried for a very long time with focused attention.
- Vedic Saint Agasthya discovered the land route to South India via Vindhyas. The Puranas say that he "subdued the arrogance of the hills", this is hidden language. Till Agastya's this great discovery kings and travellers used only sea routes. Since they knew the secret of monsoon winds they can travel to West Bengal or Maharashtra from Sri Lanka in a few months' time.
- Uparichara Vasu, an ancient king made mountain passes for the benefit of land travellers. He was a Vasu king ruling over the Chedi kingdom. Mahabharata says that he kicked the Kolahal Mountain which was blocking the flow of the Shaktimati River. This is a hidden language to say that he diverted the river for irrigation by cutting the hills.
- In short Bageerathan, Agastya, and Uparichara Vasu are the earliest engineers who built dams across the rivers. But unlike modern engineers, they did not use cement or mortar but they used the hills themselves. To avoid the force they made checks and balances. They use a hidden language saying that Shiva bore the force when Ganga came down from heaven.
- Parasuraman retrieved a lot of lands and gave it to Indians. A Pandya king called Nilam Tharu Vil Nediyon built sea walls to prevent the sea from invading the land.
- Balraman always travelled with an axe to clear the forests and make them cultivable. He was a great agriculturist. When Krishna spent most of his time in politics, his brother Balarama did constructive work.



- The Mohanjodaro, created 3000 years ago, is considered as a wonderful piece of civil engineering. Found in archaeological excavations even the ruins prove that this town was well settled and its buildings and roads all were made using symmetry and geometrical measurements. The roads found in this city were straight and were made from east to west and north to south and surprisingly they were at an angle of 90 degrees from each other. Buildings were also constructed in proportion. The intersection of the corners, the heights of the walls was equal. The city had public buildings, gardens, a restaurant, a large public bath as well as residential buildings. There was a provision for bathroom, living room etc in the residential buildings. The public buildings were 11.82m long, 7.01m wide and 2.44m high, and there were two streams of water. The building material and bricks of the walls were coated with a substance on which there was no effect of water. Archaeological research shows that people living here were well-versed in the construction techniques.
- Indus Valley Cities such as Harappa, Mohanjadaro, Lothal, Dholavira, Kalibangan need no new interpretations. The well-laid cities with uniform brick structures, Great Bath, most hygienic drainage systems, grain storage barns, and wells are all already well known to the world.
- Dwarka, also known as Lord Krishna's city, also narrates a similar story. Dr S R Rao discovered Dwarka in the archaeological excavation and found that the ancient city (Dwarka Nagar) was well built and settled. There was a wall around the city. The stones used for the construction of buildings did not erode despite the fact that the city was very close to the sea. Two-storey buildings, roads and water system are also found in the city. Copper, bronze and some alloys with zinc mixed up to 34 percent have also been found during the excavation. The size of columns, windows, etc reveals that they were designed with a complete mathematical precision.
- South Indian Tamil saint Appar always travelled with a pickaxe to clear the bushes from the temple towers. He simply followed Balarama. Great Chola king Karikalan built a dam across river Cauvery in Kal Anai. The Grand Anicut was an engineering wonder of ancient Tamils. It was built around the 1st century AD. Big temples of India, the number of which runs into thousands, stand as monumental proof for the engineering skills of Indians. Mamallapuram and other Pallavacave temples are well-known milestones in Indian architecture.
- The Group of Monuments at Hampi are also recognized as a UNESCO World Heritage Site. The Vittala temple—the stone chariot is the most iconic symbol of Hampi. The Virupaksha Temple at Hampi was built in the seventh century by the Chalukya rulers.





Virupaksha and Vithala Temple in Hampi





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Scheme & Syllabus for

B. Tech. (Robotics & Artificial Intelligence)

DEPARTMENT OF ROBOTICS & ARTIFICIAL INTELLIGENCE

2022-23

B. Tech. in Robotics & Artificial Intelligence

Vision:

Empowering people, Partnering in Community Development by achieving expertise requiring the knowledge of state of the art technology in the field of Robotics and Artificial Intelligence. **Mission:**

To impart specialized education in the field of Robotics & Artificial Intelligence that contributes to the socio-economic development of the region and to generate technical manpower with high degree of credibility, integrity and ethical standards by providing vibrant learning environment.

Program Educational Objectives (PEOs):

PEO 1: Demonstrate technical competence in Robotics and Artificial Intelligence and their applications

PEO 2: Design hardware solutions for robotics application and software solutions for implementation of Artificial Intelligence in Robotics

PEO 3: Pursue higher studies to carry out research and development in the area of Robotics and Artificial Intelligence

PEO 4: Engage in lifelong learning, communicate effectively and exhibit leadership skills and demonstrate sensitivity towards professional ethics.

Program Outcomes (POs):

Engineering Graduates will be able to:

PO1: Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.

PO2: Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.

PO3: Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.

PO4: Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.

PO5: Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.

PO6: The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

PO7: Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

PO8: Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.

PO9: Individual and team work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.

PO10: Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.

PO11: Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

PO12: Life-long learning: Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

Program Specific Outcomes (PSOs):

PSO 1: Design the robotic structure for different applications and implementation of control circuits to achieve the desired automation through analytical, logical and problem-solving skills.

PSO 2: Develop software systems for the application of artificial intelligence in robotics.

PSO 3: Apply the knowledge of robotics and Artificial intelligence in the areas of industrial robotics, service robots, exoskeletons, surgical robots, delivery vehicles, autonomous vehicles, and crewless micro aerial vehicles.

Course Numbering Scheme

Branch	Code	Course Level		Course Cod	e	Separator	Version			
Letter	Letter	Number	Number	Number	Number	-	Number			
Branch Code	RI is 2 L	etter code for the	Department	of Robotics &	¢АІ					
Course Level	prerequis L L L	Level is a 1-digit site of a course. evel-1 courses are evel-2 course(s) h evel-3 course(s) h evel-4 course(s) h	e basic cours ave Level-1 ave Level-2	es with no co course(s) as course(s) as	urses as pre- prerequisites prerequisites		ndicates the			
Course Code	number a 00 20 50 50 60 61 61	Code is a 3 Digit r assigned to a cours 01-199 is assigned 001-099 for In 101-199 for Profess 201-299 Electiv 301-399 Electiv 401-499 for Open H 51 – 599 for Voca 01-650 for Profess 51-699 for Ability 01-799 for Course	se based on t I to Profession tegrated Pro- pofessional C sional Election ves under Graves under Graves under Graves Elective Counce tional Education sional Core I ves Enhanceme	he following onal Core Co fessional Cor Core Theory C ve Courses roup I roup II rses ation Courses Lab Courses	guidelines urses e Courses [4 Courses [3 Cr	Credit]	indicates the			
Separator	"_" is use	ed as a separator b	between the (Course code a	and the version	on				
Version	Version is a 1-digit number that can have a value between 1-9 and indicates minor revisions of the same course.									

			III	SEMES	STER								
				÷	Tea	aching H	lours/Wee	k		Exam	ination		
Sl. No.		urse and urse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
				L .	L	Т	Р	J			•	E	
1.	BSC	MA2001-1	Statistics and Probability Theory	MA	3	0	0	0	03	50	50	100	3
2.	IPCC	RI2006-1	Introduction to Robotics	RI	3	0	2	0	03	50	50	100	4
3.	IPCC	RI2001-1	Analog and Digital Circuits	RI	3	0	2	0	03	50	50	100	4
4.	PCC	RI2106-1	Drive Systems for Robot	RI	2	0	2	\checkmark	03	50	50	100	3
5.	PCC	RI2105-1	Data Structures and Algorithms	RI	3	0	0	0	03	50	50	100	3
6.	PCC	RI2603-1	Data Structures and Algorithms Lab	RI	0	0	2	0	03	50	50	100	1
7.	HSMC	HU1004-1	Universal Human Values	HU	1	0	0	0	01	50	50	100	1
8.	AEC	ME1654-1	Innovations and Design Thinking	ME	1	0	0	0	01	50	50	100	1
9.	9. MNC HU1003-1 Kannada (Balake / Samskrithika)		HU	1	0	0	0	-	50	00	50	0	
			TOTAL		17	0	8	-	20	450	400	850	20

			Course presc	ribed to lateral	entry Diploma	holders ad	mitted to	III seme	ster of E	ngineering	g progra	ms			
10	MNC	MA1012 -1	Bridge course Equations	- Calculus	& Differential	MA	3	0	0	0	-	100	0	100	0

			IV S	SEMEST	TER								
				Ŀ.	Те	eaching H	Iours/Wee	ek		Exam	ination		
SI. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J	-	•	•1	F	
1.	BSC	MA2005-1	Linear Algebra and its Applications	MA	3	0	0	0	03	50	50	100	3
2.	IPCC	RI2002-1	Design of Robotic Components	RI	3	0	2	0	03	50	50	100	4
3.	IPCC	RI2005-1	Introduction to Object-Oriented Programming	RI	3	0	2	0	03	50	50	100	4
4.	PCC	RI2111-1	Smart Mobile Robots	RI	2	0	2	\checkmark	03	50	50	100	3
5.	PCC	RI2109-1	Microcontroller and its Application	RI	3	0	0	0	03	50	50	100	3
6.	PCC	RI2604-1	Microcontroller Lab	RI	0	0	2	0	03	50	50	100	1
7.	HSMC	HU2001-1	Enhancing Self Competence	HU	2	0	0	0	03	50	50	100	2
8.	VEC	RI2551-1	Department specific Vocational Education Course (Motion Control using PLC)	RI	0	0	2	0	03	50	50	100	1
9.	HEC	HU1005-1	Essence of Indian Culture	HU	1	0	0	0	-	50	00	50	0
10.	UCC	UC1001-1	Internship – I (Activity based Internship)	RI	Intern complet Lateral er	ship of 2 we ed during th ntry students	Institutional eeks duration e vacations of s have to com e vacation of	(80 - 90 h of I & II Se plete the) to be mesters. Internship	100	00	100	2
			TOTAL		16	2	10	-	24	550	400	950	23

			Course prescribed to lateral entry Diploma hole	lers admit	ted to II	I semeste	er of Engi	neering p	orogram	S			
11	MNC	MA1014-1	Bridge course - Discrete Mathematics & Numerical Methods	MA	3	0	0	0	-	100	0	100	0

			V	SEMEST	TER								
				÷	Tea	aching H	Iours/Wee	ek		Exam	ination		
SI. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
		1			L	Т	P	J					
1.	IPCC	RI2007-1	Kinematics and Dynamics of Robot	RI	2	2	2	0	3	50	50	100	4
2.	IPCC	RI2008-1	Image Processing and its Application	RI	3	0	2	0	3	50	50	100	4
3.	PCC	RI2101-1	Artificial Intelligence and ML	RI	2	2	0	0	3	50	50	100	3
4.	PCC	RI2601-1	AI and ML Lab	RI	0	0	2	0	3	50	50	100	1
5.	PEC	RI2XXX-1	Professional Elective-I	RI	3	0	0	0	3	50	50	100	3
6.	HSMC	HU1006-1	Introduction to IPR	Any Dept.	1	0	0	0	1	50	50	100	1
-	170	RIx6xx-1	Program Specific Ability Enhancement Course	RI	1	0	2	0				100	
7.	AEC	ME1659-1	Research Methodology	Any Dept.	2	0	0	0	3	50	50	100	2
8.	AEC	HU1007-1	Social Connect & Responsibility	Any Dept.	1	0	0	0	1	50	50	100	1
9.	AEC	UM1003-1	Employability Skill Development	RI	1	0	0	0	-	50	00	50	1
		•	TOTAL		14/15	6	8/6	-	20	450	400	850	20

			V	I SEMEST	ſER								
				t.	Те	aching H	lours/Wee	k		Exam	ination		
SI. No.		rse and rse code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J		-	•1		
1.	IPCC	RI2003-1	Micro Aerial Robots	RI	2	2	2	0	3	50	50	100	4
2.	PCC	RI2102-1	Control Engineering	RI	3	0	0	0	3	50	50	100	3
3.	PCC	RI2602-1	Control Engineering Lab	RI	0	0	2	0	3	50	50	100	1
4.	PEC	RIxxxx-1	Professional Elective – II [Group-1]	RI	3	0	0	0	3	50	50	100	3
5.	PEC	RIxxxx-1	Professional Elective -III [Group-2]	RI	3	0	0	0	3	50	50	100	3
6.	OEC	XXX5XX-1	Open Elective –I	Any Dept.	3	0	0	0	3	50	50	100	3
7.	HSMC	MG1003-1	Management & Entrepreneurship	Any Dept.	3	0	0	0	3	50	50	100	3
8.	AEC	HU1008-1	Life Skills for Engineers	Any Dept.	1	0	0	0	1	50	50	100	1
			TOTAL		17	4	4	-	22	400	400	800	21

			VII S	EMESTI	ER								
				÷	Те	aching H	Iours/We	ek		Exam	ination		
Sl. No.		se and se code	Course Title	Teaching Dept.	Theory Lecture	Tutorial	Practical/ Drawing	PBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
					L	Т	Р	J			•1		
1.	IPCC	RI2004-1	Industry 4.0 and IOT	RI	2	2	2	0	3	50	50	100	4
2.	PCC	RI2605-1	Robot Programming and Simulation Lab	RI	0	0	2	0	3	50	50	100	1
3.	PEC	RIXXXX-1	Professional Elective -IV [Group-1]	RI	3	0	0	0	3	50	50	100	3
4.	PEC	RIXXXX-1	Professional Elective – V [Group-2]	RI	3	0	0	0	3	50	50	100	3
5.	OEC	XXX5XX-1	Open Elective –II	Any Dept.	3	0	0	0	3	50	50	100	3
6.	HSMC	MG1002-1	Financial Management	Any Dept.	3	0	0	0	3	50	50	100	3
7.	HEC	HU1009-1	Indian Knowledge Systems	Any Dept.	1	0	0	0	-	50	00	50	1
8.	UCC	UC2002-1	Major Project Phase I	RI	-	-	4	-	-	100	00	100	2
			TOTAL		15	02	8	-	18	450	300	750	20

			VII	I SEME	STER								
				÷	Tea	aching H	Iours/Wee	ek		Exam	ination		
SI. No.	000	irse and irse code	Course Title	Teaching Dept.	T Theory Lecture	+ Tutorial	d Drawing	- BBL	Duration in hr	CIE Marks	SEE Marks	Total Marks	Credits
1.	UCC	UC2001-1	Internship- II (Societal internship and Research/Industry Internship)		Mandato 2 weeks Internsh 6 weeks Internshi a total o be comp durin	(80 - 90) ip / Indu (240 - 2) ip / Indus f 8 week leted in o in the values	etal interns b) h) and Ro stry Intern 70 h) or Ro stry interns s $(320 - 30)$ one/two st cation peri VII semes	esearch ship of esearch ship for 60 h)to retches ods	3	50	50	100	8
2.	UCC	UC3001-1	Major Project Phase II		researc institut Two interac	ch institute contact h contact h	arry out pro te/industry of Excelle ours /weel ween the pro l students.	/intra ences. x for	3	100	100	200	8
			TOTAL		-	-	-	-	6	150	150	300	16



List of Vocational Education Courses (VEC)					
Code	Elective Course Title				
RI2551-1	Motion control using PLC				
RI2552-1	Metrology and Measurement				

	Program Specific Ability Enhancement Course (AEC)					
Course Code	Course Code Course Title					
RI2651-1	Data Acquisition and Measurements					
RI2652-1	Engineering Economics					
RI2653-1	PLC Control of Hydraulic and Pneumatic Circuits					

0	Open Electives offered to other branch students by the Department [OEC]						
Course Code	Course Title						
RI2501-1	Autonomous Mobile Robots						
RI2502-1	Medical Robotics						
RI2503-1	PLC Control of Hydraulic and Pneumatic Circuits						

	List of Professiona	l Elective Cou	urses [PEC]							
	Group-1 Group-2									
	Automation Stream									
Code	Elective Course Title	Code	Elective Course Title							
RI2201-1	Automation in Manufacturing Systems	RI2301-1	Digital Manufacturing							
RI2202-1	CNC Machining	RI2302-1	Intelligent Manufacturing							
RI2203-1	Industrial Automation and Control	RI2303-1	Mechatronics							
RI2204-1	Medical Robotics	RI2304-1	Robot Gripper Design							
RI2205-1	Micro-Electro-Mechanical Systems									
	Signal Processing a	nd Programn	ning Stream							
Code	Elective Course Title	Code	Elective Course Title							
RI2211-1	Data Visualization	RI2311-1	Augmented Reality and Virtual Reality							
RI2212-1	Introduction to MATLAB Programming	RI2312-1	Computer Vision							
RI2213-1	Mobile Application Development	RI2313-1	PLC and SCADA							
RI2214-1	Virtual Instrumentation	RI2314-1	Signal Processing							
	Artificial In	telligence Str	eam							
Code	Elective Course Title	Code	Elective Course Title							
RI2221-1	Cloud Computing	RI2321-1	Autonomous Vehicles							
RI2222-1	Design and analysis of Algorithms	RI2322-1	Basics of Natural Language processing (NPTEL)							
RI2223-1	Machine Learning with Python	RI2323-1	Business Analytics							
RI2224-1	Managing Information System									



Courses from Basic Science

Cou	STATISTICS &	MA2001-1	Course Type:	BSC
	ching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03
	al Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
	requisite	MA1002-1		50150
110	•	epartment: Ma	thematics	
Cour	se Objectives:			
1.	Understand the basic principle	es of probabilit	v Baves theorem unde	rstand the
	definitions of discrete, continuo	•	5	
	variance and covariance of rand	-		
2.	Define the binomial, uniform, Po		ial and normal random va	riables use
	these principles in problem solv	•		
3.	Understand the concepts of		lation and sample vari	iables and
	attributes. Learn about moment		•	
	data and various distributions.		in studying various charac	
		UNIT-I		
PRO	BABILITY THEORY	•••••		16 Hour
inite	e sample space, probability, condit	tional probability	v and independence. Bave	s' theorem
Two-	ions, cumulative distribution funct dimensional random variable: join butions: Binomial, Poisson, Unifor	t pdf, marginal	pdf's , covariance (CO1)	probabilit
Two- Distri	dimensional random variable: join	t pdf, marginal m, Normal and es and simple p	n and variance. pdf's , covariance (CO1) exponential distributions.	
Two- Distri Mom	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- properti	nt pdf, marginal m, Normal and es and simple p UNIT-II	n and variance. pdf's , covariance (CO1) exponential distributions.	·
Two- Distri Mom SAM	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI	nt pdf, marginal m, Normal and es and simple p UNIT-II IMATION	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2)	14 Hour
Two- Distri Mom SAM Rand	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample	nt pdf, marginal m, Normal and es and simple p UNIT-II IMATION e variance, samp	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, 0	14 Hour Central lim
Two- Distri <u>Mom</u> SAM Rand theor	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p	nt pdf, marginal m, Normal and o es and simple po UNIT-II IMATION e variance, sample roportions and	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, 0	14 Hour Central lim
Two- Distri <u>Mom</u> SAM Rand theor	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distributior	nt pdf, marginal m, Normal and es and simple p UNIT-II UNIT-II IMATION e variance, samp roportions and n of variance.	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik	14 Hour Central lim oution, Ch
Two- Distri Mom SAM Rand theor squar Estim	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution nation: Point estimation, interval es	nt pdf, marginal m, Normal and es and simple p UNIT-II UNIT-II IMATION e variance, samp roportions and n of variance.	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik	14 Hour Central lim oution, Ch
Two- Distri <u>Mom</u> SAM Rand theor squar Estim (CO3)	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution ation: Point estimation, interval estimation,	nt pdf, marginal m, Normal and es and simple p UNIT-II UNIT-II IMATION e variance, samp roportions and n of variance.	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik	14 Hour Central lim Dution, Ch
Two- Distri Mom SAM Rand theor squar Estim (CO3) CURV	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution hation: Point estimation, interval est) //E FITTING AND REGRESSION	nt pdf, marginal m, Normal and es and simple pr UNIT-II IMATION e variance, sample roportions and n of variance. timation, confid	n and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik ence intervals for means a	14 Hour Central lim oution, Ch nd variance
Two- Distri <u>Mom</u> SAM Rand theor squar squar (CO3 (CO3) CURN Least	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution ation: Point estimation, interval est) /E FITTING AND REGRESSION square principle, fitting of straigh	It pdf, marginal m, Normal and es and simple part UNIT-II IMATION e variance, sample roportions and n of variance. timation, confident t lines, polynom	and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik ence intervals for means a	14 Hour Central lim oution, Ch nd variance
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Two- Distri Mom SAM Rand theor squar squar (CO3 (CO3 CUR) Least	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution ation: Point estimation, interval est) /E FITTING AND REGRESSION square principle, fitting of straigh	It pdf, marginal m, Normal and es and simple pr UNIT-II IMATION e variance, sample roportions and n of variance. timation, confident the station of the station of correlation	and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik ence intervals for means a	14 Hour Central lim oution, Ch nd variance
Two- Distri Mom SAM Rand theor squar Estim (CO3) CURV Least Corre	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution ation: Point estimation, interval est) /E FITTING AND REGRESSION square principle, fitting of straigh	It pdf, marginal m, Normal and es and simple part UNIT-II IMATION e variance, sample roportions and n of variance. timation, confident t lines, polynom	and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik ence intervals for means a	14 Hour Central lim oution, Ch nd variance es.
Two- Distri Mom SAM Rand theor squar Estim (CO3) CUR Least Corre STOC	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution hation: Point estimation, interval est) VE FITTING AND REGRESSION square principle, fitting of straigh elation, Rank correlation, Coefficien	It pdf, marginal m, Normal and es and simple pr UNIT-II IMATION e variance, sample roportions and n of variance. timation, confident t lines, polynom nt of correlation	and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrik ence intervals for means a iials and exponential curve , Linear regression. (CO4)	14 Hour Central lim oution, Ch nd variance es. 10 Hour
Two- Distri Mom SAM Rand theor squar Estim (CO3) CURV Least Corre Stoch	dimensional random variable: join butions: Binomial, Poisson, Unifor ent generating function- propertion PLING DISTRIBUTION AND ESTI om Sample, Sample mean, sample rem, sampling distributions of p re distribution. Sample distribution ation: Point estimation, interval est) /E FITTING AND REGRESSION square principle, fitting of straigh elation, Rank correlation, Coefficien CHASTIC PROCESS nastic processes, stochastic matric	It pdf, marginal m, Normal and es and simple pr UNIT-II IMATION e variance, sample roportions and n of variance. timation, confident t lines, polynomint of correlation UNIT-III	and variance. pdf's , covariance (CO1) exponential distributions. roblems.(CO2) ling distribution of mean, of sums. Student's t-distrib ence intervals for means a nials and exponential curve , Linear regression. (CO4)	14 Hour Central lim oution, Ch nd variance es. 10 Hour ces, Marko
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	(Deen	med to be University)
	1.	Apply the concepts of probability, including discrete and continuous random variables, probability distributions, conditioning, independence, expectations, and
		variances.
	2.	Define and explain the different statistical distributions (e.g., Normal, Binomial,
		Poisson) and the areas of their application.
	3.	Explain the concept of correlation and the difference between positive and negative
		correlation. Compute the correlation coefficient, r , Explain and apply the least square
		errors method numerically and algebraically to find the curve of best fit.
	4.	Able to apply the central limit theorem to sampling distribution. Translate real-world
		problems into probability models.
	5.	Identify and apply the most appropriate stochastic process technique for a given
		applied problem.
		Calculate probabilities of absorption and expected hitting times for discrete time
		Markov chains with absorbing states.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes $ ightarrow$	1	2	3	4	5	6	7	8	9	10	11	12	PS	O↓
↓ Course Outcomes													1	2
MA2001-1.1	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA2001-1.2	2	2	-	-	-	-	-	-	-	-	-	-	-	-
MA2001-1.3	3	1	-	-	-	-	-	-	-	-	-	-	-	-
MA2001-1.4	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA2001-1.5	3	2	-	-	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

NITTE

1.	Paul L Meyer, "Introductory Probability and Statistical Applications", Addison-Wesley
	Publishing Company, 2 nd Edition (Reprint), 1970.

2. Hogg and Craig, "Introduction to mathematical Statistics", Pearson Education, New Delhi, 6th Edition.

REFERENCE BOOKS:

1. Schaum Outlines, "Probability and Statistics", Mc Graw Hill, 3rd edition, 2010.

- 2. T. Veerarajan, "Engineering Mathematics", McGraw-Hill, New Delhi, 2008.
- **3.** B. V. Ramana, "Higher Engineering Mathematics", Tata Mc Graw –Hill, New Delhi,2010.

E Books / MOOCs/ NPTEL

- 1. https://nptel.ac.in/courses/110107114
- 2. https://nptel.ac.in/courses/111105090
- **3.** https://nptel.ac.in/courses/111102098



	urse Code:	MA2005-1	Course Type:	BSC
Теа	ching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03
Tot	al Teaching Hours:	40+0+0	CIE + SEE Marks:	50+50
Pre	requisites	MA1002-1, MA	1007-1	
	Teaching D	epartment: Mat	hematics	
Cour	rse Objectives:			
1.	Learn to apply elementary row	operations to sol	ve linear systems of equ	ations and
	find the eigenvalues and eigenv	vectors of a matrix	κ.	
2.	Find the eigenvalues and eigen	nvectors of a squ	are matrix using the ch	aracteristic
	polynomial and will know how	to diagonalize a n	natrix, when this is possik	ole
3.	Understand real vector spa	aces and subsp	aces, linear independ	ence and
	dependence, and find basis ar			
	space and null space of a matri			,
4.	Define a linear transformation a		ix associated with it: det	ermine the
	kernel and range of a transform			
	an orthonormal basis.			gonar ana
5.	Learn basic concepts of real qu	adratic forms de	composition of matrices	and solve
J.	problems on the same.	iadratic forms, de	composition of matrices	
	problems on the same.	UNIT-I		
solut	nentary transformation of a matrix tion of system of linear equation	ns - Gauss elimi	nation method, LU Dec	istency an
solut meth Trace symr	5	ns - Gauss elimi Gauss Seidel met n values of a matr	nation method, LU Dec thod. ix, Eigen values and Eige	istency and compositio n vectors c
solut meth Trace symr	tion of system of linear equation of and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r	ns - Gauss elimi Gauss Seidel met n values of a matr	nation method, LU Dec thod. ix, Eigen values and Eige	istency and composition n vectors c eigen vecto
solut meth Trace symr of sq Vect	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization.	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e	istency and composition n vectors c eigen vector 08 Hour
solut meth Trace symr of sq Vect Vecto	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization.	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e	istency and composition n vectors c eigen vector 08 Hour
solut meth Trace symr of sq Vect Vecto	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent redinates, row space, column space	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e	istency and composition n vectors c eigen vector 08 Hour dimensior
solut meth Trace symr of sq Vect Vecto Coor Line	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent rdinates, row space, column space ar Transformations	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space.	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and	istency and compositio n vectors c eigen vecto 08 Hour dimensior 07 Hour
solut meth Trace symr of sq Vecto Coor Linea	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent rdinates, row space, column space ar Transformations ar transformations, algebra of line	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran	istency and composition n vectors c eigen vecto 08 Hour dimension 07 Hour sformation
solut meth Trace symr of sq Vect Vecto Coor Line Line by m	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent redinates, row space, column space ar Transformations ar transformations, algebra of line matrices, isomorphism, Range and	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation Null space of a	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran linear transformation. Ra	istency and composition n vectors co eigen vecto dimension 07 Hour sformation ink – nullit
solut meth Trace symr of sq Vect Vect Coor Linea by m theo	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power requare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent dinates, row space, column space ar Transformations ar transformations, algebra of line matrices, isomorphism, Range and rem. Inner products, orthogonal s	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation Null space of a	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran linear transformation. Ra	istency and composition n vectors co eigen vecto dimension 07 Hour sformation ink – nullit
solut meth Trace symr of sq Vect Vect Coor Linea by m theo	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power requare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent dinates, row space, column space ar Transformations ar transformations, algebra of line matrices, isomorphism, Range and rem. Inner products, orthogonal s	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation Null space of a	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran linear transformation. Ra	istency and composition n vectors co eigen vecto dimension 07 Hour sformation ink – nullit
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solut meth Trace symr of sq Vect Vecto Linea by m theo proce Mat i	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power r quare matrices. Diagonalization. For Space or spaces, subspaces, linearly dependent dinates, row space, column space ar Transformations ar transformations, algebra of line natrices, isomorphism, Range and rem. Inner products, orthogonal s ess. rix Decompositions	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation Null space of a l ets of projections UNIT-III	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran linear transformation. Ra 5, Gram-Schmidt's orthog	istency and composition n vectors c eigen vector dimension 07 Hour sformation nk – nullit gonalizatio
solut meth Trace symr of sq Vect Vecto Coor Linea by m theo proce Mat	tion of system of linear equation nod and approximate solution by e, relation between trace and Eigen metric matrices, Rayleigh's power requare matrices. Diagonalization. Ear Space or spaces, subspaces, linearly dependentes, row space, column space dinates, row space, column space ar Transformations ar transformations, algebra of line natrices, isomorphism, Range and rem. Inner products, orthogonal s ess. rix Decompositions dratic forms, QR-factorization, lea principal component analysis.	ns - Gauss elimi Gauss Seidel met n values of a matr nethod to find the UNIT-II endent and indepe and null space. ar transformation Null space of a l ets of projections UNIT-III	nation method, LU Dec thod. ix, Eigen values and Eige largest eigen value and e endent vectors, basis and s, representation of tran linear transformation. Ra s, Gram-Schmidt's orthog ems, singular value dec	istency and composition n vectors c eigen vector dimension 07 Hour sformation nk – nullit gonalizatio
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Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

Ī		Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 202
	3.	Analyze finite dimensional vector spaces and subspaces over a field and their
		properties, including the basis structure of vector spaces.
	4.	Relate matrices and linear transformations, apply the properties of inner product and
		determine orthogonality on vector spaces and orthogonal bases.
	5.	Derive and utilize Quadratic forms, SVD and QR factorization of the matrix for
		efficiently solving problems in practice.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	O↓
↓ Course Outcomes													1	2
MA2006-1.1	3	1	-	-	-	-	-	-	-	-	-	-	-	-
MA2006-1.2	2	3	-	-	-	-	-	-	-	-	-	-	-	-
MA2006-1.3	2	1	-	-	-	-	-	-	-	-	-	-	-	-
MA2006-1.4	2	2	-	-	-	-	-	-	-	-	-	-	-	-
MA2006-1.5	3	2	-	-	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTE	BOOKS:
1.	Kenneth Hoffman And Ray Kunze, "Linear Algebra", Prentice-Hall, 2 nd edition, 1971
2.	David C. Lay, "Linear Algebra and Its Applications", Pearson Education, Inc., 5 th edition,
	2016.
REFER	RENCE BOOKS:
1.	Seymour Lipschutz And Marc Lars Lipson, "Schaum's outlines - Linear Algebra",
	McGraw-Hill, 4 th Edition, 2002.
2.	Gilbert Strang, "Introduction to Linear Algebra", Wellesley-Cambridge Press, 5 th
	Edition, 2016.
3.	
	Chapman and Hall, 4 th edition, 2021.
4.	Sheldon Axler, "Linear Algebra Done Right", Springer Nature, 3 rd Edition, 2015.
E Boo	ks / MOOCs/ NPTEL
1.	https://nptel.ac.in/courses/111101115
2.	https://archive.nptel.ac.in/courses/111/106/111106135/
3.	https://nptel.ac.in/courses/110104024
L	



CALCULUS & DIFFERENTIAL EQUATIONS									
(COMMON TO AM\CC\CS\IS\DS\RI)									
Course Code: MA1012-1 Course Type: MNC									
Teaching Hours/Week (L: T: P: S): 3:0:0:0 Credits:									
Total Teaching Hours:40+0+0CIE + SEE Marks:100+00									
Teaching Department: Mathematics									

Mandatory Non – credit course (MNC):

This course is prescribed to the lateral entry Diploma holders admitted to III semester of BE/B.Tech., programs, they shall attend the classes during the respective semesters to complete all the formalities of the course and appear for the Continuous Internal Evaluation (CIE). In case, any student fails to register for the said course/fails to secure the minimum 40 % of the prescribed CIE marks, he/she shall be deemed to have secured an F grade. In such a case, the student has to fulfill the requirements during subsequent semester/s to appear for CIE.

MNC Courses shall not be considered for vertical progression as well as for the calculation of SGPA and CGPA, but completion of the courses shall be mandatory for the award of degree

Course Objectives:

This course will enable the students to master the basic tools of differential calculus, partial differentiation, Vector differentiation and Integration and become skilled for solving problems in science and engineering.

UNIT-I

DIFFERENTIAL CALCULUS

Polar curves, angle between the radius vector and the tangent, angle of intersection of two curves, derivatives of arcs and radius of curvature -cartesian, parametric and polar forms (No Derivation).

Taylor's theorem for functions of single variable. Mean value theorems.

PARTIAL DIFFERENTIATION

MULTIPLE INTEGRALS

Partial derivatives of simple functions, Total differentiation - differentiation of composite and implicit functions. Taylor's theorem for functions of two variables, maxima and minima for functions of two variables.

UNIT-II

VECTOR DIFFERENTIAL CALCULUS

Vector algebra(review), scalar and vector valued functions, gradient, directional derivative and hessian of multivariable function, Divergence and curl of a vector valued function.

ORDINARY AND PARTIAL DIFFERENTIAL EQUATIONS	08 Hours
Ordinary differential equations(review), linear and nonlinear differential equation	ns. Second
and higher order linear differential equations with constant coefficients.	

Formation of partial differential equations by eliminating arbitrary constants and arbitrary functions. Solution of P.D.E by the method of separation of variables.

UNIT-III

Double integrals and triple integrals, Evaluation by change of order of integration, change of variables and applications to area and volume.

07 Hours

08 Hours

07 Hours

10 Hours

N	NITTE
~	(Deemed to be University)

Cour	Course Outcomes: At the end of the course student will be able to								
1.	Apply the concept of radius of curvature and mean value theorems.								
2.	Learn the concept of partial differentiation of a function with two or more								
	independent variables, apply them to solve engineering problems and examine the								
	given function for its extrema.								
3.	Solve the vector functions and their derivatives for engineering applications.								
4.	Apply the concepts of ordinary and partial differential equations in engineering								
	problems.								
5.	Apply the notion of multiple integrals to find areas and volumes.								

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	O↓
↓ Course Outcomes													1	2
MA1012-1.1	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1012-1.2	2	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1012-1.3	3	1	-	-	-	-	-	-	-	-	-	-	-	-
MA1012-1.4	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1012-1.5	3	2	-	-	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	B.S. Grewal,	"Higher	Engineering	Mathematics",	Khanna	Publications,	43 rd	Edition,
	2015.							

- **2.** Erwin Kreyszig, "Advanced Engineering Mathematics", John Wiley and Sons, 10th Edition (Reprint), 2016.
- **3.** Murray R. Spiegal, "Vector Analysis", Schuam Publishing Co.

REFERENCE BOOKS:

1.	G. B. Thomas and R. L. Finney, "Calculus and Analytic Geometry", Pearson, 2002.									
2.	T. Veerarajan, "Engineering Mathematics", McGraw-Hill, New Delhi, 2008.									
3.	B. V. Ramana, "Higher Engineering Mathematics", Tata Mc Graw –Hill, New									
	Delhi,2010.									



BRIDGE COURSE - DISCRETE MATHEMATICS & NUMERICAL METHODS									
(COMMON TO AM\CC\CS\IS\DS\RI)									
Course Code: MA1014-1 Course Type: MNC									
Teaching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	00						
Total Teaching Hours:40+0+0CIE + SEE Marks:100+00									
Teaching Department: Mathematics									

Mandatory Non – credit course (MNC):

This course is prescribed to the lateral entry Diploma holders admitted to III semester of BE/B.Tech., programs, they shall attend the classes during the respective semesters to complete all the formalities of the course and appear for the Continuous Internal Evaluation (CIE). In case, any student fails to register for the said course/fails to secure the minimum 40 % of the prescribed CIE marks, he/she shall be deemed to have secured an F grade. In such a case, the student has to fulfill the requirements during subsequent semester/s to appear for CIE.

MNC Courses shall not be considered for vertical progression as well as for the calculation of SGPA and CGPA, but completion of the courses shall be mandatory for the award of degree

Course Objectives:

This course will enable the students to master the basic tools of set theory and relations, propositional and predicative logics, numerical methods, Fourier series and transforms and become skilled for solving problems in science and engineering.

UNIT-I

Set Theory and Logic

Sets- operations on sets, product sets and partitions (review)

Relations- representation of relations as matrices and digraphs, equivalence relations. Functions- permutations functions, functions for computer science.

Fundamentals of logic-

Propositional logic, logical operations(review), rules of inference Predicates calculus.

Graph Theory

Graphs: Basic terminologies, some special simple graphs, bipartite graphs, adjacency matrices, incidence matrices, graph isomorphism, connectivity-vertex and edge connectivity, Euler and Hamiltonian graphs and their applications, planar graphs, graph coloring and their applications.

UNIT-II

Numerical Methods

Roots of algebraic and transcendental equations- Newton Raphson method, Regula Falsi method.

Numerical solution of ordinary differential equations- Taylor's series method, Modified Euler's method and Runge –Kutta method of fourth order.

Numerical solution of partial differential equations- Classification of partial differential equations, examples, solution of Laplace and Poisson equations by standard five-point formulae, solution of heat and wave equations by explicit method.

07 Hours

08 Hours

15 Hours



UNIT-III Fourier Series and Transforms

10 Hours

Periodic functions, Euler's formulae, Fourier series of odd and even functions, functions with arbitrary period, half range series. Fourier transform, inverse Fourier transform, Convolution theorem, Fourier sine and cosine transforms.

Cour	Course Outcomes: At the end of the course student will be able to							
1.	Represent a relation in terms of matrix and digraph, apply permutation functions for							
	encoding and decoding simple text messages and establish by deduction the validity							
	of an argument using inference rules. Identify suitable data structure for representing							
	a graph, apply the concept of connectivity in real life problems							
2.	Identify suitable data structure for representing a graph, apply the concept of							
	connectivity in real life problems.							
3.	Apply numerical methods to find solutions of algebraic equations and ordinary							
	differential equations.							
4.	Apply numerical methods to solve partial differential equations							
5.	Apply the analytical technique to express periodic function as a Fourier sine and							
	cosine series and apply the concepts of Fourier- transforms to solve engineering							
	problems.							

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	SO↓
↓ Course Outcomes													1	2
MA1014-1.1	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1014-1.2	3	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1014-1.3	2	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1014-1.4	2	2	-	-	-	-	-	-	-	-	-	-	-	-
MA1014-1.5	3	2	-	-	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** B.S. Grewal, "Higher Engineering Mathematics", Khanna Publications, 43rd Edition, 2015.
- **2.** Erwin Kreyszig, "Advanced Engineering Mathematics", John Wiley and Sons, 10th Edition (Reprint), 2016.

REFERENCE BOOKS:

1.	T. Veerarajan, "Engineering Mathematics", McGraw-Hill, New Delhi, 2008.
2.	B. V. Ramana, "Higher Engineering Mathematics", Tata Mc Graw –Hill, New Delhi,2010.



Integrated Professional Core Courses



	Deemed to be University) Analog	and Digital	Circuits								
Cou	rse Code:	RI2001-1	Course Type:	IPCC							
Teac	ching Hours/Week (L: T: P: S):	3:0:2:0	Credits:	04							
Tota	al Teaching Hours:	40+0+26	CIE + SEE Marks:	50+50							
Prer	equisite	EC1001-1									
	Teaching Depart	ment: Robotic	s & AI Engineering								
Cours	se Objectives:										
1.	To design linear amplifier using MOSFETs.										
2.	To design application circuits usi	ng OP-AMPS									
3.	Illustrate simplification of Algebr	aic equations ι	ising Karnaugh Maps								
4.	Design digital circuits for decode	ers, encoders, a	nd multiplexers								
5.	To design power supply circuits.										
		UNIT-I									
Swite	hes & Amplifiers			04 Hours							
MOSE	FET Operation as a switch, oper	ations as a lir	near amplifier (CS amplifie	er and source							
follov	ver)										
Oper	ational Amplifiers			07 Hours							
	t voltage and currents, offset com			rence							
Ampl	ifier, Instrumentation Amplifier, Br	idge circuits, P	recision Rectifiers.								
	Circuit, Voltage Level Detectors ar	nd Schmitt Trig	ger, Active Filters.	I							
Appli	ications using Linear ICs			04 hours							
	cations using Linear ICs: Data Con		5	ers: weighted							
Resist	tor, R-2R Digital to Analog Conver	ters, SAR ADC,	555 timer applications.								
		UNIT-II									
	gates & Principles of combinat			06 Hours							
	an algebra, De-Morgan's theore	•	-								
	ersal gates, Realization of Boolean	•	• •								
	s, Introduction to Min/Max term e	•	5 1	ons from truth							
	s, Karnaugh map - 3, 4 variables, 1		pecified functions.								
	sis and Design of Combination			05 Hours							
	rs and Subtractors, Cascading add	lers/subtractors	s, Multiplexers, Demultiplex	kers,							
	ders, Encoders										
	lops and its Applications:			04 Hours							
	Bistable element, Latches, SR latc			lop, I flip flop,							
JK flip	o flops, Edge triggered flip flop, Ch		uations.								
D		UNIT-III		05.11.							
	er amplifier			05 Hours							
	pull, H bridge, PWM generation										
	e <mark>r supply –</mark> Istore Linger regulatore Curitching	Mada Data 1.1	an Duale Danulate - Dan - 1 D	05 Hours							
-	lators- linear regulators, Switching	wode Regulat	or, Buck Regulator, Boost R	egulator, Buck							
Boost	Regulator										
_		ted List of Exp	eriments								
1.											
2.											
3.	OPAMP – as Comparator, Ar	nplifier (inv and	a non inv) , LPF, HPF (Hardy	ware)							

		(Curr	iculu	m —]	B.Te	ch. (Ro	obotics &	& Artific	cial Intelligenece): 2022
4.	Astable and monostable (555) (H	lardv	vare	e)						
5.	Verification of logic gates (Simul	atior	ו)	-						
6.		Designing Adders and Subtracters (Simulation)								
7.		Design of Multiplexer and Demultiplexer (Simulation)								
8.							,			
9.		(
10		Simu	latio	n)						
11	9				որ)					
	Demonstra					onte				
1.				-						
	Handling measuring equipment:		unne	eter	and	כטג	50			
2.	Introduction to the simulation to		-l		•11-1-					
	se Outcomes: At the end of the cours									
1.	Design switching circuits and linear a									
2.	Analyse the working principle of OP-					opli	catio	n circ	uits	
3.	To realise the digital circuit using Kar	้ทลนดู	gh r	nap	S					
4.	To design the digital circuit such as c	leco	ders	s, er	ncoc	lers	mul	tiplex	ers, B	oolean function
	generators									
5.	Analyse power supply design circuits									
Cour	se Outcomes Mapping with Program	n Ou	tco	me	s &	PS	C			
	Program Outcomes \rightarrow 1 2 3 4	5	6	7	8	9	10	11	12	PSO↓
	ourse Outcomes	-	-	-	-					
¥ -	RI2001-1.1 3									
	RI2001-1.2 3									
	RI2001-1.3 3									
	RI2001-1.4 3									
	RI2001-1.5 3									
	1: Low 2: Medium 3: High						1			
TEXT	BOOKS:									
	1. Sedra /Smith, "Microelectronic Cire	ruits"	6tl	٦ Ec	litior	0	vford	Unive	orsity	Press-New
	Delhi,2013.	curts	U	20	incioi	ı, U	XIOI G	Oniv	sisity	
	2. Jacob Millman & Christos C. Ha	Ikias	, "I	ntec	rate	ed E	lectr	onics".	McG	Graw Hill
	Publications, 2 nd Edition, 2011.			3	,	_		- 1		
	a. M.D Singh and K B Khanchandani, F	0\\/\PI	r ele	ctro	nics	. 2 ^{nc}	editi	on Tat	a Mc-	-Grow Hill 2009
	ISBN: 0070583897	0,000		.cuc		,	cart	Sin, rut		C. C. W. T. III, 2003,
REFEF	RENCE BOOKS:									
	1. Behzad Razavi, "Fundamentals of M	icroe	lect	roni	cs".	Wile	y 201	L3.		
	-						-		n/" 「	
	2. Nashelesky & Boylestead, "Electr Edition.2015.	onic	De	vice	SO		rcuit	Theo	ry, F	'HI, II
		4:			://	anc				
	3. Jacob Millman & Arvin Grabel, "N Publications,1987	licroe	elec	tron	ICS	Zire	Ealt	ion, iv	IcGrav	V HIII
		darn		ctra	nicc	200	Inct	umon	tation	and Mascuring
	4. A. D. Helfrick and W.D. Cooper, "Mo Techniques, Pearson, 1 st edition, 202							umen	เลเเบท	and measuring
F Roo	ks / MOOCs/ NPTEL	LJ, IS	אוטי.	570	درر	اررے	5005			
	1. Electronics for analog signal process	sing	I Dr	of k	Ra	hal	richn	a Rao		ladras
		-								
	2. NPTEL Course on Analog Electronic Circuits by Prof. Pradip Mandal, IIT Kharagpur									



Course Code	RI2002-1	Course Type:	IPCC
Teaching Hours/Week (L: T:P: S)	(3:0:2:0)	Credits:	04
Total Hours of Pedagogy	50	CIE + SEE Marks:	50+50
Prerequisite	ME 1003-1,	ME 1002-1	
Teaching Depa	artment: Robo	tics & AI Engineering	
Course objectives:			
1. Define and explain various te	rms connected	to the design of maching	ine elements-I like
static strength, fatigue stren	gth, Impact str	esses, theories of failu	res, rigidity-based
design, factor of safety, and s	tress concentra	tion etc.	
2. Explain how engineering desi	ign make use o	f the principles learnt ir	n science courses
and identify their practical ap	plications.		
3. Design and analyze proble	m-solving skil	l in design of machir	ne elements with
appropriate assumptions and		<u> </u>	
4. Develop student's ability to	understand th	ne Stresses in threaded	d Fasteners under
different loading conditions a	& Evaluate the	forces, stresses, displac	ements and other
related parameters necessary	to design diffe	rent springs.	
5. Demonstrate the ability to de	velop designs f	or different gears.	
	Unit-I		
Introduction			
Meaning of design with special refe	Terree to machi	ne design Deminion e	
of several types of designs. Concept	t of design		
of several types of designs. Concept Mechanical properties of materials.	•	nd Hooke's law. Stress	strain diagram for
Mechanical properties of materials,	Stress, Strain a		-
Mechanical properties of materials, brittle and ductile materials, Factor of	Stress, Strain a of safety, True s	stress and strain, Calcula	ation of stresses in
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section	Stress, Strain a of safety, True s ons, Stresses due	stress and strain, Calculate to temperature change	ation of stresses in e, Shear stress and
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons	stress and strain, Calcula e to temperature change stants and relations betw	ation of stresses in e, Shear stress and veen them.
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static lo	stress and strain, Calcula e to temperature change stants and relations betw bads, Theories of elastic	ation of stresses in e, Shear stress and veen them. failure – Maximum
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory,	stress and strain, Calcula e to temperature change stants and relations betw bads, Theories of elastic Distortion energy theor	ation of stresses in e, Shear stress and veen them. failure – Maximum
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum shea	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory,	stress and strain, Calcula e to temperature change stants and relations betw bads, Theories of elastic Distortion energy theor	ation of stresses in e, Shear stress and veen them. failure – Maximum
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum shea	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory,	stress and strain, Calcula e to temperature change stants and relations betw bads, Theories of elastic Distortion energy theor	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle
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Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor.	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in t	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor.	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of
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Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loadid joints.	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen <u>Unit-II</u> threaded Faste ing, shear loadi ntrifugal stress	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric s in a belt, Power tran	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted
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Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loadid joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transme	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static lo ar stress theory, s, Stress concen <u>Unit-II</u> threaded Faste ing, shear loadi ntrifugal stress hitted, Simple ne atic and dynam	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor stration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted smitted, effect of alent bearing load,
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loading joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transmom Rolling contact bearings: Types, stat load-life relationship, bearing life,	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress hitted, Simple ne atic and dynam load factor, se	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted smitted, effect of alent bearing load, m manufacturer's
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Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loadid joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transmom Rolling contact bearings: Types, stat load-life relationship, bearing life, catalogue; ball and roller bearings	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress itted, Simple me atic and dynam load factor, se s, design for se	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro variable load and spec	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted ismitted, effect of alent bearing load, im manufacturer's ed, bearings with es.
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loadid joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transmom Rolling contact bearings: Types, stat load-life relationship, bearing life, catalogue; ball and roller bearings	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress itted, Simple me atic and dynam load factor, se s, design for se	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro variable load and spec	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted ismitted, effect of alent bearing load, im manufacturer's ed, bearings with es.
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue load joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transmom Rolling contact bearings: Types, stat load-life relationship, bearing life, catalogue; ball and roller bearings	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress itted, Simple ne atic and dynam load factor, se s, design for %, bearing mate Unit-III	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro variable load and spec- erials and their propertie	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted smitted, effect of alent bearing load, m manufacturer's ed, bearings with es. 15 Hours
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue loading joints. Belt Drives: Ratio of tensions, Centrifugal tension on power transmost Rolling contact bearings: Types, stat load-life relationship, bearing life, catalogue; ball and roller bearings probability of survival other than 900	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static lo ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress litted, Simple ne atic and dynam load factor, so s, design for so %, bearing mate Unit-III mptions, deriva	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro variable load and spec- erials and their propertie	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted smitted, effect of alent bearing load, m manufacturer's ed, bearings with es. 15 Hours ms, polar modulus,
Mechanical properties of materials, brittle and ductile materials, Factor of straight, Stepped and tapered section strain, Lateral strain and Poisson's ra Design for Static Strength: Static St normal stress theory, Maximum sheat materials, Failure of ductile materials Threaded Fasteners: Stresses in the compression, Effect of Fatigue load joints. Belt Drives: Ratio of tensions, Celling contact bearings: Types, stational tension on power transmer Rolling contact bearings: Types, station load-life relationship, bearing life, catalogue; ball and roller bearing probability of survival other than 900 Shafts and Keys: Pure torsion, assu	Stress, Strain a of safety, True s ons, Stresses due tio, Elastic cons trength, Static le ar stress theory, s, Stress concen Unit-II threaded Faste ing, shear loadi ntrifugal stress itted, Simple ne atic and dynam load factor, se s, design for %, bearing mate Unit-III mptions, deriva is, Derivation o	stress and strain, Calcula e to temperature change stants and relations betwo bads, Theories of elastic Distortion energy theor tration factor. ners, Effects of initial ng, Design of eccentric in a belt, Power tran umerical problems. ic load capacities, equiva- election of bearing fro variable load and spec- erials and their propertie tion of torsional equation f power transmitted by	ation of stresses in e, Shear stress and veen them. failure – Maximum ry; Failure of brittle 15 Hours tension, Effect of ally loaded bolted smitted, effect of alent bearing load, m manufacturer's ed, bearings with es. 15 Hours ons, polar modulus, r solid and hollow

Design of Gears: Classification of Gears, Selection of type of gears, Law of Gearing, Gear terminology, Standard system of gear tooth, force analysis, Interference and undercutting, number of teeth, gear tooth failures, selection of material. Specifications of spur gear, helical gear, bevel gear, worm gears (Design not included).

09 Hours

List of Lab Experiments:

- 1. Part modeling and Assembly of robotic component using CATIA/Creo Parametric/Solid Edge
- 2. Stress concentration problems using ANSYS
- 3. Shear force and bending moment calculation using MD Solids
- 4. Design of shaft using MATLAB
- 5. Identification of different types of fasteners
- 6. Gear identification and applications
- 7. Gear clock design and fabrication
- 8. Identification of different types of bearings

26 Hours

Course Outcomes: At the end of the course student will be able to

- **1.** Determine bending stress, shear stress and design of simple machine components subjected to static loading conditions for different material properties.
- **2.** Design simple machine elements subjected to fatigue loading using Goodman and Soderberg design equations. Determine the dimensions of the machine elements subjected to impact strength.
- **3.** Design of shafts subjected to Bending, torsional and fatigue loads, with and without keys based on strength and rigidity criterion.
- **4.** Determine the parameters of helical springs and threaded fasteners for the given loads
- **5.** Design a pair of spur and helical gears given the number of teeth or pitch circle diameter, pitch line velocity and center distances and determine the gear parameters critical for the safety of the design; Outline the bevel gear terminologies; Design a pair of worm gears and compute its efficiency.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes															
RI2002-1.1	3	2	1	-	-	-	-	-	-	-	-	1	3	-	2
RI2002-1.2	3	2	1	-	-	-	-	-	-	-	-	1	3	-	2
RI2002-1.3	3	2	1	-	-	I	I	-	-	-	-	1	3	-	2
RI2002-1.4	3	2	1	-	-	-	-	-	-	-	-	1	3	-	2
RI2002-1.5	3	2	1	-	I	-	I	-	_	_	-	1	3	-	2

1: Low 2: Medium 3: High

TextBooks

- 1. Mechanical Engineering Design, Joseph E Shigley and Charles R. Mischke, McGraw Hill International edition, 2003
- Design of Machine Elements, V.B. Bhandari, Tata McGraw Hill Publishing Company Ltd., 2010
- 3. Machine Design, Robert L., Norton, Pearson Education Asia, 5th Edition, 2013



- 4. Design of Machine Elements, M.F.Spotts, T.E. Shoup, L.E. Hornberger, S.R. Jayram and C.V. Venkatesh, Pearson Education, 2006
- 5. Machine Design, Hall, Holowenko, Laughlin, (Schaum's Outlines series). Tata McGraw Hill Publishing Company Ltd., 2007

Web links and Video Lectures (e-Resources):

1. <u>https://nptel.ac.in/courses/112/105/112105124/</u>



Image Processing and its Application

Course Code:	RI2003-1	Course Type:	IPCC
Teaching Hours/Week (L: T: P: S):	3:0:2:0	Credits:	04
Total Teaching Hours:	50	CIE + SEE Marks:	50+50
Prerequisite	CS1001-1		

Teaching Department: Robotics and Artificial Intelligence

Course Objectives:

1	•	Understand the fundamentals of digital image processing
2	2.	Understand the image transform used in digital image processing
3		Understand the image enhancement techniques used in digital image processing
4	.	Understand the image restoration techniques and methods used in digital image
		processing
5	5.	Understand the Morphological Operations and Segmentation used in digital image
		processing

UNIT-I

Introduction 07 Hours What Is Digital Image Processing? Examples of Fields that Use Digital Image Processing, Fundamental Steps in Digital Image Processing, Components of an Image Processing System. Digital Image Fundamentals - Elements of Visual Perception, Brightness Adaptation and Discrimination, Light and the Electromagnetic Spectrum, Image Sensing and Acquisition, Image Sampling and Quantization, Some Basic Relationships between Pixels

Image Enhancement in the Spatial Domain 08 Hours Background, Some Basic Gray Level Transformations, Histogram Processing. Enhancement Using Arithmetic/Logic Operations, Basics of Spatial Filtering, Smoothing Spatial Filters, Sharpening Spatial Filters.

UNIT-II

Image Enhancement in the Frequency Domain	06 Hours
Background, Introduction to the Fourier Transform and the Frequency Domain,	Smoothing
Frequency-Domain Filters.	
Sharpening Frequency Domain Filters	05 Hours
Homomorphic Filtering, Image Segmentation - Detection of Discontinuities, Edge	Linking
and Boundary Detection, Thresholding, Region-Based Segmentation, Segmentati	on by
Morphological Watersheds.	
Morphological Image Processing	04 Hours
Preliminaries, Dilation and Erosion, Opening and Closing, the Hit-or-Miss Tran	sformation
Some Basic, Morphological Algorithms.	

UNIT-III 05 Hours Image Compression Fundamentals Image Compression, Models Elements of Information, Theory Error-Free Compression, Lossy Compression, Image Compression Standards.

Color Image Processing Color Fundamentals, Color Models, Pseudo color Image Processing, Basics of Full-Color Image Processing.

Suggested List of Experiments

04 Hours

Display of gray scale images Histogram Equalization Design non-linear filtering Determination of edge detection using operators 2-D DFT and DCT Filtering in Frequency domain Display of colour images Conversion between colour spaces DWT of images Segmentation using watershed transform
Design non-linear filteringDetermination of edge detection using operators2-D DFT and DCTFiltering in Frequency domainDisplay of colour imagesConversion between colour spacesDWT of images
Determination of edge detection using operators 2-D DFT and DCT Filtering in Frequency domain Display of colour images Conversion between colour spaces DWT of images
2-D DFT and DCT Filtering in Frequency domain Display of colour images Conversion between colour spaces DWT of images
Filtering in Frequency domain Display of colour images Conversion between colour spaces DWT of images
Display of colour images Conversion between colour spaces DWT of images
Conversion between colour spaces DWT of images
DWT of images
Segmentation using watershed transform
e Outcomes: At the end of the course student will be able to
Identify the concept of Digital Image Processing, Analyze Steps in Digital Image Processing, Apply the Knowledge of Image Sampling and Quantization and illustrate Some Basic Relationships between Pixels using Knowledge of 4-8 and M adjacency. Design and develop the experiments on histogram processing and gray scale images. Analyze Smoothing Spatial Filters, Sharpening Spatial Filters by applying mathematical knowledge. Explain Frequency domain and illustrate Smoothing
Frequency-Domain Filters. Design and develop the experiments on spatial domain
filters and frequency domain filters. Analyze Sharpening frequency-Domain Filters, Design and formulate Image segmentation techniques, prove the properties Region-Based Segmentation. Design and develop the experiments on image segmentation and edge detection
Illustrate and Design Image Compression Standards, Analyze the concept of Morphological Image Processing by applying mathematical knowledge.
Analyze color image processing techniques, illustrate color image sharpening, smoothing, compression, segmentation and Transform. Design and develop the experiments on color image processing.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes															
RI2003-1.1	3	1	3	2	3	-	-	-	-	-	-	2	1	2	2
RI2003-1.2	3	1	3	2	3	-	-	-	-	-	-	2	1	2	2
RI2003-1.3	3	1	3	2	3	-	I	-	-	-	-	2	1	2	2
RI2003-1.4	3	1	3	2	3	-	-	-	-	-	-	2	1	2	2
RI2003-1.5	3	1	3	2	3	-	-	-	-	-	-	2	1	2	2

1: Low 2: Medium 3: High

TEXTBOOKS:

NITTE

- **1.** Rafel C Gonzalez and Richard E Woods., Digital Image Processing, Pearson Education, 2nd Edition, 2003
- **2.** Anil K Jain., Fundamentals of Digital Image Processing, Prentice Hall of India Pvt. Ltd, 2nd Edition 1997.

REFERENCE BOOKS:

	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2022-20
1.	Milan Sonka, Vaclav Hlavac and Roger Boyle., Image Processing, Analysis and Machine Vision, Thomoson Learning, Brooks/Cole, 2 nd Edition 2001
2.	B.Chanda, D Dutta Majumder,. Digital Image Processing and Analysis, Prentice- Hall, India, 2 nd Edition 2011.
3.	Steven W. Smith,. The Scientist and Engineers Guide to Digital Signal Processing,
	California Technical Publishing, 2 nd Edition 1999.
E Boo	ks / MOOCs/ NPTEL
1.	https://nptel.ac.in/courses/117/105/117105135/
2.	https://www.tutorialspoint.com/dip/index.htm
3.	https://www.coursera.org/learn/digital
4.	Virtual Lab link- https://cse19-iiith.vlabs.ac.in/
5.	https://www.javatpoint.com/digital-image-processing-tutorial
6.	https://www.mathworks.com/discovery/digital-image-processing.html

(Deem	ITTE ed to be University) IND	USTRY 4.0 &	IOT				
Cour	rse Code:	RI2004-1	Course Type:	IPCC			
	hing Hours/Week (L: T: P: S):	(3:0:2:0)	Credits:	04			
	I Teaching Hours:	50	CIE + SEE Marks: 50+50				
	equisite	CS1001-1, I		50.50			
C	5 .		s & AI Engineering				
1.	e Objectives: Understand the drivers and enab	lers of Indust	ry 10 Explain internet of Th	ings and			
± .	its hardware and software comp			ings and			
2.	Develop the students to underst		ace I/O devices				
3.	Able to outline the various syste			ir role in			
	an Industry 4.0 world						
4.	Develop the IOT applications						
5.	Understand the opportunities, cl	nallenges brou	ught about by Industry 4.0 a	nd how			
	organisations and individuals she	-					
		UNIT-I					
ntrod	duction to Industry 4.0, Introdu	ction to IoT		08 Hours			
Basic	principles and technologies of a S	Smart Factory,	Cyber-Physical Systems (CP	S).			
Archit	ectural Overview, Design principl	es and needed	d capabilities, IoT Application	ns, Sensing,			
	tion, Basics of Networking, M2N			-			
	ays, Data management.						
Hardv	ware Elements of IoT, Software	Elements of I	IoT	08 Hours			
Comp	outing (Arduino, Raspberry Pi), Co	mmunication,	Sensing, Actuation, I/O inte	rfaces.			
		UNIT-II		1			
Augm	nented Reality			08 Hours			
	ance systems for production, 1		use-cases for Augmented	Reality ir			
	facturing, Human-Robot Collabo	ration.					
	pplication Development			08 Hours			
	on framework for IoT applications	-	_				
	sition and integration, Device data	-	structured data storage on c	loud/local			
server	r, Authentication, authorization of	devices.					
		UNIT-III					
	l Manufacturing			08 Hours			
	Manufacturing and the connect	-		-			
	onments & a Predictive Maintenar		-				
	ing Application, Safety and Secu		rked Production Environme	nts, Cyber			
Physic	cal Systems and new Business Mo						
	-	and the state of the second	•				
			eriments				
	Interfacing communication mo	dules using A					
2.	Interfacing communication mo Blinking LED lights with Arduin	dules using A o	rduino				
3.	Interfacing communication mo Blinking LED lights with Arduin Interfacing alphanumerical LCD	dules using A o) display using	rduino g Arduino				
3. 4.	Interfacing communication mo Blinking LED lights with Arduin Interfacing alphanumerical LCD Direction control of DC motor	dules using A o) display using using Arduino	rduino g Arduino				
3.	Interfacing communication mo Blinking LED lights with Arduin Interfacing alphanumerical LCD	dules using A o) display using using Arduino Arduino	rduino g Arduino				

6. Operate raspberry pi using headless mode

Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

Ī		Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2
	7.	Communication with devices through pins of the pi, RPi.GPIO library
	8.	Direction control of stepper motor using Raspberry pi
	9.	Build webserver using raspberry pi
	10.	Build NAS using raspberry pi

Cour	se Outcomes: At the end of the course student will be able to
1.	Summarise the basic principles and technologies of a Smart Factory, Cyber-Physical
	Systems (CPS) and Cyber-Physical Production Systems (CPPS)
2.	Explain internet of Things and its hardware and software components
3.	Develop Interface I/O devices. Analyse the assistance systems for production.
4.	Describe the six main use-cases for Augmented Reality in Manufacturing, Human-
	Robot Collaboration. Develop Remotely monitor data and control devices
5.	Discuss the Cloud Manufacturing, Cloud Development Environments and Artificial
	Intelligence in Production

Course Outcomes Mapping with Program Outcomes & PSO

	P	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO.	\downarrow
		ourse Outcomes													1	2	3
		RI2004-1.1	3	-	-	1	2	1	-	-			-	1	-	2	3
		RI2004-1.2	3	-	-	1	2	1	-	-			-	1	-	2	3
		RI2004-1.3	3	-	-	2	1	3	-	-			-	1	-	2	3
		RI2004-1.4	3	-	-	2	1	2	-	-			-	1	-	2	3
		RI2004-1.5	3	-	-	2	1	2	-	-			-	1	-	2	3
		1: Low 2: Medium 3: Hi	gh														
Т	EXTE	BOOKS:															
	1.	Ghosal, A., Robotics: F 2008	und	ame	enta	l Co	nce	pts	and	An	alys	is, O	kforc	d Uni	versi	ty Pr	ess,
	2.	Internet of Things: A H	lanc	ls O	n Ap	opro	bach	n, A	rsho	deep	o Ba	hga,	and	Vijay	y Ma	diset	tti,
		Orient Blackswan, 201	4														
	3.	Introduction to Indust	rial	Inte	rnet	of ⁻	Thin	igs a	and	Ind	ustr	y 4.0	, Suc	dip M	lisra,	Cha	ndana
		Roy and Anandarup N	lukł	nerje	ee, C	RC	Pres	s T	aylo	r &	Frai	ncis (Grou	p, LL	C, Fi	rst E	dition,
		2021.															
R	EFER	ENCE BOOKS:															
	1.	Fu, K., Gonzalez, R. and Intelligence, McGraw-				G., F	Rob	otic	s: C	ontr	ol, S	Sensi	ng, ۱	Visio	n and	b	
	2.	Industry 4.0:The Indust				t of	Thi	nas	Ala	isda	ir G	ilchri	st. A	pres	s. 20'	16	
	3.	The Fourth Industrial F												•			
	4.	Handbook of Industry)
	-	Daponte, and Uday Ku					-)		- 1		9-			,			
Ε	Boo	ks / MOOCs/ NPTEL															
-	1.	https://nptel.ac.in/cou	rses	/10	6/10)5/1	061	051	95/								
	2.	https://www.classcenti									an-2	2019	-intr	oduc	tion	-to-	
	-	industry-4-0-and-indu					-					-					
				-			-		, .								



Introduction to	Object Orient	ted Programming	
Course Code	RI2005-1	Course Type:	IPCC
Teaching Hours/Week (L:T:P: S)	(3:0:2:0)	Credits:	04
Total Hours of Pedagogy	50	CIE + SEE Marks:	50+50
Prerequisite	CS1001-1		
Course objectives:			

- 1. Learn fundamental features of object-oriented language and Python
- 2. Create, debug, and run a simple Python Program.
- 3. Create multi-threaded programs and event handling mechanisms.
- 4. Introduce event driven Graphical User Interface (GUI) programming using Python
- 5. Introduce event driven Graphical User Interface (GUI) programming using Python

Unit-I

Python basics: Essentials of a Python program, Integers, Floating-point numbers, Strings, Variables and scope: Variables, Type conversion Selection control statements, Collections: Lists, Tuples, Sets, Ranges, Dictionaries, Converting between collection types, Two-dimensional sequences

Loop control statements: while loop, for loop, Nested loops, Iterables, iterators and generators, Comprehensions, break and continue statements

Errors and exceptions: Errors, handling exceptions, Debugging programs

15 Hours

Unit-II

OOP Concepts: Abstraction, Encapsulation, Inheritance, Polymorphism **Classes:** Instance attributes, Class attributes, Class decorators, inspecting an object, Overriding methods. Composition, Inheritance, Virtual functions

Packaging and testing: Modules, Packages, Documentation, Testing Useful modules in the Standard Library: datetime, math, random, re, csv, sys and argparse

15 Hours

Unit-III

List of Lab Experiments:

Event-driven programming, Layout options, Custom events

09 Hours

Programs

- 1. Write a python program to print the multiplication table for the given number
- 2. Write a python program to display prime numbers less than or equal to a number 'n'.
- 3. Write a python program to find the factorial of the given number?
- 4. Write a python program to implement List operations (Nested List, Length, Concatenation, Membership, Iteration, Indexing and Slicing)
- 5. Write a python program to implement List methods (Add, Append, Extend & Delete).
- 6. Write a python program to implement simple Chatbot with minimum 10 conversations
- 7. Write a python program to Illustrate Different Set Operations
- 8. Write a python program to implement a function that counts the number of times a string(s1) occurs in another string(s2)

- 9. Write a program to illustrate Dictionary operations ([],in, traversal) and methods: keys(), values(), items()
- 10. Solve 8-Queens Problem with suitable assumptions
- 11. Write a program that inputs a text file. The program should print all of the unique words in the file in alphabetical order.
- 12. Write a python program to create a package (college), sub-package (alldept), modules (departments) and create an admin and cabin function to the module?
- 13. Program to demonstrate Creating Class and Object in Python
- 14. Program to demonstrate Creating Methods in Python
- 15. Program to demonstrate Use of Inheritance in Python
- 16. Program to demonstrate Data Encapsulation in Python
- 17. Program to demonstrate Using Polymorphism in Python
- 18. Program to demonstrate event driven programming

11 Hours

Course Outcomes: At the end of the course student will be able to

- **1.** Acquire the fundamental knowledge of Programming Language using Python
- **2.** Obtain the knowledge of Loops and Errors Exception using Python and Object-Oriented Programming Concepts
- **3.** Acquire the knowledge of Event driven application
- 4. Apply the knowledge of Object-Oriented Programming.
- 5. Apply the knowledge of Event driven application using Python

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	۶O	\checkmark
↓ Course Outcomes													1	2	3
RI2005-1.1	3	I	-	1	2	1	I	-			I	1	I	2	3
RI2005-1.2	3	-	-	1	2	1	-	-			-	1	-	2	3
RI2005-1.3	3	-	-	2	1	3	-	-			-	1	-	2	3
RI2005-1.4	3	1	-	2	1	2	1	-			1	1	1	2	3
RI2005-1.5	3	I	-	2	1	2	-	-			I	1	I	2	3

1: Low 2: Medium 3: High

Textbooks:

- 1. "Python 3 Object Oriented Programming", Dusty Phillips, Packt Publishing, 2015
- "Core Python Programming", R. Nageswara Rao, Dreamtech Press, Second edition, 2018.

Reference Books

- 1. "Let Us Python: Python Is Future, Embrace It Fast", Yashavant Kanetkar, Aditya Kanetkar, BPB Publications, 2019
- *2. "Python Programming: A modular approach"*, Taneja Sheetal, Kumar Naveen, Pearson India, 2017

E Books / MOOCs/ NPTEL

- Programming for Everybody (Getting Started with Python) https://www.coursera.org/learn/python
- Object-Oriented Python: Inheritance and Encapsulation <u>https://www.coursera.org/learn/object-oriented-python</u>



Object Oriented Programming with C++ <u>http://vlabs.iitb.ac.in/vlabs-dev/labs/oops/index.php</u>



	Introc	luction to Ro	botics	
Cou	ırse Code:	RI2006-1	Course Type:	IPCC
Теа	ching Hours/Week (L: T: P: S):	(3:0:2:0)	Credits:	04
Tot	al Teaching Hours:	40+0+26	CIE + SEE Marks:	50+50
Pre	requisite	EE1001-2, EC	1001-1	
	Teaching Depart	ment: Robotics	& AI Engineering	
Cour	se Objectives:			
1.	Familiarize with the Anatomy of	robot and 3D h	omogeneous transformati	ions.

2. To study the different sensors and actuators used in robotics

3.	Study the application of robot technology in wheeled mobile robots, medical robots,
	unmanned aerial vehicles, service robots, underwater robots

- 4. To study the linear and rotary motion control using sensors and actuators
- **5.** To understand the robot programming and 3D homogeneous transformations applied to robotics

Unit-I

Definitions- Robots, Robotics; Types of Robots- Manipulators, Mobile Robots-wheeled & Legged Robots, Aerial Robots; Anatomy of a robotic manipulator-links, joints, actuators, sensors, controller; open kinematic vs closed kinematic chain; degrees of freedom; Robot considerations for an application- number of axes, work volume, capacity & speed, stroke &reach, Repeatability, Precision and Accuracy, Operating environment, point to point control or continuous path control. **Robotic configurations and end effectors, Human factors in Robotics.**

Robot configurations-PPP, RPP, RRP, RRR; features of SCARA, PUMA Robots; Classification of robots based on motion control methods and drive technologies; 3R wrist.

Classification of End effectors - mechanical grippers, special tools, Magnetic grippers, Vacuum grippers, adhesive grippers, Active and passive grippers, selection, and design considerations of grippers in robot.

3D Homogeneous transformations: 3D homogeneous rotation Matrix, 3D Homogeneous translation Matrix, Composite rotation Matrix, Rotation Matrix about an Arbitrary Axis, Application of 3D homogeneous transformations in robotics, numerical Problems

15 Hours

Unit- II

Sensors for Robots

Sensor classification- Proprioceptive and Exteroceptive sensors, active and passive sensors, characteristics of sensors, touch, force, range, proximity, vision sensors. **Internal sensors**-Linear and rotary position sensors, velocity sensors, acceleration sensors, Force sensors; **External sensors**-contact type, noncontact type; Vision - Elements of vision sensor, image acquisition, image processing; Selection of sensors.

Actuators for Robots: classification-Electric, Hydraulic, Pneumatic actuators; their advantages and disadvantages; Electric actuators- Stepper motors, DC motors, DC servo motors and their drivers, AC motors, Linear actuators, selection of motors; Hydraulic actuators- Components and typical circuit, advantages, and disadvantages; Pneumatic Actuators- Components and typical circuit, advantages and disadvantages.



15 Hours

Unit-III

Application of Robot: Industrial Robots, aerial robots-Fixed wing unmanned aerial vehicle, helicopters, Multi rotor UAV, Flapping wing/Bio inspired UAV, wheeled mobile robots, smarm robots, Legged robots, medical/healthcare robots-Surgical Robot, Exoskeleton robot, Rehabilitation robot, hospital robot, space robots, service robots, Underwater and floating robots, Military Robots.

		Suggested List of Experiments
1.	Expe	riments on:
	i.	Linear and rotary displacement sensors
	••	

- ii. Proximity Sensors
- iii. Range Sensors-Ultrasonic, IR and laser range sensors
- iv. Force and Torque sensors
- v. Vision Sensors
- 2. Experiments on:
 - i. Stepper motor controlled linear slide
 - ii. Servo motor controlled linear slide
- 3. Experiments on sequence control using hydraulic and pneumatic circuits
- 4. Experiments on Quadcopter micro air vehicle
- 5. Experiments on 3D Homogeneous transformations using 3D Coordinate frame models
- 6. Experiments on Robot for demonstrating
 - i. Pick and Place operation
 - ii. Drawing Artwork
 - iii. 3D Printing
- iv. Accept/Reject part based on output from machine vision system
- 7. Experiments on Differential Wheel Mobile robot
- 8. Experiments on Meccanum Wheel mobile robot
- 26 Hours

Cours	se Outcomes: At the end of the course student will be able to
1.	Define, describe, and classify the different types of robots, and identify the different components of a robotic manipulator, such as links, joints, actuators, sensors, and controllers.
2.	Classify, select, and design end effectors for robots, and apply 3D homogeneous transformations to robot motion.
3.	Identify the different types of sensors and their applications, and use them to collect data for robotics applications
4.	Identify the different types of actuators and their applications and use them to control the motion of robots.
5.	Gain a comprehensive understanding of the diverse applications of robots, including industrial robots, aerial robots, wheeled mobile robots, legged robots, medical/healthcare robots, space robots, service robots, underwater and floating robots, and military robots, and their respective functions, advantages, and impact in various domains.

Cours	e Outcomes Mapping	witl	ו Pr	ogra	am	Out	cor	nes	& F	SO						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO	Ļ
	Course Outcomes													1	2	3
•	RI2006-1.1	3	1	-	-	-	-	-	-	-	-	-	-	2	-	1
	RI2006-1.2	3	1	-	-	-	-	_	-	-	_	_	_	2	-	-
	RI2006-1.3	3	1	-	-	_	-	_	_	_	-	_	-	2	1	_
	RI2006-1.4	3	1	_	_	_	-	_	_	_	_	_	_	2	1	_
	RI2006-1.5	2	1	_	_	_	_	_	_	_	-	_		2	-	2
	1: Low 2: Medium 3		_											2		2
	I. LOW 2. Medium		ign													
TEX	TBOOKS:															
1.	"Robotics and Control	oľ'	R. K	(. M	itta	I. I.	J. I	Nad	rat	n. Ta	ata-N	ЛсGr	aw-F	Hill P	ublio	atior
	2007					.,		9		-, .、					abiii	
2.	"Robotics: Control, S	ens	ing,	Vis	ion,	Int	telli	aen	ce"	'Fu	K. S	., Go	nzel	ez R	. C.,	Lee
	S. G., McGraw Hill Boo		-		- 1			y -								
REFEF	RENCE BOOKS															
1.	"Advances in Rehabi	lita	tion	Ro	bot	ics″	, Z.	Ze	nn	Bie	nDin	nitar	Ste	fano	v , S	pring
	Publications, Year-2004															
2.	"Army of None: Aut	ono	mo	us V	Nea	por	ns a	nd	the	Fut	ture	of V	Var"	, Pa	ul S	charı
	Publisher: W. W. Norto	n &	Co	mpa	iny;	- 1st	edit	ion,	Yea	ar- 2	2018,	ISBN	1-97	8-03	9360)8984
3.	"Design of Dynamic L	egg	jed	Rob	ots	", Sa	ang	bae	Kin	n, Pa	atric	kМ.	Wer	nsing	j , Pu	blish
	Now Foundations and	Trei	nds,	Yea	r-20)17,	ISB	N: 9	781	.680	8325	570.				
4.	"Introduction to M	ulti	сор	ter	De	sigr	n a	nd	Со	ntro	ol",	Qua	n C	Quar	n, S	pring
	Publications, Year-2017	7 ISI	BN:	978-	-981	10	-33	82-7	7.							
5.	"Introduction to the	Μ	echa	anic	s o	f S _l	pac	e R	obc	ots"	Gia	nca	rlo (Gent	a , S	pring
	Publications, Year-2012															
6.	"Service Robots and															
	Published by Engineeri															
7.	"Small Unmanned F			-					-							
	Sóbester, James P. So															
8.	"Surgical Robotics:	-														
	Hannaford, Richard I 1126-1.	VI. 3	bata	iva,	Spr	inge	er P	ubii	cau	on,	rear	-201	1, 15	BIN:9	10-1	441
9.	"Swarm Robotics: A F	orn	nal /	۸nn	roa	ch"	Цa	iko	La,	nan		orino	or Di	ublic	atio	
9.	2018, ISBN: 978-3-319				TUa	, iii	ne	IKU	i iai	IIai	III, 5	Jing	CIFU	ubiic	atio	1, 100
10.	"Underwater Robots				1 Fo	rce	Cor	ntro	ام	Veł	nicle	-Mai	ninu	lato	r Sve	teme
±0.	Gianluca Antonelli, Sp												-		-	
11.	"Wearable Exoskelete															
	Gurvinder S. Virk, Th		-			-									-	-
	Technology, Year-2018				-											
12.	"Wheeled Mobile Rol								ls T	owa	ards	Auto	non	nous	s Sys	tems
															-	
	Gregor Klancar , And	rej	Zde	sar,	Sas	50 B	Slaz	ic, I	gor	Skı	janc	, Pul	olish	er: B	uttei	rwort
	Gregor Klancar , And Heinemann, Year-2017	-							gor	Skı	janc	, Pul	olish	er: B	uttei	rwort

N	NITTE
U	(Deemed to be University)

1.	Introduction to Robotics https://ocw.mit.edu/courses/mechanical-engineering/2-12-
	introduction-to-robotics-fall-2005/syllabus/
2.	INTRODUCTION TO ROBOTICS https://nptel.ac.in/courses/107/106/107106090/
3.	Robotics Specialization https://www.coursera.org/specializations/robotics

Course Code:		RI2007-1	Course Type:	IPCC
Teaching Hours	/Week (L: T: P: S):	(3:0:2:0)	Credits:	04
Total Teaching H	lours:	50	CIE + SEE Marks:	50+50
Prerequisite		CV 1001-1		I
Теа	aching Department	: Robotics and A	Artificial Intelligence	
Course Objective	s:			
1. To study the	e direct kinematics s	olutions for the o	different robot configurat	ions
2. To study the	e Inverse kinematics	solutions for the	e different robot configura	ations
3. To study the	e Jacobian Matrix fo	r the different ro	bot configurations	
4. To identify t	the singular configur	rations for differe	ent robot configurations	
5. To study the	e dynamic equation	of motion and tr	ajectory planning of a rob	oot
		UNIT-I		
Direct Kinematics	and Inverse kinem	natics		15 Hours
inks joints and	their parameters, k	Cinematic Mode	ling of the manipulator,	, Denavit
-	•		ween adjacent links, I	
ransformation ma	atrix, Problems, Mar	nipulator worksp	ace, Solvability of invers	e kinemat
		•	ion technique, Closed for	
	in closed form solut			
		UNIT-II		
Manipulator Diff	erential Motion and	d Statics		15 Hours
			/, Angular velocity, Linear	15 Hours velocity du
inear and angular	velocity of rigid boo	ly, Linear velocity	/, Angular velocity, Linear lar motion, Relationshi	velocity du
inear and angular o angular moti	velocity of rigid boc on, Combined lin	ly, Linear velocity ear and angu	lar motion, Relationshi	velocity du p betwee
inear and angular o angular moti ransformation ma	velocity of rigid boc on, Combined lin trix and angular velc	ly, Linear velocity ear and angu ocity, Mapping ve	lar motion, Relationshi elocity vector, Velocity pro	velocity du p betwee pagation o
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inear and angular o angular moti ransformation ma a link, Angular velo oint Jacobian, The	velocity of rigid boc on, Combined lin trix and angular velc ocity of a link, Manip rotary joint Jacobia	ly, Linear velocity ear and angu ocity, Mapping ve oulator Jacobian, n, Jacobian inver	lar motion, Relationshi elocity vector, Velocity pro Jacobian computation, Th se, Jacobian singularity, C	velocity du p betwee pagation o ne prismat omputatio
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inear and angular o angular moti ransformation ma l link, Angular velo oint Jacobian, The of singularities, Wr Robot Dynamics	velocity of rigid boc on, Combined lin atrix and angular velc ocity of a link, Manip rotary joint Jacobia rist singularities, Arm	ly, Linear velocity ear and angulocity, Mapping ve oulator Jacobian, n, Jacobian inver singularities an UNIT-III	lar motion, Relationshi elocity vector, Velocity pro Jacobian computation, Th se, Jacobian singularity, C	velocity du p betwee pagation o ne prismat omputatio 05 Hours
inear and angular o angular moti ransformation ma l link, Angular velo oint Jacobian, The of singularities, Wr Robot Dynamics agrangian mecha	velocity of rigid boc on, Combined lin atrix and angular velc ocity of a link, Manip rotary joint Jacobia rist singularities, Arm	ly, Linear velocity ear and angulocity, Mapping ve oulator Jacobian, n, Jacobian inver n singularities an UNIT-III	lar motion, Relationshi elocity vector, Velocity pro Jacobian computation, Th se, Jacobian singularity, C d singular configurations.	velocity du p betwee pagation o ne prismat omputatio 05 Hours Lagrange
inear and angular o angular moti ransformation ma l link, Angular velo oint Jacobian, The of singularities, Wr Robot Dynamics agrangian mecha	velocity of rigid boc on, Combined lin atrix and angular velc ocity of a link, Manip rotary joint Jacobia rist singularities, Arm nics, Two degree of Velocity of a point	ly, Linear velocity ear and angulocity, Mapping ve oulator Jacobian, n, Jacobian inver singularities an UNIT-III freedom manipu	lar motion, Relationshi elocity vector, Velocity pro Jacobian computation, Th se, Jacobian singularity, C d singular configurations.	velocity du p betwee pagation on ne prismat omputation 05 Hours Lagrange the kinet
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(Dee	med to be University)
	(a) 2R robot
	(b) 3R robot
	(c) RPY wrist
6.	Experiments on Robot Singularities for
	(a) 2R robot
	(b) 3R robot
	(c) RPY wrist
7.	Experiments on simulation of cubic polynomial trajectory
8.	Experiments on simulation of trapezoidal velocity trajectory
9.	Dynamic simulation of 2R robot
Cour	se Outcomes: At the end of the course student will be able to
1.	Calculate the direct kinematic solution for a given robot configuration
2.	Calculate the inverse kinematic solution for given robot configuration
3.	Calculate the Jacobian matrix for the given robot configuration
4.	Identify the singular configurations for the given robot configuration
5.	Calculate the dynamic equation of motion and to perform the trajectory planning
	for the given robot configuration

Course Outcomes Mapping with Program Outcomes & PSO

<u> </u>	-			-											
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes													1	2	3
RI2007-1.1	3	2	1	1	1	-	-	-	-	-	-	-	3	2	-
RI2007-1.2	3	2	1	1	1	-	-	-	-	-	-	-	3	2	-
RI2007-1.3	3	2	1	1	1	-	-	-	-	-	-	-	3	2	-
RI2007-1.4	3	2	1	1	1	-	-	-	-	-	-	-	3	2	-
RI2007-1.5	3	3	2	1	1	-	-	-	-	-	-	-	3	2	-
1: Low 2: Medium 3: Hi	igh	•	•	•	•	•		•	•	•	•		•	•	

TEXTBOOKS:

IN NITTE

- **1.** Robotics and Control, R K Mithal and I J Nagrath , McGraw Hill
- **2.** Fu, K., Gonzalez, R. and Lee, C. S. G., Robotics: Control, Sensing, Vision and Intelligence, McGraw- Hill, 2008
- **3.** Introduction to Robotic Analysis Niku, S.B., Systems, Applications, Pearson Education, 2008.

REFERENCE BOOKS:

- **1.** Introduction to Robotics: Mechanics and Control- 2nd Edition Craig, J. J., Addison-Welsey, 2nd Edition1989.
- 2. Fundamentals of Robotics, Analysis and Control- Schilling R. J., PHI, 2006.

E Books / MOOCs/ NPTEL

- https://onlinecourses.nptel.ac.in/noc20_me53/preview
 https://www.classcentral.com/course/swayam-mechanics-and-control-of-robotic-manipulators-43637
 http://ulabs.iitkap.ac.in/mr/#
 - 3. http://vlabs.iitkgp.ac.in/mr/#



	Mic	ro Aerial Ro	bots	
Cou	ırse Code:	RI2008-1	Course Type:	IPCC
Теа	ching Hours/Week (L: T: P: S):	(3:0:2:0)	Credits:	04
Tot	al Teaching Hours:	50	CIE + SEE Marks:	50+50
Pre	requisite	PH 1001-1,	ME 1003-1	l
	Teaching Department	: Robotics and	d Artificial Intelligence	
Cour	se Objectives:			
1.	Comprehend the basic aviation	history and UA	AV systems.	
2.	Acquire the knowledge of basic	aerodynamics	and performance.	
3.	Understand the stability and cor	ntrol air vehicle	es	
4.	Understand the propulsion, load	ds and structur	es.	
5.	Develop and test the remote co	ntrolled, autor	nomous aerial vehicles	
		UNIT-I		
The <i>i</i>	Air Vehicle			06 Hours
defin	duction aviation history and over itions and terminology, UAV fund		-	
	um and large UAV			
	c Aerodynamics			05 Hours
	aerodynamics equations, aircraft	•	5	ed drag, the
	idary layer, flapping wings, total a ormance	ir-venicie drag		04 Hours
-	view, climbing flight, range and er	odurance – for	propeller-driven aircraft ra	
	n aircraft, guiding flight.	idurance for		nge ajet
	in an erart, garanig night.	UNIT-II		
Stab	ility and Control			15 Hours
	view, stability, longitudinal, late	ral, dynamic	stability, aerodynamics co	ntrol, pitch
	ol, lateral control, autopilots, ser	•		•
	r loops, flight-control classification			
auto	pilot.			
Prop	ulsion overview, thrust generation	, powered lift,	sources of power, the two-c	ycle engine
the r	otary engine, the gas turbine, elect	tric motors, and	d sources of electrical powe	r. Loads and
struc	tures loads, dynamic loads, ma	aterials, sandw	vich construction, skin or	reinforcing
mate	rials, resin materials, core materia	ls, constructior	n techniques.	
		UNIT-III		
	ion Planning and Control			09 Hours
	ehicle and payload control, reco			
	r payloads, data-link functions a		-	e reduction
launo	ch systems, recovery systems, laun			
- 1		ed List of Exp		
1.				
2.	Study on development and int	egration of Un	imanned Aerial Systems.	

Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

(Deer	ned to be University)
3.	Integration and testing Remote Controlled Fixed Wing UAV
4.	Integration and testing Remote Controlled Vertical Take-off and Landing UAV
5.	Integration and testing Autonomous Fixed Wing UAV
6.	Integration and testing Autonomous Vertical Take-off and Landing UAV
7.	Integration and testing of Hybrid UAV
8.	Application of UAV in Remote sensing
9.	Application of UAV in Disaster management
10	Image processing using Raspberry Pi for agricultural applications
Cours	se Outcomes: At the end of the course student will be able to
1.	Explain the basic of aerodynamics performance and apply the basic concepts of
	UAV systems and experimentally study the integration of drones.
2.	Explain the stability and control required for UAV and Select the propulsion system,
	materials for structures. Experimental studies on disaster management.
3.	Develop and test the remote controlled autonomous aerial vehicles. Experimental
	study on remote controlled and autonomous UAV.
4.	Design air vehicles for different payloads and design standards. Experimental study
	on autonomous and remote-controlled Vertical Take-off and Landing UAV
5.	Develop and test the rotary wing, fixed wing aerial vehicles. Experimental study on
	Unmanned aerial vehicles and fixed wing UAV.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		Ļ	
↓ Course Outcomes													1	2	3
RI2008-1.1	2	2	3	2	2	-	-	-	-	-	-	2	2	-	2
RI2008-1.2	2	2	3	2	2	-	-	-	-	-	-	2	2	-	2
RI2008-1.3	2	2	3	2	2	-	-	-	-	-	-	2	2	-	2
RI2008-1.4	2	2	3	2	2	-	-	-	-	-	-	2	2	-	2
RI2008-1.5	2	2	3	2	2	-	-	-	-	-	-	2	2	-	2

1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** Paul Gerin Fahlstrom, Thomas James Gleason, Introduction to UAV Systems, Wiley Publication, 4th Edition,2012.
- **2.** Landen Rosen, Unmanned Aerial Vehicle, Alpha Editions

REFERENCE BOOKS:

- **1.** Unmanned Aerial Vehicles: DOD's Acquisition, Alpha Editions
- 2. Valavanis, Kimon P, Unmanned Aerial Vehicles, Springer, 2011
- **3.** Valavanis, K., Vachtsevanos, George J, Handbook of Unmanned Aerial Vehicles, Springer, 2015.

E Books / MOOCs/ NPTEL

1. https://onlinecourses.nptel.ac.in/noc22_me38/preview



Professional Core Courses (Theory)



Artificial Intelligence and Machine Learning

	Artificial Intell	igence and N	hachine Learning	
Со	urse Code:	RI2101-1	Course Type:	PCC
Теа	ching Hours/Week (L: T: P: S):	(2:2:0:0)	Credits:	03
Tot	al Teaching Hours:	40	CIE + SEE Marks:	50+50
Pre	requisite	CS1001-1		
	Teaching Departme	nt: Robotics an	d Artificial Intelligence	
Cou	rse Objectives:			
1.	Understand the basics of Artif	icial Intelligence	e Explain what is involve	ed in learning
	models from data.	ieren internigente		
2.	Familiarize with the concepts of functions	informed and ur	ninformed search strategies	s and Heuristi
3.	Demonstrate the application of	linear regression	on and logistic regression	for real world
	problems. Explain the design an			
4.	Explain construct basic unsuper			
5.	To explain the concepts of Unce			ence using fu
	joint distributions			
		UNIT-I		
Intro	oduction to Artificial Intelligence	9		06 Hours
Histo	ory, need, applications, advantage	es and limitation	ns. what is artificial intellig	gence? why v
need	d ml? difference between ai and m	l, difference betv	ween ml and dl, different r	nl algorithms
earr earr	ning: supervised, unsupervised, re ning, error and noise, training ver ning curve			s and variand
	lligent Agents			05 Hours
-	nts and environment, structure formed search strategies, informed	-		solving agent
Prok	pabilistic reasoning			10 Hours
Repr	esenting knowledge in uncertain o	domain, Semant	cics of Bayesian networks, F	Relational and
first	order probability models			
Lear	ning from examples			04 Hours
	ns of learning, Learning Decision t	rees, the theory	of learning, Regression ar	nd classificatio
with	linear models, Nonparametric mo	dels.		
		UNIT-III		
Mac	hine Learning			05 Hours
Intro	duction to Artificial neural n	etwork, Netwo	ork architectures, Learni	ng Clusterin
Intro	duction, K-means, Hierarchical clu	stering		-
inuc				
	Jiy Of learning. Teasionity Of learn	ing, error and no	oise, training versus testing	g, 05 Hours
The		-		g, 05 Hours
Theo theo	ry of generalization, bias and varia	nce, learning cu	Jrve.	
Theo theo Supp	ry of generalization, bias and varia port Vector Machines and Kernel m	ethods - Introdu	urve. uction, statistical learning t	heory, soft vs
Theo theo Supp nard	ry of generalization, bias and varia	nce, learning cu ethods - Introdu early separable a	urve. uction, statistical learning t and non-separable pattern	heory, soft vs

							Cu	rricu	ılum	– B.7	Гech.	(Robo	otics &	Artific	cial Int	elligen	ece): 2	022-2
1.	E>	plain about Artificial Ir	ntell	iger	nce,	ider	ntify	its	rela	tion	ship	o witl	n Ma	chin	e lea	rning	g, De	ер
		earning and foundation		-			5										-	•
2.	D	escribe the working of	Line	ear F	Regr	essi	on r	noc	dels	and	ΙMι	ltipl	e Lin	ear F	Regre	essio	n	
	m	odels																
3.	Ex	plain Probability theor	y ar	nd E	nser	nble	es m	neth	ods	5								
4.	Ex	plain decision tree mo	dell	ing	and	diff	erer	nt c	uste	ering	g m	etho	ds					
5.	K	now the fundamental c	onc	ept	of n	eur	al ne	etw	ork	tech	niq	ues a	and l	earn	ing a	Igori	ithms	\$
Со	urse	Outcomes Mapping w	ith	Pro	gra	m C	outc	om	es 8	<u>ک</u> ک	50							
	P	rogram Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ	
	↓ Co	ourse Outcomes													1	2	3	
		RI2101-1.1	3	2	2	1	2	-	-	-	-	-	-	-	2	2	2	
		RI2101-1.2	3	2	2	1	2	-	-	-	-	-	-	-	2	2	2	
		RI2101-1.3	2	2	2	1	2	-	-	-	-	-	-	-	2	2	2	
		RI2101-1.4	2	2	2	1	2	-	-	-	-	_	-	-	2	2	2	
		RI2101-1.5	2	2	2	1	2	-	-	-	-	-	-	-	2	2	2	
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	<u>1.</u>	Stuart Russel and Pet	tor	Mon	via	" A rt	ifici		atall	iaar		A N.A.	odor	n An	nror	ch"	Door	
	⊥.	3rd Edition, 2016		NOT	vig,		inci		nen	igei			Juen	п др	piuc	icii,	i cai	3011
	2.	Tom. M. Mitche, "Mad	chin	e Le	earn	ina"	. Mo	Gra	aw F	liah	er E	d. 1s	t edi	tion	2013	3.		
	3.	Understanding Machi															Shw	artz
		and Shai Ben-David			•	-			-									
		Hardback				-			,									
	4.	Neural Networks – A	com	npre	hen	sive	Fou	Inda	atio	n, Si	moi	n Ha	ykin,	Pear	son	Pren	tice H	-lall,
		Second Edition, 2005,	ISE	8N 8	- 11	780	8 -3	00 -	- 0									
REI	FERE	NCE BOOKS:																
	1.	DAN W PATTERSON			oduc	tior	n to	Ar	tific	ial	[nte	lliger	nce	and	Expe	ert S	yster	ns",
		PEARSON, 1st edition																
	2.	Elaine Rich, "Artificial		-														
	3.	Er. Rajiv Chopra, "Arti	ticia	al In	tellig	geno	ce –	Αp	orac	tical	ар	oroa	ch", (_han	d pu	iblica	ition,	1st
5 D		edition 2012																
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	5.	https://nptel.ac.in/cou																
	6.	https://onlinecourses									ew							

- 6. https://onlinecourses.nptel.ac.in/noc21_ge20/preview
- 7. http://vlabs.iitb.ac.in/vlabs-dev/labs/machine_learning/labs/index.php

Course Code:	RI2102-1	Course Type	PCC
Teaching Hours/Week (L: T: P: S)	2:2:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EC1001-1,	EE1001-1	
Teaching Departme	nt: Robotics ar	nd Artificial Intelligenc	e
Course Objectives:			
1. Understand the basic concept	of control Engi	neering and to obtain r	nathematical
model and transfer function c	of control system	٦.	
2. Obtain overall transfer of the	system by redu	ction algebra and signal	l flow graph.
3. Obtain the response equation			<u> </u>
4. Understand the concept of sta			n using Nyquist
and Bode methods.	,	, , , , , , , , , , , , , , , , , , ,	5 , 1
5. Obtain the system gain for sta	ability by root lo	ocus plot and to underst	and the basic
concept of control action.	5		
· · ·	UNIT-I		
Modelling of Systems and Block d	iagram		07 Hours
ntroduction to Control Systems, T		ol Systems, with examp	oles. Concept o
nathematical modelling of physi	• •		
accelerometer, systems excluded), a		systems. Introduction t	o Block diagran
accelerometer, systems excluded), a algebra, block diagram reduction. N	and Rotational	•	o Block diagran
-	and Rotational	•	_
algebra, block diagram reduction. N	and Rotational umerical proble	ms on all topics.	05 Hours
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1.	Illustrate open loop an	d cl	osed	d loo	op c	ont	rols	syste	ems	rea	l life	exar	nple	s. De	evelo	p the
	mathematical model a				•			-					•			
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2.	Reduce the block diag	ram	to c	oper	n loc	op f	orm	usi	ng k	oloc	k dia	grar	n rec	lucti	on	
	algebra and signal flov	v gr	aph	(Ma	son	's g	ain	form	nula) in	orde	er to	calcu	ulate	ove	rall
	transfer function of the	e sys	stem	า.												
3.	Develop the time respo	onse	e of	1st	and	2nc	dor	der	syst	ems	for	unit	step	inpu	ut.	
	Calculate parameters of	of 2r	nd o	rder	un	der	dan	npeo	d sys	sten	n res	pons	se. D	escri	be	
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	system using R-H crite															
4.	Analyse the stability of							-								
5.	Analyse the parameter					-				-			-	ot Ic	ocus	plot.
	Describe the different											ems.				
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↓	Course Outcomes	2		2	2	2							2	2		
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	2. Benjamin.Kuo.C. (1995															се
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	3. Appukuttan K. K. Cont	rol	Engi	inee	ring	, Ох	for	d un	niver	sity	pub	licati	on, 2	2009		
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Ta	(Deemed to be University)			
re	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
То	tal Teaching Hours	40	CIE + SEE Marks	50+50
Pre	erequisite	CS1001-1		
	Teaching Departr	nent: Roboti	cs & AI Engineering	
Cour	rse Objectives:			
1.	Explain fundamentals of dat	ta structure	es and their applica	ations
	essential for programming/pro	oblem solving].	
2.	Illustrate linear representation of	data structu	res: Stack, Queues, Lists ar	nd Trees.
3.	Demonstrate sorting and search	ing algorithm	S.	
4.	Find suitable data structure durir	ng applicatior	n development/Problem S	olving
5.	Apply Algorithm for solving prot	olems like sor	ting, searching, insertion a	and deletion of
	data			
		UNIT – I		
intro	duction: Data Structure, Classif	ication (Prim	itive and non-primitive),	data structure
oper	ations. Pointers: Definition and Co	ncepts, Array	of pointers, Structure and	pointers
Line	ar Data Structures – Stacks : Intro	duction and	Definition, Representation	n of stack: Array
	structure representation of stacks,	•		
App	lications of Stack: Conversion of E	Expressions, E	valuation of expressions.	
Line	ar Data Structures – Queues: Intro	oduction and	Definition Representation	of Queue: Array
repre	esentation of queues.			
Line	ar Data Structures - Singly Linkec	l lists: Dynam	ic Memory allocation fund	tions. Definition
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2.	Apply the fundamental p	rogi	ramı	min	g kr	now	edg	je o	f da	ta s	truct	ures	to a	nalyz	ze an	d	
	design linear data structu	ires,	nar	nely	, sta	ack,	que	eue,	sing	<mark>jly l</mark> i	inkec	l list	and	dou	bly li	nke	b
	list and use them for solv	ring	prol	blen	ns.												
3.	Implement and apply the	cor	ncep	ot of	bin	ary	tree	es ar	nd g	rap	h dat	ta str	uctu	ires a	and a	also	
	understand their traversa																
4.	Analyze non-recursive an	id re	curs	sive	algo	oritł	nms	and	l to	rep	reser	nt in	term	ns of	stan	darc	
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	Pearson Education, 2007.																
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ì	"Fundamentals of Data S		ctui	res i	in C	Ϊ, Ε	llis	Но	row	itz a	and	Sarta	aj Sa	ahni,	Uni	versi	ues
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		Systems for		Ι				
Co	urse Code:	RI2106-1	Course Type:	PCC				
Теа	aching Hours/Week (L: T: P: S):	3:0:2:0	Credits: 03					
Tot	tal Teaching Hours:	40	CIE + SEE Marks: 50+50					
Pre	erequisite	EE 1001-1		•				
	Teaching Depart	ment: Robotic	s & AI Engineering					
Cou	rse Objectives:							
1.	Understand the principles of flu	id power and h	nydraulic pumps, including	g Pascal's La				
	and pumping theory.							
2.	Gain knowledge of hydraulic ad	ctuators and co	ontrol components, includ	ling cylinde				
	motors, and valves.							
3.	Learn about pneumatic circuits a	nd systems, incl	uding air properties, comp	ressor desig				
4.	Learn about and electro-pneuma	atic logic circuit	S.					
5.	Understand the working princip	les of electrica	l drives such as servo driv	ves, harmor				
	drives, compact drives and varial	ole frequency d	rives and their applications	S.				
		UNIT – I						
opei	OGRAMMABLE LOGIC CONTROLI ration, Programming and concept es using PLC. PLC based electro pne	of ladder diagi	ram, concept of latching c					
90.00				03 Hou				
		UNIT – II						
HYC	DRAULIC ACTUATORS AND CONT	FROL COMPON	NENTS					
Hyd	raulic Actuators: Cylinders – Types	s and construct	ion, Application, Hydrauli	c cushioning				
-	raulic motors - Control Componen		-					
	es – Types, Construction and Oper		-					
	essories: Reservoirs, Pressure Swit	tches – Applic	ations – Fluid Power AN	,				
	olems.	-		04 Hou				
	UMATIC CIRCUITS AND SYSTEM	-						
	perties of air – Perfect Gas Laws –	•	-					
	trol Valves, Quick Exhaust Valves,		-					
	cade method – Electro Pneumatic S	ystem – Elemel	nts – Lauder diagram – Pro	iems, elec 06 Hot				
priet	umatic logic circuits.	UNIT – III						
Flor	trical Drives: Working principle	_	A Harmonic Drives come	act drives a				
	trical Drives: Working principle able frequency drives and its applic		s, mannonic prives, comp	act unves d				
	of Experiments:			06 Hour 14 Hours				

^{1.} A furnace door is opened and closed by a double-acting cylinder. The cylinder is activated by a 4/2-way valve with spring return. This ensures that the door opens

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	only as long as the valve is actuated. When the valve actuating lever is released, the door closes again.
2.	The cover of a hardening furnace is to be raised by a single-acting cylinder. The cylinder is activated by a 3/2-way valve. A 9 kg weight is attached to the cylinder to represent the load. Measure and calculate the following values: 1. Travel pressure, load pressure, resistances and back pressure 2. Advance-stroke time and speed
3.	Design pneumatic circuit to a sorting device for metal stampings. Through operation of the push button on the actuating valve, metal stampings lying in random positions are sorted out and transferred to a second conveyor belt. The forward motion of the piston rod of a single acting cylinder (1A) takes $t = 0.4$ seconds. When the push button is released, the piston rod travels to the retracted end position. A pressure gauge is fitted before and after the one-way flow control valve.
4.	A double-acting cylinder (1A) guides cylinder pins towards a measuring device. The pins are separated by means of a continuous to and fro movement. The oscillating motion can be started by means of a valve with selector switch. The duration of the forward stroke of the cylinder is to be $t_1 = 0.6$ seconds, the return stroke $t_3 = 0.4$ seconds. The cylinder is to remain in the forward end position for $t_2 = 1.0$ seconds, resulting in a cycle time of $t_4 = 2.0$ seconds.
5.	Design a circuit using the cascade system to operate two cylinders (A and B) which, on the operation of a start valve, produces the sequence $A + B + B - A$. The cylinders should park in the positions B - A + when the start switch is in the 'off' position.
6.	A sorting device is used to sort heavy steel workpieces. When a START pushbutton is pressed, the piston rod of a double-acting cylinder pushes the adjacent workpiece off the conveyor belt. When the START pushbutton is released, the piston rod returns to its retracted end position.
7.	A double-acting hydraulic cylinder is used to open and close a furnace door. INCHING operation allows the door to be driven to any desired intermediate position. The cylinder is hydraulically clamped in all such positions.
8.	Using a rotary indexing table plastic containers are to be separated in linear sequence. By pressing a pushbutton switch the oscillating piston rod of a cylinder drives the rotary table in sequence via a pawl. When the pushbutton is pressed again, this drive is switched off.
9.	Using a diverting device parts are to be removed from one conveyor track onto another in linear sequence. By pressing a pushbutton switch the oscillating piston rod of a cylinder pushes the turntable via a pawl in stepped sequence. The parts are diverted and transported onwards in the opposite direction. By pressing another pushbutton switch the drive unit is switched off.
10.	Using a transfer station blocks are to be transferred from a magazine to a processing station. The blocks are pushed out of the magazine by cylinder 1A and transferred to the processing station by cylinder 2A. The piston rod of cylinder 2A may only return when the piston rod of cylinder 1A has reached the retracted end position. The magazine is monitored by means of a limit switch. If there are no more blocks in the magazine, it is not possible to start the cycle. This is indicated by means of an audible signal. The control is to be operated in single cycle.
11.	A stamping device can be operated from three sides. A workpiece is inserted via a guide, whereby it touches two of the three proximity swit- ches B1, B2 and B3. This

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		causes a pneumatic	cylii	nder	· 1.0	to	exte	end	via	a sc	len	oid v	valve	(coil	Y1),	whe	ereby	а
		recess is to be stam	ped	into	o th	e w	ork	oiec	e Tl	he s	tam	ping	сус	le is	to b	e trig	ggere	be
		only if two signal ger	hera	ators	s are	ad	dres	sed	. Fo	r re	asoi	ns of	safe	ety th	ie cy	linde	er mu	st
		be prevented from a	dva	ncin	g, if	all	thre	е рі	oxi	mity	' ser	nsors	are	cont	acteo	d		
	12.	Cylinder A extends a	nd l	bring	gs a	job	un	der	the	star	npii	ng cy	/lind	er B.	Cylir	nder	B the	en
		extends and stamps t	the _	job.	Cyli	nde	r A	can	retu	urn (only	' afte	r cyli	inder	r B ha	as re	tracte	be
		fully. An electro-pne	um	atic	cor	ntro	l cir	cuit	ha	s to	be	dev	elop	ed f	or re	ealizi	ng th	ne
		control task.																
	-	Dutcomes: At the end																
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		oplication of Pascal's La			•	•												
2.		cquire knowledge of h					ors a	and	con	itrol	cor	npor	nents	s suc	h as	cylin	ders,	
		otors, and various type																
3.		nderstand pneumatic o				-	em	s, in	cluc	ling	aır	prop	ertie	es, co	mpr	esso	r	
		esign, and electro-pne																
4.		evelop skills in designi				tic (Ircu	lits	usin	ig ca	isca	ae n	ietho		ogy a	ina e	electro)-
5.		neumatic system comp				<u>ل</u> م ا	o ctr	ical	مارين		incl	udin	<u> </u>	20	drive	he h	-	nic
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Microcontroller and Its Application

Car		DI2100 1		DCC			
	rse Code:	RI2109-1	Course Type:				
	ching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03 50+50			
Tota	Total Teaching Hours:39+0+0CIE + SEE Marks:						
Prei	requisite	CS1001-1, EC1	.001-1				
	Teaching De	partment: Robo	tics and AI				
Cour	se Objectives:						
1.	Identify the architecture of 8 bit	Microcontroller.					
2.	Develop application using 8051	Interrupts, Timer	s/Counters and IO port.				
3.	Understand ARM architecture.						
		UNIT-I					
	duction to 8 bit Microcontrolle			07 Hours			
8051	Architecture, Memory organization	on, addressing m	odes, Basic instructions f	ormat			
	uction set and Programming			08 Hours			
	transfer group, Arithmetic group,	5 5 1	ontrol transfer group, 80	51 Assembly			
Lang	uage programs, Machine Cycles, I						
		UNIT-II					
Micr	ocontroller Peripheral Modules			06 Hours			
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	ramming 8051 I/O port, I/O interfa	J	ising C programs (LED, S	witch and			
	n segment LED using multiplexing	J	ising C programs (LED, S				
Seve	n segment LED using multiplexing	technique)	ising C programs (LED, S				
Sever	n segment LED using multiplexing	ication		05 Hours			
Sever Time 8051	n segment LED using multiplexing ers/Counters and serial commun Timers/Counters in Mode1 & Mo	ication de 2, Timer Prog	ramming examples using	05 Hours C, Serial			
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EXTBO	DOKS:															
1.	The 8051 Microcontro	ller	and	Em	bed	ded	l Sys	sten	1s –	usir	ng as	sem	bly a	nd C,	,	
1	Muhammad Ali Mazid	i an	d Ja	nice	e Gil	lesp	oie N	/lazi	di a	nd I	Rollir	n D. I	ИсКі	nlay;	PHI,	2006
	/ Pearson, 2006.													-		
	Steve Furber, "ARM Sy	/ster	n A	rchit	tect	ure"	, Ed	isor	n We	esley	y Lor	ngma	n 19	96		
REFERE	NCE BOOKS:															
1.	The 8051 Microcontro	ller,	Ker	nnet	h J.	Aya	la, 3	3rd I	Editi	ion,	Thor	nsor	n/Cer	ngage	е	
1	Learning.															
2.	William Hohl, ARM As	sem	bly	Lan	gua	ge –	- Fu	nda	mer	ntals	and	Tecl	hniqu	Jes",	CRC	Press
,	, 2009		-		-	-							-			
Book	s / MOOCs/ NPTEL															
1.	http://nptel.ac.in/co	urse	es/1	061	081	.00/	,									
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Sm	art Mobile R	obots	
Course Code:	RI2111-1	Course Type:	PCC
Teaching Hours/Week (L: T: P: S):	(2:0:2:J)	Credits:	03
Total Teaching Hours:	40	CIE + SEE Marks:	50+50
Prerequisite	EC 1001-1 M	E 1003-1	

Course Learning Objectives:

This Course will enable students to:

- 1. Introduce students to the fundamental concepts of mobile robotics, including various types of mobile robots, their key components, locomotion systems, and wheel configurations.
- 2. Teach students how to develop kinematic models for holonomic and nonholonomic mobile robots and understand their implications on robot motion and control.
- 3. Provide students with a thorough understanding of mobile robot dynamics, focusing on Lagrange-Euler and Newton-Euler methods, and instruct them on how to create computer-based dynamic simulations for wheeled mobile robots.
- 4. Equip students with the skills necessary to implement localization and mapping techniques, such as SLAM and EKF SLAM, and utilize various sensor technologies to enhance mobile robot navigation capabilities.
- 5. Enable students to apply mobile robot navigation competences, including path planning methods, graph construction and search algorithms, and obstacle avoidance techniques, in order to design and implement effective autonomous navigation strategies for mobile robots.

Unit I

Introduction: Introduction to mobile robots and mobile manipulators. Components of a mobile robot. Types of mobile robots.

Locomotion: Introduction, Key issues for locomotion, Types of land-based mobile robots, wheeled locomotion case studies.

Mobile Robot Kinematics: Introduction, Need of mathematical model, degree of freedom. Differential Kinematics: Representing robot position, forward differential kinematics, Inverse differential kinematics, Degree of manoeuvrability, Types of wheels for mobile robots. Kinematic simulation of a mobile robot. A generalized wheel model, Examples: Differential wheel drive mobile robot, Skid steering wheel drive mobile robot, Omni wheel drive mobile robot, Mecanum wheel drive mobile robot, Tricycle wheel drive mobile robot.

Types of Mobile Robots based on Wheel configuration: Holonomic and non-holonomic systems, kinematic model, Pseudo Inverse.

15 Hours

Unit II

Dynamics of mobile robot: Introduction to Mobile robot dynamics, Equations of Motion, Lagrange-Euler Formulation, Derivation of Mobile robot dynamic relation, Dynamic Models for differential drive robot, skid steering drive robot, Omni wheel drive robot, Mecanum wheel robot, tricycle wheel drive robot.

Perception: Sensors for Mobile Robots, Sensor classification, characterizing sensor performance, Wheel/motor sensors, Heading sensors, Ground-based beacons, Active ranging, Motion/speed sensors, Vision-based sensors.

Mobile Robots - Localisation and Mapping: Autonomy for Robots, Building Blocks of Navigation, Challenges of Localization, Noise and Aliasing, Mobile robot localisation: Odometry, Dead reckoning, Map based localisation, Markov Localisation, Kalman Filter. Autonomous map building: SLAM, EKF SLAM. **15 Hours**

NITTE

Unit-III

Mobile Robot Navigation: Competences for Navigation, Path Planning Methods, Graph Construction: Visibility graph, Voronoi diagram, Cell decomposition methods, Graph Search Methods and Algorithms: Deterministic Graph Search, Breadth-first search, Depth-first search, Grass fire, Dijkstra's algorithm. Path Planning- A* Algorithm and Potential Field methods. Obstacle Avoidance: Bug Algorithm.

10 Hours

List of Simulation Experiments:

Kinematic simulation and motion animation of a land based mobile robot using a MATLAB

- simulation of mobile robot using MATLAB a general model 0
- simulation of Deferential wheel drive mobile robot using MATLAB 0
- simulation of Skid steering wheel drive mobile robot using MATLAB 0
- simulation of an Omni directional wheel drive mobile robot using MATLAB 0

	\circ simulation of Mecanum wheel drive mobile robot using MATLAB
	05 Hours
	List of practical experiments
	Introduction to ESP-32
	 Different ways to program it (Embedded C, micro python) comparison.
	 Simple blinking program with using
	 Analogue write
	 LEDC write (Including parameters such as resolution, frequency)
	 Controlling a motor
	 Circuit connection and Explanation.
	 Calculation for Duty cycle.
	 Effect of Duty cycle on the motor.
	 Effect of frequency on the motor.
	 Communication using ESP32 Controlling a GM/hashed Makila Bakata (d)/f(controlling to the back to the ECP32
_	 Controlling of Wheeled Mobile Robot of different wheel types using ESP32 Differential wheeler as his relativistic PC control
-	Differential wheel mobile robot using RC control
	Mecanum wheel mobile robot using RC control 10 Hours
C	se Outcomes: At the end of the course student will be able to
1	
1.	Develop a comprehensive understanding of the different types of mobile robots
	and their key components, including locomotion systems and wheel configurations.
2.	Build kinematic models of holonomic and nonholonomic mobile robots
3.	Apply and analyze the principles of mobile robot dynamics to design and develop
	efficient computer-based dynamic simulations of various wheeled mobile robots,
	accounting for their motion and control.
4.	Acquire skills in implementing localization and mapping techniques for mobile
	robots, including SLAM and EKF SLAM, and apply various sensor technologies for
	robot perception to enhance navigation capabilities.

5. Apply mobile robot navigation competences, including path planning methods, graph construction and search algorithms, and obstacle avoidance techniques, to effectively design and implement autonomous navigation strategies for mobile robots.

Program Outcomes→	1	2	2	1	-	C	7	0	0	10	11	10		PSO.	Ļ
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RI2111-1.2	3	2	1	-	-	-	-	-	-	-	-	1	3	1	1
RI2111-1.3	3	2	1	-	1	-	-	-	-	-	-	1	3	2	2
RI2111-1.4	3	2	1	-	1	-	-	-	-	-	-	1	2	2	2
RI2111-1.5	3	2	1	-	1	-	-	-	-	-	-	1	2	2	2

1: Low 2: Medium 3: High

TEXTBOOKS:

NITTE

- 1. R Siegwart, IR Nourbakhsh, D Scaramuzza, Introduction to Autonomous Mobile Robots, MIT Press, USA, 2011.
- 2. SG Tzafestas, Introduction to Mobile Robot Control, Elsevier, USA, 2014.
- 3. A Kelly, Mobile Robotics: Mathematics, Models, and Methods, Cambridge University Press, USA, 2013.
- 4. S Thrun, W Burgard, D Fox, Probabilistic Robotics, MIT Press, USA, 2005.
- 5. G Dudek, M Jenkin, Computational Principles of Mobile Robotics, Cambridge University Press, USA, 2010.

Web links and Video Lectures (e-Resources):

https://onlinecourses.nptel.ac.in/noc22_me38/preview



Professional Core Courses (Lab)

Feachin	Code:			R	260	1-1		Co	ourse	Тур	e:			P	CC La	b
	g Hours/Week (L: T: P: S):			0:	0:2:0)		Cr	edits	:				0	1	
Fotal Te	aching Hours:			15	5			CI	E + S	SEE N	/larks	:		5(0+50	
Prerequi	-			C	5100	1-1										
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	lake use of Data sets in imp			_												
	nplement the machine learn			· ·		algo	rithm	ns in	any	suita	ble la	ngua	ge of	choic	е	
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3.	Implement and Demonstr		· ·				<u> </u>									
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	on a given set of training				_				-			•				
5.	Write a program to imple	men	t k-N	leare	est N	eighl	oor a	Igori	thm	to cl	assify	the i	ris dat	ta set		
	Print the output predictio	ns.				_		-								
6.	Write a program to const								-						del to	
	demonstrate the diagnost						-				art Di	sease	e Data	Set.		
7.	Demonstrate the working															
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9.	building and apply this kr Experiment on anomaly d			to c	lassi	iy a r	iew s	amp	ie.							
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	utcomes Mapping with P			1	1	1		_	0	0	10		10			
	rogram Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	ř
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	RI2601-1.3	3	3	2	3	3	-	-	-	-	I	-	3	3	3	3

	Contro	ol Engineer	ing Lab	
Cou	ırse Code:	RI2602-1	Course Type:	PCC Lab
Теа	ching Hours/Week (L: T: P: S):	0:0:2:0	Credits:	01
Tota	al Teaching Hours:	15	CIE + SEE Marks:	50+50
Pre	requisite	EC1001-1,	EE1001-1	
	Teaching Department	: Robotics ar	d Artificial Intelliger	nce
Cour	rse Objectives:			
1.	To determine the time and free	quency doma	in reposes of a given s	second order
	system using softwarepackage	or discrete co	mponents.	
2.	To design and analyze Lead, Lag	and Lag – Lea	ad compensators for g	iven
	specifications.			
3.	To draw the performance chara	cteristics of a	c and DC servomotors	s and synchro-
	transmitter receiver pair.			
4.	To study the DC position & feed	lback control	system and to study t	he effect of P, PI,
	PD and PID controller and Lead of	compensator	on the step response	of the system.
5.	To write a script file to plot ro	ot locus, boc	le plot, to study the s	stability of the
	system			
	Lis	t of Experim	ents	
1.	Speed control Experiments			
	a) Speed control of DC mo	tor		
	b) Speed control of AC mo	tor		
	c) Speed control of Steppe	r motor		
	d) Speed control of BLDC n	notor		
2.	Experiment to determine freque	• •	-	
	a) To design a passive RC l	ead compens	ating network for the	given
	specifications, viz, the m	•		ncy at which it
	occurs and to obtain the		•	
	b) To design a passive RC	•	-	-
	specifications, viz, the m		. .	cy at which it
	occurs and to obtain the		•	
	c) To determine experimen	itally the trans	fer function of the lag	compensating
	network			
3.	To study a second order system	and verify the	e effect of (a) P, (b) PI,	(c) PD and (d) PID
	controller on the step response.			
4.	To simulate a typical second ord	er system and	d determine step respo	onse and evaluate
	timeresponse specifications.			
	To evaluate the effect of adding			e of second order
	system. To evaluate the effect of			
5.	To examine the relationship be	•		onse and stability,
	open-loop frequency and closed			
6.	To study the effect of open loop	•		ntour Comparative
	study of Bode, Nyquistand root			
7.	To simulate a D.C. Position contr			
8.	To verify the effect of input wave		n and system type on s	steady state errors.
9.	Inverted Pendulum control Expe	riment		

	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 202
10.	Experiments on Height and orientation control of a Quadcopter
Cou	rse Outcomes: At the end of the course student will be able to
1.	Utilize software package and discrete components in assessing the time and
	frequency domain response of a given second order system.
2.	Determine the performance characteristics of AC and DC motors used in control
	systems.
3.	Simulate the DC position and feedback control system to study the effect of P, PI,
	PD and PID controller and Lead compensator on the step response of the system.
4.	Develop script files to plot Root locus, Bode plot and Nyquist plot to study the
	stability of control system.
5.	Stabilization and control of the unstable inverted pendulum system with a close-
	loop control system and Design a Controller for Quadcopter height and orientation
C -	

Course Outcomes Mapping with Program Outcomes & PSO

ourse outcomes mapping			- egi	•••••											
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO,	Ļ
↓ Course Outcomes															
RI2602-1.1	3	3	2	2	2	-	I	-	I	-	-	2	2	1	2
RI2602-1.2	3	3	2	2	2	-	I	-	I	-	-	2	2	1	2
RI2602-1.3	3	3	2	2	2	-	I	-	I	-	-	2	2	1	2
RI2602-1.4	3	3	2	2	2	-	I	-	I	-	-	2	2	1	2
RI2602-1.5	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2

1: Low 2: Medium 3: High

REFERENCE BOOKS:

1.	Katsuhiko Ogata (2004) " Modern Control Engineering" Prentice Hall of India Ltd.,
	New Delhi
2.	I. J. Nagarath and M. Gopal, (2002) "Control system" New Age International Publisher
3.	Harrison H.L. and Bollinger J.G. (1968) "Automatic controls", 2PndP edition,
	Interna¬tional Text Book Co. U.S.A.
4.	Gopal M (2005) " Modern Control Systems", New Age International Publisher
5.	Benjamin.Kuo.C. (1995) "Automatic Control Systems", EEE, 7PthP Edition Prentice Hall
	of India Ltd. New Delhi
6.	Appukuttan K. K. Control Engineering, Oxford university publication, 2009



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	Teaching De	par	tme	nt: I	Rob	otic	:s &	. AI	Eng	ine	ering	J				
C οι	ırse Objectives:															
1.	Linear data structures and th	neir	арр	licat	ions	suc	h a	s sta	acks	, qu	eues	and	lists			
2.	Non-Linear data structures a	nd	thei	r ap	olica	tio	ns si	uch	as t	rees	5					
3.	Sorting and searching algori	thm	IS													
4.	Basic algorithm implementat	tion	S													
5.	Implementation of DFS, BFS	trav	/ersa	als o	fag	rap	h a	nd F	Prim	s alg	gorit	hm				
		L	.ist (of E	xper	im	ents	S								
1	Pointer implementations usi	ng a	array	/s ar	nd st	ruc	ture	es								
2	Stack implementation using	arra	ays													
3	Queue implementation array	/S														
4	Evaluation of arithmetic exp	ress	ion	usin	g sta	acks	5									
5	Tower of Hanoi problem usi	ng r	ecu	rsior	۱.											
6	Singly Linked list implement	atio	n.													
7	Dynamic implementation of	stad	ck d	ata s	struc	ture	e (lii	nked	d list	t).						
8	Dynamic implementation of	que	eue	data	stru	ctu	re (l	linke	ed li	st).						
9	Binary Tree Construction and	d Tr	ee ti	rave	rsal (ope	rati	ons.								
10	Implementation of quick sor			-			-									
11	Implement Linear search and		nary	/ Sea	arch	alg	orit	hms	s to	sea	rch a	n ele	emer	nt in	a gi	ven
	array. (with calculation of tim															
12	Construction of Binary Searc	h Ti	ee a	and	post	fix e	expi	ressi	ion t	tree	•					
13	Implement N-Queens proble								niq	ue.						
14	Implementation of DFS and			/ersa	als o	faq	grap	bh								
15	Implementation of Prims alg	orit	hm													
-	Irse Outcomes: At the end of											<u> </u>				
1.	Design and Implement vario													ictur	es lil	<e< th=""></e<>
-	linked list and its different ty												ots.			
2.	Implement different types of	raig	jorit	nms	and	i an	alys	se th	eir	effic	lency	y				
Cai					0 ±			0. P	60							
COL	Irse Outcomes Mapping with					5				0	10	11	10		<u>`</u>	1
-	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		0 ↓	-
-	↓ Course Outcomes	2	2		2	2							1	1	2	_
	RI2603-1.1	3	2	-	3	3	-	-	-	-	-	-	1	-	3	-
	RI2603-1.2	3	1	-	3	3	-	-	-	-	-	-	1	-	3	
	ow 2: Medium 3: High															
	esources					,										
1.	Data Structures <u>https://cse02</u>	L-iii	th.vl	abs.	ac.in	1/										



Cour	se Code:			R	1260)4-1		C	ours	e T	ype			Р	CC L	.ab
	hing Hours/Week (L: T	• D • (5)	_	:0:2		•		redi		JPC			0		
	I Teaching Hours			2							E Ma	rks			<u>-</u> 0+5	0
	equisite			_	-	01-	1 F(01-:		- 1114	IKS		J		0
Tere	Teaching	Don	ərtr								noor	ina				
ours	e Objectives:	Бер		nen	L. IX		iic5	u i		ingi	icei	iiig				
1	Introduce the instruction s	et of	8051	1 mic	roco	ontro	oller									
2.	Write program for interfac							,								
3.	Write program to interface					I UN	ITs									
1.	Write program to interface	-				•										
5.	Write program to interfaci						on									
		<u>g</u> 56				peri		nts								
1.	Data Transfer - Block	mo							v La	nau	iade					
2.	Arithmetic Instructio											and	divis	sion	Nur	nbo
	conversion – Assemb							·		•						
3.	LED, Seven Segment	-		-		rfac	e –	Emb	bedc	led	C pro	ograi	mmii	ng		
4.	DC Motor speed con	trol	usin	g P	ΜM	— E	mbe	edde	ed C	Pro	grar	nmir	ng			
5.	Interfacing linear act	uato	r us	ing	step	per	mo	tor	– En	nbe	ddec	I C Pi	rogra	amm	ing	
6.	Servo motor interfac	e – E	mb	edd	ed (C Pro	ogra	mm	ning							
7.	Interfacing Robotic A	ARM	with	י-X ו	Y-Z	axis	mo	tior	1 – E	mbe	edde	d C I	Prog	ramr	ning	
8.	Interfacing Solenoid	valv	/e us	sing	rela	ay –	Emb	bed	ded	СР	rogra	amm	ing			
9.	External ADC and Te	mpe	ratu	re c	onti	rol ii	nter	face	e to	805	1.					
10.	Cenerate amerent						•			0		Ramp	o etc	: us	ing	DA
	interface to 8051; ch							am	plit	ude	•					
11.	Bropper motor conta					051	•									
12.	DC motor control int	erfa	ce to	o 80	51.											
								•••								
1	e Outcomes: At the end						ent	WIII	be a	ble	to					
L.	Use instruction set to solve	<u> </u>							1				. .			
2.	Develop embedded C codi interface ADC and DAC	ng to	Inte	errac	e l e l	J, Se	ven	segn	nent	and	LCD,	emb	eaae	acc	oaing	g to
3.		nato	into	rface	octo	0.00 or	mot	ora	n d D	Cm	atore	ontro			alan	
> .	Develop embedded C codi embedded C coding to der									Cm		ontre	n and	Dev	eiop	
ourc	e Outcomes Mapping									0						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO	1
	urse Outcomes	- -	2	5	-			,	0		10		12	1	2	3
	RI2604-1.1	3	2	1	_	_	-	_	-	-	_	_	1	2	1	2
	RI2604-1.2	3	2	1	_	_	-	_	-	-	_	-	1	2	2	2
	RI2604-1.3	3	2	1	_	-	-	_	-	_	_	<u> </u>	1	2	2	2
	1: Low 2: Medium 3	-		-	1	1	1	<u> </u>	1	l	1	1	L +	~		1 4
EFFR	RENCE BOOKS:		7''													
											FOR					

	Robot Progra	mming and Si	mulation Lab	
Cou	ırse Code:	RI2605-1	Course Type:	PCC Lab
Теа	ching Hours/Week (L: T: P: S):	0:0:2:0	Credits:	01
Tot	al Teaching Hours:	15	CIE + SEE Marks:	50+50
	requisite	CS1001-1		
	Teaching Depart	nent: Robotics &	k AI Engineering	
Cour	rse Objectives:			
1.	Understand the features of Dok	oot Magician and	Dobot Studio Software	
2.	Understand the concept of RAF			
3.	Understand the hardware confi	guration and abil	ities of ABB IRB 1600 Rob	ot
4.	Understand the features of CO	GNIX camera and	its application	
	Li	st of Experiment	S	
1.	Experiment on pick and plac			obot)
	Using Suction Cup and b) Us	J.		
2.	Experiment to perform differ	ent operations us	sing DOBOT Magician (mi	ni robot)
	(a) Sorting operation			
	(b) Stacking operation			
2	(c) Palletising operation			
3.	Experiment to Write and Dra			
4. 5.	Demonstration of 3D Printin			
э.	Software simulation in Rok			bot Studio,
6.	Programming concepts, Libr Introduction to RAPID progra			oons Bulos
0.	and recommendations for R	-	of RAPID Programming, L	loops, Rules
	RAPID robot functionality: In	•	anals RAPID Programmin	a Structure
	Rapid Procedure, Modules, D	-		-
7.	Simulation to perform pick			
	Software	und place oper		
8.	Simulation to perform conve	vor tracking and	palletizing operation in R	obot Studio
	Software	,		
9.	Simulation to perform sortin	g operation of ar	object in Robot Studio S	oftware
10.	Introduction to COGNEX C			
	camera programming using			
11.	ABB IRB 1600 robot: Introduc	tion to ABB robo	t, IRC5 single cabinet cont	roller, teach
	pendent, hardware connection		-	
12.	Demonstration of ABB IRB	1600 robot: Pick	and place operation usi	ng two jaw
	gripper, three jaw gripper an	d suction cup. W	elding operation.	
13.	Demonstration of RAPID pro	gramming in teac	h pendant and execution	of the same
	using ABB robot.			
	rse Outcomes: At the end of the			
1.	Develop ABB program for exect	uting any defined	task	

2. Perform process automation using involved with Robots

Course (Outcomes Mapping v	vith	Pro	ogra	m C	Duto	om	es 8	<u></u> ያ ይ	50						
Pr	rogram Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Cours	se Outcomes													1	2	3
	RI2605-1.1	3	2	-	3	3	-	-	-	-	-	-	1	-	3	2
	RI2605-1.2	3	1	-	3	3	-	-	-	-	-	-	1	-	3	2
	1: Low 2: Medium 3:	Hi	gh													
REFERE	NCE BOOKS:															
1.	ROBOTICS Product sp	beci	ficat	tion	IRB	160	0/1	660,	ABE	Ro	bots	5				
2.	ABB Robotics Operat	ing	Mar	nual	Rot	ots	tudi	0								



Program Specific Ability Enhancement Courses (AEC)

	NS AND DESI	GN THINKING	
Course Code:	ME1654-2	Course Type	AEC
Teaching Hours/Week (L: T: P: S)	1:0:0:0	Credits	01
Total Teaching Hours	15+0+0+0	CIE + SEE Marks	50+50
Teaching Departme	ent: Robotics and	Artificial Intelligence	e
Course Objectives:			
1. To explain the concept of des	sign thinking for p	product and service dev	elopment
2. To explain the fundamental co	oncept of innova	tion and design thinking	g
3. To discuss the methods of im	plementing desig	In thinking in the real w	vorld.
	UNIT-I		
Design Thinking			03 Hours
Understanding Design Thinking:			
Shared model in team-based desigr	n – Theory and p	ractice in Design thinkir	na – Explore the
presentation.	, , ,	5	5 1
Tools for Design Thinking:			
Real-Time design interaction capture	e and analysis –	Empathy for design	
Teaching-Learning Process:		inputity for design	
Introduction about the design thinki	ing [.] Chalk and Ta	lk method	
Theory and practice through presen	-	ik method	
Case studies on design thinking for		ion and analysis	
case studies on design tranking for	UNIT-II	ion and analysis	
Desian Thinking for Strategic Inno	ovations		05 Hours
Design Thinking for Strategic Inno Design Thinking in IT	ovations		05 Hours
Design Thinking in IT		nario-based Prototyping	
		nario-based Prototyping	
Design Thinking in IT Design Thinking to Business Process	s modeling – Scer	nario-based Prototyping	
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova	s modeling – Scer ations]
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio	s modeling – Scer ations on – Strategic Fe	oresight - Change – S) Sense Making –
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re	s modeling – Scer ations on – Strategic Fo edefinition - Extre	oresight - Change – S me Competition – exp	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re Standardization – Humanization -	s modeling – Scer ations on – Strategic Fe edefinition - Extre Creative Culture	oresight - Change – S me Competition – exp	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re	s modeling – Scer ations on – Strategic Fe edefinition - Extre Creative Culture	oresight - Change – S me Competition – exp	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig	s modeling – Scer ations on – Strategic Fe edefinition - Extre Creative Culture	oresight - Change – S me Competition – exp	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn.	oresight - Change – S me Competition – exp e – Rapid prototyping	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn.	oresight - Change – S me Competition – exp e – Rapid prototyping	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representatio Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs	oresight - Change – S me Competition – exp e – Rapid prototyping	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization – Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn.	oresight - Change – S me Competition – exp e – Rapid prototyping	g Gense Making – erience design - g, Strategy and
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs UNIT-III	oresight - Change – S me Competition – exp e – Rapid prototyping	9 Sense Making – erience design -
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization – Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs UNIT-III	oresight - Change – S me Competition – exp e – Rapid prototyping	g Gense Making – erience design - g, Strategy and
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success Design Thinking Workshop Design Thinking Workshop Empathi	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs UNIT-III	oresight - Change – S me Competition – exp e – Rapid prototyping	g Gense Making – erience design - g, Strategy and
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success Design Thinking Workshop Design Thinking Workshop Empathi Teaching-Learning Process	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs UNIT-III ze, Design, Ideate	oresight - Change – S me Competition – exp e – Rapid prototyping ance of the design	Sense Making – erience design - g, Strategy and 07 Hours
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success Design Thinking Workshop Design Thinking Workshop Empathi Teaching-Learning Process Presentation by the students on the	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Cultur gn. I business accepta sful designs UNIT-III ze, Design, Ideate	oresight - Change – S me Competition – exp e – Rapid prototyping ance of the design	Sense Making – erience design - g, Strategy and 07 Hours
Design Thinking in IT Design Thinking to Business Process Design Thinking for Strategic Innova Growth – Storytelling representation Maintenance - Relevance – Value re Standardization – Humanization - Organization – Business Model desig Teaching-Learning Process Case studies on design thinking and Business model examples of success Design Thinking Workshop Design Thinking Workshop Empathi Teaching-Learning Process	s modeling – Scer ations on – Strategic Fo edefinition - Extre Creative Culture gn. I business accepta sful designs UNIT-III ze, Design, Ideate success of Live p	presight - Change – S me Competition – exp e – Rapid prototyping ance of the design e, Prototype and Test	Sense Making – erience design - g, Strategy and 07 Hours

N (N	ITTE					Curr	iculu	ım — İ	B.Te	ch. (F	Robotic	s & A1	rtificia	l Intell	igenec	e): 202
1.	Explain various design p	roc	ess	proc	edu	re										
2.	Generate and develop d						h d	iffer	ent	tecł	nniqu	les				
3.	Explain the significance	of E	Desig	gn T	hink	ing	to l	Jnd	ersta	and	proc	lucts				
Cours	e Outcomes Mapping v	vith	Pro	ogra	m C	Duto	om	es 8	<u>ک</u> PS	50						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PS	50 ↓
↓ Co	urse Outcomes													1	2	3
	ME1013-1.1	2	-	2	-	-	-	-	-	-	-	-	-			
	ME1013-1.2	-	-		-	-	-	2	2	-	-	-	-			
	ME1013-1.3	-	-		-	-	-	-	-	-	3	3	-			
											1: Lo	ow 2	: Me	diur	n 3:	Higł
ΓΕΧΤΙ	BOOKS:															
1.	John.R.Karsnitz, Stephe	en (D'Br	ien	and	Jo	hn	P. I	Huto	hin	son,	"Eng	ginee	ering	De	sign"
	Cengage learning (Inter	nat	iona	al ed	itior	n) Se	ecor	nd E	ditic	on, 2	2013.					
2.		0					-	esig	n Tl	nink	ing i	s the	e Ne>	kt Co	mpe	titive
	Advantage", Harvard Bu															
3.	Hasso Plattner, Christop					arry	Lei	fer (eds)	, "D	esig	n Thi	nkin	g: Ur	nder	stanc
	– Improve– Apply", Spr															
4.	Idris Mootee, "Design 1		-			-					What	: The	y Ca	n't T	each	ι Υοι
	at Business or Design S															
5.		⁻ М.	Sha	hin,	"En	gine	erir	ng D	esig	jn P	roce	ss", (Ceng	Jage	Lear	ning
	Second Edition, 2011.						_				•			•.		•
6.	Jeanne Liedtka, Andre		-								-					-
	Thinking - Ten Stories	of	Wha	at W	ork	s", (_olu	mbi	аВ	usin	ess :	scho	OI PI	ublis	hing	, Sep
- D	2013.															
<u>е воо</u> 1.	oks / MOOCs/ NPTEL		nro	ont.	atio	oc /	Inre	- du	~+ ;f/		lo/d	faul	t htn	al		
<u> </u>	www.tutor2u.net/busine https://docs.oracle.com													11		
<u>2.</u> 3.	www.bizfilings.com > Ho				_											
<u> </u>	https://www.mindtools.							uci			ושוווע	1				
<u> </u>	https://www.quicksprou							50-0	nair	IPPr	-\/\-	r-co	mne	tit		
<u> </u>	www.vertabelo.com/blo												npe			
7.	https://support.microsc								cing	, ne	enng	1				
8.	https://support.google.								hl=	en						
<u> </u>	https://support.googic.															

9. https://www.youtube.com/watch?v=2mjSDIBaUIM

- **10.** thevirtualinstructor.com/foreshortening.html
- **11.** https://dschool.stanford.edu/.../designresources/.../ModeGuideBOOTCAMP2010L.pdf
- https://dschool.stanford.edu/use-our-methods/ 6. https://www.interactiondesign. 12.

org/literature/article/5-stages-in-the-design-thinking-process 7.

- http://www.creativityatwork.com/design-thinking-strategy-for-innovation/ 49 8. 13.
- 14. https://www.nngroup.com/articles/design-thinking/ 9.
- **15.** https://designthinkingforeducators.com/design-thinking/ 10.



	Resea	rch Metho	dology	
Cou	irse Code	RI1659-1	Course Type	AEC
Tea	ching Hours/Week (L: T: P: S)	2:0:0:0	Credits	02
Tota	al Teaching Hours	25	CIE + SEE Marks	50+50
Pre	requisite	HU 1001-1	, MA 1001-1, MA 1003	3-1
	Teaching De	epartment: R	obotics & AI	
Cour	se Objectives:			
1.	Explain the importance of resear	rch methodolo	ogy, Explain the steps ir	n defining the
_	research problem.	1	· · · · ·	
2.	Explain methods of reviewing th			
3.	Discuss the methods of designin measuring of the data.	g sampling su	irvey. Discuss methods (bi scaling and
4.	Perform Hypothesis testing usin	g the concept	t of mean and variance.	
		J		
5.	Discuss interpretation and repor	rt writing tech	niques.	
		Unit-1		
to res Rese	ewing the literature: Place of the search problem arch Design: Meaning of Resear d Design ours			-
		Unit-2		
and N Data Colle Study	gn of Sample Surveys: Design of Non-sampling Errors, Collection: Introduction, Experim ction of Secondary, Data, Selectio y Method. ing of Hypotheses: Hypothesis, B	nental and Sui n of Appropri	veys, Collection of Prin ate Method for Data Co	nary Data, ollection, Case
7 ho			concerning resting of	nypotneses,
		Unit-3		
Interµ in W	pretation, Precaution in Interpreta riting Report, Layout of the Reso nanics of Writing a Research R	ntion, Signification,	Types of Reports, Or	Different Steps al Presentation

Course Outcomes: At the end of the course student will be able to

1.	Explain the importance of research methodology, Explain the steps in defining the research problem.
2.	Explain methods of reviewing the literature and research design.
3.	Discuss the methods of designing sampling survey.
4.	Perform Hypothesis testing using the concept of mean and variance
-	

5. Discuss interpretation and report writing techniques.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	0 ↓	
↓ Course Outcomes													1	2	3
RI1653-1.1	3	2								3					1
RI1653-1.2	3	2								3					1
RI1653-1.3	3	2								3					1
RI1653-1.4	3	2								3					1
RI1653-1.5	3	2								3					1
1															

1: Low 2: Medium 3: High

REFERENCE MATERIALS:

1.	Research Methodology: Methods and Techniques, C.R. Kothari, Gaurav Garg, New Age International 4 th Edition, 2018
2.	Research Methodology a step-by step guide for beginners. (For the topic Reviewing the literature under Unit 2), Ranjit Kumar, SAGE Publications Ltd . 3 rd Edition, 2011
3.	Research Methods: the concise knowledge base Trochim Atomic Dog Publishing 2005
4.	Conducting Research Literature Reviews: From the Internet to Paper Fink A Sage Publications, 2009
E Resou	rces
1.	NPTEL course material related to operations management, operations research and entrepreneurship



	SOCIAL CO	ONN	IECT	AND F	ESP	ONS	IBIL	Y I I.							
C ου	ırse Code:		HU	1007-1			С	ourse	е Тур	e:	AEC				
Теа	ching Hours/Week (L: T: P	: S):	1:0:	0:0			C	Credit	ts:	01					
Tot	al Teaching Hours:		15				CIE +	SEE	Mark	s:	50+5	50			
	Teaching D	epar	tment	t: Respe	ctive	Dep	artm	ent							
Cour	se Objectives:														
1.	Understand Rural Society														
2.	Acquire the knowledge ab	out R	Rural E	conomy											
3.	Know the working of rural	adm	inistra ⁻	tion											
4.	Familiarize the different ru	ral sc	heme	s of Gov	ernar	nce									
			U	NIT-I											
Аррг	reciation of Rural Society										3 Ho	ours			
	l Society, Caste and Gend	er re	elation	s, Rural	valu	ies, l	latur	e an	d Re	SOL	irces,	Rura			
	structure.										1				
	erstanding Rural Economy										3 Ho				
-	culture, Farming, Landowne	-			geme	ent, A	nima	al Hu	sband	dry,	Non	-Farr			
Liveli	hoods And Artisans, Rural Er	ntrep													
			U	NIT-II					UNIT-II						
	I Transfit the read														
	l Institutions										3 Ho				
Tradi	itional Rural Organizations, S			roups, P	ancha	ayat	Raj Ir	nstitut	tions	- G	_				
Tradi Gran	tional Rural Organizations, S n Panchayat, Standing Comm	nittee		roups, P	ancha	ayat	Raj Ir	stitut	tions	- G	ram S	abha			
Tradi Gram Rura	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programme	nittee es	25	•							ram S 3 H	abha ours			
Tradi Gram Rura Histo	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programmo pry of Rural Development	nittee es in In	es dia, C	urrent	Natio	onal I	Progr	amm	es -	Sai	ram S 3 H va Sh	abha ours niksh			
Tradi Gram Rura Histo Abhi	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programm ory of Rural Development yaan, Beti Bachao – Beti P	nittee es in In adha	dia, C o, Ayı	urrent Jshmaar	Natio 1 Bha	onal I arath,	Progr	amm	es -	Sai	ram S 3 H va Sh	abha ours niksh			
Tradi Gram Rura Histo Abhi	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programmo pry of Rural Development	nittee es in In adha	dia, C o, Ayı	urrent Jshmaar	Natio 1 Bha	onal I arath,	Progr	amm	es -	Sai	ram S 3 H va Sh	abha ours niksh			
Tradi Gram Rura Histo Abhi	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programm ory of Rural Development yaan, Beti Bachao – Beti P	nittee es in In adha	dia, C o, Ayu ning, N	urrent ushmaar IRLM, M	Natio 1 Bha	onal I arath,	Progr	amm	es -	Sai	ram S 3 H va Sh	abha ours niksh			
Tradi Gram Rura Histo Abhi Yojar	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programm ory of Rural Development yaan, Beti Bachao – Beti P na, Skill India, Decentralised	nittee es in In adha Planr	dia, C o, Ayu ning, N	urrent Jshmaar	Natio 1 Bha	onal I arath,	Progr	amm	es -	Sai	ram S 3 H va Sh PM A	abha ours niksh Awaa			
Tradi Gram Rura Histc Abhi Yojar Corp	itional Rural Organizations, S n Panchayat, Standing Comm I Development Programm ory of Rural Development yaan, Beti Bachao – Beti P na, Skill India, Decentralised porate Social Responsibility	nittee es in In adha Planr	dia, C o, Ayu ning, N UI R)	urrent ushmaar IRLM, M NIT-III	Natio Bha NREC	onal I arath, GA	Progr Swa	amm chh I	es -	Sai	ram S 3 H va Sh	abha ours niksh Awaa			
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1: Low 2: Medium 3: High

REFERENCES:

UGC., "Unnat Bharat Abhiyan", 2020

Agarwal, S.K., "Corporate Social Responsibility in India", SAGE Publication, 2008.

Unnat Bharat Abhiyan. (n.d.). Unnat Bharat Abhiyan Brochure. Retrieved from

https://unnatbharatabhiyan.gov.in/app/webroot/files/brochure.pdf

EMPLOYABILITY SKILL DEVELOPMENT

00
50+00
-

Teaching Department: Robotics and Artificial Intelligence

Course Objectives:				
1.	To explain the students the necessity of clearing the aptitude tests irrespective of the written test is for jobs or higher education.			
2.	To assess the readiness of the students to appear for the aptitude test and assisting them to better it if already ready, else train them.			
3.	To evaluate the understanding of the students in answering quantitative multiple- choice questions and guide them to improve it.			
4.	To evaluate the preparedness of the students to answer the analytical and logical questions.			
5.	To evaluate the quality of the students with regard to their professional language grammar, vocabulary and communication skills.			

UNIT-I

Quantitative06 HoursNumbers (Odd, even, H.C.F & L.C.M, Square roots & cube roots, Average, Percentage), Ratios& Proportions, Partnership, Time & work, Pipes & Cistern, Speed, Problems on trains,Problems on boats & streams, Allegation & Mixtures.

Analytical/ Logical

Numerical logic (next number in series, odd man out), Coded language, Syllogism, Direction (N-E-W-S), Seating arrangement, Blood relations, Statement & Conclusion

UNIT-II

UNIT-III

Verbal

Vocabulary (root words, prefix, suffix, synonyms, antonyms), One word substitution, Idiom/phrases, Sentence completion, Active & Passive voice, Direct and indirect speech.

Course Outcomes: At the end of the course student will be able to

1. Answer the quantitative multiple-choice questions.

2. Analyse the analytical and logical questions.

03 Hours

06 Hours

Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

_	(Deem	ned to be University)
	3.	Improve the professional language grammar, vocabulary and communication skills.
	4.	Clear the aptitude tests of any employer or higher educational institution.
	5.	Advance in the chosen field of interest by appending aptitude skills with the technical
		skills

Course Outcomes Mapping with Program Outcomes & PSO

			<u> </u>												
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PS	O↓
↓ Course Outcomes													1	2	3
UM1003-1.1	3	3	-	-	-	-	-	-	2	2	1	-			
UM1003-1.2	3	3	-	-	-	-	-	-	2	2	1	-			
UM1003-1.3	3	3	2	-	-	-	-	-	2	2	1	-			
UM1003-1.4	3	3	2	-	-	-	-	-	2	2	1	-			
UM1003-1.5	3	3	2	-	-	-	-	-	2	2	1	-			
										4 1 .	2	N.4	. I •		

1: Low 2: Medium 3: High

TEXTBOOKS:

NITTE

- **1.** Aggarwal R.S, "Quantitative Aptitude for Competitive Examinations", S Chand Publishing.
- **2.** Aggarwal R.S, "A modern approach to verbal and non-verbal reasoning", S Chand Publishing.

REFERENCE BOOKS:

- **1.** Bharath Patodi and Aditya Choudhary, "Verbal Ability & Comprehension", Disha Publication, Second edition, 2015.
- **2.** Shakuntala Devi, "Joy of numbers", Orient Black Swan.
- **3.** Shakuntala Devi, "More puzzles to puzzle you", Orient Black Swan.

E Books / MOOCs/ NPTEL

- **1.** https://www.indiabix.com
- 2. https://www.faceprep.in



LIFE SKILLS FOR ENGINEERS						
Course Code:HU1008-1Course Type:AEC						
Tea	Teaching Hours/Week (L: T: P: S):1:0:0:0Credits:01					
Tota	al Teaching Hours:	15	CIE + SEE Marks:	50+50		
	Teaching Depart	tment: Respect	tive Department			
Cour	se Objectives:					
1.	Understand Time Management, Managing Information Overload, Coping with Peer pressure and Stress Management					
2.	Familiarize the Science behind P	ersonal Health	Management and Addictic	ons		
3.	Appreciate the importance of cultivating good hobbies, need for forming good habits and discarding bad habits and holding difficult conversations during crises					
4.	Comprehend the importance of Creative Thinking, Continuous and Lifelong Learning, Collaboration and Team Work					
5.	Equip them to excel in real work	environment p	proactively			

UNIT-I

3 Hours

3 Hours

Introduction to Life Skills Meaning and Importance of Life Skills, Competitive Job market, Fast paced changes in Technology, Proliferation of Electronic Gadgets and harmful online content.

Time Management

Introduction to Time Management, Impulsive Behaviour vis-a-vis goal Directive Behaviour, Time log, Information Overload and coping with Information & Communication Technology (ICT) Revolution; Proliferation of Electronic Media; Exponential growth in online content; Impact of Information Overload on human brain

Science behind Personal Health Management

Ignorance in Society on health issues, World Health Organization (WHO) - Definition of Health, Human Evolution, Importance of physical work for human body & mind, Dangers of sedentary lifestyle, Germ diseases versus Lifestyle diseases, Integrating physical exercise into daily life

Science behind Addictions

Addiction - Meaning, Neurology and Hormonal basics of Addictive Behaviour, How addictions are formed; Harmful effects of addictions on Physical and Mental Health, Recognizing addictions in oneself, Coming out of addictions

UNIT-II	
Need for cultivating good hobbies	3 Hours
Need for Hobbies in maintaining Work-Life Balance; how hobbies help in mainta	ining good
physical and mental health, Various Hobbies	_



Habits

Difference between hobbies & habits, Cultivating good habits & discarding bad habits: Role of habits for a successful life, How habits form; Analyzing one's own habits; Recognizing useless & harmful habits, Cultivating & Sustaining useful habits

Peer pressure and How to cope with it	3 Hours				
Human being as a Social Animal, Physical Pain & Social Pain; Awareness of Har	mful Social				
Pressure, Role of Prefrontal Cortex in Judgement and Decision Making, why tee	nagers are				
vulnerable to peer pressure, strategies to overcome harmful peer pressure					
Stress Management					
Stress, Types of Stress, Fight & Flight Response of Humans; Harmful effects of chr	onic stress;				
Symptoms of Poor Coping Skills of Stress, Stress & Psychiatric problems, Ea	asy coping				
strategies for stress					
UNIT-III					
Continuous & Lifelong Learning	3 Hours				

Accelerated change in Technology Landscape, Shorter Life Cycles of Technologies, Need for Continuous Learning of other skills

Team Working Skills & Collaboration

Team Work – Meaning, Skills and Relevance, Importance of Collaboration to succeed in one's own career, How to be a good team member

Cour	Course Outcomes: At the end of the course student will be able to					
1.	Apply the concept of Time Management, cope with Information Overload and					
	withstand harmful peer pressure					
2.	Comprehend the need to stay away from addictions by realizing the biological basis					
	behind these concepts					
3.	Develop good hobbies to maintain ideal work-life balance					
4.	Develop the aptitude for finding creative solutions to problems and realize the					
	importance of continuous and lifelong learning					
5.	Demonstrate positive and progressive abilities					

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	PSO↓	
↓ Course Outcomes													1	2	
HU1008-1.1	-	-	-	-	-	-	-	-	-	2	1	3	-	-	
HU1008-1.2	-	-	-	-	-	-	-	-	-	3	2	3	-	-	
HU1008-1.3	-	-	-	-	-	-	-	-	-	3	1	3	-	-	
HU1008-1.4	-	-	-	-	-	-	-	-	2	2	1	2	-	-	
HU1008-1.5	-	-	-	-	-	-	-	-	1	2	1	2	-	-	

1: Low 2: Medium 3: High

REFERENCES:

- **1.** Lieberman, D.E., "The Story of the Human Body", Pantheon Books, 2013.
- **2.** Ratey, J.J., "Spark. Little Brown Spark", 2013.
- **3.** De Bono, E., "Creative Thinking", Penguin UK, 2016.
- **4.** Pachter, B., "The Power of Positive Confrontation", Da Capo Lifelong Books, 1999.
- **5.** Duhigg, C., "The Power of Habit", Random House Trade Paperbacks, 2012.

	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2022-26
6.	Sharma, S., & Mishra, B., "Communication Skills for Engineers and Scientists", PHI
	Learning, 2009.
7.	Tracy, B., "Time Management", AMACOM, 2014.

Vocational Education Courses (VEC)

NITTE Deemed to be University

Ue (De	eemed to be University)	Motio	on Co	ontrol	Using	PLC						
Cοι	ırse Code:		RI2	2551-1	Cour	se Ty)e		V	Έ		
Теа	ching Hours/Week (L:	T: P: S)	2:0	:0:0	Cred	its			0	2		
Tot	al Teaching Hours		25		CIE +	SEE	Marks	5	5	0+5	0	
Pre	requisite		EE	1001-1,	EC 10	01-1						
	Teaching De	partme	nt: Ro	botics	and Ar	rtificia	l Inte	lliger	nce			
Cour	se Objectives:											
1.	To control Stepper mo	otor with	PLC	progran	n and D	DC mo	tor wi	th PL	C pr	ogra	m	
2.	To control AC motor w	ith PLC	progr	ram and	To un	dersta	nd HN	/I pro	ogra	ming	g	
	and interfacing.											
				UNIT-I						1		
Step	per Motor Control usir	ng PLC								05	Но	urs
	erstanding the construct				cation	of ste	oper r	noto	rs, ra	ating	g ch	eckin
	per motor driver selection		onneo	ction.						1		
	Aotor Control using PL										Но	
	truction and working of			-								
	ionship between duty cy		•	d of the	notor.	Establ	ishing	a rel	atio	nshi	p be	twee
	cycle and speed experir		•							1		
	Notor Control using PL										Но	
	struction and working o	of AC in	ductio	on moto	ors, its	differe	ent ty	pes a	nd	inter	faci	ng A
moto	ors and PLC.											
				UNIT-II								
	programming and Inte		-								Но	
	d for human machine in		-							-		
	nine linking of control sw	vitches a	ind da	ata regis	ters to	the la	dder i	nstru	ctioi	n thr	oug	n HIV
tools												
	Project	! . I.N. 4T			.11			<u>(</u>]			Но	
	ication of PLC control a				ai maci	nine, t	esting	the	corr	ecth	ess	ot th
nstn	uction, and reiterating at	iterimp	roven	ients.								
	rse Outcomes: At the er	d of the		co ctud		ha ah	lo +o					
												1
<u>1.</u>	Control of Stepper mo											-
2.	Operate various device	0		0					-			
	Interface PLC circuit, w motors and use HMI for	•	-				Stion	mun	ierei	IL		
<u> </u>]
	rse Outcomes Mapping							1				1
	Program Outcomes→	1 2	3 4	5 6	7 8	9 1	1	1		PSO	ř – –	-
↓ C	ourse Outcomes	1 2	1 -			0		2	1 3	2 3	3	-
	RI2551-1.1						_	1				-
	RI2551-1.2	2 2	1 -	- -			· -	μ	3	3	3	J
1: Lo	ow 2: Medium 3: High											
FEX1	BOOKS:											

	Control of electrical machines by S.K.Bhattacharya Birjindersingh, New Age									
	International.									
2.	Robotics and Industrial Automation by R.K. Rajput, S. CHAND PUBLISHING.									
3.	Introduction to PLC by Gary Dunning, Cengage Learning.									
4.	PLC, Principles and Applications by John W. Webb and Ronald A. Reis									
Web	links and Video Lectures (e-Resources):									
1.	https://www.udemy.com/course/siemens-s71200-motion-control-training/									
	https://www.udemy.com/course/plc-programming-100/									

Teaching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 Total Teaching Hours 39 CIE + SEE Marks 50+50 Prerequisite ME 1003-1 Image: Cite Action of Cite Actit Action of Cite Action of Cite Action of Cite Action o	Course Code:	RI2552-1	Course Type	VEC	
Total Teaching Hours 39 CIE + SEE Marks 50+50 Prerequisite ME 1003-1 Teaching Department: Robotics & AI Course Objectives: Image: Course Objectives: Image: Course Objectives: 1. Appreciate various standards of measurements, their classification and various terms related to measurements. Appreciate working principle, construction, and use of different comparators and angle measuring instruments. 3. Appreciate important parameters of screw threads and gears and their measurement designing of fits according to IS: 919-1963 and design gauges to inspect the fits. 4. Explain the generalized measurement system and various elements used in different stages. 5. Explain the principle, operation and characteristics of different measuring instruments used for the measurement of different physical parameters. UNIT-I Standards of measurement: Objectives of metrology. Standards of length - International prototype metric measuring instruments used for the measurement of different physical parameters. UNIT-I Standards of measurement: Objectives of metrology. Standards of length - International prototype metric measurements Comparators: Objectives of metrology. Standards of length - International prototype metric measurements <td c<="" th=""><th>Teaching Hours/Week (L: T: P: S)</th><th>3:0:0:0</th><th></th><th>03</th></td>	<th>Teaching Hours/Week (L: T: P: S)</th> <th>3:0:0:0</th> <th></th> <th>03</th>	Teaching Hours/Week (L: T: P: S)	3:0:0:0		03
Prerequisite ME 1003-1 Teaching Department: Robotics & AI Course Objectives: 1. Appreciate various standards of measurements, their classification and various terms related to measurements. 2. Appreciate working principle, construction, and use of different comparators and angle measuring instruments. 3. Appreciate important parameters of screw threads and gears and their measurement designing of fits according to IS: 919-1963 and design gauges to inspect the fits. 4. Explain the generalized measurement system and various elements used in different stages. 5. Explain the generalized measurement of different measuring instruments used for the measurement of different physical parameters. UNIT-1 OB Hou Definition and Objectives of metrology. Standards of length - International prototype met mperial standard yard, Wave length standard, subdivision of standards, line and er standard. Calibration of end bars. Slip gauges, wringing phenomena, Indian Standards (NI, M-112), and numerical problems on building of slip gauges. Errors in Measurements Comparators: UNIT-1I System of limits, Fits, Tolerances and gauging OB Hou Definition of tolerance and its Specification in assembly, concept of limits, fitypes of sign 200 <				50+50	
Teaching Department: Robotics & AI Course Objectives: 1. Appreciate various standards of measurements, their classification and various terms related to measurements. 2. Appreciate working principle, construction, and use of different comparators and angle measuring instruments. 3. Appreciate mortant parameters of screw threads and gears and their measurement designing of fits according to IS: 919-1963 and design gauges to inspect the fits. 4. Explain the generalized measurement system and various elements used in different stages. 5. Explain the principle, operation and characteristics of different measuring instruments used for the measurement of different physical parameters. UNIT-I Standards of measurement: 08 Hou Definition and Objectives of metrology. Standards of length - International prototype met Impreciate unerical problems on building of slip gauges. Errors in Measurements Comparators: OP Hou Introduction to Comparators, Classification and Characteristics of comparators. Principles mechanical, optical, electrical & electronic and pneumatic comparators. Working of Sign Zeis, LVDT and Solex comparators. Comparators: OP Hou Definition of tolerances and gauging					
Course Objectives: 1. Appreciate various standards of measurements, their classification and various terms related to measurements. 2. Appreciate working principle, construction, and use of different comparators and angle measuring instruments. 3. Appreciate important parameters of screw threads and gears and their measurement designing of fits according to IS: 919-1963 and design gauges to inspect the fits. 4. Explain the generalized measurement system and various elements used in different stages. 5. Explain the principle, operation and characteristics of different measuring instruments used for the measurement of different physical parameters. UNIT-I Standards of measurement: 08 Hou Definition and Objectives of metrology. Standards of length - International prototype met Imperial standard yard, Wave length standard, subdivision of standards, line and er standard. Calibration of end bars. Slip gauges, wringing phenomena, Indian Standards (Na, M-112), and numerical problems on building of slip gauges. Errors in Measurements Comparators: OP Hou UNIT-II System of limits, Fits, Tolerances and gauging Os Hou Definition of tolerance, accumulation of tolerance, definition of fits, types of fand their designation (IS 919 - 1963.). Principle of inter changaebility and selective assemb hole basis			obotics & AI		
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Cour	rse Outcomes: At the end of the course student will be able to
1.	Explain classification and application of material and wavelength standards used in engineering measurements and the terms related to measurements
2.	Describe working principle, construction, and use of different comparators and angle measuring instruments.
3.	Explain the important parameters of screw threads and gears and their measurement designing of fits according to IS: 919-1963 and design gauges to inspect the fits.
4.	Explain the elements of generalized measurement system.
5.	Explain the advances in metrology

Course Outcomes Mapping with Program Outcomes & PSO

	-		- 9-	-											
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO↓	
↓ Course Outcomes													1	2	3
RI2552-1.1	3	2	1										1		
RI2552-1.2	3	2	1										1		
RI2552-1.3	3	2	1										1		
RI2552-1.4	3	2	1										1		
RI2552-1.5	3	2	1										1		
1. Low 2. Madium 2		i ar la													

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	Mechanical measurements" by Beckwith Marangoni and Lienhard, Pearson
	Education, 6th Ed., 2006

2. "Engineering Metrology" by R.K.Jain, Khanna Publishers.20/e-2004

REFERENCE BOOKS:

- **1.** "Mechanical Measurements" by Thomas G Beckwith, Prentice-Hall, Pearson Education Limited.
- 2. "Engineering Metrology" by I.C.Gupta, Dhanpat Rai Publications, 7th Edition,2012
 - **3.** "Measurement Systems Applications and Design" by Ernest O, Doblin, McGRAW Hill Book Co. 5th Ed.,2003
 - **4.** "A Textbook of Measurements and Metrology" M.Mahajan, Dhanpat Rai &Co.2014

E Books / MOOCs/ NPTEL

1.	ENGINEERING METROLOGY https://nptel.ac.in/courses/112/104/112104250/
2.	Mechanical Measurements and Metrology
	https://nptel.ac.in/courses/112/106/112106138/
3.	MECHANICAL MEASUREMENT SYSTEM
	https://nptel.ac.in/courses/112/107/112107242/



Program Specific Ability Enhancement Course (AEC)

Coi	Data Acc	F	RI2652-1	Cour	rse Type		Δ	EC
	ching Hours/Week (L: T: P: S		2:0:0:0	Crec			02	
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	requisite		C 1001-1			IKJ	51	
	Teaching Depart				ificial Int	lligonc	•	
<u></u>	Irse Objectives:	ment.	NUDUICS			enigence	e	
<u>1.</u>	To understand the type	of con	sor roqu	uirad for	the me		nt of	nhycica
	phenomenon, to study the s							
	for the signal measurement.	-		stics and	the signe		lonnig	requiree
2.	To study the calibration met		or a given	sensor fo	or the me	asureme	nt of a	a physica
	phenomenon		giren					
	Ľ		UNIT-I	[
Dat	a Acquisition System Feature	es						10 Hours
	em Components, Signal Charac		s, Signal C	Condition	ing, Signal	Source	and M	easureme
-	em Configuration, Introduction		-					
			UNIT-I	I				
Sen	sor calibration:							15 Hours
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Engineering Economics												
Course Code:	RI2652-1	Course Type	AEC									
Teaching Hours/Week (L: T: P: S)	1:0:2:0	Credits	03									
Total Teaching Hours	40	CIE + SEE Marks	50+50									
Prerequisite	PH1001 -1											
 Evaluate the worth of creation benefit analysis) and take decis with the help of suitable tools. Determine the cost involved in fix suitable selling price for the and to prepare ledgers, journal Fundamental economic concepts: C Economy of organization, Demand th of supply, Determinants of supply, Latercises) Interest: Rate of interest, Determinin Compound interest, Nominal and eff formulae [single payment, uniform senformulae [discrete compounding only] Economic Analysis of Alternatives A 	ions with the li each operatic product and k s, balance shee <u>Unit-I</u> consumer goo beory, Law of aw of increasin og rate of inte ective interest ries and arithm Analysis base	mited resources, the rel on, a product should un know the different term ets and profit and loss a ds, Producer goods, F demand, Exceptions to g returns and law of o rest, Time value of m rate, Equivalence invo netic gradient only], pr d on: Present Worth [6	evant course of action indergo with an aim to inology of Economics accounts Factors of production b law of demand, Law diminishing returns(No oney, Simple interest living interest, Interest roblems using interest equal life and unequa									
ife situations], Future Worth, Payba xercises.	08 Hours		valent Annual Worth									
Pedagogy Chalk and talk n	nethod, Power	Point Presentation										
	Unit-II	· · · · · ·										
Rate of Returns: Analysis based on Ra Depreciation: Causes of depreciation,			•									
•	•	•										
balance, Double declining balance, SYI	es used in acc ng basic financ	ounting, Journal and	ledger, Profit and los									
statement, Balance sheet, Understandi Estimating and Costing: Component Prime cost, Factory cost, Total cost], De Mensuration: Machine shop c	ts of cost [Ma etermination o	terial cost, Labour cos f selling price of a proc	t, Overhead expenses luct, Exercises									
statement, Balance sheet, Understandi Estimating and Costing: Component Prime cost, Factory cost, Total cost], De Mensuration: Machine shop c D7 Hours	ts of cost [Ma etermination o alculations,	terial cost, Labour cos f selling price of a proc Forging shop cal	t, Overhead expenses luct, Exercises									
07 Hours	ts of cost [Ma etermination o alculations,	terial cost, Labour cos f selling price of a proc	t, Overhead expenses luct, Exercises									

Assessment Details (both CIE and SEE)

(methods of CIE need to be define topic wise i.e.- MCQ, Quizzes, Open book test, Seminar or micro project)

The weightage of Continuous Internal Evaluation (CIE) is 50% and for Semester End Exam (SEE) is



50%. The student has to obtain minimum of 40% marks individually both in CIE and SEE to pass. Theory Semester End Exam (SEE) is conducted for 100 marks (3 Hours duration). Based on this grading will be awarded.

Continuous Internal Evaluation:

- 1. Methods suggested: Test, Open Book test, Written Quiz, Seminar, report writing etc.
- 2. The class teacher has to decide the topic for closed book test, open book test, Written Quiz and Seminar. In the beginning only teacher has to announce the methods of CIE for the subject.

Semester End Examination:

Theory SEE will be conducted by University as per scheduled time table, with common question papers for subject

- The question paper will have ten questions. Each question is set for 20 marks.
- There will be 2 questions from each module. Each of the two questions under a module (with a maximum of 3 sub questions), should have a mix of topics under that module.
- The students have to answer 5 full questions, selecting one full question from each module

Suggested Learning Resources:

Books

- 1. Engineering Economics, Riggs J.L.,4th edition, Tata McGraw-Hill, 2004
- 2. Mechanical Estimating and Costing, Banga and Sharma, 16th edition, Khanna Publishers, 2012
- 3. Engineering Economy, E Paul Degarmo, Macmillan Publishing, 2001
- 4. Engineering Economy, Gerald J Thuesen & W J Fabrycky, Prentice Hall of India, 9th ed.
- 5. Engineering Economics, Tarachand, Nemchand & Bros, 1996
- 6. Financial Management, I M Pandey, Vikas Publishing House, 2002

COURSE ARTICULATION MATRIX:

	Course Code / Name : RI2652/ Engineering Economics														
Course		Program Outcomes (PO) PSO													
Outcomes (CO)	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
C- RI2652 .1	3	2	2	1	2	-	-	-	-	-	3	3	-	-	-
C- RI2652 .2	3	2	2	1	2	-	-	-	-	-	3	3	-	-	-
1: 1ow 2: M	ediur	m 3:	: Hig	h											



Со	urse Code:	RI2653-1	Course Type	AEC				
		4						
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PLC CONTROL OF HYDRAULIC AND PNEUMATIC CIRCUITS Course Code: R12653-1 Course Type AEC Teaching Hours/Week (L: T: P: S) 1:0:2:0 Credits 02 Total Teaching Hours 25 CIE + SEE Marks 50+50 Prerequisite EE 1001-1, EC 1001-1 EE 1001-2, EC 1001-1 Teaching Department: Robotics and Artificial Intelligence Course Objectives: 1. To understand the fundamentals of fluid power transmission systems 2. To design various pneumatic system components. . 3. To design various pneumatic system components. . 4. Learn various types of hydraulic and pneumatic power circuits using PLC. . UNIT-1 Fluid power systems and fundamentals Of Hours Of Hours of Hydraulics-Applications of Pascal's Law Vpres of fluid power, Advantages of fluid power, Application of fluid power system. Types of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators-Single acting and double acting cylinders, Rotary actuators - Fluid motors. Ost Hours								
Cour								
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Fluid	power systems and fundamenta	-		06 Hours				
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of pu	ımps - Variable displacement pu	mps, pump pe		-				
			erformance. Actuators: L	inear hydraulic				
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2.	Explain the working p													ontrol
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4.	Design various types o			· ·			/				· · ·			
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1.	Majumdar S.R., "Pneuma 2008.	atic	syste	ems	- Pri	ncip	les a	nd r	main	tena	nce",	Tata	McGr	aw Hill,
2.	Anthony Esposito, "Fluid	Pow	/er w	vith A	Appli	catio	ons",	Pear	rson	Educ	cation	2009		
REF	ERENCE BOOKS:													
1.	Majumdar S.R., "Oil Hydr	aulio	cs", T	ata l	McG	raw-	Hill,	2000).					
2.	Harry L. Stevart D. B,	"Pra	octica	al gu	uide	to	fluid	ро	wer"	, Та	raoea	la so	ns an	d Port
	Ltd.Broadey, 2010.													
3.	Michael J, Prinches and A		-			-								
4.	Dudelyt, A. Pease and Jo	hn T	. Pip	peng	ger, '	'Basi	c Flu	id Po	ower	", Pr	entice	e Hall,	2011.	
	ooks / MOOCs/ NPTEL													
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- http://vlabs.iitb.ac.in/vlabs-3.
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Professional Elective Courses (Automation Stream)



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	Automation	in Manufac	turing Systems			
Co ι	urse Code:	RI2201-1	Course Type	PEC		
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03		
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50		
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Man Math Math Meth Wes Meth Auto Desig devid Com Com CAPI bene Indu Defin Accu	GROUP-I Automation in Manufacturing Systems Durse Code: R12201-1 Course Type PEC aching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 tatal Teaching Hours 40 CIE + SEE Marks 50-50 erequisite ME 1003-1, IS 1001-1 Teaching Department: Robotics and Artificial Intelligence arse Objectives: To understand the concepts of automation in manufacturing systems To gain the knowledge of a line balancing and assembly systems To gain the knowledge of automated inspection and shop floor control To understand the concepts of additive manufacturing and latest trends in manufacturing manufacturing Operations: OJ Hours MUTEI roduction OJ Hours OLIT-I roduction principles &strategies nufacturing Operations: OJ Hours Nufacturing Operations. Production concepts and thematical models & costs of man					
GROUP-I Automation in Manufacturing Systems Course Code: RI2201-1 PEC Teaching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 Total Teaching Hours 40 CIE + SEE Marks 50+50 Prerequisite ME 1003-1, IS 1001-1 Teaching Department: Robotics and Artificial Intelligence Course Objectives:						
Course Code: RI2201-1 Course Type PEC Teaching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 Total Teaching Hours 40 CIE + SEE Marks 50+50 Prerequisite ME 1003-1, IS 1001-1 Image: Course Objectives: Image: Course Course: Image: Course: Course: Image: Course: Course: Image: Course: Course: Course: Course: Course: Course: Course: Course: Course: Course: Course: Course: Cou						
Man Man Math Math Meth Wes meth Auto Desid devid Com Com CAPI bene Defin Accu Mato Auto	ufacturing Operations: ufacturing operations, Product/ nematical models & costs of m lels Balancing nods of line balancing, Numerica ter's method, and ranked position nods. Dimated Assembly System gn for automated assembly, types ces, Analysis of single and multi-s Inderized Manufacture Plannin puter aided process planning (CA P. Material requirement planning, efits. Automated Guided Vehicles Instrial Robotics nition, Robot anatomy, Joints and uracy and repeatability, End effect erial handling, Processing, assemb ection Technologies mated inspection, coordinate	(production r anufacturing I problems or ional weights s of automater tation assemb UNIT-II 1g and AGVS APP), Retrieval Inputs to MR System: Appli d links, Robot tors, Sensors i bly and inspection	operations. Problems of In largest candidate rule, method, computerized d assembly system, Parts ly machines and Generative systems, P system, working of MI cations, Guidance and ro configurations, Robot of n robotics. Industrial rob tion.	concepts and n mathematica 05 Hours Kilbridge's and l line balancing 04 Hours feeding 06 Hours and benefits o RP, Outputs and outing, 04 Hours control systems bot applications 09 eration 8		
Man Math Math Math Meth Wes Meth Auto Desid devid Com Com Com Com Com Com Com Com Com Com	Automation in Manufacturing Systems Course Code: R12201-1 Course Type PEC Teaching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 Total Teaching Hours 40 CIE + SEE Marks 50+50 Prerequisite ME 1003-1, IS 1001-1 Teaching Department: Robotics and Artificial Intelligence Course Objectives: 1 To understand the concepts of automation in manufacturing systems 2 1. To impart the knowledge of a line balancing and assembly systems 3 3 To explore the idea of robotics and understand the computerized manufacturing planning Planning 03 Hours 4. To gain the knowledge of automated inspection and shop floor control 5. To understand the concepts of additive manufacturing and latest trends in manufacturing 9. To auderstand the concepts of additive manufacturing and latest trends in manufacturing Operations: 03 Hours Production system facilities, Manufacturing support systems, Automation in production systems, Automation principles & kstrategies 04 Hours Manufacturing Operations; Product/production relationship, Production concepts and Mathematical models & costs of manufacturing operations. Problems on mathematical models 05 Hours Line Balancing					



	ned to be University)				UN	IIT-	III									
Shop	Floor Control and Aut	om	atic	Ide	ntif	icat	ion	Тес	:hni	que	S				05	Hours
Shop	floor control, Factory of	data	col	llecti	ion	syst	em	, Αι	uton	natio	: ide	ntifio	catio	n me	ethoo	ds, Bar
codet	technology, Automatic c	lata	coll	ectio	on s	yste	ems.	An	Intr	odu	ctior	n to C	QR Co	ode ⁻	Fechr	nology
	tive Manufacturing Sys															Hours
Basic	principles of additive r	man	ufa	cturi	ng,	Slic	ing	CA	Dn	nod	els f	or A	M, A	dva	ntage	es and
limita	tions of AM technologie	es, R	lece	nt tr	end	ls in	ma	nuf	actu	iring	ј, Ну	brid	man	ufac	turing	g.
	e of Automated Facto														02	Hours
	s in manufacturing, the			auto	mat	ed f	fact	ory,	Hui	man	wor	kers	in fu	ture		
	nated factory, Social imp															
Cours	e Outcomes: At the en															
1.	Explain the basics of p							-					actur	ing		
	operations. Solve the s	imp	le p	robl	ems	s on	ma	the	mat	ical	mod	lel.				
2.	Analyze and solve prob	olen	ns o	n lin	e ba	alan	cing	g								
3.	Explain CAPP and MRP															
4.	Understand the inspec															
5.	Explain the modern tre	nds	in a	addi	tive	ma	nufa	actu	ring) and	d aut	oma	ted f	facto	ry	
Cours	se Outcomes Mapping	wit	h Pi	rogr	am	Ou	tco	mes	8	PSO)					
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ C	ourse Outcomes															
	RI2201-1.1	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2201-1.2	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2201-1.3	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2201-1.4	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2201-1.5	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	1: Low 2: Medium	3: H	igh													
TEXT	BOOKS:															
1.	Mikell PGroover, Auto	oma	tion	, Pro	odu	ctio	n Sy	vster	ns a	and	Com	pute	er-Int	egra	ted	
	Manufacturing, PHI Le	earn	ing,	, 3rc	d Ed	litio	n, 2	009								
2.	P N Rao, CAD / CAM	Prin	cipl	es a	nd A	٩ppl	licat	tion	s, T	ata	McG	raw-	Hill,	3rd	Editi	on,
	2015															
3.	Ian Gibson, David W. F	Rose	en, E	Brent	tStu	cke	r, A	ddi	tive	Mai	nufa	cturi	ng Te	echn	ologi	es:
	Rapid Prototyping to I	Dire	ct D	igita	al M	anu	fact	turir	ng,	Spri	nger	, 2n	d Ed.	(20	15)	
REFE	RENCE BOOKS:															
1.	Dr.Nanua Singh, Syste	ems	Ар	oroa	ch t	o C	om	pute	er In	tegi	rated	l Des	sign 8	શ		
	Manufacturing, Wiley	, 19	96													
2.	P. Radhakrishnan, S. S	ubra	ama	nyar	n, U	.Rajı	u, C		/CA	M/C	CIM,	Revi	sed ⁻	Thirc	l Edit	ion
	2007															



	C	NC Machin	ing	
Course Co	de:	RI2202-1	Course Type	PEC
Teaching	Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Tead	hing Hours	40	CIE + SEE Marks	50+50
Prerequisi	te	ME 1003-1		L
	Teaching Departmen	t: Robotics ar	d Artificial Intelligence)
Course Obj	ectives:			
	uate manufacturing assignr . Become a good commun		. .	blem solving
2. Prac	tice writing complex "G" cc specification			hat meet the
3. Inter	pret and demonstrate com t the part specification	plex "G" code	programs for CNC millir	ig centers that
4. Prep	are "G: code programs to p ntersinking, counter boring,			g tapping,
5. Desc	ribe and illustrate commor			CNC
prog	ramming and machining.	UNIT-I		
echnologic CNC progra ntroduction programmin programmin	ols CNC control and CN al data for CNC machining amming n to CNC programming, Ir ng or lathe & milling ma ng for lathe and milling ma Procedures Associated w	CNC clampin ntroduction ar chine using is achines using	g system. d demonstration of line so codes into the CNC different machining cycl	09 Hours programs CNC simulator. CNC es into the CNC
	rocess planning issues and Subprograms	l path plannin	g, G & M Codes, Interpo	olations, Cannee
roaram a				
	provision for CNC	UNIT-II		04 Hours
•	eneration for CNC milling ensations Exposure for p ng exercise.	and turning	and simulator of FANI	04 Hours JC, SINUMERIC
Programmi	ensations Exposure for p ng exercise.	and turning	and simulator of FAN	
Programmin CNC Turnin Plan and op etc. and set or the lath est run pro	ensations Exposure for p ng exercise. g timize programs for CNC to a references for the various e operations like turning, g grammed Execute program	y and turning programming urning operations. Progrooving etc. I or and inspect s	ons. Calculate parameter epare operation and ope Prepare & set CNC lathe	JC, SINUMERIC 05 Hours s like speed fee eration sequenc operations and
Programmin CNC Turnin Plan and op etc. and set or the lath est run pro	ensations Exposure for p ng exercise. g timize programs for CNC to a references for the various e operations like turning, g grammed Execute program us PPE's on CNC lathe mad	y and turning programming urning operations. Progrooving etc. I or and inspect s	ons. Calculate parameter epare operation and ope Prepare & set CNC lathe	JC, SINUMERIC 05 Hours s like speed fee eration sequence operations an

Plan and optimize programs for CNC Milling operations. Calculate parameters like speed feed, depth of cut etc. and set a references for the various operations. Various methods of work process like edge finding block center etc. Prepare & set CNC Milling operations and test run programmed. Execute program and inspect simple geometrical forms / standard parts. Use of various PPE's on CNC milling machine

Modern CNC systems	10 Hours
Introduction to advanced CNC systems: Computer Aided Part Programming	g (CAPP), it's
application using Solidworks/MasterCAM. comparison of manual part programm	ing and CAPP
for a simple component, Automatic Tool Changer, Automatic Pallet Contro	ol, Automatic
Storage & Retrieval Systems.	

UNIT-III

Cour	se Outcomes: At the end of the course student will be able to
1.	Explain applications and advantages of CNC machines and technology. Demonstrate and
	explain various CNC control Calculate technological data for CNC machining
2.	Understand the importance and use of PPE's. Prepare and understand line program for
	various profiles Identify and set parameters for various simulators
3.	Prepare programs, demonstrate, simulate and operate CNC lathe machines for various
	machining operations
4.	Prepare programs , demonstrate , simulate and operate CNC milling machines for various
	machining operations
5.	Define and explain Modern CNC systems and explain its importance in manufacturing

Course Outcomes Mapping with Program Outcomes & PSO

			- 9-												
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO	Ļ
↓ Course Outcomes															
RI2202-1.1	1	2	1	-	-	-	-	-	-	-	-	1	-	-	3
RI2202-1.2	2	2	1	-	-	-	-	-	-	-	-	1	-	-	3
RI2202-1.3	2	2	2	-	-	-	-	-	-	-	-	2	-	-	2
RI2202-1.4	2	2	2	-	-	-	-	-	-	-	-	2	-	-	2
RI2202-1.5	2	2	2	-	-	-	-	-	-	-	-	2	-	-	2
1. Low 2. Medium 3	. Ці	ah													

1: Low 2: Medium 3: High

TEXT	BOOKS:
1.	Programming of CNC machines, by Ken Evans
2.	CNC Programming Handbook by Peter Smid
3.	NC Control by Kundra Rao, Tewari CNC Machines, Pabla B.S., Adithan M., New Age
	International, New Delhi,2014(reprint).
REFE	RENCE BOOKS:
1.	CAD/CAM: computer aided design and manufacturing, Groover Mikell P, Zimmered W
	Emory, Prentice Hall 2014
2.	Computer Numerical Control- Turning and Machining centers. Quesada Robert,
	Prentice Hall 2014
3.	https://cache.industry.siemens.com/dl/files/554/74475554/att_56792/v1/PGsl_0313_e_
	n_en-US.pdf



4.	G codes, M codes Handbook, by Mazak Corporation, sources: available at Mini Tool
	Room, Parlakhemundi campus, CUTM
	https://gist.github.com/anonymous/f14c73a7174bf8a43f0c970817897454
E Boc	oks / MOOCs/ NPTEL
1.	https://cache.industry.siemens.com/dl/files/554/74475554/att_56792/v1/PGsl_0313_e
	n_en-US.pdf
2.	https://www.classcentral.com/course/youtube-computer-numerical-control-cnc-of-machine-tool-and-
	process-47871
3.	https://www.udemy.com/course/mastering-artcam-2017/
4.	https://fabcoep.vlabs.ac.in/exp1/Video.html?domain=Mechanical%20Engineering&lab
	=FAB%20laboratory
5.	http://vlabs.iitkgp.ac.in/psac/newlabs2020/vlabiitkgpAM/exp2/index.html#

(Deemed to be University) Industrial A	utomation	and Control	
Course Code:	RI2203-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EE 1001-1,		
	hing Depart		
Course Objectives:			
1. Understand the fundamentals o	f industrial au	tomation system and v	arious control
process.		,	
2. Understand the various sequence	ce controls use	ed in industries.	
3. Understand the various hydrauli	ic control syst	ems to control the flow	valves.
4. Understand the different types of	of electric driv	es used in industrial au	tomation
5. Understand the different types of	of electric mot	tor drives used in indus	trial
automation			
	UNIT-I		
Introduction			07 Hours
Architecture of Industrial Automation	Systems, Mea	surement Systems Cha	racteristics, Data
Acquisition Systems Introduction to A	utomatic Con	trol, P-I-D Control, PID	Control Tuning
Feed forward Control Ratio Control, ⁻	Time Delay S	ystems and Inverse Re	sponse Systems
Special Control Structures, Concluding	Lesson on Pro	ocess Control (Self-stuc	ly).
Introduction to Sequence Control			07 Hours
PLC, RLL, Sequence Control. Scan Cycle	•	-	
Sequence Control. More RLL Elemer	•	ax, A Structured Desig	gn Approach to
Sequence Control, PLC Hardware Envir			
	UNIT-II		
Flow Control Valves, Hydraulic Cont			08 Hours
Flow Control Valves, Hydraulic Control	=		
Hydraulic Circuit, Pneumatic Control Sy			
Variable Speed Drives, Introduction to	CNC Machine	s The Field bus Network	< – I, Higher Leve
Automation Systems			00.11
Electric Drives			08 Hours
Introduction, Energy Saving with Adjus	•		•
Construction and Drives, DC Motor Dri	ves: Introduct	ion, DC Converters, Adj	justable Speed
Drives			
Industion Motor Drives	UNIT-III		10
Induction Motor Drives	la Speed Driv	ing Superropous Moto	10 Hours
Introduction, Characteristics, Adjustib	•	•	
Principles, Adjustible Speed and Sei		-	
Controllers: The Fieldbus The Fieldbus Control Systems.	Communicat		
Course Outcomes: At the end of the c	ourse student	t will be able to	
			and how thou
		Automation systems a	nd now they
are organized hierarchically in le		D controllor	
 Create the input-output relation Describe the physical organization 			
3. Describe the physical organizati	on or nardwal	e in the PLC.	

						Curr	iculu	ım –	B.Te	ch. (I	Robotic	cs & A	rtificia	l Intell	igenec	e): 202
4.	Describe motivations fo	r fo	rma	l mo	deli	ng i	n th	ne d	esig	n of	fseq	uenc	e co	ntrol		
	programs for an					5			5		•					
5.	Industrial control proble	em														
																1
Cours	e Outcomes Mapping v	with	Pro	ogra	m (Duto	or	ies a	& P:	SO						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO	\downarrow
↓ Co	urse Outcomes													1	2	3
	RI2203-1.1	3	-	1		3		-	-			-	2	-	2	
	RI2203-1.2	3	-	1		3		-	-			-	2	-	2	
	RI2203-1.3	3	-	2		3		-	-			-	2	-	2	
	RI2203-1.4	3	-	3		2		-	-			-	2	-	2	
	RI2203-1.5	3	-	1		3		-	-			-	2	-	2	
	1: Low 2: Medium 3:	Hi	ah	1					1							 _
ΓΕΧΤΙ	BOOKS:															
1.	Introduction to Industri	al A	uto	mati	on,	Star	mat	ios	Man	esis	, Geo	orge	Niko	lako	pou	lo
	CRC press 1st Edition, 2	2018	3									5			•	
2.	Drives and Control for I	indu	Istria	al Au	utor	natio	on,	Kok	Kio	ng 1	Tan, A	Andi	Sudj	ana	Putr	а
	Springer-verlag Londoa	an li	mite	ed 11	Lth	Editi	ion,	201	.8	-			-			
3.	Electrical Measurement	and	d Co	ontro	ol (V	/BSC	CTE)	, S.ŀ	K. Bł	natta	achar	'ya 8	ι S. V	'ikas		
	Publishing House Pvt L	td 2	nd E	diti	on, İ	2015	5									
REFE	RENCE BOOKS:															
1.	Introduction to Industri	al A	uto	mati	on,	Star	mat	ios I	Man	lesis	, Geo	orge	Niko	lako	pou	lo
	CRC press 1st Edition, 2															
2.	Drives and Control for I									ng 1	Tan, <i>I</i>	Andi	Sudj	ana	Putr	а
	Springer-verlag Londoa															
3.	Electrical Measurement				-		-	, S.ł	K. Bł	natta	achar	'ya 8	ι S. V	'ikas		
	Publishing House Pvt L	td 2	nd E	diti	on, i	2015	5									
NPTE			100	1050												
	https://nptel.ac.in/cours	es/	108	1050) <u>63</u>											

N NITTE

	ırse Code:	RI2204-1	Course Type	PEC
	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
	requisite		IS 1001-1, CY 1001-1	50.50
FIE				
•)epartment: R	obotics & Al	
.oui 1.	rse Objectives:		in the field of healthcare	
<u>1.</u> 2.	Understand the types of medica Explain the various localization			
<u>2.</u> 3.	Understand the applications of			se studies
<u>3.</u> 4.	Understand Rehabilitation of lir			
т.	case studies			
5.	Understand the design method	ology of medie	cal robots.	
		UNIT-I		
ntro	oduction			08 Hour
уре	s of medical robots - Navigatior	n - Motion Rep	blication - Imaging - Rel	habilitation an
rost	thetics - State of art of robotics in	the field of he	althcare. Localization Ar	nd Tracking
Posi	tion sensors requirements			07 Hour
	king - Mechanical linkages - Optic		-	pedance-base
In-l	bore MRI tracking - Video matchi	ng - Fiber opti	c tracking	
		UNIT-II		07.11
	trol Modes		u and Dahatic Imaging	07 Hour
) a di	osurgery - Orthopedic Surgery - U	rologic surger	y and Robotic Imaging -	Cardiac Surger
	urosurgeny – case studies			
Ne	urosurgery – case studies.			08 Hour
Ne Reha	abilitation	ine Interfaces -	Steerable Needles – cas	
Ne Reha		ine Interfaces -	Steerable Needles – cas	
Ne Reha	abilitation		Steerable Needles – cas	
Ne Reha Reha	abilitation abilitation for Limbs - Brain-Machi	ine Interfaces - UNIT-III	Steerable Needles – cas	se studies.
Ne Reha Reha Desi	abilitation	UNIT-III		se studies.
Ne Reha Reha Desi	abilitation abilitation for Limbs - Brain-Machi gn of Medical Robots	UNIT-III		10 Hours
Ne Reha Reha Desi	abilitation abilitation for Limbs - Brain-Machi gn of Medical Robots acterization of gestures to the de	UNIT-III		se studies.
Ne Reha Reha Desi Char	abilitation abilitation for Limbs - Brain-Machi gn of Medical Robots acterization of gestures to the de ces - Security.	UNIT-III sign of robots	- Design methodologies	se studies.
Ne Reha Reha Char hoio	abilitation abilitation for Limbs - Brain-Maching gn of Medical Robots acterization of gestures to the de ces - Security.	UNIT-III sign of robots course student	- Design methodologies : will be able to	10 Hour 10 Hour - Technologica
Ne Reha Reha Desi Char	abilitation abilitation for Limbs - Brain-Maching gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical r	UNIT-III sign of robots course student	- Design methodologies : will be able to	10 Hour 10 Hour
Ne Reha Reha Desi Char hoid Cour 1.	abilitation abilitation for Limbs - Brain-Maching gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical r replication.	UNIT-III sign of robots course student obots and the	- Design methodologies : will be able to concepts of navigation a	10 Hour 10 Hour
Ne Reha Reha Desi Char hoid Cour 1.	abilitation abilitation for Limbs - Brain-Machina gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical ro- replication. Describe about the sensors use	UNIT-III esign of robots course student obots and the d for localization	- Design methodologies : will be able to concepts of navigation a	10 Hour 10 Hour
Ne Reha Reha Desi Char hoid 1. 2. 3.	abilitation abilitation for Limbs - Brain-Machina gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical r replication. Describe about the sensors use Explain the applications of surg	UNIT-III esign of robots course student obots and the d for localization ical robots	- Design methodologies : will be able to concepts of navigation a on and tracking	and motion
Ne Reha Reha Desi Char hoid 1. 2. 3. 4.	abilitation abilitation for Limbs - Brain-Machina gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical raises replication. Describe about the sensors use Explain the applications of surg Explain the concepts in Rehabil	UNIT-III esign of robots course student obots and the d for localization ical robots itation of limbs	- Design methodologies : will be able to concepts of navigation a on and tracking s and brain machine inte	and motion
Ne Reha Reha Desi Char hoid 1. 2. 3.	abilitation abilitation for Limbs - Brain-Machina gn of Medical Robots acterization of gestures to the de ces - Security. rse Outcomes: At the end of the Describe the types of medical r replication. Describe about the sensors use Explain the applications of surg	UNIT-III esign of robots course student obots and the d for localization ical robots itation of limbs obots and analy	- Design methodologies will be able to concepts of navigation a on and tracking s and brain machine inte ze the design characteri	and motion

	Program Outcomes →	1	2	3	4	5	6	7	8	9	10	11	12	F	SO	\downarrow
↓ Co	urse Outcomes													1	2	3
	RI2204-1.1	3	-	1				-	-			-	2	-	2	2
	RI2204-1.2	3	-	1				-	-			-	2	-	2	2
	RI2204-1.3	3	-	2				-	-			-	2	-	2	2
	RI2204-1.4	3	-	2				-	-			-	2	-	3	3
	RI2204-1.5	3	-	3				-	-			-	2	-	2	3
	1: Low 2: Medium 3:	Hi	gh													
TEXTE	BOOKS:															
1.	Robot Modeling and Co	ontr	ol, N	Mark	W.	Spo	na	Set	h Hi	utch	inso	n, an	d M.	Vid	vasad	gar,
						- 6 -	''''''	000				•		-		<i>,</i>
	Wiley Publishers, 2006					- 4-	, ng,	000				•		-		, ,
2.	Wiley Publishers, 2006 Medical robotics- Minir	nall	y, In	vasi		•	5							-		
2. 3.	,				ve s	urge	ery,	Pau	la G	iom	es, W	/ood		-		
3.	Medical robotics- Minir				ve s	urge	ery,	Pau	la G	iom	es, W	/ood		-		
3.	Medical robotics- Minir Medical Robotics, Achir	n S	chw	eika	ve s rd, F	urge Ioris	ery, s Err	Pau nst, 1	la G Spri	iom	es, W	/ood		-		
3. REFEF	Medical robotics- Minir Medical Robotics, Achir RENCE BOOKS:	n So yne	chw Tro	eika ccaz	ve s rd, F z, Wi	urge loris ley-	ery, s Err ISTE	Pau nst, 1 E, 20	la G Spri)12	iom nge	es, W r, 20	/ood 15	heac	I, 20:	12	
3. REFER 1.	Medical robotics- Minir Medical Robotics, Achir RENCE BOOKS: Medical Robotics, Jocel	n So yne a Bc	chw Tro onzo	eika ccaz vic, i	ve s rd, F z, Wi I-teo	urge loris ley- ch Ec	ery, s Err ISTE duca	Pau hst, 1 E, 20 atio	la G Spri)12 n pu	iom nge ublis	es, W r, 20	/ood 15	heac	I, 20:	12	
3. REFER 1. 2.	Medical robotics- Minir Medical Robotics, Achir RENCE BOOKS: Medical Robotics, Jocel Medical Robotics, Vanja	m So yne a Bc el Fa	Tro nzo	eika ccaz vic, 1 , Ros	ve s rd, F z, Wi I-teo sen	urge loris ley- ch Ec Publ	ery, s Err ISTE duca	Pau nst, 1 E, 20 atio ers, 1	la G Spri)12 n pu 201	iom nge ublis	es, W r, 20	/ood 15	heac	I, 20:	12	
3. REFER 1. 2. 3. 4.	Medical robotics- Minir Medical Robotics, Achir RENCE BOOKS: Medical Robotics, Jocel Medical Robotics, Vanja Medical Robotics, Danir	m So yne a Bc el Fa	Tro nzo	eika ccaz vic, 1 , Ros	ve s rd, F z, Wi I-teo sen	urge loris ley- ch Ec Publ	ery, s Err ISTE duca	Pau nst, 1 E, 20 atio ers, 1	la G Spri)12 n pu 201	iom nge ublis	es, W r, 20	/ood 15	heac	I, 20:	12	
3. REFER 1. 2. 3. 4.	Medical robotics- Minir Medical Robotics, Achir RENCE BOOKS: Medical Robotics, Jocel Medical Robotics, Vanja Medical Robotics, Danie Medical Robotics, Jocel	m So yne a Bc el Fa yne	Tro nzo aust	eika ccaz vic, 1 , Ros ccaz	ve s rd, F z, Wi I-teo sen z, Wi	urge loris ley- ch Eo Publ ley-	ery, s Err ISTE duca lishe ISTE	Pau hst, 1 E, 20 atio ers, 1 E, 20	la G Spri)12 n pu 201)12	iom nge ublis 6	es, W r, 20 hing	/ood 15 Aus	heac tria, 1	I, 20:	12	

Course Code:	RI2205-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EC 1001-1		
-	t: Robotics an	d Artificial Intelligence	9
ourse Objectives:			
1. Understand the fundamental pr	inciples of ME	MS and their applicatior	าร.
2. Explain the capabilities and limit			
3. Understand the concepts of Mid			
4. Understand the applicability of	various sensor	rs and actuation systems	of MEMS
5. Understand the basic concepts	of thermal and	d fluidic MEMS.	
	UNIT-I		
Aicro-Electro-Mechanical Systems			04 Hou
ntroduction and overview, Principles of 1EMS, Scaling and performance, Co 1arkets, Overview of MEMS application	ost reduction,		
Micromachining Techniques			07 Hou
common semiconductors, Mechanica vafer types, Micromachining Technic sotropic etching, Anisotropic etching	l properties, I ques – Bulk M J, EDP, KOH, T	licromachining, Wet etc MAH, Etch stop layers,	, Typical silico ching of silico Masking, Ma
common semiconductors, Mechanica wafer types, Micromachining Technic sotropic etching, Anisotropic etching erosion around edges, bulk micromach Porous silicon, One- sided wafer etchir DRIE, Bosch process, Cryogenic dry etc and anisotropic dry etching, SCREAM,	I properties, I ques – Bulk M g, EDP, KOH, T nining process ng, Vapor phas hing, Sidewall	Native oxides of silicon licromachining, Wet etc MAH, Etch stop layers, flow, Electrochemical etc se etching (XeFR2R), Dry	I properties , Typical silico ching of silico Masking, Ma ching, Etch sto etching, SFR6 nbined isotrop
common semiconductors, Mechanica wafer types, Micromachining Technic Isotropic etching, Anisotropic etching erosion around edges, bulk micromach Porous silicon, One- sided wafer etchir DRIE, Bosch process, Cryogenic dry etc and anisotropic dry etching, SCREAM, Micromachining Techniques	l properties, I ques – Bulk M J, EDP, KOH, T nining process ng, Vapor phas hing, Sidewall ASIP	Native oxides of silicon licromachining, Wet etc MAH, Etch stop layers, flow, Electrochemical etc se etching (XeFR2R), Dry roughness, Etch lag, Con	I properties , Typical silico ching of silico Masking, Ma ching, Etch sto etching, SFR6 nbined isotrop 05 Hou
common semiconductors, Mechanica wafer types, Micromachining Technic sotropic etching, Anisotropic etching erosion around edges, bulk micromach Porous silicon, One- sided wafer etchir DRIE, Bosch process, Cryogenic dry etc and anisotropic dry etching, SCREAM, Micromachining Techniques Surface Micromachining, Thin film p stoichiometric, Iow-stress), Poly (stree process flow, Release, Wet–Stiction, E	I properties, I ques – Bulk M g, EDP, KOH, T nining process ng, Vapor phas hing, Sidewall ASIP processes, Ox ess, stress-grad Dry - Critical p	Native oxides of silicon ficromachining, Wet etc TMAH, Etch stop layers, flow, Electrochemical etc se etching (XeFR2R), Dry roughness, Etch lag, Con ide (thermal, deposited dients), Metal, surface point drying, Vapor HF,	I properties , Typical silico ching of silico Masking, Ma ching, Etch sto etching, SFR6 nbined isotrop 05 Hou d LTO), Nitrio micromachinin Microelectror
common semiconductors, Mechanica vafer types, Micromachining Technic sotropic etching, Anisotropic etching erosion around edges, bulk micromach Porous silicon, One- sided wafer etchin DRIE, Bosch process, Cryogenic dry etc and anisotropic dry etching, SCREAM, Micromachining Techniques Surface Micromachining, Thin film p stoichiometric, low-stress), Poly (stree process flow, Release, Wet–Stiction, E ntegration – prior, mixed and post, Ele	I properties, I ques – Bulk M g, EDP, KOH, T nining process ng, Vapor phas hing, Sidewall ASIP processes, Ox ess, stress-grad Dry - Critical p	Native oxides of silicon ficromachining, Wet etc TMAH, Etch stop layers, flow, Electrochemical etc se etching (XeFR2R), Dry roughness, Etch lag, Con ide (thermal, deposited dients), Metal, surface point drying, Vapor HF,	I properties , Typical silico ching of silico Masking, Ma ching, Etch sto etching, SFR6 nbined isotrop 05 Hou d LTO), Nitrio Microelectror ing
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common semiconductors, Mechanica vafer types, Micromachining Technic sotropic etching, Anisotropic etching erosion around edges, bulk micromach Porous silicon, One- sided wafer etchin DRIE, Bosch process, Cryogenic dry etc and anisotropic dry etching, SCREAM, Micromachining Techniques Surface Micromachining, Thin film p stoichiometric, low-stress), Poly (stree process flow, Release, Wet–Stiction, E ntegration – prior, mixed and post, Ele Micro-Mechanics Basic Mechanics, Axial stress & strain, deflection equations, Static beam equa Cantilever beams, Clamped-clamped b Springs – folded, torsional, Dynan	I properties, I ques – Bulk M g, EDP, KOH, T nining process ng, Vapor phas hing, Sidewall ASIP processes, Ox ess, stress-grad Dry - Critical p ectro-deposition UNIT-II Shear stress & ations, Static to peams, Membrinics, Spring-n	Native oxides of silicon Aicromachining, Wet etc MAH, Etch stop layers, flow, Electrochemical etc se etching (XeFR2R), Dry roughness, Etch lag, Con ide (thermal, deposited dients), Metal, surface i point drying, Vapor HF, on, Hybrid Micromachin strain, Poisson's Ratio, Corsion equations, Static ranes, nass-damper system, r	I properties , Typical silico ching of silico Masking, Ma ching, Etch sto etching, SFR6 nbined isotrop 05 Hou d LTO), Nitrio microelectror ing 06 Hou Commonly use plate equation resonance, Te
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mechanisms, Mechanical Sensors, Resistive and piezoresistive strain sensors, Semiconductor strain gauges, Capacitive sensing, Micromachined mechanical sensors,

Accelerometers 04 Hours Basic accelerometer concepts, Force-balanced accelerometer concepts, Strain guage accelerometers, Capacitive accelerometers, Gyroscopes, Pressure sensors, Piezoresistive pressure sensors, Capacitive pressure sensors, Electrostatics, Actuation mechanisms, Electrostatic actuation, Parallel plate actuators, Torsional electrostatic actuators, Electrostatic comb drives, Electrostatic cantilever actuators, Electrostatic linear micromotors (scratch drive), Electrostatic rotary micro-motors.

UNIT-III

Thermal actuators, Thermal expansion of solids, Bimorph thermal actuators, Bent beam actuators, Thermal array actuators, Volume expansion and phase-change actuators, Thermal sensors, Bolometers, Uncooled bolometers, Air flow sensor.

Course Outcomes:	At the end of the course student will be able	e to

- **1.** Describe the basics and capabilities and limitation of MEMS.
- **2.** Explain and differentiate important micromachining techniques
- **3.** Apply the concepts of Micro mechanics and materials for micromachining
- 4. Describe sensors and actuation systems used in MEMS
- **5.** Explain the basics of thermal and fluidic MEMS.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes															
RI2205-1.1	3	-	1	-	-	-	-	-			-	1	3		2
RI2205-1.2	3	-	1	-	-	-	-	-			-	1	3		2
RI2205-1.3	3	-	2	-	-	-	-	-			-	1	3		2
RI2205-1.4	3	-	2	-	-	-	-	-			-	1	3		2
RI2205-1.5	3	-	1	-	-	-	-	-			-	1	3		2
1. Lour 2. Madium '		: -													

1: Low 2: Medium 3: High

TEXTBOOKS:

- 1. Micromachined Transducers Sourcebook, Greg Kovacs, McGraw-Hill publications, New York, 1998
- 2. Microsystem Design, Stephen D. Senturia, Kluwer Publications, Boston, 2001

REFERENCE BOOKS:

1. MEMS/NEMS – Handbook: Techniques and Applications, Cornelius T. Leondes, Springer-Verlag Publications, 2005

Thermal MEMS

05 Hours

05 Hours

2. Fundamentals of Microfabrication, Marc J. Madou, Taylor & Francis Publications, 2nd, 2002

E Boo	ks / MOOCs/ NPTEL
1.	https://nptel.ac.in/courses/117/105/117105082/
2.	https://nptel.ac.in/courses/108/108/108108113/
3.	https://nptel.ac.in/courses/112/108/112108092/
4.	https://nptel.ac.in/courses/108/106/108106165/
5.	https://www.udemy.com/course/introduction-to-micro-and-nano-fabrication-
	techniques-by-essamberikaa/
NPTE	
	https://nptel.ac.in/courses/117105082

GROUP-II

	Digit	tal Manufac	turing	
Co ι	urse Code:	RI2301-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	ME 1003-1		
	Teaching Departmen	t: Robotics an	d Artificial Intelligence)
Cou	rse Objectives:			
1.	Learn the fundamentals of Digi			
	and CAD/CAM/CAE technologic			
2.	Use of Finite Element Analysis		•	
3.	Learn the General stages of the	•		
	loading (loads, displacements c verifications	onstraints), p	ost-processing, results a	ind
4.	Learn about the Digitizing meth	ods and main	technologies: applicatio	ns and
4.	selection of reverse engineering		technologies. applicatio	
5.	Know about the Main additive		technologies, principles	and
	applications		eeee.e.g.ee, pe.p.ee	
		UNIT-I		
Intro	oduction			07 Hours
Impo	ortance of Digital manufacturing	, Fundamental	concepts of Industry 4	1.0 & Industria
Robo	otics			
C				
	ception and development of pro			
Desi	gn processes and methods. C	CAD/CAM/CAE	•	oduct lifecycl
Desi man	gn processes and methods. C agement (PLM). Concepts genera	CAD/CAM/CAE	•	oduct lifecycl
Desi man idea	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches	CAD/CAM/CAE ation and emb	odiment. Expression of	oduct lifecycl
Desi man idea:	gn processes and methods. C agement (PLM). Concepts genera	CAD/CAM/CAE ation and emb gital transform	odiment. Expression of	oduct lifecycl
Desi man idea: Driv	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di	CAD/CAM/CAE ation and emb	odiment. Expression of	oduct lifecycl product desig
Desig man idea: Driv Com	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD)	CAD/CAM/CAE ation and emb gital transform UNIT-II	odiment. Expression of ation challenges	oduct lifecycl product design 06 Hours
Desi man idea: Driv Driv Com 3D n	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD) nodeling. Parametric design. Asse	CAD/CAM/CAE ation and emb gital transform UNIT-II	odiment. Expression of ation challenges	oduct lifecycl product design 06 Hours
Desi man idea: Driv Com 3D n CAD	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD) nodeling. Parametric design. Asse	CAD/CAM/CAE ation and emb gital transform UNIT-II	odiment. Expression of ation challenges	oduct lifecycle product design 06 Hours e of a product
Designan idea: Driv Com 3D n CAD	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD) nodeling. Parametric design. Asse	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling	odiment. Expression of ation challenges g. Render the appearance	oduct lifecycle product design 06 Hours e of a product 08 Hours
Designan idea: Driv Com 3D n CAD Finit	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD) nodeling. Parametric design. Asse puter Aided Engineering (CAE) e Element Analysis (FEA) to valida	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling te functional p	odiment. Expression of ation challenges g. Render the appearance erformance: general stag	oduct lifecycl product design 06 Hours e of a product 08 Hours ges of the
Designan idea: Driv Com 3D n CAD CAD Finite proc	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Di puter Aided Design (CAD) nodeling. Parametric design. Asse	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling te functional p als definition, l	odiment. Expression of ation challenges g. Render the appearance erformance: general stag oading (loads, displacen	oduct lifecycle product design 06 Hours e of a product 08 Hours ges of the nents
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Designan idea: Driv Com 3D n CAD CAD Finite proc cons man Reve Gene	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Dis puter Aided Design (CAD) nodeling. Parametric design. Asse puter Aided Engineering (CAE) e Element Analysis (FEA) to valida ess, solid and FEA models, materi traints), post-processing, results ufacturing. erse engineering eral methodology: point clouds, models. Digitizing methods and n	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling te functional p als definition, l and verificatio UNIT-III meshes (.stl), nain technolog	odiment. Expression of ation challenges g. Render the appearance erformance: general stag oading (loads, displacen ons. Topology optimizati ons. Topology optimizati	oduct lifecycl product design 06 Hours e of a product 08 Hours ges of the nents on in additive 05 Hours and parametri ection of revers
Designan idea: Driv Com 3D n CAD Finit proc cons man Gene CAD engi	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Dis puter Aided Design (CAD) nodeling. Parametric design. Asse puter Aided Engineering (CAE) e Element Analysis (FEA) to valida ess, solid and FEA models, materi traints), post-processing, results ufacturing. erse engineering eral methodology: point clouds, models. Digitizing methods and n neering systems. Hardware and	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling te functional p als definition, l and verificatio UNIT-III meshes (.stl), nain technolog	odiment. Expression of ation challenges g. Render the appearance erformance: general stag oading (loads, displacen ons. Topology optimizati ons. Topology optimizati	oduct lifecycl product desig 06 Hour e of a product 08 Hour ges of the nents on in additive 05 Hour and parametri ection of revers
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Designan idea: Driv Com 3D n CAD Finit proc cons man Gene CAD engi man Add	gn processes and methods. C agement (PLM). Concepts genera s using 2D sketches ers for digital transformations, Dis puter Aided Design (CAD) nodeling. Parametric design. Asse puter Aided Engineering (CAE) e Element Analysis (FEA) to valida ess, solid and FEA models, materi traints), post-processing, results ufacturing. erse engineering eral methodology: point clouds, models. Digitizing methods and n neering systems. Hardware and ufacturing itive manufacturing eral methodology, stages and con	CAD/CAM/CAE ation and emb gital transform UNIT-II mbly modeling te functional p als definition, l and verificatio UNIT-III meshes (.stl), nain technolog software invol	odiment. Expression of ation challenges g. Render the appearance erformance: general stag oading (loads, displacen ons. Topology optimizati ons. Topology optimizati NURBS surface models ies: applications and sele ved. Reverse engineerir	product design 06 Hours e of a product 08 Hours ges of the nents on in additive 05 Hours and parametric ection of reverse and additive 05 Hours of the of the ection of reverse of the of the and parametric of the of the of the begies, principles



manufacturing technologies. Main brands and suppliers available. Design for Additive Manufacturing (DFAM). Design for functionality and 3D printability. Planning and slicing additive manufacturing software

Cour	se Outcomes: At the end of the course student will be able to
1.	Explain the fundamental concepts of Digital manufacturing, about product
	development and the drivers and challenges regarding digital transformation.
2.	Discuss the use of CAD in product development.
3.	Discuss about FEA for validating the functional performance of products.
4.	Discuss the application and selection of reverse engineering systems.
5.	Discuss about the major additive manufacturing technologies, its principles and
	applications.

Course Outcomes Mapping with Program Outcomes & PSO

ourse outcomes mapping			9-											
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PSO,	Ļ
↓ Course Outcomes														
RI2301-1.1	3					1	2			1		1		2
RI2301-1.2	3					1	2			1		1		2
RI2301-1.3	3					1	2			1		1		2
RI2301-1.4	3					1	2			1		1		2
RI2301-1.5	3					1	2			1		1		2

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	K. T. Ulrich and S. D. Eppinger, Product Design and Development, 6 th Ed., McGraw-
	Hill Education, 2015. ISBN-13: 978-0-078-02906-6
2.	Parametric Technology Corporation (PTC), Simulation using Creo Parametric user
	guides.
3.	V. Raja and K. J. Fernandes (eds.), Reverse Engineering. An Industrial Perspective, 1 st
	Ed., Springer-Verlag London, 2008. ISBN-13: 978-1-849-96660-3
REFER	RENCE BOOKS:
1.	N. Hopkinson, R. J. M. Hague and P. M. Dickens (eds.), Rapid Manufacturing: An Industrial Revolution
	for the Digital Age, 1 st Ed., John Wiley & Sons, 2005. ISBN-13: 978-0-470-01613-8
2.	K. Otto and K. Wood, Product Design: Techniques in Reverse Engineering and New Product
	Development, 1 st Ed., Prentice Hall, 2000. ISBN-13: 978-0-130-21271-9
3.	Z. Zhou, S. Xie, and D. Chen, Fundamentals of Digital Manufacturing Science, 1 st Ed., Springer-Verlag
	London, 2012. ISBN-13: 978-1-447-12714-7
4.	I. Gibson, D. W. Rosen, and B. Stucker, Additive Manufacturing Technologies: Rapid Prototyping to
	Direct Digital Manufacturing. Springer-Verlag Boston, 2010. ISBN-13: 978-1-441-91119-3
5.	C. K. Chua, K. F. Leong, and C. S. Lim, Rapid Prototyping: Principles and Applications, 3 rd Ed., World
	Scientific, 2010. ISBN-13: 978-9-812-77898-7
E Boo	ks / MOOCs/ NPTEL
1.	Jack C Chaplin, Claudia Pagano & Santi Fort, "Digital Manufacturing for SMEs – An Introduction",
	Digit –T, Digital Manufacturing Training,
	file:///G:/digital%20manufacturing/Digital%20Manufacturing%20for%20SMEs.pdf
2.	Mark J. Barrenechea & Tom Jenkins, "Digital Manufacturing", Open Text Corporation, Canada, ISBN
	978-0-9936047-8-2, 2018. file:///G:/digital%20manufacturing/opentext-wp-digital-manufacturing-
	ebook-en.pdf



	Intellig	ent Manufa	acturing	
Cou	arse Code:	RI2302-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	IS1001-1		
		partment: Ro	botics and AI	
Cou	rse Objectives:			
1.	Describe the structure and funct		J J	
2.	Discuss the manufacturing com	•	•	nts and
	architecture of intelligent manuf			
3.	Apply the understanding of com	•		
	learning develop a systematic ap	oproach for de	esign and implementation	on of
	manufacturing systems.			
4.	Apply the understanding of Auto	•		
1	systems and machine learning to		stematic approach for c	lesign and
_	implementation of manufacturir	0 /		•
5.	Design the Information dashboa	-	ent manufacturing syste	ms using
	models, algorithms and method			
_		UNIT-I		00.11
	puter integrated manufacturing			08 Hours
of Cl	ture and functional areas of CIM s	ystem - AD, C	APP, CAIVI, CAQC, ASRS	and advantages
	ufacturing communication syste	mc		08 Hours
	P/TOP OSI model, data redundan		and bottom-up appro	
				ach, volume of
	mation Intelligent manufacturing	- system con	nnonents system archit	ecture and data
infor	mation. Intelligent manufacturing	– system con	nponents, system archit	ecture and data
infor	mation. Intelligent manufacturing system operation	– system con	nponents, system archit	ecture and data
infor			nponents, system archit	ecture and data
infor flow,	system operation	UNIT-II	nponents, system archite	
infor flow, Com	system operation	UNIT-II vstems		08 Hours
infor flow, Com basic	system operation ponents of knowledge-based system components of knowledge base	UNIT-II rstems d systems, kn	owledge representation	08 Hours
infor flow, Com basic knov	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in	UNIT-II rstems d systems, kno terference eng	owledge representation gine, knowledge acquisit	08 Hours , comparison of ion
infor flow, Com basio know Mac	system operation ponents of knowledge-based sy c components of knowledge base vledge representation schemes, in hine learning – concept of artific	UNIT-II rstems d systems, kn terference eng ial intelligenc	owledge representation gine, knowledge acquisit e, conceptual learning,	08 Hours , comparison of ion artificial neura
infor flow, Com basic knov Mac netw	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in	UNIT-II rstems d systems, kn terference eng ial intelligenc	owledge representation gine, knowledge acquisit e, conceptual learning,	08 Hours , comparison of ion artificial neura
infor flow, Com basic know Mac netw man	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific vorks - biological neuron, artificia	UNIT-II rstems d systems, kn terference eng ial intelligenc	owledge representation gine, knowledge acquisit e, conceptual learning,	08 Hours , comparison of ion artificial neural
infor flow, flow, basic basic know Mac Mac netw man Auto	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific vorks - biological neuron, artifician ufacturing	UNIT-II vstems d systems, kno terference eng ial intelligence al neuron, typ	owledge representation gine, knowledge acquisit e, conceptual learning, pes of neural networks,	08 Hours , comparison of ion artificial neural applications in 08 Hours
infor flow, flow, basic basic know Mac netw man Auto varia	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific vorks - biological neuron, artificia ufacturing pmated process planning	UNIT-II rstems d systems, kno terference eng ial intelligence al neuron, typ , expert system	owledge representation gine, knowledge acquisit e, conceptual learning, pes of neural networks,	08 Hours , comparison of ion artificial neura applications in 08 Hours
infor flow, flow, basic basic know Mac Mac netw man Auto varia reco	ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific orks - biological neuron, artificia ufacturing omated process planning int approach, generative approach	UNIT-II vstems d systems, kno terference eng ial intelligence al neuron, typ , expert system g	owledge representation gine, knowledge acquisit e, conceptual learning, pes of neural networks, ms for process planning,	08 Hours , comparison of ion artificial neura applications in 08 Hours feature
infor flow, flow, flow, basic basic know Mac netw man Auto varia reco Know	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific vorks - biological neuron, artificia ufacturing omated process planning int approach, generative approach gnition, phases of process plannin	UNIT-II rstems d systems, kno terference eng ial intelligence al neuron, typ , expert system g nt Selection (k	owledge representation gine, knowledge acquisit e, conceptual learning, bes of neural networks, ms for process planning, (BSES) – Manufacturing	08 Hours , comparison of ion artificial neura applications in 08 Hours feature system design,
infor flow, flow, flow, flow, basic basic basic know areco Know equi	system operation ponents of knowledge-based sy c components of knowledge based vledge representation schemes, in hine learning – concept of artific vorks - biological neuron, artificia ufacturing pmated process planning int approach, generative approach gnition, phases of process plannin wledge Based System for Equipme	UNIT-II vstems d systems, known terference english ial intelligence al neuron, typ , expert system g nt Selection (known ng the manufactor	owledge representation gine, knowledge acquisit e, conceptual learning, ses of neural networks, ms for process planning, (BSES) – Manufacturing acturing equipment sele	08 Hours , comparison of ion artificial neura applications ir 08 Hours feature system design,



Information Dashboard Design

08 Hours

Group technology: models and algorithms – visual method, coding method, cluster analysis method, matrix formation – similarity coefficient method, sorting-based algorithms, bond energy algorithm, cost-based method, cluster identification method, extended CI method.

-	
Cour	se Outcomes: At the end of the course student will be able to
1.	Explain the structure and function of manufacturing systems
2.	Discuss the manufacturing communication systems and the components and architecture of intelligent manufacturing systems.
3.	Apply the understanding of components in knowledge-based systems and machine learning develop a systematic approach for design and implementation of manufacturing systems.
4.	Apply the understanding of Automated process planning approaches and KBSES systems and machine learning to develop a systematic approach for design and implementation of manufacturing systems.
5.	Design the Information dashboard for intelligent manufacturing systems using models, algorithms and methods

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO \	\checkmark
↓ Course Outcomes													1	2	3
RI2302-1.1	3	-	1				-	-			-	2	-	2	2
RI2302-1.2	3	I	1				-	-			-	2	-	2	2
RI2302-1.3	3	-	2				-	-			-	2	-	2	2
RI2302-1.4	3	-	2				-	-			-	2	-	3	3
RI2302-1.5	3	-	3				-	-			-	2	-	2	3
1															

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	Automation, Production Systems and Computer Integrated Manufacturing, Mikell P.
	Groover,PHI,8th edition, 2008.

- 2. Artificial Neural Networks, Yagna Narayana, PHI, 2009
- **3.** Futuristic Trends in Intelligent Manufacturing: Optimization and Intelligence in Manufacturing (Materials Forming, Machining and Tribology), K. Palanikumar, Elango Natarajan, et al., Springer, 2021

REFERENCE BOOKS:

1. Intelligent Manufacturing, Sunil Puranik, Springer, 2021

E Books / MOOCs/ NPTEL

- **1.** https://nptel.ac.in/courses/110/106/110106044/
- 2. https://www.udemy.com/course/intelligent-manufacturing-system/

N NITTE

<u>C</u> ~-	urse Code:	Mechatroni RI2303-1	Course Type	PEC
	iching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
	requisite	EC 1001-1,		50+50
110	Teaching Department			
`ouu	rse Objectives:		ia Artificial Intelligen	
1.	Understand basic mechatronic s	systems mech	anical components ac	tuators sensors
±.	and also with controllers of med	-	-	
2.	Gaining knowledge of pneumat		•	
_ .	actuators.			
3.	To familiarize with the various ty	vnes mechani	cal switches. Solid stat	e switches
5.	drives and controls, characterist			
	actuators.			
4.	Provide sound understanding o	f signal conve	rsion i.e. ADC to DAC	and vice versa
	amplifiers,			
5.	Understand architecture of 808	5 microproces	sors, micro controller	and basic
	architecture of PLC system	1		
		UNIT-I		
ntro nicro ypic Revi	oduction oduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. Tew of Transducers and Sensors	tems, Meası echatronics a	pproach. Examples ar	control system nd discussions c 04 Hou
ntro nicro ypic Revi ntro ind Pneu	oduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. Tew of Transducers and Sensors oduction to Transducers and senso Hall-effect sensor, encoders, selec umatic Systems	tems, Measi echatronics a ors, their classi tion of sensor	pproach. Examples ar fication, light sensors, s.	04 Hour proximity senso 05 Hour
ntro nicro ypic Revi ntro ind Pneu ntro	oduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. Tew of Transducers and Sensors oduction to Transducers and senso Hall-effect sensor, encoders, selec umatic Systems oduction, Basic structure of pneu	tems, Measi echatronics a ors, their classi tion of sensor umatic system	pproach. Examples ar fication, light sensors, s. us, filter, lubricator, re	control system nd discussions o 04 Hou proximity senso 05 Hou egulator, Valves
ntro ypic Revi ntro ind Pneu ntro Class	oduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. ew of Transducers and Sensors oduction to Transducers and senso Hall-effect sensor, encoders, selec umatic Systems oduction, Basic structure of pneu sification, Pressure control valve,	tems, Measi echatronics a ors, their classi tion of sensor umatic system Flow control	pproach. Examples ar fication, light sensors, s. s, filter, lubricator, re valve, Direction contr	control system nd discussions of 04 Hou proximity senso 05 Hou egulator, Valves ol valve. Types
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ntro nicro ypic Revi ntro ntro Class cylin :ircu	eduction to Mechatronic systems oprocessor based controllers, Mechatronic systems. ew of Transducers and Sensors oduction to Transducers and sensor Hall-effect sensor, encoders, select umatic Systems oduction, Basic structure of pneusification, Pressure control valve, ders, air motors, air compressor its. Active learning component on es and controls	tems, Measu echatronics a ors, their classi tion of sensor umatic system Flow control rs, Symbols o Pneumatics UNIT-II	pproach. Examples ar fication, light sensors, s. s, filter, lubricator, re valve, Direction contr f Pneumatic elements	control system of discussions of 04 Hou proximity senso 05 Hou egulator, Valves ol valve. Types s and application 04 Hou
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ntro nicro ypic Revi ntro ntro Class ylin ircu Driv Mecl bear	eduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. ew of Transducers and Sensors oduction to Transducers and senso Hall-effect sensor, encoders, selec umatic Systems oduction, Basic structure of pneu sification, Pressure control valve, ders, air motors, air compressor its. Active learning component on es and controls hanical system, Anti Friction guid ings trical Actuation Systems	tems, Measu echatronics a ors, their classi tion of sensor umatic system Flow control rs, Symbols o Pneumatics UNIT-II e ways, timer	pproach. Examples ar fication, light sensors, s. us, filter, lubricator, re valve, Direction contro f Pneumatic elements belt and pulley, high	control system od discussions of 04 Hou proximity senso 05 Hou egulator, Valves ol valve. Types s and application 04 Hou speed precession 04 Hou
ntro nicro ypic Revi ntro ntro Class ylin ircu Driv Mecl Dear	oduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. Tew of Transducers and Sensors oduction to Transducers and sensor Hall-effect sensor, encoders, select umatic Systems oduction, Basic structure of pneu sification, Pressure control valve, ders, air motors, air compressor its. Active learning component on es and controls hanical system, Anti Friction guid ings trical Actuation Systems ators and actuator system, classif	tems, Measu echatronics a ors, their classi tion of sensor imatic system Flow control rs, Symbols o Pneumatics UNIT-II e ways, timer	pproach. Examples ar fication, light sensors, s. is, filter, lubricator, re valve, Direction contr f Pneumatic elements belt and pulley, high anical switches, Solene	control system od discussions of 04 Hou proximity senso 05 Hou egulator, Valves ol valve. Types s and application 04 Hou speed precession 04 Hou
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ntro nicro ypic Revi ntro Intro Class ylin Class ylin ircu Vecl Mecl Drive Mecl Dear ilect Actu tate iign ntro	eduction to Mechatronic sys oprocessor based controllers, Me cal mechatronic systems. ew of Transducers and Sensors oduction to Transducers and sensor Hall-effect sensor, encoders, selec umatic Systems oduction, Basic structure of pneu sification, Pressure control valve, ders, air motors, air compressor its. Active learning component on es and controls hanical system, Anti Friction guid ings trical Actuation Systems ators and actuator system, classif e switches, Motors- DC & AC moto	tems, Measu echatronics a ors, their classi tion of sensor umatic system Flow control rs, Symbols o Pneumatics UNIT-II e ways, timer fication, Mech ors, Stepper m , Operational	pproach. Examples ar fication, light sensors, s. as, filter, lubricator, revalve, Direction contro f Pneumatic elements belt and pulley, high anical switches, Solen otors, servo motor. amplifier, Inverting,	control system d discussions of 04 Hou proximity senso 05 Hou egulator, Valves ol valve. Types s and application 04 Hou speed precession 04 Hou oids, relays, solice 06 Hou Non- invertin



Microprocessors

05 Hours

05 Hours

Introduction to microprocessor, 8085 microprocessor architecture and terminology, Microcontrollers. Differences b/w microprocessor & micro controllers. Classification of micro controllers.

UNIT-III

Programmable logic controller

Introduction to PLC's, basic structure, Principle of operation, Programming and concept of ladder diagram, concept of latching &selection of a PLC. Active learning component on PLC.

Course Outcomes: At the end of the course student will be able to

- **1.** Summarize significance of mechatronics to attain better performance of electro mechanic systems. Identify key elements of the mechatronic system and represent them as block diagrams. Demonstrate Hall effect, inductive, capacitive and photodiode transducers, which are used in vital mechatronic applications
- **2.** Describe the pneumatic components such as FRL unit, Valves and pneumatic actuators along with their functions. Design, simulate and develop pneumatic circuits for Industrial applications using these pneumatic components.
- **3.** Illustrate the operational characteristics of solid state switches, mechanical and electrical actuator systems. Identify suitable drives for mechatronics systems.
- **4.** Describe the concept of Amplifiers, Filters, Analogue and digital signal, Converters (ADC, DAC) and DAQ for its industrial applications.
- **5.** Utilize the knowledge of, microprocessor, microcontroller, and PLC. Develop PLC ladder programming for industrial applications.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes															
RI2303-1.1	3	1	1		1				3	1		2	2		2
RI2303-1.2	3	2	2	2	2				2	1	2	2	2		2
RI2303-1.3	3	2	3	2	3				3	2	2	3	2		2
RI2303-1.4	3	2	2	1	2				2	1	2	2	2		2
RI2303-1.5	3			2	3				2	2	2	3	2		2

1: Low 2: Medium 3: High

TEXTBOOKS: 1. Mechatronics, W. Bolton, Pearson education, 3rd edition. 2013 2. Microprocessor Architecture, programming and applications with 8085, R.S. Ganokar, Wiley, Eastern, 1st 1987 **3.** Introduction to Mechatronics, K. K., Appukuttan, Oxford University press 1st 2007 **REFERENCE BOOKS:** Pneumatic systems, S. R Majumdar, Tata Mc.Graw-Hill, Publishing company, ltd, 1st ,1997 1. A Textbook of Mechatronics, RK Raput, S.Chand Publishing,, 1st 2007 2. 3. Mechatronics, NitaigourPrem chandMahilik, Tata Mc.Graw-Hill, Publishing company Ltd., 1st 2003 **E Books / MOOCs/ NPTEL** https://nptel.ac.in/courses/112/103/112103174/ 1. https://nptel.ac.in/courses/112/107/112107298/ 2.



3. https://nptel.ac.in/courses/112/101/112101304/

	Rob	ot Gripper	Design	
Cour	se Code:	RI2304-1	Course Type	PEC
Teac	hing Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tota	l Teaching Hours	40	CIE + SEE Marks	50+50
Prer	equisite	ME 1003-1,	ME 1002-1	
	Teaching	Department	Robotics & AI	
Cour	se Objectives:			
1.	Study the overview about the gr	ippers.		
2.	Understand the working princip	le different ty	pes of the mechanical g	ripper.
3.	Understand the working princip	le different ty	pes of the non-mechani	cal gripper.
4.	Study different gripper materials	5.		
5.	Understand different hybrid grip	pers mechan	ism.	
		UNIT-I		
	duction to Prehension Tech			
	mation, Definitions and concep		Grasping in natural sy	
Histo	rical Overview of Technical Hand	S.		07 Houi
Auto	matic Prehension: Active Pair N	Mating Pair M	lating, Strategy & Proce	edures,
Duck			5	
Pren	ension Strategy, Gripper Procedu	ure, Conditior	ns & Force, Gripper Fle	xibility,
	ension Strategy, Gripper Procedu per Classification, Requirements			-
Gripp	.			-
Gripp selec	per Classification, Requirements tion of grippers.	and Gripper UNIT-II	Characteristics & Plann	ning & 09 Hou i
Gripp selec Impa Pneu Gripp Impa Gripp Finge Secu	per Classification, Requirements	and Gripper UNIT-II Gripper Drives Grippers (Capability, Ro Grippers, Secu	Characteristics & Plann s, Electro-Mechanical E ctuation, Design of Import mpactive Grippers, Ar (Centring Grippers), In tatable Jaw Grippers, Gruppers, Gru	Drives, 09 Hour Orives , 06 Hour active ngular ternal ripper orces,
Gripp selec Impa Pneu Gripp Impa Gripp Finge Secu	ber Classification, Requirements tion of grippers. Active Mechanical Grippers: G matic Drives, Electrostrictive & Pl bers, Systematics & Kinematic ctive Grippers, Radial Impactiv bers, Gripper with Self-blocking of er & Jaw Design, Self-Securing (ring through object Mass, Three-	and Gripper UNIT-II Gripper Drives Grippers (Capability, Ro Grippers, Secu	Characteristics & Plann s, Electro-Mechanical E ctuation, Design of Import mpactive Grippers, Ar (Centring Grippers), In tatable Jaw Grippers, Gruppers, Gru	Drives, 09 Hour Orives , 06 Hour active ngular ternal ripper orces,
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Gripp selec Impa Pneu Gripp Impa Gripp Finge Secu Four Ingre	ber Classification, Requirements tion of grippers. Active Mechanical Grippers: G matic Drives, Electrostrictive & Pi bers, Systematics & Kinematic ctive Grippers, Radial Impactiv bers, Gripper with Self-blocking of er & Jaw Design, Self-Securing (ring through object Mass, Three- point Prehension. essive Grippers: Flexible Ma	and Gripper UNIT-II iripper Drives iezoelectric A s, Parallel I re Grippers (capability, Ro Grippers, Secu finger Grippe	Characteristics & Plann s, Electro-Mechanical E ctuation, Design of Impo mpactive Grippers, Ar (Centring Grippers), In tatable Jaw Grippers, Gr uring Through Spring F rs & Four-finger gripper	orives, active ngular ternal ripper orces, 's and



Contigutive Prehension: Chemo-adhesion, Thermo-adhesion.

04 Hours

Course Outcomes: At the end of the course student will be able to

- **1.** Determine different types of gripper used in robots.
- 2. Summarize forces acting on the grippers, requirements & selection criteria of grippers.
- **3.** Explain working concept of different types of mechanical grippers.
- **4.** Determine knowledge of different materials used for grippers.
- **5.** Identify concept of different types of non-mechanical grippers.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO (Ļ
↓ Course Outcomes													1	2	3
RI2304-1.1	3	-	3				-	-			-	2	3		3
RI2304-1.2	3	-	3				-	-			-	2	3		3
RI2304-1.3	3	-	3				-	-			-	2	3		3
RI2304-1.4	3	-	3				-	-			-	2	3		3
RI2304-1.5	3	-	3				-	-			-	2	3		3
1. Low 2. Modium 2	. ц:	arla													

1: Low 2: Medium 3: High

TEXTBOOKS:

ILAIDOORS.	
1.	Robot Grippers, Prof. Gareth J. Monkman, Dr. Stefan Hesse Ralf Steinmann,
	Wiley-VCH Verlag GmbH & Co., 1st Edition 2006.
2.	Robot Grippers, (International Trends in Manufacturing), D.T. Pham, W.
	B.Heginbotham, IFS, 1986.
3.	Make Your First Robot, Kumar Vineesh, Notion Press Inc, Edition: 1, 2017
4.	Topology Design of Robot Mechanisms, Yang Tingli, Springer Verlag, 2018.
5.	Kinematic Analysis of, Robot Manipulators, Carl D. Crane III, Joseph Duffy,
	Import, 3rd Edition 2008.
E Books / MC	OCs/ NPTEL

1. https://nptel.ac.in/courses/112/107/112107289/



Professional Elective Courses (Signal Processing and Programming Stream)



GROUP-I

	Dat	a Visualizat	ion	
Cour	se Code:	RI2211-1	Course Type	PEC
Teac	hing Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tota	l Teaching Hours	40	CIE + SEE Marks	50+50
Prere	equisite	CS1001-1		
	Теас	hing Departn	nent:	
Cours	e Objectives:			
1.	Explain the applications of data v	visualization.		
2.	Explore the various advanced vis	ualization too	S.	
3.	Understand the basics of data vis	sualization tab	les.	
4.	Apply visualization techniques for	or various data	analysis tasks.	
5.	Understand the considerations for	or designing tl	ne information dashboa	ird.
		UNIT-I		
Apply	visualization techniques for va	arious data an	alysis tasks.	07 Hours
Acquir	ring and Visualizing Data, Simult	aneous acquis	ition and visualization,	Applications of
	Visualization, Keys factors of Dat			
Better	JavaScript processing, Rise of HT	ML5, Lowering	g the implementation B	ar)
-	ring the Visual Data Spectrum			09 Hours
	ng Primitives (Data Points, Line C			
	ced Visualizations (Candlestick (ts, Map Charts,
Infogr	aphics). Making use of HTML5 CA		ating SVG	
		UNIT-II		
	of Data Visualization	a .		07 Hours
	Reading Data from Standard			
	itting Basic Table Data (Buildin	-	-	
	ns), Assuring Maximum readabili		-	
-	nic Highlighting), Including comp	utations, Using	g data tables library, rela	ating data table
to a ch				00 110
	lizing data Programmatically	LE Capyon basi	ce linear interpolation	08 Hours
	ng HTML5 CANVAS Charts (HTM In Chart, Animations), Starting wi		-	•
	art, A basic Pie chart, Working wi	-	-	dasics, A dasic
	art, A basic rie chart, Working wi			
Inform	nation Dashboard Design			09 Hours
	uction, Dashboard design issu	es and asses	sment of needs Con	
	ning dashboard-visual perceptic			
-	ry of Graphs, Designing Bullet Gra	-		
	l Design Practices, Putting it all to			Display Meala,
Critica				
Cours	e Outcomes: At the end of the co	ourse student	will be able to	
1.	Explain principles of visual perce			
2.	Use advanced visualization tools		ANVAS, Integrating SV(3
	Apply basic skills for visual analy			-

NN	ITTE					Curr	iculu	m –	B.Te	ch. (I	Robotic	es & Ai	rtificial	Intelli	igenec	e): 2022
4.	Apply visualization tech	niqu	Jes a	and	Crea	ating	g HT	ſML	5 C/	ANV	'AS C	hart	s and	d Goo	ogle	
	charts for various data a	nal	ysis	task	S.		-								-	
5.	Design information das	hbo	ard													
Cours	se Outcomes Mapping v	with	Pro	ogra	m (Duto	om	es a	& P:	SO						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO.	\downarrow
↓ Co	ourse Outcomes													1	2	3
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	RI2211-1.2	3	-	1		3		-	-			-	2	-	2	
	RI2211-1.3	3	-	3		3		-	-			-	2	-	2	
	RI2211-1.4	3	-	3		3		-	-			-	2	-	2	
	RI2211-1.5	3	-	1		3		-	-			-	2	-	2	
	1: Low 2: Medium 3:	Hi	gh													· · · · ·
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1.	Information Dashboard	l De	sign	: Dis	splay	ying	Da	ta fo	or A	t-a-	gland	ce M	onito	oring	,	
	Stephen Few, Analytics	Pre	ss, 2	nd ,	201	L3										
2.	Beautiful Visualization,	Julie	e Ste	eele,	No	ah I	iins	ky, (O'Re	eilly	Med	ia, Ir	nc., 19	st Ec	ditio	ח,
	June 2010															
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1.	https://www.coursera.o	rg/s	spec	ializ	atio	ns/c	lata	-vis	ualiz	zatio	on					
2.	https://www.coursera.o	rg/l	earr	n/an	alyti	cs-t	able	eau								
3.	https://www.edx.org/co	ours	e/da	ata-s	cier		vicu	əliz	atio	n						

	to IVIAI LAB	Programming	
Course Code:	RI2212-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CS1001-1, I	S1001-1	
Teaching Department	: Robotics an	d Artificial Intelligence	
Course Objectives:			
1. Explain the main features of the	he MATLAB p	rogram development env	rironment to
enable their usage in the simple	e engineering p	problems.	
2. Implement simple mathemati	ical functions,	/equations in numerical	computing
environment such as MATLAB			
3. Able to program scripts and fun	ctions using th	ne MATLAB development e	environment.
4. Create and control simple plot a	and user-interf	face graphics objects in M	ATLAB
5. Apply numeric techniques and	computer sim	nulations to solve enginee	ering-related
problems.			
	UNIT-I		
MATLAB Basics			06 Hours
The MATLAB environment - Basic o			
operators. Array operations in MATLA			
and functions (m-files), Reading and	-	file handling - Personalize	d functions
Toolbox structure, Plotting and Output	t		
Errors and Approximations			05 Hours
Errors in Numerical Computation, Trun		-	Off Errors; and
Iterative Methods, Stepwise Methods a		agation.	04.11-
Numerical Differentiation and Integ	ration		
Differentiation in Cinale Veriable. Liab		entiation Formerulas Dontio	
Differentiation in Single Variable, High	er Order Differ		l Differentials
Numerical Integration, Multiple App	er Order Differ		l Differentials
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Image Representation, Image Resampling, Image Intensity & Color Distributions, Image Filtering, Image Segmentation. Cropping, Color Images, Motion, Convex Hull, Dilation and Erosion. Signals as Time Dependent Data, Signal Interpolation. Signal Frequency Analysis, Sampling and Aliasing. **Course Outcomes:** At the end of the course student will be able to 1. Explain the main features of the MATLAB program development environment to enable their usage in the simple engineering problems. 2. Implement simple mathematical functions/equations in numerical computing environment such as MATLAB Able to program scripts and functions using the MATLAB development environment 3. 4. Create and control simple plot and user-interface graphics objects in MATLAB 5. Apply numeric techniques and computer simulations to solve engineering-related problems **Course Outcomes Mapping with Program Outcomes & PSO** 6 **Program Outcomes**→ 2 3 4 5 7 8 9 10 11 12 **PSO** 1 **Course Outcomes** 1 2 3 2 2 2 RI2212-1.1 3 3 3 3 2 _ _ _ _ _ _ _ _ _ _ RI2212-1.2 3 2 3 3 3 ---2 2 -2 3 2 3 3 3 _ 2 2 RI2212-1.3 _ _ 2 _ _ _ _ _ RI2212-1.4 3 2 3 3 3 _ -_ _ -2 2 -2 3 RI2212-1.5 3 2 3 3 _ -2 2 2 _ -_ -_ 1: Low 2: Medium 3: High **TEXTBOOKS: 1.** Mastering MATLAB, Duane C. Hanselman, Bruce L. Littlefield, Pearson1st Edition, 2011 **REFERENCE BOOKS:** Stephen J. Chapman, Essentials of MATLAB Programming, Published by Cengage 1. Learning, 2nd Edition, 2009 MATLAB and its Applications in Engineering, Raj Kumar Bansal, Ashok kumar Goel, 2. Pearson 2016 3. Getting Started with MATLAB A Quick Introduction for Scientists and Engineers, Rudra

Pratap Oxford, 7th Edition, 2010

E Books / MOOCs/ NPTEL

- https://www.coursera.org/learn/matlab 1.
- https://nptel.ac.in/courses/103/106/103106118/ 2.
- https://ocw.mit.edu/courses/mathematics/18-s997-introduction-to-matlab-3. programming-fall-2011/
- **4.** https://in.mathworks.com/help/examples.html?s tid=CRUX topnav



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213-1.3	3	-	-	2	1	3	-	-	-	-	-	1	-	3	3
213-1.4	3	-	-	2	1	2	-	-	-	-	-	1	-	3	h
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	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2022-
2.	Android Wireless Application Development, Lauren Darcey and Shane, Pearson
	Education, 2nd Edn. 2011
REFER	ENCE BOOKS:
1.	Professional Android 2 Application Development, Reto Meier, Wiley, 2010
2.	Android Programming – Pushing the Limits, Erik Hellman, Wiley, 2014
3.	Headfirst Android Development, Dawn Griffiths and David, O'Reilly SPD Publishers,
	1st Edn. 2015
4.	Beginning Android Programming with Android, J F DiMarzio, Wiley, 4th Edn. 2016
E Boo	ks / MOOCs/ NPTEL
1.	https://nptel.ac.in/courses/106/106/106106156/
2.	https://nptel.ac.in/courses/106/106/106106147/
3.	https://www.udemy.com/course/introduction-to-mobile-application-development/
4.	https://www.udemy.com/course/android-app-development-course/

	NITTE eemed to be University)	Curret	num – D. reen. (Kobones & Alum	enar interingeneee). 2
	Virtua	al Instrume	ntation	
Cou	ırse Code:	RI2214-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	EC 1001-1		
		: Robotics ar	nd Artificial Intelligence	3
	rse Objectives:			
1.	Describe virtual instrumentation			
2.	Describe data acquisition metho			
3.	Describe PC Buses used in virtua			
4.	Solve simple VI design problem			
5.	Apply the concept of VI for data		nd control.	
		UNIT-I		
Virtu	ual Instrumentation			07 Hour
	File Input / Output.			09 Hour
	and D/A converters -in Analog Input / Output cards -			
-	isition modules with serial commu t –Timers and Counters.			
• •		UNIT-II		
	oduction to PC Buses – Local bus			08 Hour
	PCI, RS232, RS422 and RS485 –			
	umentation Buses :- Modbus and	GPIB – Netwo	rked dusses – ISO/OSI R	eference mode
	rnet and TCP/ IP Protocols.			06 Hour
	gns using VI Software	rollar Mada	ling and basis control of	
	OFF controller – Proportional cont		•	level and
Teaci	tor processes – Case studies on de			
		UNIT-III		
				10 Hour
PC a	rchitecture, current trends, opera	ting system r	auirements PC hased i	
	og and digital interfaces, PXI and S		-	
	wer, speed and timing considerati			
Cour	rse Outcomes: At the end of the c	course studen	t will be able to	
1.	Explain virtual instrumentation a			
2.	Explain data acquisition method			
3.	Explain PC Buses used in virtual			

- **3.** Explain PC Buses used in virtual instrumentation systems.
- **4.** Solve simple VI design problems using the tools of VI software.

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5. Explain the implementation methods for instrumentation and the basic concepts of interfacing of VI.

Cours	e Outcomes Mapping	wit	h Pı	rogi	am	Ou	tco	mes	8	PSC)					
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↓ Co	ourse Outcomes															
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	RI2214-1.2	2	2	2	2	3	-	-	-	-	-	-	3	3	2	3
	RI2214-1.3	2	2	2	2	3	-	-	-	-	-	-	3	3	2	3
	RI2214-1.4	2	2	2	2	3	-	-	-	-	-	-	3	3	2	3
	RI2214-1.5	2	2	2	2	3	-	-	-	-	-	-	3	3	2	3
	1: Low 2: Medium 3: High															
TEXTE	BOOKS:															
1.	LabVIEW Graphical Pr	ogr	amr	ning	, Ga	ary	W	Johr	nsor	ı, Ri	char	d Jer	nning	js, N	1cGra	aw-Hill
	Professional Publishing	g, 3r	d eo	ditio	n, 2	001										
2.	Lab view for Everyone	l, Li	sa K	We	lls, F	Pren	ntice	Ha	ll of	Ind	ia. 3ı	rd ed	lition	, 200)6	
REFER	RENCE BOOKS:															
1.	Sensor, transducers ar	nd L	ab v	iew,	Bar	ry P	ato	n, P	ren	tice	Hall	of In	dia, I	2000).	
2.	Computer buses, Buch	ana	n, V	V, Cl	rc f	res	s 20	00								
E Boo	ks / MOOCs/ NPTEL															
1.	https://www.ni.com/ (web	site)												
2.	https://www.ni.com/er	n-in	/inn	0.1/2	tion	c /\w	hito	-nai	nord	106	Wirt	ıəl_ir	octru	mon	tatia	n html



GROUP-II

	nted Reality and	Virtual Reality	
Course Code:	RI2311-1	Course Type	PEC
Teaching Hours/Week (L: T: I	P: S) 3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	ME 1002-1	·	·
	Teaching Depart	ment:	
Course Objectives:	- _ •		
1. Explain the strategic role	of AR		
2. Discuss the Interactive Te	chniques in Virtual F	Reality	
3. Apply the concept of Visu	ual Computation in V	/irtual Reality	
4. Discuss the features and	methods of Augmen	ted and Mixed Reality	
5. Explain the Multiple Mod			eality.
	UNIT-I		
Introduction to Virtual Reality	/:		07 Hours
Fundamental Concept and Cor	mponents of Virtual	Reality. Primary Featur	es and Present
Development on Virtual Reality	•		
Simulation, Virtual environme	ent requirement, k	penefits of virtual rea	ality, Historical
development of VR, Scientific I	-		
world space, positioning the virt	-	-	
perspective projection, 3D clippi	-		
Reflection models, Shading a			
Stereographic image.		-	
Interactive Techniques in Virt	ual Poality:		
	ual Reality.		09 Hours
Introduction, From 2D to 3D,) boundary representati	
Introduction, From 2D to 3D, 3 Transformations: Introduction,	3D space curves, 3D	, ,	on Geometrical
	3D space curves, 3D Frames of reference	e, Modeling transformat	on Geometrical ions, Instances,
Transformations: Introduction,	3D space curves, 3D Frames of reference Collision detection (e, Modeling transformat Generic VR system: Intro	on Geometrical ions, Instances, duction, Virtual
Transformations: Introduction, Picking, Flying, Scaling the VE,	3D space curves, 3D Frames of reference Collision detection (e, Modeling transformat Generic VR system: Intro	on Geometrical ions, Instances, duction, Virtual
Transformations: Introduction, Picking, Flying, Scaling the VE,	3D space curves, 3D Frames of reference Collision detection (Iment, VR technolog UNIT-II	e, Modeling transformat Generic VR system: Intro	on Geometrical ions, Instances, duction, Virtual
Transformations: Introduction, Picking, Flying, Scaling the VE, environment, Computer environ	3D space curves, 3D Frames of reference Collision detection (ment, VR technolog UNIT-II Reality:	e, Modeling transformat Generic VR system: Intro y, Model of interaction, N	on Geometrical ions, Instances, duction, Virtual /R Systems. 06 Hours
Transformations: Introduction, Picking, Flying, Scaling the VE, environment, Computer environ Visual Computation in Virtual	3D space curves, 3D Frames of reference Collision detection (Iment, VR technolog UNIT-II Reality: ment: Introduction,	e, Modeling transformat Generic VR system: Intro y, Model of interaction, N The dynamics of numb	on Geometrical ions, Instances, duction, Virtual /R Systems. 06 Hours ers, Linear and
Transformations: Introduction, Picking, Flying, Scaling the VE, environment, Computer environ Visual Computation in Virtual Animating the Virtual Environr	3D space curves, 3D Frames of reference Collision detection (Iment, VR technolog UNIT-II Reality: ment: Introduction, mation of objects, lir	e, Modeling transformat Generic VR system: Intro y, Model of interaction, V The dynamics of numb near and non-linear trans	on Geometrical ions, Instances, duction, Virtual /R Systems. 06 Hours ers, Linear and slation, shape &
Transformations: Introduction, Picking, Flying, Scaling the VE, environment, Computer environ Visual Computation in Virtual Animating the Virtual Environr Nonlinear interpolation, the anim	3D space curves, 3D Frames of reference Collision detection (ment, VR technolog UNIT-II Reality: ment: Introduction, mation of objects, lin com deformation,	e, Modeling transformat Generic VR system: Intro y, Model of interaction, V The dynamics of numb near and non-linear trans	on Geometrical ions, Instances, duction, Virtual /R Systems. 06 Hours ers, Linear and slation, shape &
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Transformations: Introduction, Picking, Flying, Scaling the VE, environment, Computer environ Visual Computation in Virtual Animating the Virtual Environr Nonlinear interpolation, the ani object inbetweening, free fr Introduction, Objects falling in a gravitational field, Rotating whe Flight dynamics of an aircraft. Animating the Virtual Environ	3D space curves, 3D Frames of reference Collision detection (<u>ment, VR technolog</u> UNIT-II Reality: ment: Introduction, mation of objects, lin om deformation, eels, Elastic collisions ment: ar and Nonlinear inte	e, Modeling transformat Generic VR system: Intro y, Model of interaction, N The dynamics of numb near and non-linear trans particle system. Physic s, projectiles, simple pen	on Geometrical ions, Instances, duction, Virtual /R Systems. 06 Hours ers, Linear and slation, shape & cal Simulation: dulum, springs, 08 Hours of objects,
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techniques for augmented reality, wireless displays in educational augmented reality applications, mobile projection interfaces, marker-less tracking for augmented reality, enhancing interactivity in AR environments, evaluating AR systems.

UNIT-III

Multiple Models of Input and Output Interface in Virtual Reality:	05 Hours

Human factors: Introduction, the eye, the ear, the somatic senses. VR Hardware: Introduction, sensor hardware, Head-coupled displays, Acoustic hardware, Integrated VR systems. VR Software: Introduction, Modeling virtual world, Physical simulation, VR toolkits, Introduction to VRML, Input -Tracker, Sensor, Digital Glove, Movement Capture, Video-based Input, 3D Menus & 3DScanner etc. Output -- Visual /Auditory / Haptic Devices.

VR Technology in Film & TV Production. VR Technology in Physical Exercises and Games. Demonstration of Digital Entertainment by VR.

Course Outcomes: At the end of the course student will be able to

I. Explain the strategic role of AR	1.	Explain the strategic role of AF
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2.	Discuss the Interactive Techniques in Virtual Reality
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3. Apply the concept of Visual Computation in Virtual Reality

4. Discuss the features and methods of Augmented and Mixed Reality

5. Explain the Multiple Models of Input and Output Interface in Virtual Reality.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO \	\downarrow
↓ Course Outcomes													1	2	3
RI2311-1.1	3	-	-		2		-	-			-	2	-	3	
RI2311-1.2	3	-	-		2		-	-			1	2	-	3	
RI2311-1.3	3	-	-		3		I	-			I	2	I	3	
RI2311-1.4	3	-	-		3		-	-			-	2	-	3	
RI2311-1.5	3	-	-		3		-	-			-	2	-	3	
1: Low 2: Medium 3	: Hig	gh													

TEXTBOOKS:

- Virtual Reality Technology, Burdea, G. C. and P. Coffet., Wiley-IEEE Press, Second Edition, 2003/2006.
 Understanding Augmented Reality Concents and Applications, Alap P. Craig
- 2. Understanding Augmented Reality, Concepts and Applications, Alan B. Craig, Morgan Kaufmann,, 2013.
- **3.** Developing Virtual Reality Applications, Foundations of Effective Design, Alan Craig, William Sherman and Jeffrey Will, Morgan Kaufmann, 2009

REFERENCE BOOKS:

- **1.** Virtual Reality Systems, Pearson Education, John Vince, 2007
- 2. Augmented and Virtual Reality, Anand R, Khanna Publishing House, Delhi
- **3.** Visualizations of Virtual, Adams, Tata McGraw Hill, 2000.

E Books / MOOCs/ NPTEL

- **1.** https://nptel.ac.in/courses/121/106/121106013/
- **2.** https://www.udemy.com/course/augment-reality-merge-cube-ar-introduction-to-augment-reality-ar/
- 3. https://www.udemy.com/course/businesses-in-augmented-reality-virtual-reality/



	omputer Vis	sion	
Course Code:	RI2312-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CS1001-1		
Teaching Departmen	t: Robotics an	d Artificial Intelligence	•
Course Objectives:			
1. Understand digital image forma	ation and proce	ess image using various t	ransformation
filtering, enhancement and histo	ogram process	ing.	
2. Understand depth information	and tracking o	bject through multi-cam	era views.
3. Understand feature extraction a	and image segi	mentation techniques	
4. Know the clustering and classifi	ication techniq	ues to analyse patterns	
5. Tracking of an object through in	U	5	and estimating
the shape from texture, color, m	Ŭ.	les	
	UNIT-I		
Digital Image Formation and low-le			07 Hour
Overview and State-of-the-art, Fu		-	
Orthogonal, Euclidean, Affine, Project	tive, etc; Fourie	er Transform, Convolutio	on and Filtering
Restoration.			
Depth estimation and Multi-camera			09 Hour
Perspective, Binocular Stereopsis:			5 1 3
Rectification, DLT, RANSAC, 3-D recor		ework; Auto-calibration.	
F	UNIT-II		
			08 Hour
Feature Extraction Edges - Canny, LOG, DOG; Line detec	tors (Hough T		08 Hour rris and Hessia
Edges - Canny, LOG, DOG; Line detec Affine, Orientation Histogram, SIFT,	tors (Hough T , SURF, HOG,	GLOH, Scale-Space A	08 Hour rris and Hessia
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Edges - Canny, LOG, DOG; Line detec Affine, Orientation Histogram, SIFT, Pyramids and Gaussian derivative filte Pattern Analysis: Clustering	tors (Hough T , SURF, HOG, ers, Gabor Filter	GLOH, Scale-Space A rs and DWT.	08 Hour rris and Hessia analysis- Imag 06 Hour
Edges - Canny, LOG, DOG; Line detect Affine, Orientation Histogram, SIFT, Pyramids and Gaussian derivative filte Pattern Analysis: Clustering K-Means, K-Medoids, Mixture of Gaus	tors (Hough T , SURF, HOG, ers, Gabor Filter sians, Classifica	GLOH, Scale-Space A rs and DWT. ation: Discriminant Funct	08 Hour rris and Hessia analysis- Imag 06 Hour ion, Supervised
Edges - Canny, LOG, DOG; Line detec Affine, Orientation Histogram, SIFT, Pyramids and Gaussian derivative filte Pattern Analysis: Clustering K-Means, K-Medoids, Mixture of Gaus Un-supervised, Semi-supervised; Cla	ctors (Hough T , SURF, HOG, ers, Gabor Filter sians, Classifica assifiers: Bayes	GLOH, Scale-Space A rs and DWT. ation: Discriminant Funct s, KNN, ANN models;	08 Hour rris and Hessia analysis- Imag 06 Hour ion, Supervised
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 Multiple View Geometry in Computer Vision, Hartley & Zisserman, Cambridge University Press; 2 edition (2004) REFERENCE BOOKS: Machine vision, Jain, Ramesh and Rangachar Kasturi and Brian G. Schunck; McGrav Hill, Edition-1995. Introductory computer vision and image processing, Low, Adrian; McGraw-Hill, Edition-1991. Digital image processing, Gonzalez, Rafael C. and Richard E. Woods; Addison-Wes Edition: 3rd, Year:1998. E Books / MOOCs/ NPTEL https://nptel.ac.in/courses/106/105/106105216/ 	2.		ode	rn A	ppr	oac	h, D	avio	A.	Fors	syth	& Je	ean P	once	e, Pre	entice	e Hall;
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	LC and SCA		
Course Code:	RI2313-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EE 1001-1,	EC 1001-1	
Teaching Department	t: Robotics an	d Artificial Intelligenc	е
Course Objectives:			
1. Gain knowledge in the concept	s of developing	g basic skills necessary f	for PLC &
SCADA			
2. Understand the basic programm	J	and various Operation u	using RELAY
LOGIC devices used in PLC and S	SCADA		
3. Diagnose the problem related t	21 ·		System and
Communication Networks (Bus	Systems) using	Standard Protocol.	
4. Understand the concepts of SC	ADA fundamer	ntals.	
5. Understand the human machine	e interfacing co	omponent for control a	pplication.
	UNIT-I		
Programmable Logic Controllers			07 Hours
Introduction, Parts of a PLC, Principle	s of Operation	, Modifying the Operat	tion, PLCs versus
Computers, PLC Size and Application.	PLC Hardware	Components: The I/O	Section, Discrete
I/O Modules, Analog I/O Modules, S	Special I/O M	odules, I/O Specificatio	ons, The Centra
Processing Unit (CPU), Memory Desi	•	•	
Recording and Retrieving Data, Huma			
Basics of PLC Programming			09 Hours
Processor Memory Organization, Proc	gram Scan, PLC	Programming Langua	ges, Relay- Type
Instructions, Instruction Addressing,	•		
Programming Examine If Closed and			-
Diagram, Modes of operation.			J
	UNIT-II		
Developing Fundamental PLC Wirin	g Diagrams a	nd Ladder Logic Progr	ams 07 Hours
Electromagnetic Control Relays, Cont			
Mechanically Operated Switches, Sens		• •	
Relays, Converting Relay Schematics	•		•
Program Directly from a Narrative D			-
Relays, Timer Instructions, On-Delay Ti	•		-
Timer, Cascading Timers.		, ,	
SCADA Fundamentals			07 Hours
Introduction, Open system: Need an	nd advantages	s. Building blocks of S	
Remote terminal unit (RTU): Evoluti	-	-	-
subsystem, Logic subsystem, Terminat		-	
(HMI) subsystem, Power supplies, Adva	•	-	
(IEDs), Data concentrators and mergin		-	
	UNIT-III		
Master Station			05 Hours
Master station software components,	Master station	hardware components	
in the master station, small, medium,			
(GPS), Master station performance			storing systems
(Gro), musici station performance	111		



Human-Machine Interface (HMI)

05 Hours

HMI components, HMI software functionalities, Situational awareness, Intelligent alarm filtering: Need and technique, Alarm suppression techniques, Operator needs and requirements, SCADA Systems: Building the SCADA systems, legacy, hybrid, and new systems, Classification of SCADA systems, SCADA implementation: A laboratory model: The SCADA laboratory, System hardware, System software, SCADA lab field design.

Course Outcomes: At the end of the course student will be able to

1	Explain the principles of operation, hardware components and applications of PLC
⊥.	Explain the principles of operation, hardware components and applications of FEC

- 2. Develop Fundamental PLC Wiring Diagrams and Ladder Logic Programs
- **3.** Explain the building blocks and fundamentals of SCADA system
- **4.** Explain the master station software and hardware components and server system
- 5. Design Human-Machine Interface (HMI) for a control application

Course Outcomes Mapping with Program Outcomes & PSO

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1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** "Programmable Logic Controllers And Industrial Automation An Introduction" by Madhuchhanda Mitra, Penram International Publishing, 2008
- **2.** Ronald L Krutz, "Securing SCADA System", Wiley Publication, 2005
- **3.** Gary Dunning," Introduction to Programmable Logic Controllers", Thomson, 2nd Edition.

REFERENCE BOOKS:

- **1.** John W Webb, Ronald A Reis,"Programmable Logic Controllers: Principles and Application", PHI Learning, Newdelhi, 5 th Edition.
- **2.** Stuart A Boyer, "SCADA Supervisory Control and Data Acquisition", ISA, 4 th Revised edition
- **3.** SCADA Supervisory Control and Data Acquisition, Stuart A Boyer, ISA, 4th Revised edition 1993

E Books / MOOCs/ NPTEL

- **1.** https://nptel.ac.in/courses/108/105/108105088/
 - 2. Virtual Lab link- https://plc-coep.vlabs.ac.in/
- 3. <u>https://new.abb.com/plc</u>
- **4.** https://new.siemens.com/global/en/products/automation/industrysoftware/automation- software/scada.html



	SIGN	IAL PROCES	SSING	
Cou	ırse Code:	RI2314-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	EE 1001-1,	EC 1001-1	
	Teaching Department	: Robotics an	d Artificial Intelligence	9
Cour	rse Objectives:			
1.	Understand the concept of Freq	luency Domai	n Sampling, Computatio	n of DFT and
	properties of DFT			
2.	Understand Linear Filtering met	hods using Ov	erlap Add and Overlap S	Save
	Algorithms.			
3.	Understand the Fast Fourier Tra	Ű		Ŭ
4.	Design and Analyze the charact		log filters using Butterw	orth &
	Chebyshev approximation techr			
5.	Understand architecture of DSP	Processors ar	nd Filter Implementation	s using Fixed
	Point DSP processors.			
		UNIT-I		
	rete Fourier Transform			08 Hours
	rete Fourier Transform (DFT), D			perties of DF
deri	vation not included);Overlap-save	and Overlap-	add method;	
Fast	Fourier Transform		.	
F ast Decii	mation in Time FFT (DITFFT) alg			
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3.	Make use of Butterworth & Chebyshev approximations to design and implement analog and digital IIR Filters.
4.	Design & implement FIR Filters using windowing and Frequency sampling. approaches.
5.	Identify architectural features of Fixed-point DSP processors and plan the
	implementation of Filters.

Course Outcomes Mapping with Program Outcomes & PSO

source outcomes mapping			· • g·		• •			\sim							
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes													01	02	03
RI2314-1.1	3	-	-	-	-	-	-	-	-	-	-	-	3	-	-
RI2314-1.2	3	-	-	-	-	-	-	-	-	-	-	-	3	-	-
RI2314-1.3	3	-	1	-	1	-	-	-	-	-	-	-	3	2	-
RI2314-1.4	3	-	1	-	1	-	-	-	-	-	-	-	3	2	-
RI2314-1.5	3	-	-	-	-	-	-	-	-	-	-	-	3	2	-
1. Low 2. Modiums	5. 11	:													

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	Proakis, Manolakis, "Digital Signal Processing – Principles Algorithms & Applications",
	PHI, 4thEdition, New Delhi, 2007.

- **2.** Li Tan, "Digital Signal processing Fundamentals and Applications", Academic Press, 2008.
- **3.** Avtar Singh, S Srinivasan, "Digital Signal Processing", Thomson Publishing, 2004.

REFERENCE BOOKS:

- **1.** Oppenheim & Schaffer, "Discrete Time Signal Processing", PHI, 2003
- 2. S. K. Mitra, "Digital Signal Processing", Tata McGraw Hill, 2nd Edition, 2004

E Books / MOOCs/ NPTEL

1. https://nptel.ac.in/courses/117102060



Professional Elective Courses (Artificial Intelligence Stream)



U	N N	ed to be University)	Curricu	um – B. Peen. (Robones & Alth	iciai interligenece). 202.
			GF	OUP-I	
		Clo	oud Comput	ting	
	Cour	rse Code:	RI2221-1	Course Type	PEC
	Teac	hing Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	Tota	I Teaching Hours	40	CIE + SEE Marks	50+50
	Prer	equisite	IS1001-1		
		Теас	ching Departı	nent:	
(Cours	e Objectives:			1
l	1.	Explain the various elements of	distributed co	mputing.	
	2.	Explain the types of cloud and it			
	3.	Explain the characteristics of virt	tualized enviro	nment and understand	l the
-		technologies used.			
	4.	Understand the security concern		nputing.	
			UNIT-I		
		duction to Cloud Computing			07 Hours
		f computing, Parallel vs. Distribut allel computing, hardware archit			
 (1	progra (Gene for di distrib Classi	amming, levels of parallelism, La ral concepts and definitions, con istributed computing, models to puted computing-Remote proced c data center, its elements, challe tioning to cloud- consolidation, a	aws of cautior nponents of a for inter-proc lure call, Servio enges and ben	a). Elements of Distributed system, Are distributed system, Are ess communication, T ce oriented computing) efits. Data center mana	ted Computing- chitectural styles echnologies for
(Cloud	I computing Architecture			07 Hours
I	Platfo	luction, Cloud reference models rm as a service, Software as a ser d Clouds, Community Clouds), Ec	vice), Types o onomics of clo	f cloud – (Public Clouds	
			UNIT-II		
_		alization			8 Hours
1	techni Netwo	luction, characteristics of virtu ique- (execution of virtualizatic ork, Desktop, Application). Virtu lization,	on, other type	es of virtualization-Co	mpute, Storage,
	Techr	nology examples			7 Hours
)	XEN, ۱	/Mware, Microsoft Hyper-V.			
	Securi	ity Concerns, Risk Issues:- Cloud	Computing- S	ecurity Concerns. A Clo	ser Examination:

Virtualization, A Closer Examination: Provisioning.

Securing the Cloud: Key Strategies and Best Practices: - Overall Strategy: Effectively Managing Risk- Risk Management: Stages and Activities. Overview of Security Controls, Cloud Security Controls Must Meet Your Needs, NIST Definitions for Security Controls, Unclassified Models, Classified Model The Cloud Security Alliance Approach. The Limits of Security Controls -Security Exposure Will Vary over Time, Exploits Don't Play Fair. Best Practices: Best Practices for Cloud Computing- First Principals, Best Practices across the Cloud Community. Other Best Practices for Cloud Computing-

Cloud Service Consumers, Cloud Service Providers. Security Monitoring.



UNIT-III	
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Cloud Computing Security

10 Hours

The Purpose of Security Monitoring, Transforming an Event Stream, The Need for C.I.A. in Security Monitoring, the Opportunity for MaaS.

Case studies: Public cloud- AWS, Windows Azure, Google App Engine. Private Cloud- Open stack, Eucalyptus

Course Outcomes: At the end of the course student will be able to

- Explain the infrastructure management for cloud environment. 2.
- 3. Apply the concepts of Virtualization at all levels using technology XEN, Vmware, Microsoft Hyper-v.
- Explain the security concepts in cloud computing and securing the cloud. 4.
- Apply the concepts of Security Monitoring, Transforming an Event Stream using 5. case studies of public cloud such as AWS, Google App Engine and private cloud such as Open Stack.

Course Outcomes Mapping with Program Outcomes & PSO

			9.0												
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO	\downarrow
↓ Course Outcomes													1	2	3
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RI2221-1.2	3	3	-	-	-	-	I	1			-	2	1	2	-
RI2221-1.3	3	3	-	-	-	-	I	1			-	2	1	2	-
RI2221-1.4	3	3	-	-	-	-	I	I			-	2	I	2	-
RI2221-1.5	3	3	-	-	-	-	-	-			-	2	-	2	-

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	Mastering Cloud Computing Fundamentals and Applications Programming, Buyya,
	Rajkumar, Christian Vecchiola and Thamarai Selvi, McGraw Hill, 2013.

- 2. Information Storage and, Management, G., Somasundarm and Alok Srivatsa, Wiley Publishing Inc., 2009
- Moving to the Cloud Developing Apps in the World of Cloud Computing, Sitaram, 3. Dinakar and Geetha Manjunath, Elsevier, 2012

KFFFK	RENCE BOOKS:
1.	Cloud Computing Bible, Sosinsky, Barrie, Wiley India Pvt. Ltd., 2013
2.	
	Vic(J.R.), Elsevier Inc., 2012
3.	Cloud computing for dummies, Hurwitz, Judith, Wiley India Pvt Ltd, 2011
4.	Cloud Computing, A Practical Approach, Velte, Toby, Anthony Velte and R.
	Elsenpete, Tata McGraw-Hill, 2010
E Boo	ks / MOOCs/ NPTEL
1.	https://nptel.ac.in/courses/106/105/106105167/
2.	https://nptel.ac.in/courses/106/105/106105223/
3	https://www.udemy.com/course/introduction-to-cloud-computing/

/ww.udemy.com/course/introduction-to-cloud-computing/ 4. https://www.udemy.com/course/intro-to-cloud-computing/



	urse Code:	RI2222-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	CS1001-1		
	Teaching Department	: Robotics an	d Artificial Intelligen	ce
Cou	rse Objectives:			
1.	Understand the non-recursive of	or recursive a	lgorithm and to repres	sent in terms of
	standard Asymptotic notations.			
2.	Understand the Brute Force or D			
3.	Understand the Decrease and Co	•	ansform and Conquer a	algorithm desigr
	techniques to a given real time			<u> </u>
4.	Understand the Time and Space		0 0 0	ind also to apply
-	dynamic programming to a give	· · · ·		
5.	Understand the Dynamic prog	-		-
	Apply the dynamic programmin	g by using va	rious memory function	is to a given real
	time problem.	UNIT-I		
ntre	oduction	UNIT-I		06 Hour
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	es, Fundamental Data Structures.		·	
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	techniques to a given re	eal ti	ime	prol	blen	า.										
4.	Analyze Time and Space Trade off sin designing algorithms and also to apply															
	dynamic programming to a given real time problem.															
5.	Apply Greedy, Backtracking and Branch and Bound algorithm design techniques to									to						
	real time problems															
Cours	se Outcomes Mapping v	with	Pro	ogra	m C	Juto	om	es 8	<u>k P</u> S	50		1	T	r		
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1. <u>REFEI</u> 1. 2. 3. <u>E Boc</u> 1. 2. 3.	1: Low 2: Medium 3: BOOKS: Anany Levitin, "Introdu Pearson Education, 200 RENCE BOOKS: Thomas H. Cormen, Ch to Algorithms", 2nd Edi Horowitz E., Sahni S., F 2001. R.C.T. Lee, S.S. Tseng, R of Algorithms a Strateg bks / MOOCs/ NPTEL https://onlinecourses.n https://www.coursera.o introduction-xaxyP Virtual Lab link- https:// https://www.aziksa.com	ictic intion arle tion Raja: .C. C ic A ptel rg/l /cs4	gh on to s E. h, PH seka Chan ppro .ac.ii ectu	D the Leis II,20 Iran Ig & Oach Ire/a aa.w	e De ersc 06. S, " Y.T. n", T. n", T. llgon vixsit s-de	esign n, R Con T sa ata _cs2 rithr	Rona npu McC 27/p ms-p	al L. ter , brevi orevi algo	Rive Algc duc v Hil iew 1/ar	est, (prith tion I,200	Cliffc ms", to tl 05. sis-o	ord S Galo he Do f-alg	tein, gotia esigr	, 2nd "Inti n Puk	rodu olicat	ition, ction
1. <u>REFEI</u> 1. 2. 3. <u>E Boc</u> 1. 2. 3. 4.	1: Low 2: Medium 3: BOOKS: Anany Levitin, "Introdu Pearson Education, 200 RENCE BOOKS: Thomas H. Cormen, Ch to Algorithms", 2nd Edi Horowitz E., Sahni S., F 2001. R.C.T. Lee, S.S. Tseng, R of Algorithms a Strateg oks / MOOCs/ NPTEL https://onlinecourses.n https://www.coursera.o introduction-xaxyP Virtual Lab link- https:// https://www.aziksa.com	ictic intion arle tion Raja: .C. C ic A ptel rg/l /cs4	gh on to s E. h, PH seka Chan ppro .ac.ii ectu	D the Leis II,20 Iran Ig & Oach Ire/a aa.w	e De ersc 06. S, " Y.T. n", T. n", T. llgon vixsit s-de	esign n, R Con T sa ata _cs2 rithr	Rona npu McC 27/p ms-p	al L. ter , brevi orevi algo	Rive Algc duc v Hil iew 1/ar	est, (prith tion I,200	Cliffc ms", to tl 05. sis-o	ord S Galo he Do f-alg	tein, gotia esigr	, 2nd "Inti n Puk	rodu olicat	ition, ction

Cours	Machine L			
	e Code:	RI2223-1	Course Type	PEC
Teach	ing Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total	Teaching Hours	40	CIE + SEE Marks	50+50
Prere	quisite	CS1001-1		
	Teaching Department:	Robotics and	l Artificial Intelligend	:e
Course	Objectives:			
	Understand the fundamentals o learning	f Machine Lea	arning, data types, ty	pes of machine
	Understand the application of lin	ear regressior	and logistic regressic	on for real world
	Understanding and implementat	ion of algorith	ms for supervised lear	rnina
	Understand the application of			
	learning models and understand	•		5
	Make use of Data sets in imp		•	algorithms and
	implement the machine learning	-	-	-
	of choice			
		UNIT-I		
Found	ations of Machine Learning			09 Hours
What i	s machine learning? Applicatior	ns of Machine	e learning, Understand	d Data, Types of
machir	e learning: Supervised, Unsupe	rvised, Reinfo	rcement Learning, Th	eory of learning:
feasibil	ity of learning, error and noise, t	training versus	s testing, theory of ge	neralization, bias
and va	riance, learning curve.			
Superv	vised Learning-I			07 Hours
	Regression: Introduction, univar	iate linear reg	ression, multivariate l	linear regression,
regular	ized regression			
		UNIT-II		
	vised Learning – II			15 Hours
-	c regression: classification, Artific			
	cation: Introduction, Decision Tre		•	-
model,	Bayesian Learning, Introduction		rkov Models and deep	p learning
	· · · ·	UNIT-III		
	ervised Learning			05 Hours
Combi	ing: Introduction, K-means, I ning Learners Evaluation Measu			
	lypothesis Testing,			
	ning Learners			05 Hours
-	Bagging, Boosting			
—	• Outcomes: At the end of the co			
	Develop an appreciation for wha			
	Demonstrate the application of li problems	_		on for real world
	Design and implement algorithm	•		
4.	Construct basic unsupervised l	learning algo	rithms and evaluate	the generated

						Curr	iculu	m – 1	B.Te	ch. (F	Robotic	cs & Ai	rtificial	Intelli	igenece	e): 202
5.	Identify and apply Mach	nine	Lea	rnin	g al	gori	thm	is to	sol	ve r	eal w	vorld	prot	olem	S	
Cours	e Outcomes Mapping v	vith	Pro	ogra	m C	Duto	om	es 8	<u> </u>	50	1	Т	T	1		
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO (r
↓ Co	urse Outcomes													1	2	3
	RI2223-1.1	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2223-1.2	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2223-1.3	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2223-1.4	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	RI2223-1.5	3	3	2	2	2	-	-	-	-	-	-	2	2	-	2
	1: Low 2: Medium 3:	Hi	gh													
TEXTE	BOOKS:															
1.	C. M. Bishop, Pattern Re	eco	gniti	on a	and	Mac	hin	e Le	arni	ng,	Sprii	nger,	2006	6		
2.	Ethem Alpaydin, Introd	ucti	on t	o M	achi	ne l	ear	ning	g, Se	cor	nd Ed	lition	, 200)4		
REFER	RENCE BOOKS:															
1.	T. M. Mitchell, "Machine															
2.	R. O. Duda, P. E. Hart ar	nd D). G.	Sto	rk Pa	atte	rn C	lass	ifica	tior	n, Wi	ley P	ublic	atior	าร, 20)01
3.	T. Hastie, R. Tibshirani, .	J. Fr	iedn	nan.	The	e Ele	mei	nts d	of St	atis	tical	Lear	ning,	, 2e,	2008	•
4.	P. Flach, "Machine Lea		0				scie	nce	of	algo	orithr	ns th	nat m	nake	sens	e of
	data", Cambridge Unive															
5.	K. P. Murphy, "Machine															
6.	M. Mohri, A. Rostamiza	deh	, and	d A.	Talw	alka	ar, "I	Fou	ndat	tion	s of I	Mach	nine L	earn	ing",	MIT
	Press, 2012.															
7.	S. Russel and P. Norvig	g, "A	٩rtifi	icial	Inte	ellige	ence	e: A	Мо	der	n Ap	proa	ich",	Thire	d Edi	tion,
	Prentice Hall, 2009.															
	ks / MOOCs/ NPTEL	-														
1.	https://onlinecourses.n									<u> </u>		<u> </u>				
2.	https://www.coursera.o	rg/l	ectu	ire/a	Igo	rithr	ns-l	oart	1/ar	naly	sis-o	t-alg	orith	ms-		
	introduction-xaxyP								•.•							
3.	Virtual Lab link- https://									ms/	/virtu	ial-la	b			
4.	https://www.aziksa.com	n/alg	gorit	thms	s-de	sigr	n-an	alys	sis							



Со	urse Code:	RI2224-1	Course Type	PEC
Tea	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	tal Teaching Hours	40	CIE + SEE Marks	50+50
	erequisite	CS1001-1, I		
	Teaching Department			۵
Cou	rse Objectives:			C
1.	To describe the role of inform	ation technol	ogy and decision supp	ort systems in
	business and record the current			
	problems.			
2.	To introduce the fundamental	principles of	computer-based inforr	nation systems
	analysis and design and develo		•	•
	used.		5 1 1	·
3.	To provide the theoretical mode	els used in dat	abase management sys	tems to
	answer business questions			
4.	To enable students, understand	the various kr	nowledge representatio	n methods and
	different expert system structure	es as strategic	weapons to counter the	e threats to
	business and make business mc	ore competitive	2.	
5.	To enable the students to use i	nformation to	assess the impact of the	ne Internet and
	Internet technology on electron	ic commerce a	nd electronic business a	and understand
	the specific threats and vulneral	pilities of com	outer systems.	
		UNIT-I		
ntro	oduction			07 Hour
	a, Information, Intelligence, Informa		.,	
	ed on functions and hierarchy,	-	•	gies, Functiona
	rmation Systems, DSS, EIS, KMS, G	IS, Internation	al Information System.	
	em Analysis and Design			09 Hour
	e tools - System flow chart, Decisic			tity Relationshi
ER),	Object Oriented Analysis and Des	lign (OOAD), L	JML diagram.	
	abasa Managamant Systems	UNIT-II		07 Hour
1-+-	abase Management Systems		Juany Processing SO	
BN	1S HDBMS, NDBMS, RDBMS,		zuciy riocessing, SQ	L, Concurrent
9BN ∕Ian	agement, Data warehousing and I			
DBN ∕Ian S ecu	agement, Data warehousing and I urity, Control and Reporting	Data Mart.		07 Hour
DBM /lan ecu	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont	Data Mart. rols, IS Vulnera	ability, Disaster Manage	07 Hour ment, Compute
)BN /lan ecu ecu	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont nes, Securing the Web, Intranets an	Data Mart. rols, IS Vulnera	ability, Disaster Manage	07 Hour ment, Compute
)BN /lan ecu ecu	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont	Data Mart. rols, IS Vulnera d Wireless Ne	ability, Disaster Manage	07 Hour ment, Compute
DBM Man Secu Secu Crim	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont nes, Securing the Web, Intranets an rface and reporting	Data Mart. rols, IS Vulnera	ability, Disaster Manage	07 Hour ment, Compute Ethics in IT, Use
DBN Aan Secu Secu Crim	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont nes, Securing the Web, Intranets an rface and reporting v IT Initiatives	Data Mart. rols, IS Vulnera d Wireless Ne UNIT-III	ability, Disaster Manage tworks, Software Audit,	07 Hour ment, Compute Ethics in IT, Use 10 Hour
DBN Jan Jecu Crim Inter	agement, Data warehousing and E urity, Control and Reporting urity, Testing, Error detection, Cont nes, Securing the Web, Intranets an rface and reporting	Data Mart. rols, IS Vulnera Id Wireless Ne UNIT-III RP, e- busines	ability, Disaster Manage tworks, Software Audit, s, e-governance, Data I	07 Hour ment, Compute Ethics in IT, Use 10 Hour

Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

$\overline{\mathbb{O}}$		ned to be University)					Cu	rricu	lum	– B.7	Гесh.	(Robo	tics &	Artific	ial Inte	elligen	ece): 202
	1.	Relate the basic concepinformation systems.	pts a	and	tecł	nnol	ogie	es u	sed	in t	he f	ield	of m	anag	eme	nt	
	•	· · · · · · · · · · · · · · · · · · ·	(.1.		• • •						••••		<u></u>	1.		
-	2.	Compare the processes of developing and implementing information systems.															
	3.	Apply the understanding of how various information system like DBMS work															
		together to accomplish the information objectives of an organization.															
4	4.	Outline the role of the	ethi	ical,	soc	ial a	nd s	secu	urity	issu	Jes	of in	form	atior	n sys	tem.	
	5.	Translate the role of in	forn	nati	on s	yste	ms	in o	rga	niza	tior	n, the	stra	tegic	mai	nage	ment
		Translate the role of information systems in organization, the strategic management process, with the implementation for the management.															
									<u> </u>								
С	ours	se Outcomes Mapping	wit	h Pı	rogi	am	Ou	tco	mes	8	PSC)					
		Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
	↓ C	ourse Outcomes															
		RI2224-1.1	3	2	1	-	-	-	-	-	-	-	-	1	-	-	3
		RI2224-1.2	3	2	1	-	-	-	-	-	-	-	-	1	-	-	3
		RI2224-1.3	3	2	1	-	-	-	-	-	-	-	-	1	-	-	3
		RI2224-1.4	3	2	1	-	-	-	-	-	-	-	-	1	-	-	3
		RI2224-1.5	3	2	1	-	-	-	-	-	-	-	-	1	-	-	3

1: Low 2: Medium 3: High

TEXTBOOKS: 1. Robert Schultheis and Mary Summer, Management Information Systems - The Managers View, Tata McGraw Hill, 2008 Kenneth C. Laudon and Jane Price Laudon, Management Information Systems -2. Managing the digital firm, PHI Learning / Pearson Education, PHI, Asia, 2012

3.

REFERENCE BOOKS:

1.	Gordon Davis, Management Information System: Conceptual Foundations, Structure
	and Development, Tata McGraw Hill, 21st Reprint 2008
2.	Haag, Cummings and Mc Cubbrey, Management Information Systems for the
	Information Age, McGraw Hill, 2005, 9th edition, 2013
3.	Raymond McLeod and Jr. George P. Schell, Management Information Systems,
	Pearson Education, 2007
4.	James O Brien, Management Information Systems – Managing Information
	Technology in the E- business enterprise, Tata McGraw Hill, 2004
5.	Raplh Stair and George Reynolds, Information Systems, Cengage Learning, 10th
	Edition, 2012
6.	Frederick, Gallegor, Sandra, Senft, Daniel P. Manson and Carol Gonzales, Information
	Technology Control and Audit, Auerbach Publications, 4th Edition, 2013



(De	eemed to be University)	GR	OUP-II	
	Auto	nomous Ve	hicles	
Cοι	ırse Code:	RI2321-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite		, IS 1001-1, EC 1001-1	
		: Robotics an	d Artificial Intelligenc	e
	rse Objectives:			
1.	Introduce the fundamental aspe			ad in
2.	Gain Knowledge about the Sens Autonomous vehicles.	ang rechnolog	gy and Algorithms appli	ed in
3.	Understand the fundamentals o	f car technolo	av	
<u> </u>	Understand the Connectivity As		*/	rless cars
5.	Understand the aspects related			
2.	Autonomous Vehicles	to compate		.9.01
		UNIT-I		
Intro	oduction			07 Hours
Evolu	ution of Automotive Electronics -I	Basic Control S	System Theory applied	to Automobiles
Over	view of the Operation of ECUs -In	fotainment, Bo	ody, Chassis, and Power	rain Electronics
Adva	anced Driver Assistance Systems-A	utonomous V	'ehicles.	
Sens	or Technology for Autonomous	Vehicles		09 Hours
Basic	cs of Radar Technology and	Systems -Ult	rasonic Sonar System	s-LIDAR Senso
Tech	nology and Systems -Camera Tech	nnology -Nigh	t Vision Technology -Us	e of Sensor Dat
Fusic	on-Kalman Filters.			
		UNIT-II		
	nected Car Technology			07 Hours
	nectivity Fundamentals -DSRC (Dir			
	nology and Applications -\	/ehicle-to-Roa	idside and Vehicle-	to-Infrastructur
	ications -Security Issues.			
	onomous Vehicle Technology			07 Hours
	erless Car Technology-Different Le			5
	rollers to Actuate a Vehicle -PID C	Controllers - Mo	odel Predictive Controll	ers, ROS
Fram	nework.			
_		UNIT-III		
	puter Vision and Deep Learning			05 Hours
	puter Vision Fundamentals -Adva	anced Compu	ter Vision -Neural Net	works for Imag
	essing			
	onomous Vehicles' Biggest Chall			05 Hours
Tech	nical Issues, Security Issues, Mora	and Legal Iss	ues.	
	rse Outcomes: At the end of the c			
1.	Explain the evolution of Automo		cs and the operation of	ECUS.
2.	Compare the different type of so Vehicles.	ensing mecha		omous

(Deem	ITTE net to be University)												Artific			ece): 2
•	Identify the different le															
•	Discuss about the use	of c	omp	oute	er vis	sion	in v	ehi	cles	alo	ng w	ith it	s cha	lleng	ges.	
ours	e Outcomes Mapping	wit	h P	rog	ram	Ou	tco	mes	s &	PSC)		•			
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	ŀ
↓ C	ourse Outcomes															
	RI2321-1.1	2	2	2	2	3	-	-	-	-	-	-	3	2	2	2
	RI2321-1.2	2	2	2	2	3	-	-	-	-	-	-	3	2	2	2
	RI2321-1.3	2	2	2	2	3	-	-	-	-	-	-	3	2	2	2
	RI2321-1.4	2	2	2	2	3	-	-	-	-	-	-	3	2	2	2
	RI2321-1.5	2	2	2	2	3	-	-	-	-	-	-	3	2	2	2
	1: Low 2: Medium	3: H	igh		•	•				•	•			•		
ХТ	BOOKS:															
1.	Autonomous Intellige Cheng Springer, 2011	nt V	'ehio	cles:	The	eory,	Alg	gori	thm	s an	d Im	plen	nenta	ation	, Hor	ng
2.		otiv	/e El	lectr	oni	cs, V	Villia	ams	. B.	Ribb	oens,	Else	vier I	nc 7	th Ed	ln.
3.	Creating Autonomous Publishers	Vel	hicle	e Sys	sten	ns, S	hac	sha	n Li	u, Li	yun	Li, M	orga	n an	d Cla	уро
FEF	RENCE BOOKS:															
1.	Autonomous Driving: Christian Gerde, Spring				.ega	lan	d Sc	ocial	Asp	bect	s , M	arcu	s Ma	urer,	J.	
2.	Autonomous Vehicles	for	Safe	er D	rivir	ng, R	lona	ald.	K. Ju	urge	n, SA	AE In	terna	tion	al, 20)13
3.	Autonomous Vehicle KalraNidhi, Karlyn Sta						de	for	Poli	cym	aker	s, Jai	mes	Ande	ersor	١,
Boo	oks / MOOCs/ NPTEL															
1.	https://www.coursera.	org	/spe	ecial	izati	ons	/sel	f-dr	ivin	g-ca	ar <u>s</u>					
2.	https://www.udacity.co ud0419									<u> </u>		tals-f	eatu	ring-	apol	<u>lo</u>
	440111															

3. https://waymo.com/

(Deemed to be University) Basics of Nat	ural Langu	age Processing	
Course Code:	RI2322-1	Course Type	PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CS1001-1		
	t: Robotics an	nd Artificial Intelligenc	e
Course Objectives:			
1. To learn the fundamentals of na		, <u>,</u>	
2. To understand the use of CFG a			
3. To understand the role of sema			
4. To apply the NLP techniques to		IS	
Introduction to NUD and Oromian a	UNIT-I		07.110
Introduction to NLP and Overview a			07 Hours
Overview: Origins and challenges c Languages- NLP Applications Informa	-	-	-
based Language	tion Retrieval.	Language wouldning. Va	
Models-Statistical Language Model:	•		09 Hours
Word Level Analysis Unsmoothed N-		ting N-grams Smoothi	
and Backoff – Word Classes, Par	-		•
Transformation-based tagging, Issue	•	00 0	
Entropy models.	5 65 ta.g	gg	
	UNIT-II		
Programming Parsing			08 Hours
Programming parsing – Shallow parsi	ng – Probabil	istic CFG, Probabilistic C	YK, Probabilistic
Lexicalized CFGs – Feature structures,	Unification of	feature structures;	
Mining Diagnostic Text Reports by Lea	arning to Anno	otate Knowledge Roles:	
Introduction, Domain Knowledge and	Knowledge Ro	oles, Frame Semantics ar	nd Semantic Role
Labelling, Learning to Annotate Cases	with Knowled	ge Roles and Evaluatior	
Discourse Analysis and Lexical Reso			08 Hours
Discourse segmentation, Coherence –		•	solution using
Hobbs and Cantering Algorithm – Co-			
Extracting Relations from Text: From V			
Subsequence Kernels for Relation Extr	•	endency-Path Kernel for	Relation
Extraction and Experimental Evaluation			
Evaluating Solf Evaluations in iSTA	UNIT-III		08 Hours
Evaluating Self-Explanations in iSTA Word Matching, Latent Semantic Anal		c Models:	
Introduction, iSTART: Feedback System			stems
Textual Signatures: Identifying Text-T			
Cohesion of Text Structures:	JPCS Comy L		
Introduction, Cohesion, Coh-Metrix,	Approaches	to Analysing Texts. I	atent Semantic
Analysis, Predictions, Results of Experi		<u> </u>	
Automatic Document Separation: A C			tion and Finita
		of Probabilistic Classifica	ation and Finite
State Sequence Modeling:		of Probabilistic Classifica	
-			



Evolving Explanatory Novel Patterns for Semantically-Based Text Mining: Related Work, A Semantically Guided Model for Effective Text Mining.

Cour	se Outcomes: At the end of the course student will be able to
1.	Tag a given text with basic Language features
2.	design an innovative application using NLP components
3.	implement a rule based system to tackle morphology/syntax of a language
4.	design a tag set to be used for statistical processing for real-time applications
5.	compare and contrast the use of different statistical approaches for different types
	of NLP applications

Course Outcomes Mapping with Program Outcomes & PSO

			-9					~							
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	°SO \	\checkmark
↓ Course Outcomes													1	2	3
RI2322-1.1	2	1	-	-	-	-	1	1	-	-	-	2	1	2	2
RI2322-1.2	2	2	-	-	-	-	1	1	-	-	-	1	1	2	2
RI2322-1.3	2	3	-	-	-	-	-	-	-	-	-	2	-	2	2
RI2322-1.4	1	1	-	-	-	-	1	1	-	-	-	1	-	2	2
RI2322-1.5	2	2	-	-	-	-	1	-	-	_	_	1	-	2	2
1		. 1.													

1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** Speech and Language Processing: An Introduction to Natural Language Processing, Computational Linguistics and Speech Daniel Jurafsky, James H. Martin, Pearson Publication, 2nd Edition., 2014.
- **2.** Natural Language Processing and Text Mining, Anne Kao and Stephen R. Poteet (Eds), Springer-Verlag London Limited, 1st Edition.,2007
- **3.** Handbook of Natural Language Processing, Breck Baldwin, Chapman and Hall/CRC Press, 2nd Edition., 2010

REFERENCE BOOKS:

- **1.** Natural Language Processing and Information Retrieval, Tanveer Siddiqui, U.S Tiwary, Oxford University Press, 2nd Edition., 2008
- **2.** Natural Language Understanding, James Allen, Benjamin/Cummings publishing company, 2nd edition.,1995.

E Books / MOOCs/ NPTEL https://nptel.ac.in/courses/106/105/106105158/ https://www.udemy.com/course/nlp-natural-language-processing-with-python/ https://www.udemy.com/course/data-science-natural-language-processing-in-python/ https://www.udemy.com/course/natural-language-processing/ https://www.udemy.com/course/natural-language-processing/ https://www.udemy.com/course/natural-language-processing/

1. <u>https://onlinecourses.nptel.ac.in/noc19_cs56/preview</u>

	Bu	siness Analy	/tics	
Cοι	ırse Code:	RI2323-1	Course Type	PEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
	requisite	MA 1001-1	, MA 1003-1	
		t: Robotics an	d Artificial Intelligence	9
Coui	rse Objectives:		-	
1.	To gain an understanding of ho	w managers u	se business analytics	
2.	to formulate and solve busines	s problems an	d to support managerial	l decision
	making.			
3.	To become familiar with the pro	ocesses needed	d to develop, report, and	d analyse
	business data.			
4.	To learn how to use and apply I		add-ins to solve busine	ess problems.
		UNIT-I		
	criptive Statistics	II I		07 Hour
	ning, Scope, types, functions and			
	an,Median, Mode, Quartiles, Mea	•	•	-
	ation, Standard deviation, Varianc	e, Coefficient d	of Variation, Skew-ness a	
	e Series & Index Number			09 Hou
		1 8 4 1.1 11		
	series analysis: Concept, Additive		•	
Fren	d analysis: Least Square method		•	
Tren	-		•	
Fren	d analysis: Least Square method	- Linear and	•	
Fren ousir	d analysis: Least Square method ness decision-making.		•	Applications
Tren ousin Corr	d analysis: Least Square method ness decision-making. elation & Regression Analysis	- Linear and UNIT-II	Non- Linear equations,	Applications Applications Image: state stat
Tren ousir Corr	d analysis: Least Square method ness decision-making. elation & Regression Analysis elation Analysis: Rank Method & K	- Linear and UNIT-II (arl Pearson's (Non- Linear equations,	Applications Applications 16 Hour and Propertie
Tren ousin Corr Corr of Co	d analysis: Least Square method ness decision-making. elation & Regression Analysis elation Analysis: Rank Method & k prrelation. Regression Analysis: Fit	- Linear and UNIT-II Karl Pearson's C ting of a Regre	Non- Linear equations, Coefficient of Correlation	Applications 16 Hour n and Propertie ation of Result
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N NITTE

5.

Explain the practical application of Descriptive and Inferential Statistics concepts and their uses for Business Analytics.

Cours	e Outcomes Mapping v	vith	Pro	ogra	m C	Duto	om	es 8	ያ ይ	50						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	F	SO	\downarrow
↓ Cοι	urse Outcomes													1	2	3
	RI2323-1.1	З	3	-				-	-			2	1	-		
	RI2323-1.2	З	3	-				-	-			2	1	-		
	RI2323-1.3	З	3	-				-	-			2	1	-		
	RI2323-1.4	3	3	-				-	-			2	1	-		
	RI2323-1.5	3	3	-				-	-			2	1	-		
	1: Low 2: Medium 3:	Hi	gh													
TEXTE	BOOKS:															
1.	Business Statistics, G C	Beri	i, TA	TAN	ИcG	raw	Hill,	3rc								
2.	Statistics for Managers,	Ch	andı	rase	kara	n 8	κ PΗ	II Le	arni	ing,	1st e	ditic	n.,20)16		
3.	Staistical techniques in	bus	ines	s an	d eo	cond	omi	cs, L	ind,	Ma	rchal	,, Wa	ather	n, Mo	Gra	W
	Hill, 18th ed., Jan 2020															
REFER	ENCE BOOKS:															
1.	Statistics for Business a	nd l	Ecor	nom	ics, l	New	bol	d, C	arls	on,F	ears	on, 6	th ea	d.,20	13	
E Boo	ks / MOOCs/ NPTEL															
1.	https://nptel.ac.in/cour	ses/	110,	/105	5/11	010	508	9/								
2.	https://www.udemy.com	n/c	ours	e/ap	oplie	ed-b	ousir	ness	-ana	alyti	cs/					
3.	https://www.coursera.o	rg/s	spec	ializ	atio	ns/b	busir	ness	-an	alyti	ics					



University Core Courses (UCC)



INTERNSHIP-I

Course Code	UC1001-2	CIE Marks	100	
Teaching Hours/Week (L: T: P: S)	-	-		
			100	
			(Evaluation in	
	80-90 Hours		I/II/III Semester	
Total Hours of Pedagogy	(During I/II	Total Marks	and grades earned	
	semesters)		shall be included in	
			IV Semester grade	
			card)	
Credits	2	Exam Hours		

Course objective

 This course is meant to provide students an opportunity to be involved in Inter/ Intra Institutional Activities viz; Training with higher Institutions; Soft skill training organized by Training and Placement Cell of the institution; contribution at incubation/ innovation /entrepreneurship cell of the institution; participation in conferences/ workshops/ competitions etc.; Learning at Departmental Lab/ Tinkering Lab/ Institutional workshop; Working for consultancy/ research projects within the institution and Participation in all the activities of Institute's Innovation Council.

Activities: Refer Appendix B - 3.4 for details

Course outcomes

- **1.** Experience the working in Inter / Institutional activities
- 2. Work in teams and communicate efficiently both written and oral.
- **3.** Develop the ability to do work in different activities, which will provide the necessary understanding and contribute to the same and provide a foundation to undergo higher level training in subsequent internships.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	2	4	г	G	7	8	a	10	11	12	P	SO	Ų
↓ Course Outcomes	T	2	3	4	כ	ю	/	ð	פ	10	TT	12	1	2	3
UC2001-1.1	3	1	-	-	1	-	-	-	2	3	1	-	-	-	-
UC2001-1.2	3	1	-	-	1	1	-	1	2	3	1	-	1	1	-
UC2001-1.3	3	1	-	-	1	-	-	-	2	3	1	-	-	-	-
1: Low 2: Medium 3: Hig	Jh														



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Cour	rse Code:				U	C20	01	2	C	our	se Ty	/pe:					UCC
Teac	hing Hours/Week (L: T: P:	S):					-		С	red	its:						08
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Cours	e Objectives:																
cours	This course is meant to p	rovi	do	ctu	don	tc a	n a	/oni		· 0 11	ndor	ctand	t tha	wo	rk o	nvirc	nmon
1.	ethics and practices in an																
	ethics and practices in an	mut	JSU.	y/01	yai	ΠZa	tion	and	i la	KE (ip as	sigili	nent	5/]01	05 11	i the	Tuture
Cours	e Outcomes: At the end of	the		urse	e stu	ıdeı	nt w	ill b	e a	ble	to						
1.												that	is ass	sign	ed to	o the	em.
	Analyse and develop technical solutions for a specific problem that is assigned to them. Communicate ideas that are developed through brainstorming, presentation and prepare a																
2.	report.			'			5				-	// I				•	•
3.	Understand and inculcate	ind	ustr	y pi	ract	ices	in t	hei	r pr	ofes	ssion	al ca	reer.				
				2													
Cours	e Outcomes Mapping wit	h Pr	rog	ram	1 O I	itco	me	s &	PS	ο							
	Program Outcomes→		_	_		_	_		_	_					PS	0 ↓	
	↓ Course Outcomes	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
	UC2001-1.1	3	2	-	-	1	1	-	-	2	3	1	-	1	1	1	
	UC2001-1.2	3	2	-	-	1	1	-	-	2	3	1	-	1	1	1	
	UC2001-1.3	3	2	-	-	1	1	-	-	2	3	1	-	1	1	1	
1: Lov	v 2: Medium 3: High										•		•				



N	IAJOR PROJE	СТ	
Course Code:	UC2002-2 & UC3001-2	Course Type:	UCC
Teaching Hours/Week (L: T: P: S):	24	Credits:	2+8
Total Teaching Hours:	-	CIE + SEE Marks:	(100+0) + 100+100

Course Objectives:

1	To perform effective literature survey, identification of research problem / project
1.	idea.
2.	To develop skills of planning to execute the project
3.	To assess the needs and necessity of a project.
4.	To learn time management and documentation.
-	To expose the students to research aspects like literature review, executing
5.	experiments and analysis of results.
6	To expose the students to research aspects like literature review, executing
6.	experiments and analysis of results.

A group of students (not more than 4) is assigned to a guide/project supervisor. The students must do a thorough literature review and come out with a project plan. They are expected submit a project proposal (not more than 10 pages) including project idea, protocols, designs (if any), expected outcome, major requirements, and approximate budget. They shall present the same in a proposal seminar in front of the panel of internal examiners (involving guide) and shall get their proposal approved. The presentation must involve projected timeline of the project execution.

Assessment Details (both CIE and SEE)

CIE procedure: Shall involve project proposal, proposal seminar, continuous evaluation of the project progress by Guide and HOD. Monthly progress is evaluated.

Semester End Examination:

SEE procedure:

i)Single discipline: Contribution to the project and the performance of each group member shall be assessed individually in semester end examination (SEE) conducted at the department.

ii) Interdisciplinary: Contribution to the project and the performance of each group member shall be assessed individually in semester end examination (SEE) conducted separately at the departments to which the student/s belong to.

SCHEME OF EVALUATION:

Project demonstration, Viva voce

Total marks: 100 Marks

The distribution of marks shall be proportioned based on the type of the project and it is based on fulfilling the following requisites.

The evaluation of students is proposed to be done by internal faculty with active involvement of industrial personnel. The evaluation may be based on following criteria:

- Punctuality and Attendance "Interpersonal relations
- Sense of Responsibility



- Clarity of concepts, principles and procedures
- Self-expression/communication skills
- Report Writing Skills
- Creativity/conceiving new and unusual ideas
- Problem-solving skills

At the end of the project work course students are required to submit a working model of the equipment they have designed and developed or if it is a theoretical or experimental work, they are expected to study a detailed analysis and findings from their work.

Course Outcomes: At the end of the course student will be able to

- **1.** Use various methods or sources for finding literature and analyze data for relevance and appropriateness to the research project undertaken.
- **2.** Identify and propose suitable methods of analysis and/or design or develop appropriate experiments to address the specific research objectives.
- **3.** Apply suitable standardized method/s for experimental design.
- **4.** Analyze and interpret the research findings and compare with reported results to arrive at suitable conclusions.
- **5.** Adopt appropriate documentation protocol to organize research findings, learn good laboratory practices and work in a team.

Program Outcomes→	_				_		_	_	_					PS	SO ↓
↓ Course Outcomes	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
UC2002-1/UC3001-1.1	-	1	-	-	2	2	3	1	-	-	-	1	1	2	2
UC2002-1/UC3001-1.2	-	1	2	1	1	-	1	2	1	-	1	1	1	2	2
UC2002-1/UC3001-1.3	-	1	2	2	1	-	1	1	1	1	1	1	1	2	2
UC2002-1/UC3001-1.4	1	3	2	2	1	2	2	3	3	3	3	2	1	2	2
UC2002-1/UC3001-1.5	-	1	1	-	1	2	2	3	3	3	3	1	1	2	2

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Open Elective Course [OEC]



(De		nous Mobile	Robots	
Cou	ırse Code:	RI2501-1	Course Type	OEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
	requisite	EC 1001-1, N	ИЕ 1003-1	
	Teaching Department:	Robotics and	Artificial Intelligenc	е
Cour	se Objectives:			
1.	Explain different types of locom	otion in mobil	e robots to obtain a re	equired task.
2.	Understand the different types	of kinematics	and dynamics involv	red in a mobile
	robot.			
3.	Study the different types of sense			
4.	Understand the different types robot.	of algorithms	to identify the positio	n of the mobile
5.	Understand the various algorith	ms for plannin	g and navigation of th	e mobile robot.
		UNIT-I		
Robo	ot locomotion:			07 Hours
• •	s of locomotion, hopping ro euverability, and controllability.	bots, legged	robots, wheeled r	obots, stability
	ile robot kinematics and dynam	ics:		09 Hours
	ard and inverse kinematics, holono		olonomic constraints, k	inematic models
	nple car and legged robots, dynan			
		UNIT-II		
Perc	eption:			07 Hours
Prop	rioceptive/Exteroceptive and passi	ive/active sense	ors, performance mea	sures of sensors,
senso	ors for mobile robots like global po	sitioning syste	m (GPS), Doppler effec	t-based sensors
visio	n-based sensors, uncertainty in ser	nsing, filtering.		1
	lization:			07 Hours
	metric position estimation, beli ization, Bayesian localization, Kalm	•	•	
		UNIT-III		
	duction to planning and naviga			10 Hours
	planning algorithms based on A-st	-	•	•
	1), rapidly exploring random trees	(RRT), Markov	Decision Processes (MDP), stochastic
dyna	mic programming (SDP).			
Cour	rse Outcomes: At the end of the c	ourse student	will be able to	
1.	Explain different types of locom	otion in mobil	e robots to obtain a re	quired task.
2.	Identify the different types of ki			
3.	Apply the different types of sense			
4.	Apply the different types of algo			
5.	Apply the various algorithms for reach the destination.			
L				

Cours	se Outcomes Mapping	wit	h Pı	rogi	ram	Ou	tco	mes	s &	PSC)					
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ C	Course Outcomes															
	RI2501-1.1	3	3	3	3	2	1	-	-	-	-	-	3	3	2	3
	RI2501-1.2	3	3	3	3	2	1	-	-	-	-	-	3	3	2	3
	RI2501-1.3	3	3	3	3	2	1	-	-	-	-	-	3	3	2	3
	RI2501-1.4	3	3	3	3	2	1	-	-	-	-	-	3	3	2	3
	RI2501-1.5	3	3	3	3	2	1	-	-	-	-	-	3	3	2	3
	1: Low 2: Medium	3: H	igh													
TEXT	BOOKS:															
1.	R. Siegwart, I. R. Nourl	bakł	nsh,	"Int	rod	uctio	on t	o Ai	utor	nom	ous	Mob	ile Ro	obot	s", Tl	ne MIT
	Press, 2011.															
2.	Peter Corke, Robotic	s, V	'isio	n ar	nd	Con	trol	: Fu	Inda	me	ntal	Algo	orithr	ns ir	n M	ATLAB,
	Springer Tracts in Adv	anc	ed F	Robo	otics	, 20	11.									
3.	S. M. LaValle, "Planni	ng	Algo	orith	ms'	, Ca	amb	orido	ge l	Jniv	ersity	y Pre	ess, 2	2006.	(Av	ailable
	online http://planning	.cs.u	uiuc.	.edu	/)											
REFE	RENCE BOOKS:															
1.	Thrun, S., Burgard, W., 2005.	and	d Fo	x, D	., Pr	oba	bilis	stic	Rob	otic	s. M	T Pro	ess, C	Camb	oridg	e, MA,
2.	Melgar, E. R., Diez, C. C 2012.	., A	rdui	no, a	and	Kin	ect	Proj	ects	: De	sign	, Buil	d, Blo	ow T	heir	Minds,
3.	H. Choset, K. M. Lynch,	S. H	lutc	hins	son,	G. K	ant	or, \	N. B	urga	ard, I	E. k	Cavra	ki, ar	nd S.	Thrun,
	Principles of Robot Me															
E Boo	oks / MOOCs/ NPTEL															
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1.	https://archive.nptel.a	C.III/	cou	11262	»/ ТТ	Z/ I(10/1	. 1 2 1	1062	298/						

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(Deemed to be University)	edical I	Roboti	CS				
Course Code:	RI250	2-1	Cou	rse Ty	/pe		PEC
Teaching Hours/Week (L: T: P: S)	3:0:0:	0	Crea	dits			03
Total Teaching Hours	40		CIE	+ SEE	Mark	s	50+50
Prerequisite	PH 10	01-1, IS	5 100	1-1, (CY 100	1-1	
Teaching Department	: Robot	ics and	Artif	icial I	ntellig	ence	
Course Objectives:							
1. Understand the types of medica	l robots	used in	the f	ield o	f healt	hcare.	
2. Explain the various localization a	and tracl	king ser	sors				
3. Understand the applications of s	surgical	robots v	with t	he he	lp of fe	ew case	e studies
4. Understand Rehabilitation of lim case studies	ibs and	brain m	achin	ie inte	rface v	vith th	e help of few
5. Understand the design methodo	ology of	medica	l robo	ots.			
	UNI						
Introduction							07 Hours
Types of medical robots - Navigation	- Motic	n Repli	catior	n - Im	aging	- Reha	abilitation and
Prosthetics - State of art of robotics in		•					
Position sensors requirements							09 Hours
Tracking - Mechanical linkages - Optica	l - Soun	d-basec	l - Ele	ctrom	agneti	c -Imp	edance-based
- In-bore MRI tracking - Video matchin	ig - Fibe	r optic	tracki	ng			
	UNI	T-II					
Control Modes Radiosurgery							07 Hours
Orthopedic Surgery - Urologic Sur	gery ar	nd Rob	otic	Imagi	ing -	Cardi	ac Surgery –
Neurosurgery – case studies.							
Rehabilitation							07 Hours
Rehabilitation for Limbs - Brain-Machir	ne Interf	aces - S	teera	ble N	eedles	– case	studies.
	UNI	Γ-III					
Design of Medical Robots							10 Hours
Characterization of gestures to the des	sign of r	obots-	Desig	n met	hodol	ogies-	Technological
choices - Security							
	_		••••				
Course Outcomes: At the end of the c							
1. Describe the types of medical ro	bots an	d the co	oncep	its of I	navigat	tion ar	nd motion
replication.							
2. Describe about the sensors used			n and	tracki	ng		
3. Explain the applications of surging the second				•		• . •	_
4. Explain the concepts in Rehabilit							
5. Classify the types of assistive rol		,				acteris	tics,
methodology and technological	choices	tor me	dical	robot	S.		
			-				
Course Outcomes Mapping with Pro						<u>т, т</u>	1
Program Outcomes123 \downarrow Course Outcomes123	3 4 5	6 7	8	9 1	0 11	12	PSO↓

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RI2502-1.1 3 - 1 - - - - 1 3 - RI2502-1.2 3 - 1 - - - - - 1 3 - RI2502-1.3 3 - 1 - - - - - 1 3 - RI2502-1.4 3 - 1 - - - - - 1 3 - RI2502-1.5 3 - 1 - - - - - 1 3 - RI2502-1.5 3 - 3 - - - - - 1 3 - I: Low 2: Medium 3: High - - - - - - - 1 3 - I: Low 2: Medium 3: High - - - - - - - 1 3 - I: Low 2: Medium 3: High - - - - - - - 1 3	3 3
RI2502-1.2 0 1 - - - - 1 3 RI2502-1.3 3 - 1 - - - - 1 3 - RI2502-1.4 3 - 1 - - - - 1 3 - RI2502-1.5 3 - 1 - - - - 1 3 - RI2502-1.5 3 - 3 - - - - 1 3 - I: Low 2: Medium 3: High - - - - - - 1 3 - TEXTBOOKS: - - - - - - 1 3 - I. Robot Modeling and Control, Mark W. Spong, Seth Hutchinson, and M. Vidyasag Wiley Publishers, 2006 - - - - - - - - - 1 3 - 2. Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012 - - - - - - <th< th=""><th></th></th<>	
RI2502-1.4 3 - 1 - - - - 1 3 - RI2502-1.5 3 - 3 - - - - 1 3 - RI2502-1.5 3 - 3 - - - - 1 3 - I: Low 2: Medium 3: High - - - - - 1 3 - TEXTBOOKS: - - - - - - 1 3 - Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012	3
RI2502-1.5 3 - - - - 1 3 I: Low 2: Medium 3: High TEXTBOOKS: I. Robot Modeling and Control, Mark W. Spong, Seth Hutchinson, and M. Vidyasag Wiley Publishers, 2006 Viley Publishers, 2006 2. Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012	9
1: Low 2: Medium 3: High TEXTBOOKS: 1. Robot Modeling and Control, Mark W. Spong, Seth Hutchinson, and M. Vidyasag Wiley Publishers, 2006 2. Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012	3
 TEXTBOOKS: 1. Robot Modeling and Control, Mark W. Spong, Seth Hutchinson, and M. Vidyasag Wiley Publishers, 2006 2. Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012 	3
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 Robot Modeling and Control, Mark W. Spong, Seth Hutchinson, and M. Vidyasag Wiley Publishers, 2006 Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012 	
Wiley Publishers, 20062.Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012	
2. Medical robotics- Minimally, Invasive surgery, Paula Gomes, Woodhead, 2012	jar,
3. Medical Robotics, Achim Schweikard, Floris Ernst, Springer, 2015	
REFERENCE BOOKS:	
1. Medical Robotics, Jocelyne Troccaz, Wiley-ISTE, 2012	
2. Medical Robotics, Vanja Bonzovic, I-tech Education publishing Austria, 2008	
3. Medical Robotics, Daniel Faust, Rosen Publishers, 2016	
4. Medical Robotics, Jocelyne Troccaz, Wiley, 2013	
E Books / MOOCs/ NPTEL	
1. https://www.futurelearn.com/courses/medtech-ai-and-medical-robots	
2. https://web.stanford.edu/class/me328/	

2. https://web.stanford.edu/class/me328/

PLC Control of Hyd	draulic and	Pneumatic Circuits	
Course Code:	RI2503-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EE 1001-1		
Teaching Department:	Robotics an	d Artificial Intelligence	•
Course Objectives:			
1. To understand the fundamentals	s of fluid powe	er transmission systems	
2. To design various hydraulic syste	em componer	nts.	
3. To design various pneumatic sys	tem compone	ents.	
4. Learn various types of hydraulic	and pneumat	ic power circuits.	
5. Learn various types of applicatio	ns in fluid pov	wer circuits.	
	UNIT-I		
Fluid power systems and fundament	als		06 Hours
Introduction to fluid power, Advantage	s of fluid pow	er, Application of fluid p	oower system.
Types of fluid power systems, General t	ypes of fluids	- Properties of hydrauli	c fluids -Fluid
power symbols. Basics of Hydraulics-Ap	oplications of	Pascal's	
Hydraulic system components			05 Hours
Sources of Hydraulic Power: Pumping th	•		-
of pumps - Variable displacement pur			
actuators-Single acting and double act	ing cylinders,	Rotary actuators - Fluid	
Control Components			04 Hours
Direction control valve - Valve terminol		-	
valve - pressure control valve - pressure	e reducing va	lve, sequence valve. Flov	v control valves
- Fixed and adjustable Safety valves.			
Ducumentia sustem componente	UNIT-II		07 Центе
Pneumatic system components Pneumatic Components: Properties of	air Compros	ore EDI Unit Air contr	07 Hours
exhaust valves and pneumatic actuators			
Fluidics & Pneumatic circuit design	s- cylinders, al		08 Hours
Fluidics - Introduction to fluidic device	cos simple ci	ircuits Introduction to I	
Pneumatic logic circuits, PLC application	•		•
simple applications using classic, cascac		-	-
and combinational circuit design metho	•	er, logie with karnaugh	venenmapping
	UNIT-III		
Fluid power circuits			10 Hours
Speed control circuits, synchronizing	circuit. Pneun	no hydraulic circuit. Ac	
Intensifiers-Accumulator circuits, Intens		-	
systems, Electrohydraulic servo syste			
hydrostatics transmission circuits, cont	-	-	
Material handling equipment. Fluid			
Robot Applications- medical, mining,	•		-
Industrial Applications- Material handli	•	-	
Course Outcomes: At the end of the co		· · · · =	~
1. Compare the basics of hydraulic			ystems
			,

2.	Explain the working pr	inci	ple	of h	nvdr	aulio	C SV	ster	ns i	inclu	Judino	u nu	mps	and	cor	trol
	components.				. ,)					, I				
3.	Explain the working prir	ncip	le of	⁻ pne	eum	atic	sys	tem	s an	d th	neir c	omp	oner	nts.		
4.	Design various types of	hyd	lraul	ic ar	nd p	neu	ma	tic p	owe	er ci	rcuit	S				
5.	Design various types of	app	olica	tion	s in	fluic	d po	wer	circ	cuits	•					
Cour	se Outcomes Mapping v	vith	Pro	ogra	m C	Duto	om	es 8	<u>ያ</u> ይ	50						
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	ļ
↓ Co	ourse Outcomes													1	2	3
	RI2503-1.1	3	2	3	2	3	-	-	-	-	-	-	3	3	2	3
	RI2503-1.2	3	2	3	2	3	-	-	-	-	-	-	3	3	2	3
	RI2503-1.3	3	2	3	2	3	-	-	-	-	-	-	3	3	2	3
	RI2503-1.4	3	2	3	2	3	-	-	-	-	-	-	3	3	2	3
	RI2503-1.5	3	2	3	2	3	-	-	-	-	-	-	3	3	2	3
TEXT 1.	,	atic	sys	tem	s - F	Princ	iple	es ar	nd m	nain	tena	nce",	Tata	a Mc	Graw	ı Hil
1.	Majumdar S.R., "Pneum 2008		-													ı Hil
1. 2.	Majumdar S.R., "Pneum 2008 Anthony Esposito, "Flui		-													ı Hil
1. 2.	Majumdar S.R., "Pneum 2008 Anthony Esposito, "Flui RENCE BOOKS:	d Po	owei	r wit	h Aj	oplic	catio	ons"	', Pe	arsc						/ Hil
1. 2. REFE	Majumdar S.R., "Pneum 2008 Anthony Esposito, "Flui RENCE BOOKS: Majumdar S.R., "Oil Hyo Harry L. Stevart D. B,	d Po drau	owei ilics'	r wit ', Ta	h Aj ta N	oplio 1cGr	catio aw-	ons" Hill	', Pe , 200	arsc 00.	on Ed	ucat	ion 2	2009.		
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1. 2. REFE <u>1.</u> 2.	Majumdar S.R., "Pneum 2008 Anthony Esposito, "Flui RENCE BOOKS: Majumdar S.R., "Oil Hyo Harry L. Stevart D. B, Ltd.Broadey, 2010 Michael J, Prinches and	d Po drau "Pr Asł	ower Ilics' actio	r wit ', Ta cal g J. G,	h Aj ta M guid "Po	oplic 1cGr e to wer	catio raw- o flu Hyo	ons" Hill uid drau	', Pe , 20(pov	arsc 00. ver", ", Pr	on Ed , Tar entic	aoea aoea	ion 2 ala so all, 20	2009. ons)11.	and	Por
1. 2. REFE 1. 2. 3. 4.	Majumdar S.R., "Pneum 2008 Anthony Esposito, "Flui RENCE BOOKS: Majumdar S.R., "Oil Hyo Harry L. Stevart D. B, Ltd.Broadey, 2010 Michael J, Prinches and	d Po drau "Pr Asł	ower Ilics' actio	r wit ', Ta cal g J. G,	h Aj ta M guid "Po	oplic 1cGr e to wer	catio raw- o flu Hyo	ons" Hill uid drau	', Pe , 20(pov	arsc 00. ver", ", Pr	on Ed , Tar entic	aoea aoea	ion 2 ala so all, 20	2009. ons)11.	and	Por
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Humanities & Management Courses

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	aching Hours/Week (L: T	• P • 9	5)	_	:0:0		-	-	redi		<u>, </u>)2
	tal Teaching Hours			_	<u></u> 6+0		⊦∩	_			Ma	rkc		-	50+50
100		achi	ina												0130
Cou	rse Objectives:	acm	ing	Бер		nei	16. 1	Iuiii		105					
1.	Introspect and learn abo	out a	าทค	self											
2.	Develop professional wi														
3.	Acquaint with the variou				navi	our	and	etic	nuet	te.					
4.	Apply the techniques of										S .				
5.	Develop necessary tech														
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Pers	onality Traits													1	09 Hour
	es & Kinds of personality, V	Vays	to l	iden	tify	Self	(SW	/OT	Ana	lysis	s, Joh	ari V	Vindo		
	elf-Management and Self-	-			,									,,	- 1-
	ctive Communication Ski														
One	-way and Two-way Comm	unic	atic	on, Ir	nter	oers	ona	1&	Soci	al S	kills			1	
					UN	IT-II	[
Soci	al Behaviour and Cultura	al Et	iqu	ette										(09 Hour
Time	e Management, Personal G	iroo	min	g, N	1akiı	ng S	mal	l Ta	lk, C	usto	oms	& M	anne	rs	
Prof	fessional Presentation Te	chn	iqu	es											
Form	nal Presentation, Sensitivit	y to	ware	ds m	nulti	-cul	tura	l wo	orks	bace	es				
					UNI	T-II	Ι								
	-Related Communication														08 Hour
Resu	ume & Cover Letter, Forma	al E-i	mail	ls, Fr	ami	ng l	Requ	Jest	s, G	reet	ings,	Salu	utatic	ons,	Close
	rse Outcomes: At the end								be a	ble	to				
1.	Understand the importa														
2.	Demonstrate knowledge									offi	ce co	omm	unic	atio	<u>n.</u>
3.	Develop and assess vari														
4.	Be Familiar with the cur		•												
5.	Prepare and deliver pres	sent	atio	n ap	pro	pria	te f	or th	ne w	ork	place	9.			
Cou	rse Outcomes Mapping v	with	Pro	ogra	m (Duto	om	es 8	32 PS	50			1		
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	<u> </u>	PSO ↓
	ourse Outcomes													1	2 3
↓ C		-	1	-	-	-	2	2	-	3	_	-	-		
↓ C	HU2001-1.1		1		_	-	-	-	3	2	1	-	1	1	1 1
↓ C	HU2001-1.1 HU2001-1.2	-	-	-					•	_			-		
↓ C		-	-	2	-	-	2	2	2	-	-	-	2		
↓ C	HU2001-1.2	-	- - 3	2	-	-	2 -	2		- 2	- 3	- 2			

TΕ

1: Low 2: Medium 3: High

	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2022-
REFER	ENCE BOOKS:
1.	R R Gaur, R Sangal, G P Bagaria, "Human Values and Professional Ethics", Excel Books, New Delhi, 2010.
2.	Ronald B Adler and Jeanne Marquardt Elmhorst, "Communicating at Work – Principles and Practices for Business and the Professions", 6th Edition, McGraw Hill College.
3.	Stephen R. Covey, "The 7 Habits of Highly Effective People", Simon & Schuster, 1994.
4.	Sarvesh Gulati, "Corporate grooming and Etiquette", Rupa Publications India Pvt. Ltd., 2010.
5.	Fred. Luthans, "Organizational Behaviour", McGraw Hill International.
6.	Tom Rath, "Strengths Finder 2.0", Gallup Press, 2007.
7.	M Ashraf Rizvi, "Effective Technical Communication", Tata McGraw- Hill, 2005.
8.	Stephen P. Robbins, "Organizational Behaviour", Prentice Hall.
9.	Dale Carnegie, "How to Win Friends and Influence People", Gallery Books, 2016.



	UNIVER	SAL HUMAN	VALUES	
Co ι	urse Code:	HU1004-1	Course Type	HSMC
Tea	aching Hours/Week (L: T: P: S)	1:0:0:0	Credits	01
Tot	tal Teaching Hours	15+0+0+0	CIE + SEE Marks	50+50
		Department: H	lumanities	
	rse Objectives:			
1.	Enable students appreciate w understanding of 'Self' to att aspirations of life.			
2.	Develop a holistic perspective prosperity of life.	e among the s	tudents towards physic	cal needs and
3.	Develop a holistic approach a	nd understand	the importance of co-	-existence and
	living in harmony ensuring mut	ually fulfilling ir	nteraction with the socie	ety and nature.
4.	Strengthening of self-reflection			
5.	Development of commitment a	and courage to a	act.	
		UNIT-I		
	d, Basic Guidelines, Content and			06 Hours
	Exploration; 'Natural Acceptance'	-		
	perity; Right understanding, Relat		sical Facility; Understan	ding Happines
and	Prosperity - living in harmony at v	various levels.		
				0.011
	erstanding Harmony in the Hur			06 Hours
	erstanding human being as a co- ds of Self ('I') and 'Body'; the Body (-
	, <u>,</u>		• •	
		al harmonious	order in society- Unc	,
			order in society- Unc	
	versal Order- from family to world		order in society- Unc	,
			order in society- Unc	,
			order in society- Unc	,
Univ	versal Order- from family to world	family. UNIT-III		divided Society
Univ Whc	versal Order- from family to world	family. UNIT-III Implications	of the above Holi	divided Society
Univ Whc Und	versal Order- from family to world	family. UNIT-III Implications ofessional Ethic	of the above Holi	divided Society
Univ Who Und	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro	family. UNIT-III Implications ofessional Ethic ature and Existe	of the above Holi s nce; Existence as Co-ex	divided Society stic 03 Hours istence, Holisti
Univ Who Und Dnd	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro erstanding the harmony in the Na	family. UNIT-III Implications ofessional Ethic ature and Existe	of the above Holi s nce; Existence as Co-ex	divided Society stic 03 Hours istence, Holisti
Univ Who Und Dnd	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro erstanding the harmony in the Na reption of harmony at all levels	family. UNIT-III Implications ofessional Ethic ature and Existe	of the above Holi s nce; Existence as Co-ex	divided Society stic 03 Hours istence, Holisti
Univ Who Und Ond	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro erstanding the harmony in the Na reption of harmony at all levels	family. UNIT-III Implications ofessional Ethic ature and Existe	of the above Holi s nce; Existence as Co-ex	divided Society stic 03 Hours istence, Holisti
Univ Who Und Derc Profe	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro erstanding the harmony in the Na reption of harmony at all levels	family. UNIT-III Implications ofessional Ethic ature and Existe of existence;	of the above Holi s nce; Existence as Co-ex Natural acceptance of	divided Society stic 03 Hours istence, Holisti
Univ Who Und perc Profe	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro- erstanding the harmony in the Na- seption of harmony at all levels lessional Ethics	family. UNIT-III Implications ofessional Ethic ature and Existe of existence; course student	of the above Holi s nce; Existence as Co-ex Natural acceptance of will be able to	stic 03 Hours istence, Holisti human values
Univ Who Und perc Profe	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro- erstanding the harmony in the Na- reption of harmony at all levels essional Ethics rse Outcomes: At the end of the Have a better self-exploration a	family. UNIT-III Implications ofessional Ethic ature and Existe of existence; I course student and understand	of the above Holi s nce; Existence as Co-ex Natural acceptance of will be able to	stic 03 Hours istence, Holistic human values
Univ Who Undo perco Profe Court 1.	versal Order- from family to world ole existence as Coexistence: lerstanding of Harmony and Pro- erstanding the harmony in the Na- ception of harmony at all levels essional Ethics rse Outcomes: At the end of the Have a better self-exploration a priorities of life. Generate Sustainable solution t	family. UNIT-III Implications ofessional Ethic ature and Existe of existence; I course student and understand co problems wit	of the above Holi s nce; Existence as Co-ex Natural acceptance of will be able to ing with a capacity to id h focus on human value	stic 03 Hours istence, Holistic human values

5. Exhibit Professional Ethics in the workplace

NITTE

	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PSC		Ļ
L Co	urse Outcomes													1	2	3
	HU1004-1.1	-	-	-	-	-	-	-	3	-	-	2	2			
	HU1004-1.2	-	-	-	-	-	-	-	2	-	-	2	2			
	HU1004-1.3	-	-	2	-	-	-	1	2	-	-	2	2			
	HU1004-1.4	-	-	-	-	-	-	-	1	-	-	-	-			
	HU1004-1.5	-	-	1	-	-	-	-	3	-	-	2	2			
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ΈΧΤΙ	BOOKS:															
1.	R R Gaur, R Sangal, G P	Bag	garia	а, "Н	uma	an V	'alue	es a	nd F	Profe	essio	nal E	thics	:". Ex	cel	
														· /		
	Books, New Delhi, 2010)	_											,		
REFEF	Books, New Delhi, 2010 BENCE BOOKS:)	_	·												
REFEF 1.	RENCE BOOKS:		Ek Pa													999
	RENCE BOOKS: A Nagaraj, "Jeevan Vidy	/a: E		arich	naya	", Je	eva	n Vi	dya	Pra	kasha	an, A	marl	kant		999
1.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V	/a: E /alu		arich	naya	", Je	eva	n Vi	dya	Pra	kasha	an, A	marl	kant		999
1. 2.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Bool	/a: E /alu <).	es",	arich Nev	naya v Ag	", Je Je In	eva itl. P	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Bool	/a: [/alu <). d Ga	es", andh	arich Nev ii, "T	naya v Ag The S	", Je Je In	eva itl. P	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3. 4.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Book Mohandas Karamchanc E. F Schumacher, "Smal	/a: [/alu <). l Ga l is	es", andh Beau	arich Nev ni, "T utifu	naya v Ag The S	", Je Je In	eva itl. P	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3. 4. 5.	A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Bool Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i	/a: E /alu <). d Ga l is s Be	es", andh Beau eaut	arich Nev ni, "T utifu iful"	naya v Ag The S I''	", Je Je In Story	eva Itl. P y of	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3. 4. 5. 6.	A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Bool Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i	/a: E /alu <). l Ga l is s Be my	es", andh Beau eaut of P	arich Nev ni, "T utifu iful" erm	naya v Ag The S I'' ane	", Je je In Story nce"	evai itl. P y of	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3. 4. 5. 6. 7.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Book Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i J C Kumarappa, "Econo	/a: E /alu <). d Ga l is s Be my at N	es", andh Beau eaut of P Iein	arich Nev ni, "T utifu iful" Anc	naya v Ag The S I'' ane	", Je je In Story nce"	evai itl. P y of	n Vi ubli	dya ishe	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999
1. 2. 3. 4. 5. 6. 7. 8.	A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Bool Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i J C Kumarappa, "Econo Pandit Sunderlal, "Bhara	/a: E /alu <). I Ga I is s Be my at N rinc	es", andh Beau eaut of P Iein J Inc	arich Nev ii, "T utifu iful" erm Anc lia"	haya v Ag he S l" ane greji	", Je je In Story nce" Raj'	evai itl. P y of	n Vi ubli My	dya ishe Exp	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		9999
1. 2. 3. 4. 5. 6. 7. 8. 9.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Book Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i J C Kumarappa, "Econo Pandit Sunderlal, "Bhara Dharampal, "Rediscove	/a: E /alu <). d Ga l is s Be my at N rinc d Ga	es", andh Beau eaut of P Jein J Inc	arich Nev ni, "T utifu iful" erm Ang lia" ni, "Ir	naya v Ag he S l" ane greji	", Je je In Story Raj' n Ho	eval tl. P y of	n Vi ubli My	dya ishe Exp	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		9999
1. 2. 3. 4. 5. 6. 7. 8. 9. 10.	RENCE BOOKS: A Nagaraj, "Jeevan Vidy A.N. Tripathi, "Human V The Story of Stuff (Book Mohandas Karamchanc E. F Schumacher, "Smal Cecile Andrews, "Slow i J C Kumarappa, "Econo Pandit Sunderlal, "Bhara Dharampal, "Rediscove Mohandas Karamchanc Maulana Abdul Kalam A	/a: E /alu <). d Ga l is s Be my at N rinc d Ga Azae	es", andh Beau eaut of P Aein J Ind andh d, "Ii	arich Nev ni, "T utifu iful" erm Anc lia" ndia	naya v Ag he S l" ane greji	", Je je In Story Raj' n Ho	eval tl. P y of	n Vi ubli My	dya ishe Exp	Pra rs, N	kasha Jew [an, A Delhi	marl , 200	kant)4		999

~	Technology Mana			
	urse Code:	MG1006-1	Course Type	PEC
	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	tal Teaching Hours	40	CIE + SEE Marks	50+50
	Teaching Department	: Robotics and	Artificial Intelligenc	е
Cou	rse Objectives:			
1.	Define production/Technology	-		management
	framework and activities viz., ac	quisition and ex	ploitation.	
2.	Explain the technology manage	ment activities	viz., Identification, lear	ning
	protection and election			
3.	Discuss the technology manage		Patent analysis, Portfo	olio
	management and Roadmapping	g		
4.	Discuss technology managemer			del, and value
	analysis. Explain Technology ma			_
5.	Discuss Entrepreneurship. Expla	in the features	of Small Scale Industri	es. Identify and
	differentiate the different nation	nal and state lev	el funding agencies.	
		UNIT-I		1
	oduction			06 Hours
	nition, Difference between Techno	logy Managem	ent (TM) and Innovation	on Management
	framework.			
M	activities			07 11
icqi Exp	uisition – Internal and external uisition decisions loitation – Commercialization/ N cesses, reverse innovation			t assessment i
Exp Droc den Lea Prot	uisition decisions loitation – Commercialization/ N	Marketing and entification proc s, improving lea cess, recent cha ss, strategic ana	Technology transfer cesses arning environment allenges	t assessment i
Exp Droc den Lea Prot Sele	uisition decisions loitation – Commercialization/ M cesses, reverse innovation utification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process	Marketing and entification proc s, improving lea cess, recent cha	Technology transfer cesses arning environment allenges	and utilization
Exp proc den Lea Prot Sele	uisition decisions loitation – Commercialization/ N cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process	Marketing and entification proc s, improving lea cess, recent cha ss, strategic ana UNIT-II	Technology transfer cesses arning environment allenges alysis and choices	and utilization
Exp oroc den Lea Prot Sele	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process Tools ent Analysis - Introduction, where a	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use	Technology transfer cesses arning environment allenges alysis and choices ed, process.	and utilization
Exp Doroc den Lea Prot Sele Prot Sele Pate	uisition decisions loitation – Commercialization/ M cesses, reverse innovation utification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process Tools ent Analysis - Introduction, where a folio Management – Introduction,	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use	Technology transfer cesses arning environment allenges alysis and choices ed, process.	and utilization
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Acqu Exp proc den Lea Prot Sele Prot Sele Pate Port Roa ntrc	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process Tools ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used	Marketing and entification proc s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road	Technology transfer cesses arning environment allenges alysis and choices ed, process. y it is used, process mapping emerging tec	and utilization of Hours 06 Hours
Acqu Exp poroc den Lea Prot Sele Port Roa ntrc S –	uisition decisions loitation – Commercialization/ M cesses, reverse innovation ntification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pr	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec rocess, Managing IP th	and utilization and utilization 04 Hours 06 Hours chnologies rough lifecycle.
Acqu Exp Droc den Lea Prot Sele Pate Pate Pate Stag	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process tools ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, whe	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pr	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec rocess, Managing IP th	and utilization and utilization 04 Hours 06 Hours chnologies rough lifecycle.
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acqu Exp proc den Lea Prot Sele Port CM Pate Port Roa Stag gate Jalu	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, where e models in Analysis and Innovation	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pr ere and why it i	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec cocess, Managing IP th s used, process, next o	and utilization O4 Hours chnologies rough lifecycle. generation stage 04 Hours
Acqu Exp Doroc den Lea Prot Sele Port Pate Port Roa Stag gate Jalu ntro	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, whe e models the Analysis and Innovation oduction, where and why it is used	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pr ere and why it i	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec cocess, Managing IP th s used, process, next o	04 Hours of Utilization 04 Hours chnologies rough lifecycle. generation stage
Acqu Exp Doroc den Lea Prot Sele Port Pate Port Roa Stag gate /alu ntro	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, where e models in Analysis and Innovation	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pr ere and why it i , expanding val	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec cocess, Managing IP th s used, process, next o	04 Hours of Utilization 04 Hours chnologies rough lifecycle. generation stage
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Acqu Exp Droc den Lea Prot Sele Pate Pate Pate Pate Sag Stag gate Chal Intro Con	uisition decisions loitation – Commercialization/ M cesses, reverse innovation atification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, whe emodels te Analysis and Innovation oduction, where and why it is used lenges ahead.	Marketing and entification proc s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pre- ere and why it i , expanding val UNIT-III in entrepreneu	Technology transfer cesses arning environment allenges alysis and choices ed, process. v it is used, process mapping emerging tec cocess, Managing IP th s used, process, next of ue analysis Managing	and utilization and utilization 04 Hours 06 Hours chnologies rough lifecycle. generation stage 04 Hours Technology and 05 Hours entrepreneurs in
Exp Doroc den Lea Prot Sele Port Road ntrc S – Stag gate Jalu ntrc Chal	uisition decisions loitation – Commercialization/ M cesses, reverse innovation ntification – Definition, different ide rning – Definition, learning process ection – Definition, protection pro ction – Definition, Selection process ent Analysis - Introduction, where a folio Management – Introduction, dmapping oduction, where and why it is used Curve - Introduction, where and w ge Gate Model - Introduction, whe e models the Analysis and Innovation oduction, where and why it is used lenges ahead.	Marketing and entification proo s, improving lea cess, recent cha ss, strategic and UNIT-II and why it is use where and why , process, Road why it is used, pre- ere and why it i ere and why it i , expanding val UNIT-III in entrepreneutrepreneutrepreneurship,	Technology transfer cesses arning environment allenges alysis and choices ed, process. r it is used, process mapping emerging tec cocess, Managing IP th s used, process, next of ue analysis Managing ue analysis Managing	and utilization and utilization 04 Hours 06 Hours chnologies rough lifecycle. generation stage 04 Hours Technology and 05 Hours entrepreneurs in



Small Scale Industries 04 Hours Definition; Characteristics; Need and rationale; Objectives; Scope; role of SSI in Economic Development. Advantages of SSI, Steps to start and SSI, Government policy towards SSI; **Different Policies of SSI. Institutional Support** 04 Hours Different Schemes; TECKSOK; KIADB; KSSIDC; KSIMC; DIC Single Window Agency; SISI; NSIC; SIDBI; KSFC **Course Outcomes:** At the end of the course student will be able to 1. Define production/Technology management, Explain the technology management framework and activities viz., acquisition and exploitation. 2. Explain the technology management activities viz., Identification, learning protection and election 3. Discuss the technology management tools viz., Patent analysis, Portfolio management and Roadmapping Discuss technology management tools viz., S-Curve, Stage- gate model, and value 4. analysis. Explain Technology management challenges ahead 5. Discuss Entrepreneurship. Explain the features of Small Scale Industries. Identify and differentiate the different national and state level funding agencies. **Course Outcomes Mapping with Program Outcomes & PSO Program Outcomes**→ 1 2 3 4 5 6 7 8 9 10 11 12 **PSO Course Outcomes** 3 1 3 1 1 1 1 1 MG1006-1.1 1 1 2 1 2 1 1 MG1006-1.2 2 2 1 1 1 2 2 1 MG1006-1.3 3 1 3 3 1 1 1 1 MG1006-1.4 1 1 1 1 1 1 1 2 1 MG1006-1.5 1: Low 2: Medium 3: High **TEXTBOOKS**: Technology management: Activities and Tools – Dilek Cetindamar, Rob Phaal & 1. David Probert, 2nd edition, Palgrave -Macmillan Education, 2016 2. Entrepreneurship Development – Poornima. M. Charantimath – Small Business Enterprises – Pearson Education – 2006 (2 & 4). **REFERENCE BOOKS:** Handbook of Technology management – Gerard H Gaynor, McGraw Hill 1. Publications, 1999 Managing Technology, Competing through New Ventures, Innovation and 2. Corporate Research - Frederick Betz, Prentice Hall, Englewood Cliffs, New Jersey, 1987

3. Entrepreneurship Development – S.S.Khanka – S.Chand & Co.



	IN	TRO							
Cou	rse Code:		HU100	6-1		С	ourse Typ	be:	HSMC
Теа	ching Hours/Week (L: T: P:	S):	1:0:0:0				Credi	ts:	01
Tota	al Teaching Hours:		15			CIE +	SEE Mark	ks:	50+50
	Teaching De	epartr	nent: R	especti	ve De	partm	ent		
Cour	se Objectives:								
1.	Enhancing the learning sys	stem t	hrough	innova	tion a	nd cre	eative thin	iking	g skills for
	effective business process.								
2.	Acquaint with special challe								
3.	Facilitate Entrepreneurial advantages.	skills	in re	cognizir	ng op	oportu	nities for	C C	ompetitive
4.	Provide insights of financial	laspe	cts in pl	anning	and ex	kecutir	ng a busine	ess	plan.
5.	Ascertain the role of IPR to	prote	ct innov	ations a	nd in	tangib	le assets.		
			UNI	Г -I					
	lectual Property Rights (IPR								6 Hours
	duction to IPR: Business P	•						De	evelopmen
inter	national Context, Concept of	IP Ma	nageme	ent, Use	s in m	arketir	ng		
			UNIT	'_TT					
				-11					
Туре	s of Intellectual Property		UIII	-11					6 Hours
	s of Intellectual Property nt - Procedure, Licensing a	ind A			ringen	nent a	and Penal	lty,	
Pater			ssignme	ent, Inf	-			-	Trademar
Pater Exam	nt - Procedure, Licensing a	in nar	ssignme me, Geo	ent, Infi ographi	cal In	dicatio	ns, Copyr	-	Trademar
Pater Exam	nt - Procedure, Licensing a ple of Trademarks - Doma	in nar	ssignme me, Geo	ent, Infi ographi	cal In	dicatio	ns, Copyr	-	Trademar
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Pater Exam Desig	nt - Procedure, Licensing a pple of Trademarks - Doma gns, Class Discussion - Major	in nar Court hnolo	ssignme me, Geo Cases r UNIT	ent, Infr ographi egardin -III 2000	cal Ind g viola	dicatio ation c	ons, Copyr of Patents	right	Trademarl t, Industria 3 Hours
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1: Low 2: Medium 3: High

REFERENCES:

- **1.** Tidd, J., & Bessant, J., "Managing Innovation: Integrating Technological, Market and Organizational Change", Wiley, 2021.
- **2.** Case Study Materials: To be distributed for Class Discussion
- **3.** Reddy, G. B., "Intellectual Property Rights and the Law", Gogia Law Agency, 2012.
- **4.** Wadehra, B. L., "Law relating to Intellectual Property", Universal Law Publishing Co., 2011.
- 5. Narayanan, P., "IPR", Eastern Law House Private Ltd, 2017.



Course Code:	MG1003-1	Course Type	HSMC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	39	CIE + SEE Marks	50+50
Teach	ning Departme	nt: Any	
Course Objectives:			
1. To introduce the field of mana	agement, task o	f the manager, importa	nce of planning
and types of planning, staff re	-	- .	
2. To discuss the ways in which w	vork is allocatio	n, structure of organiza	tions, modes of
communication and need of c	oordination be	tween the manager and	l staff
3. To explain the role and impor	tance of the ent	trepreneur and their fur	nctions in
economic development and the	ne concepts of	entrepreneurship.	
4. To discuss the importance of s			generating
new business ideas and busine			
5. To introduce the concepts of t	financial concep UNIT-I	ots in enterprises.	
Management:	UNIT-1		03 Hours
Definition, Importance – Nature and C	haracteristics o	f Management, Manag	ement Function
Roles of Manager, Levels of Managen			
Management as a Science, Art & Profe	ssion.		
Planning:			03 Hours
Nature, Importance and Purpose of Pl		-	-
Planning, Decision Making – Meaning	, Types of Decis	ions- Steps in Decision	
Organizing and Staffing			04 Hours
Meaning, Nature and Characteristics c	0		•
Organization, Departmentalization, Co			
Centralization Versus Decentralization	•	. , ,	
Definition only), Nature and Importan	ice of Staning, i		04 Hours
Directing and Controlling Meaning and Nature of Directing-Lead	dershin Styles	Activation Theories Cou	
Meaning and Importance, Coordinatic			
Coordination. Controlling – Meaning,	-		
	UNIT-II		
Social Responsibilities of Business:			03 Hours
Meaning of Social Responsibility, Social	al Responsibiliti	es of Business towards	Different Group
Social Audit, Business Ethics, and Corp			·
intrepreneurship			05 Hours
Definition of Entrepreneur, Importan	ce of Entreprer	neurship, concepts of E	Intrepreneurshi
Characteristics of successful Entrepre	neur, Classificat	ion of Entrepreneurs, In	ntrapreneur – A
Emerging Class, Comparison bet	ween Entrepr		



	Deemed to be University epreneurship, Entrepreneu	urial	De	velo	pme	ent i	noc	dels	, Ent	rep	rene	urial	deve	elopr	nent	cycle,
	lems faced by Entreprene				•					-				•		,
Mod	ern Small Business Ente	rpri	ses			-								05	Но	urs
Role	of Small Scale Industries,	Cor	ncep	ots a	nd c	lefir	nitio	ns c	of SS	SI Er	terp	rises,	, Gov	ernn	nent	policy
and o	development of the Smal	l Sc	ale	sect	or ir	n Ind	dia,	Gro	wth	and	d Per	form	nance	e of S	Smal	l Scale
Indus	stries in India, Sickness	in S	SSI s	ecto	or, P	rob	lem	s fo	or S	mall	Sca	le Ir	ndust	ries,	Imp	act of
	alization on SSI, Impact	of	WT	0/G	ATT	on	SS	Is, A	Anci	llary	Ind	ustry	/ and	d Tin	iy In	dustry
-	nition only).															
	tutional Support for Bus														Ho	urs
Intro	duction, Policies & Schen	nes	of C	entr				titu	tion	s, St	ate-l	Level	Inst	itutic	ons	
					UN	IT-I	II									
	nce Management in ent														Ho	
	duction, functions, Accou		0				• •			cial	State	emer	nts, V	Vork	ing (Capita
Mana	agement, Break even Ana	lysis	s, Fir	nanc	ial r	atio	Ana	alysi	IS.							
	rse Outcomes: At the end															.
1.	Describe the field of m	ana	gem	ient,	the	tas	k o	t the	e ma	anag	ger, p	olanr	ning,	and	step	os in
•	decision making.	<u> </u>										-•				
2.	Discuss the structure o			•			•								• •	·
	modes of communication	on, t	.ecn	niqu	es c	T CO	ora	inat	lon,	anc	imp	orta	nce c	or ma	inag	eriai
2	control in the business.	10	~ f		+					. d						a dial
3.	Describe the conception of the conceptine of the conceptine of the conceptine of the						eurs	nip	ar	10	aı	JUSIT	nessn	nan s	S	ocial
4.	responsibilities towards Develop an understand			-				c in	tha	da	<i>v</i> olo <i>r</i>	mor	t of	6011	otru	and
4.	state/central level instit	-									-				itty	anu
5.	Apply the concepts of f							-								
	rse Outcomes Mapping				<u> </u>						use			1505		
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	O↓	
	ourse Outcomes	-			'	5	Ŭ	ļ ,			-0			1	2	_
_	MG1003-1.1	3	-	-	-	-	_	-	2	2	_	3	_	-	1	
	MG1003-1.2	3	-	-	-	-	_	-	2	2	_	3	_	_	2	_
	MG1003-1.3	3	-	-	-	-	_	-	2	2	_	3	_	_	2	_
	MG1003-1.4	3	_	-	-	-	_	-	2	2	_	3	_	_	2	-
	MG1003-1.5	3	-	-	-	-	-	-	2	2	_	3	-	- 1	2	-
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	1: Low 2: Medium 3:	Hig	gh													
TEXT	FBOOKS:															
	1. P. C. Tripathi, P. N. Re															
	2. Poornima M. Chara						neu	ırsh	ip D	eve	lopm	nent	and	Sma	ll Bu	usines
	Enterprises", Pearson															
	3. W.D Stevenson, "Ele	mer	nts c	of Po	wer	Sys	tem	n An	alys	is", 4	4 th eo	ditior	n, TM	IH, 2	001.	
REFE	RENCE BOOKS:			_	_											
	1. Vasant Desai, "Dyr					epre	eneu	urial	De	evelo	opme	ent	and	Mar	nage	ment"
	Himalaya Publishing							_								
	Harold Koontz, He														erna	tional
2.	Innovation and Leac	ersł	nip r	bers	pect	ive"	, Mo	cGra	aw⊦	Iill, 1	LO th E	ditic	on, 20)16.		



	FINANC		GEMENT	
Cou	rse Code:	MG1002-1	Course Type	HSMC
Tea	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	39	CIE + SEE Marks	50+50
	Teachi	ng Departme	nt: Any	
Cour	se Objectives:			
1.	Develop basic financial manag	ement knowle	dge essential to make	a managerial
	career in professional life.			
2.	Impart some of the crucial and b	pasic skills requ	iired to work in the area	of budgeting,
	investment and financial decisio			
3.	Enable in making a right decisio			
4.	Understand the basics of finar	nce and finance	cial markets, project e	valuation and
	selection.			
		UNIT-I		
	Value of Money			15 Hours
	cial Management: Concepts and	-		
	cial Management; Profit Maximiz		5 5	0
lime	Value of Money: Techniques and		f Compounding and Dis	scounting.
Carrie		UNIT-II		15
	al Budgeting and Working Cap		ac), Davida als David M	15 Hours
	al Budgeting (Investment Evalua h Method; Annual Worth Method	•	-	
	of Capital: Sources of various T			
	rential Capital; Cost of Term Loan	• • • •		
	ing Capital: Factors influencing W	•	, ,	
			riequirementsi	
		UNIT-III		
Inver	ntory Management and Break E	ven Analysis		9 Hours
	tory Management: Techniques of		lanagement and Control	ol – EOQ, ABC
	sis, Just-in-Time (JIT) System	-	-	
Break	Even Analysis: Estimation of Brea	ak-Even Point a	ind Values.	
Cour	se Outcomes: At the end of the c	ourse student	will be able to	
1.	Describe the basic financial mar	agement skills	required for a profession	onal.
2.	Explain techniques and applicat	•	5 5	and calculate
	compounded/discounted amou			
3.	Evaluate the given investment o			
4.	Describe the basics of cost of	•	orking capital. Determir	ne the cost of
	capital for the given investment			
5.	Describe the basics of invento			
	quantity and reorder point for th	ne given condit	ions. Calculate breakeve	n point for the
	given manufacturing setup.			

	e Outcomes Mapping v Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PS	O]
Со	urse Outcomes	1	-			5	Ŭ		Ū					1	2	3
	MG1002-1.1	3	-	-	-	-	-	-	-	1	1	-	1	-	-	-
	MG1002-1.2	1	3	-	-	_	-	-	-	1	1	-	1	-	-	-
	MG1002-1.3	2	3	-	-	-	-	-	-	1	1	-	1	-	-	-
	MG1002-1.4	2	3	-	-	-	-	-	-	1	1	-	1	-	-	-
	MG1002-1.5	1	3	-	-	-	-	-	-	1	1	-	1	-	-	-
	1: Low 2: Medium 3	: Hie	gh		•					•	•					
1.	BOOKS: M Y Khan, P K Jain , "I 2015; McGraw Hill Educ										olem	s & (Case	s",7t	h Ed	itic
~	I M Pandey, "Financial I		-		-						Vikas	; Pub	lishi	ng H	lous	e Pv
2.	Ltd. (UP) India.										- "F.	•	•	-	onor	nic
2. 3.						Sab	ah l	J. Ra	andł	าลพ	a, Er	igine	ering	g Ec	onor	me:
3.	James L. Riggs, David D					Sab	ah l	J. Ra	andł	naw	a, Er	igine	ering	g Ec		
3.	James L. Riggs, David D 4th Edition, Tata McGra	aw⊦	lill E	ditio	on.											
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	Deemed to be University) ESSENC	CE C)F II	NDI/	AN C	CUL	TUF	RE					
C οι	urse Code:		HU1	L005-	-1			C	ours	e Ty	pe:	HE	C
Теа	aching Hours/Week (L: T: P: S)	:	1:0:	0:0						Cred	its:	01	
Tot	tal Teaching Hours:		15				С	IE +	SEE	Mar	·ks:	50-	⊦50
	Teaching Dep	artn	nent	: Res	pecti	ve	Depa	rtm	ent				
Cou	rse Objectives:												
1.	To facilitate students with the	con		ts of I	ndia	า Cเ	Ilture	anc	l to r	nake	the	m	
	understand the roots of know		•										
2.	To acquaint students with Ind					culc	ate a	n ab	ility	to ar	nalyz	e it.	
3.	To apply various approaches												dian
	traditional knowledge.							5					
			U	NIT-I									
Intro	oduction to Traditional Knowl	edg										6 H	lours
Defir	ne traditional knowledge, natu	re a	nd c	harad	teris	tics,	sco	oe a	nd iı	mpo	rtano	ce, k	inds c
tradi	itional knowledge, Indigenous K	ínow	ledg	je an	d its	char	acte	ristic	s, Tra	aditio	onal	Kno	wledg
vis-a	a-vis Indigenous Knowledge, Tra	ditic	onal	Know	ledg	e vis	s-a-v	is W	ester	'n Kn	owle	edge	
			U	NIT-II	[-	
Sign	nificance of Traditional Knowle	edge	9									6 H	lours
	e of Traditional Knowledge in	-			-								
	litional Knowledge, Traditional	med	icine	e syst	em,	Trac	litior	al K	now	ledge	e in	agri	culture
food	and healthcare.												
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				IIT-II	I								
	stic Healthcare for Human We		-										lours
	nition of Ayurveda, Ayurveda fo				and	Wel	l-bei	ng, I	ntro	ducti	on t	o pr	inciple
ot Ay	yurvedic healing and Astanga A	yurv	eda.										
C						.:11 1-							
	rse Outcomes: At the end of th												
1.	Identify the concept of Tradit												
2.	Explain the need for and impo					-					age.		
3.	Illustrate the various enactme Familiarize the importance of						nai K	now	leag	e.			
	I FAMILIARIZE THE IMPORTANCE OF	HOI	ISUC	Healt	.ncar	z .							
4.													
	rse Outcomes Mapping with P	Prog	ram	Outo	come	es &	PSC)					
	rse Outcomes Mapping with P	-				-		<u>г г</u>	10	11	12	DS	
Cou		Prog	ram 3		:ome 5 6	s &	PSC	9	10	11	12	PS	2 2

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1: Low 2: Medium 3: High

REFEF	REFERENCES:									
1.	Jha, A., "Traditional Knowledge System in India", Atlantic Publishers, 2002.									
2.	Kapoor, K., & Danino, M., "Knowledge Traditions and Practices of India", 2012.									
3.	Kapil Kapoor, Michel Danino, "Knowledge Traditions and Practices of India", Medknow									
	Publications and Media.									
4.	Jha, R.N., "Science of Consciousness Psychotherapy and Yoga Practices", Delhi:									
	Vidyanidhi Prakashan, 2015.									
5.	TEDx Talks. (2015, February 6). Unleashing the Power of Traditional Medicine Dr.									
	Arvind Singh [Video file]. Retrieved from									
	https://www.youtube.com/watch?v=LZP1StpYEPM									

INDIAN KNOWLEDGE SYSTEMS										
Cou	irse Code:	HU1009-1	Course Type:	HEC						
Теа	ching Hours/Week (L: T: P: S):	1:0:0:0	Credits:	01						
Tot	al Teaching Hours:	15	CIE + SEE Marks:	50+50						
	Teaching Depart	ment: Respect	ive Department							
Cour	se Objectives:									
1.	Enhance knowledge about the H	listory of Ancie	nt India and Rich Culture o	f the						
	country									
	2. Gain an introduction to ancient Indian Engineering Technology and Architecture									
	3. Familiarize Indian indigenous wisdom in Modern scientific paradigm									
-	4. Understanding the Scientific Value of the Traditional Knowledge of our country									
5.	Comprehend and compare the A	Ancient and Cu	rrent Knowledge Systems							
	UNIT-I									
	Indian History 6 Hours									
	bry - Land, Environment, and people		-							
	Nālandā University, Hunting to Agr	iculture; Introd	uction to Vedas and Upanis	shads; Great						
India	n Epics; Indian Festivals									
		UNIT-II								
Engi	neering, Technology, and Archit	ecture		6 Hours						
	Harappan and Sindhu Valley Civiliz		ory and Apparatus, Juices,	Dyes, Paints						
and	Cements, Glass and Pottery, Met	allurgy, Engine	ering Science and Techno	ology in the						
Vedio	c Age and Post-Vedic Records, Iro	n Pillar of Delh	i, Rakhigarhi, Mehrgarh, Si	ndhu Valley						
Civili	zation, Marine Technology									
		UNIT-III								
	nce, Astronomy, and Mathemati			3 Hours						
	ept of Matter, Life and Universe,			•						
_	, Vimāna: Aeronautics, Vedic Cosn									
	nomy, Sun, Earth, Moon, Eclipses,			Pi, Number						
Syste	em, Pythagoras Theorem and Vedio	c Mathematics.								
	• · · · · · · · · · · · · · · · · · · ·									
	Course Outcomes: At the end of the course student will be able to									
1.	Understand the relevance of stud	dying history								

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1. Understand the relevance of studying history 2. Comprehend the origin of Vedas and epics 3. Realize the scientific value of the Traditional Knowledge of India Converting the Bhāratīya wisdom into the applied aspect of the modern scientific 4. paradigm 5. Preserve and disseminate Indian Knowledge Systems in Research and Societal applications

C	ourse Outcomes Mapping wit	th P	rog	ram	Ou	tcoi	mes	8	PSO)					
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PSO↓	

	(Deeme	ed to be University)															
	↓C	Course Outcomes													1	2	
		HU1009-1.1	-	-	-	-	-	-	-	-	-	-	2	3	-	-	
		HU1009-1.2	-	-	-	-	-	-	-	-	-	-	3	3	-	-	
	HU1009-1.3		-	-	-	-	-	-	-	-	-	-	2	3	-	-	
	HU1009-1.4			-	-	-	-	-	-	-	-	-	2	2	-	-	
		HU1009-1.5	-	-	-	-	-	-	-	-	-	-	2	2	-	-	
	1: Low 2: Medium 3: High																
	¥																
RE	REFERENCES:																
	1.	Tripati, R.S., "History of A	ncie	nt Ir	ndia	", M	otila	al Ba	anar	sida	ss, 1	.942.					
	2.	Mahajan, V.D "Ancient Ir	ndia	", S.	Cha	nd a	and	Cor	npa	ny, :	1985	5.					
	3.	Ramasubramanian, K., &	Srin	ivas	, M.I	D., "	Dev	elop	ome	nt o	f Ca	lculu	s in l	India	", 20	10.	
	4.	Ramasubramanian, K., Sri	niva	is, N	1.D.,	& S	rirar	n, N	1.S.,	"Th	e Tra	aditio	onali	India	in Pla	aneta	iry
		Model and its Revision by	/ Nil	laka	ntha	So	may	aji",	201	L1.							-
	5.	Srinivas, M.D., "Proofs in I	ndia	an N	/lath	ema	atics	", H	indu	usta	n Bc	ok A	geno	cy, 20	005.		
	6.	Srinivas, M.D., "The Algor	ithm	nic A	Appr	oac	h of	Ind	ian	Mat	hem	natics	s", <mark>2</mark> 0	15.			
	7.	Srinivas, M.D. "Indian Trad	ditic	on o	f Sci	ence	e: Ai	ו In	trod	lucto	ory () Dver	/iew'	', 201	16.		
	8.	Rahika, M., & Balasubran	nani	ian,	A.V.	, "A	Ayur	ved	ic P	rinci	ples	s of F	ood	and	Nut	ritio	n",

Part 1. Lok Swasthya Parampara Samvardhan Samithi, 1990.



ಆಡಳಿತ ಕನ್ನಡ (Kannada for Administration)											
Cour	Course Code HU1003-1 Course Type MNC										
Teac	ching Hours/Week (L:T:P:S)	1:0:0:0	Credits	0							
Tota	Il Teaching Hours	15+0+0+0	CIE + SEE Marks	50+0							
	Teaching Dep	partment: Any	Department								
Cours	se Objectives:										
1.	ಪದವಿ ವಿದ್ಯಾರ್ಥಿಗಳಾಗಿರುವುದರಿಂದ ಸಾಂ	J .		್ನದ ಸಾಹಿತ್ಯ,							
	ಸಂಸ್ಕ್ರತೆ ಮತ್ತು ನಾಡು ನುಡಿಯ ಪರಿಚಯ										
2. ವಿದ್ಯಾರ್ಥಿಗಳಲ್ಲಿ ಕನ್ನಡ ಭಾಷೆಯ ವ್ಯಾಕರಣದ ಬಗ್ಗೆ ಅರಿವು ಮೂಡಿಸುವುದು ಮತ್ತು ಕನ್ನಡ ಭಾಷಾ ರಚನೆಯಲ್ಲಿನ											
ನಿಯಮಗಳನ್ನು ಪರಿಚಯಿಸುವುದು.											
3.	ಕನ್ನಡ ಭಾಷಾ ಬರೆಹದಲ್ಲಿ ಕಂಡುಬರುವ ದೆ	ೋಷಗಳು ಹಾಗು (ಅವುಗಳನಿವಾರಣೆ.								
4.	ಸಾಮಾನ್ಯ ಅರ್ಜಿಗಳು, ಸರ್ಕಾರಿ ಮತ್ತು ಅಂ	ರೆಸರ್ಕಾರಿ ಪತ್ರ ವ್ಯ	ವಹಾರದ ಬಗ್ಗೆ ಅರಿವು ಮೂಡಿಡಿಸು	ವುದು.							
5.	ಕನ್ನಡ ಭಾಷಾಭ್ಯಾಸ, ಸಾಮಾನ್ಯ ಕನ್ನಡ ಹ	ನಾಗೂ ಆಡಳಿತ ಕನ	<u>ನ್ನ</u> ಡ ದಪದಗಳ ಪರಿಚಯ ಮಾಡಿ ಕೊ	ಾಡುವುಧು.							
UNIT - I Uiundruit: 1. ಕರ್ನಾಟಕ ಸಂಸ್ಕೃತಿ: ಹಂಪನಾಗರಾಜಯ್ಯೆ 2. ಕರ್ನಾಟಕದ ಏಕೀಕರಣ: ಒಂದು ಅಪೂರ್ವಚರಿತ್ರೆ - ಜಿ. ವೆಂಕಟಸುಬ್ಬಯ್ಯೆ 3. ಅಡಳಿತ ಭಾಷೆಯಾಗಿ ಕನ್ನಡ - ವಿತಾವಿಯ ಆಡಳಿತ ಕನ್ನಡ ಪುಸ್ತಕದಿಂದ ಆಯ್ದ ಲೇಖನ Baigraphi (ಅಧುನಿಕಪೂರ್ವ) 1. ವಚನಗಳು: ಬಸವಣ್ಣ, ಅಕ್ಕಮಹಾದೇವಿ, ಅಲ್ಲಮಪ್ರಭು, ಆಯ್ದಕ್ಕಿಮಾರಯ್ಯ, ಜೇಡರದಾಸಿಮಯ್ಯ, ಆಯ್ದಕ್ಕಿಲಕ್ಕಮ್ಮ 2. ಕೀರ್ತನಗಳು: ಅದರಿಂದೇನು ಫಲ ಇದರಿಂದೇನು ಫಲ - ಪುರಂದರದಾಸ 3. ತಲ್ಲಣಿಸದಿರು ಕಂಡ್ಯ ತಾಳುಮನವೆ - ಕನಕದಾಸ 4. ತತ್ವಪದಗಳು: ಸಾವಿರ ಕೊಡಗಳಸುಟ್ಟು - ಶಿಶುನಾಳಪಂಥಷರೀಷ 5. ಶಿವಯೋಗಿ: ಬಾಲಲೀಲಾ ಮಹಾಂತ ಶಿವಯೋಗಿ 6. ಜನಪದಗೀತೆ: ಬೀಸುವಷದ, ಬಡವರಿಗೆ ಸಾವ ಕೊಡಬೇಡ											
	ರಾದ (ಜಾದು ನಿಕು	UNIT – II									
0	ರಾಗ (ಆಧುನಿಕ) ಕುತಿನು ನ ಕರ್ಷಡಿ ವಿ ಜೆ										
1. ಮಂ	ಕುತಿಮ್ಮನ ಕಗ್ಗ. ಡಿ.ವಿ.ಜಿ.										
1. ಮಂ 2. ಕುರ	ಕುತಿಮ್ಮನ ಕಗ್ಗ: ಡಿ.ವಿ.ಜಿ. ಬಡು ಕಾಂಚಾಣ: ದ.ರಾ.ಬೇಂದ್ರೆ			06							
1. ಮಂ 2. ಕುರ 3. ಹೊ	ಕುತಿಮ್ಮನ ಕಗ್ಗ: ಡಿ.ವಿ.ಜಿ. ಬಡು ಕಾಂಚಾಣ: ದ.ರಾ.ಬೇಂದ್ರೆ ಸಬಾಳಿನ ಗೀತೆ: ಕುವೆಂಪು			06 Hours							
1. ಮಂ 2. ಕುರ 3. ಹೊ 4. ಹೆಂ	ಕುತಿಮ್ಮನ ಕಗ್ಗ: ಡಿ.ವಿ.ಜಿ. ಬಡು ಕಾಂಚಾಣ: ದ.ರಾ.ಬೇಂದ್ರೆ										

7. ಚೋಮನ ಮಕ್ಕಳ ಹಾಡು: ಸಿದ್ದೇ	ರಿಂಗಯ್ಯ	

ತಾಂತ್ರಿಕ ವ್ಯಕ್ತಿಪರಿಚಯ, ಕಥೆ ಮತ್ತು ಪ್ರವಾಸ ಕಥನ

- 1. ಡಾ. ಸ ರ್ಎಂ ವಿಶ್ವೇಶ್ವರಯ್ಯ ವ್ಯಕ್ತಿ ಮತ್ತು ಐತಿಹ್ಯ: ಎ ಎನ್ಮೂರ್ತಿ ರಾವ್
- 2. ಯುಗಾದಿ: ವಸುಧೇಂದ್ರ

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3. ಮೆಗಾನೆ ಎಂಬ ಗಿರಿಜನ ಪರ್ವತ: ಹಿ. ಚಿ. ಬೋರಲಿಂಗಯ್ಯ

UNIT – III

ವಿಜ್ಞಾನ ವ	ುತ್ತು	ತಂತ್ರಜ್ಞಾನ:	
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- 1. ಕರಕುಶಲ ಕಲೆಗಳು ಮತ್ತು ಪರಂಪರೆಯ ವಿಜ್ಞಾನ. ಕರೀಗೌಡ ಬೀಚನಹಳ್ಳಿ
- 2. 'ಕ' ಮತ್ತು 'ಬ' ಬರಹ ತಂತ್ರಾಂಶಗಳು ಮತ್ತು ಕನ್ನಡ ಚೈಪಿಂಗ್
- 3. ಕನ್ನಡ: ಕಂಪ್ಯೂಟರ್ಶಬ್ದಕೋಶ
- 4. ತಾಂತ್ರಿಕ ಪದಕೋಶ. ತಾಂತ್ರಿಕ ಹಾಗೂ ಪಾರಿಭಾಷಿಕ ಕನ್ನಡ ಪದಗಳು

Course Outcomes: At the end of the course student will be able to

1.	ಪದವಿ ವಿದ್ಯಾರ್ಥಿಗಳಾಗಿರುವುದರಿಂದ ಸಾಂಸ್ಕ್ರತಿಕ ಕನ್ನಡದ ಜೊತೆಗೆ ಕ್ರಿಯಾತ್ಮಕ ಕನ್ನಡವನ್ನು, ಕನ್ನಡಸಾಹಿತ್ಯ,
	ಸಂಸ್ಕೃತಿ ಮತ್ತು ನಾಡುನುಡಿಯ ಪರಿಚಯ ಮಾಡಿಕೊಡುವುದು.

- ವಿದ್ಯಾರ್ಥಿಗಳಲ್ಲಿ ಕನ್ನಡಭಾಷೆಯ ವ್ಯಾಕರಣದ ಬಗ್ಗೆ ಅರಿವು ಮೂಡಿಸುವುದು ಮತ್ತು ಕನ್ನಡ ಭಾಷಾ ರಚನೆಯಲ್ಲಿನ ನಿಯಮಗಳನ್ನು ಪರಿಚಯಿಸುವುದು.
- 3. ಕನ್ನಡ ಭಾಷಾ ಬರೆಹದಲ್ಲಿ ಕಂಡುಬರುವ ದೋಷಗಳು ಹಾಗು ಅವುಗಳ ನಿವಾರಣೆ.
- 4. ಸಾಮಾನ್ಯ ಅರ್ಜಿಗಳು, ಸರ್ಕಾರಿ ಮತ್ತು ಅರೆ ಸರ್ಕಾರಿ ಪತ್ರ ವ್ಯವಹಾರದ ಬಗ್ಗೆ ಅರಿವು ಮೂಡಿಸುವುದು.
- 5. ಕನ್ನಡ ಭಾಷಾಭ್ಯಾಸ, ಸಾಮಾನ್ಯ ಕನ್ನಡ ಹಾಗೂ ಆಡಳಿತ ಕನ್ನಡದ ಪದಗಳ ಪರಿಚಯ ಮಾಡಿಕೊಡುವುಧು.

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12		PSO.	Ļ
↓ Course Outcomes													1	2	3
HU1003-1.1	-	-	-	-	-	-	-	3	-	-	1	1			
HU1003-1.2	-	-	-	-	-	-	-	2	-	-	1	1			
HU1003-1.3	-	-	2	-	-	-	1	2	-	-	1	1			
HU1003-1.4	-	-	-	-	-	-	-	1	-	-	I	-			
HU1003-1.5	-	-	1	-	-	-	-	3	-	-	1	1			

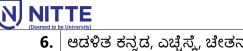
1: Low 2: Medium 3: High

03

Hours

REFERENCE MATERIALS:

- **1.** ಸಂಕ್ಷಿಪ್ತ ಕನ್ನಡನಿಗಂಟು (ಪರಿಷ್ಕ್ರತ), ಕನ್ನಡ ಸಾಹಿತ್ಯ ಪರಿಷತ್, ಬೆಂಗಳೂರು.
- 2. ಆಡಳಿತ ಪದಕೋಶ, ಕನ್ನಡ ಅಭಿವೃದ್ಧಿಪ್ರಾಧಿಕಾರ, ಬೆಂಗಳೂರು.
- ಕಾನೂನು ಪದಕೋಶ (ಪರಿಷ್ಕ್ರತ) ಕನ್ನಡ- ಇಂಗ್ಲಿಷ್, ಕನ್ನಡ ಮತ್ತು ಸಂಸ್ಕೃತಿ ನಿರ್ದೇಶನಾಲಯ, ಬೆಂಗಳೂರು.
- **4.** ಡಿ.ಎನ್. ಶಂಕರ್ಭಟ್, ಕನ್ನಡವಾಕ್ಯಗಳ ಒಳರಚನೆ, ೨೦೦೬, ಭಾಷಾಪ್ರಕಾಶನ, ಮೈಸೂರು.
- 5. ಕನ್ನಡ ಭಾಷಿಕ (ಅವಿಸ್ತರ)- ಪ್ರಬಂಧ ಮತ್ತು ಆಡಳಿತ ಕನ್ನಡ, ಕರ್ನಾಟಕ ರಾಜ್ಯ ಮುಕ್ತ ವಿಶ್ವವಿದ್ಯಾಲಯ, ಮೈಸೂರು.



ಆಡಳಿತ ಕನ್ನಡ, ಎಚ್ಚೆಸ್ಕೆ, ಚೇತನ ಬುಕ್ಹೌಸ್, ಮೈಸೂರು.

Course Code	HU1003-1	Course Type	MNC
Teaching Hours/Week (L: T: P: S)	1:0:0:0	Credits	0
Total Teaching Hours	15+0+0+0	CIE + SEE Marks	50+0
Teaching De	epartment: Any	Department	
Course Objectives:			
1. The course will enable the stud	lents to cognize	e Kannada and communica	te in basic
Kannada language.	5		
	UNIT - I		
Basic Kannada Grammar			
Personal Pronouns, Possessive Forms, Inte	errogative words		
Possessive forms of nouns, Dubitive quest		ouns	
Qualitative, Quantitative and Colour Adjee	ctives, Numerals		
Predictive Forms, Locative Case			
Dative Cases, and Numerals			
Ordinal numerals and Plural markers			
Defective / Negative Verbs and Colour Ac	•		
Permission, Commands, encouraging and	0 0	•	06
Accusative Cases and Potential Forms use			
Helping Verbs "iru and iralla", Correspond			
Comparative Deletionship Identification	0	-	Hours
Comparative, Relationship, Identification a	and Negation Wor	-	Hours
Different types of forms of Tense, Time ar	and Negation Wor nd Verbs	ds	Hours
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter	and Negation Wor nd Verbs nse Sentences with	ds	Hours
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information	and Negation Wor nd Verbs nse Sentences with	ds	Hour
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature	and Negation Wor nd Verbs nse Sentences with	ds	Hour
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information	and Negation Wor nd Verbs nse Sentences with	ds	Hour
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature	and Negation Wor nd Verbs nse Sentences with	ds	Hours
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature	and Negation Wor nd Verbs nse Sentences with	ds	Hours
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature Do's and Don'ts in Learning a Language	and Negation Wor nd Verbs nse Sentences with about the State	ds	Hours 06
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature	and Negation Wor nd Verbs nse Sentences with about the State	ds	Hours 06 Hours
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature Do's and Don'ts in Learning a Language	and Negation Wor nd Verbs nse Sentences with about the State	ds	06
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature Do's and Don'ts in Learning a Language	and Negation Wor nd Verbs nse Sentences with about the State UNIT – II	ds Verb Forms	06
Different types of forms of Tense, Time ar Formation of Past, Future and Present Ter Karnataka State and General Information Kannada Language and Literature Do's and Don'ts in Learning a Language	and Negation Wor nd Verbs nse Sentences with about the State UNIT – II	ds Verb Forms	06

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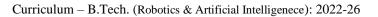
- **1.** Understand the parts of speech of Kannada
- **2.** Know the script in Kannada
- 3. Able to Converse daily usages in Kannada
- **4.** Enrich Basic Kannada Vocabulary
- **5.** Have knowledge about Karnataka and its culture

Course Outcomes Mapping with Program Outcomes & PSO

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	PS	O ↓
↓ Course Outcomes													1	2
HU1003-1.1	-	-	-	-	-	-	-	3	-	-	1	1		
HU1003-1.2	I	-	-	-	-	-	-	2	-	-	1	1		
HU1003-1.3	I	-	2	-	-	-	1	2	-	-	1	1		
HU1003-1.4	I	-	-	-	-	-	-	1	-	-	-	I		
HU1003-1.5	I	-	1	-	-	-	-	3	-	-	1	1		
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1: Low 2: Medium 3: High

REFERENCE MATERIALS: 1. English –Kannada Rapidex Dictionary of Spoken Words, S N Raju, Bengaluru 2. English Kannada Standard Dictionary, D K Bharadwaj, Sankeshwar Printers Pvt Ltd, Bengaluru 3. ಮಾತಾಡುವ ಕನ್ನಡ, ಕನ್ನಡ ಸಾಹಿತ್ಯ ಪರಿಷತ್, ಬೆಂಗಳೂರು (೨೦೧೬). 4. ಸಂಕ್ಷಿಪ್ತ ಕನ್ನಡನಿಗಂಟು (ಪರಿಷ್ಕೃತ), ಕನ್ನಡ ಸಾಹಿತ್ಯ ಪರಿಷತ್, ಬೆಂಗಳೂರು. 5. ಆಡಳಿತ ಪದಕೋಶ, ಕನ್ನಡ ಅಭಿವೃದ್ಧಿಪ್ರಾಧಿಕಾರ, ಬೆಂಗಳೂರು. 6. ಕನ್ನಡ ಭಾಷಾಕೈಪಿಡಿ, ಸಂಗಮೇಶ್ಸವ ದತ್ತಿಮಠ, ರೂಪರಶ್ಮಿ ಪ್ರಕಾಶನ, ಗುಲ್ಬರ್ಗ, ೧೯೯೫. 7. ಡಿ.ಎನ್. ಶಂಕರ್ಭಟ್, ಕನ್ನಡ ವಾಕ್ಯಗಳ ಒಳ ರಚನೆ, ೨೦೦೬, ಭಾಷಾ ಪ್ರಕಾಶನ, ಮೈಸೂರು. 8. ಕಾನೂನು ಪದಕೋಶ (ಪರಿಷ್ಕೃತ) ಕನ್ನಡ- ಇಂಗ್ಲಿಷ್, ಕನ್ನಡ ಮತ್ತು ಸಂಸ್ಕೃತಿ ನಿರ್ದೇಶನಾಲಯ, ಬೆಂಗಳೂರು.





LIST OF OPEN ELECTIVE COURSES

SI No.	Department	Course Codes	Open Elective Courses
1	BT	BT1501-1	Bio Fuel Engineering
2	BT	BT1502-1	Solid Waste Management
3	CS	CS2501-1	Fundamentals of AI and ML
4	CS	CS2502-1	Introduction to Data Structures
5	CV	CV2501-1	Disaster Management
6	CV	CV2502-1	Environmental Hygiene, Sanitation and Waste Management
7	CV	CV2503-1	Environmental Impact Assessment
8	CV	CV2504-1	Introduction to Geoinformatics
9	CY	CY2501-1	Corrosion Science (Only for CV and ME)
10	CY	CY2502-1	Natural Products Chemistry (Only For BT)
11	EC	EC1501-1	Artificial Neural Network Systems
12	EC	EC1502-1	Introduction to MATLAB Programming: A Hands-on Approach
12	EC	EC1302-1	(only for CV and BT)
13	EC	EC1503-1	Robotics
14	EC	EC2501-1	Consumer Electronics
15	EC	EC2502-1	PCB Design and Fabrication
16	EC	EC2503-1	Space Technology and Applications
17	EE	EE2501-1	Battery Management System
18	EE	EE2502-1	Biomedical Instrumentation
19	EE	EE2503-1	Electric Vehicle Technology
20	EE	EE2504-1	Fundamentals of PLC and its applications
21	EE	EE2505-1	Motors and Motor Control Circuits
22	EE	EE2506-1	Non-Conventional Energy sources
23	HU	HU1501-1	Elements of Yoga
24	HU	HU1502-1	Intellectual Property Rights
25	HU	HU1503-1	Introduction to German Language
26	HU	HU1504-1	Introduction to Japanese Language
27	HU	HU1505-1	National Cadet Corps: Organization, Functions & Capabilities
28	HU	HU1506-1	Overview of Indian Culture
29	HU	HU1507-1	Philosophy
30	HU	HU1508-1	Principles of Physical Education
31	HU	HU1509-1	Indian Culture – Dance *
32	HU	HU1510-1	Indian Culture – Music *
33	HU	HU1511-1	Engineering Ethics *
34	HU	HU1512-1	Art of Communication and Interpersonal Skills*
35	HU	HU2501-1	Common sense and Critical Thinking
36	HU	HU2502-1	Linguistics & Language Technology
37	IS	IS2501-1	Introduction to Cyber Security (except EC, EE, AM, AD, CC, CS, IS)
38	IS	IS2502-1	Python Application Programming
39	IS	IS2503-1	Software Engineering Practices
40	IS	IS2504-1	Web technologies
41	MA	MA1501-1	Graph Theory (for BT, CV, EC, EE, ME and RI)

	E to be University		Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2022-26
SI No.	Department	Course Codes	Open Elective Courses
42	MA	MA1502-1	Number Theory
43	MA	MA3501-1	Linear Algebra (for BT, CV, EE, ME and RI)
44	ME	ME1501-1	Automotive Engineering
45	ME	ME1502-1	Industrial Pollution Control
46	ME	ME1503-1	Sustainable Development Goals
47	ME	ME1504-1	Technology Innovation
48	MG	MG1501-1	Human Resource Management
49	MG	MG1502-1	Management Accounting and Control Systems
50	MG	MG1503-1	Operations and Quality Management
51	MG	MG1504-1	Organizational Behaviour
52	MG	MG1505-1	Taxation for Engineers
53	MG	MG1506-1	Working Capital Management
54	PH	PH2501-1	Nanotechnology
55	PH	PH2502-1	Optoelectronic Devices (EC, EE, CSE, ISE, AM and CC branches)
56	RI	RI2501-1	Autonomous Mobile Robots
57	RI	RI2502-1	Medical Robotics (for all except AI)
58	RI	RI2503-1	PLC Control of Hydraulic and Pneumatic Circuits (for all except AI)

* For students admitted under Twinning Program

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Description and classification of Biofuels; Primary biomass: Plant Materials-Woody biomass Lignocellulosic and agroindustrial by-products, starchy and sugary crops. Secondary biomass Waste residues and co-products- wood residues, animal waste, municipal solid waste. Bioma production for fuel – algal cultures, yeasts (Lipid and carbohydrate). Production of biodiesel: Sources of Oils – edible and non-edible; Esterification ar Transesterification. Free fatty acids; saponification; Single step and two step biodiesel productio Catalysts for biodiesel production – homogeneous (alkali/acidic) and heterogeneous; Lipas mediated process. General procedure of biodiesel production and purification Quality Contr. Aspects: GC analysis of biodiesel, fuel property measurements, ASTM (D-6751) and India standards (IS15607). Algal Biodiesel production. Production of Bioethanol: Bioethanol production using Sugar; Starch and Lignocellulos feedstocks; Pretreatment of lignocellulosic feed stock UNIT-II Biohydrogen and Microbial Fuel Cells Enzymes involved in H ₂ Production; Photobiological H ₂ Production: Biophotolysis and Phot fermentation; H ₂ Production by Fermentation: Biochemical Pathway, Batch Fermentation, Facto affecting H ₂ production. Microbial Fuel cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartmer Microbial Fuel cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartmer Microbial Cultures, Redox Mediators, Exchange Membrane, Power Density; MFC Performance Power Density, Single vs Two-Chamber Designs, Wastewater Treatment Effectiveness; Advances in MFC. UNIT-III Recovery of Biological Conversion Products IO Hours Bio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan	BIOF	UEL ENGIN	EERING	
Total Teaching Hours: 40 CIE + SEE Marks: 50+50 Teaching Department: Biotechnology Course Objectives: 1. To learn the fundamental concepts of biofuels, types of biofuels, their production technologies. 2. To learn the concepts of feedstock utilization and energy conversion technologies. UNIT-I Liquid Biofuels Description and classification of Biofuels; Primary biomass: Plant Materials-Woody biomass Lignocellulosic and agroindustrial by-products, starchy and sugary crops. Secondary biomass Waste residues and co-products- wood residues, animal waste, municipal solid waste. Bioma production for fuel – algal cultures, yeasts (Lipid and carbohydrate). Production of biodiesel: Sources of Oils – edible and non-edible; Esterification ar Transesterification. Free fatty acids; saponification; Single step and two step biodiesel productio Catalysts for biodiesel production – homogeneous (alkal/acidic) and heterogeneous, Lipa: mediated process. General procedure of biodiesel production and purification Quality Contr Aspects: GC analysis of biodiesel, fuel property measurements, ASTM (D-6751) and India standards (IS15607). Algal Biodiesel production. Production of Bioethanol: Bioethanol production using Sugar; Starch and Lignocellulos feedstocks; Pretreatment of lignocellulosic feed stock UNIT-II 15 Hours Biohydrogen and Microbial Fuel Cells 15 Hours Enzymes involved	Course Code:	BT1501-1	Course Type:	OEC
Teaching Department: Biotechnology Course Objectives: 1. To learn the fundamental concepts of biofuels, types of biofuels, their production technologies. 2. To learn the concepts of feedstock utilization and energy conversion technologies. UNIT-1 Liquid Biofuels 15 Hours Description and classification of Biofuels; Primary biomass: Plant Materials-Woody biomas Lignocellulosic and agroindustrial by-products, starchy and sugary crops. Secondary biomass residues and co-products- wood residues, animal waste, municipal solid waste. Bioma production of fuel – algal cultures, yeasts (Lipid and carbohydrate). Production of biodiesel: Sources of Oils – edible and non-edible; Esterification ar Transesterification. Free fatty acids; saponification; Single step and two step biodiesel productio Catalysts for biodiesel production – homogeneous (alkal/acidic) and heterogeneous; Lipaa mediated process. General procedure of biodiesel production and purification Quality Contr Aspects: GC analysis of biodiesel, fuel property measurements, ASTM (D-6751) and India standards (IS15607). Algal Biodiesel production. Production of Bioethanol: Bioethanol production using Sugar; Starch and Lignocellulos feedstocks; Pretreatment of lignocellulosic feed stock UNIT-II 15 Hours Biohydrogen and Microbial Fuel Cells 15 Hours Enzymes involved in H ₂ Production; Photobiological H ₂ Production: Biophotolysis and Phoi fermentation; H ₂ Production by Fermentation: Biochemical Pathway, Batch Fermentation, Facto affecti	Teaching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03
Course Objectives:	Total Teaching Hours:	40	CIE + SEE Marks:	50+50
1. To learn the fundamental concepts of biofuels, types of biofuels, their production technologies. 2. To learn the concepts of feedstock utilization and energy conversion technologies. UNIT-I Liquid Biofuels Description and classification of Biofuels; Primary biomass: Plant Materials-Woody biomass Lignocellulosic and agroindustrial by-products, starchy and sugary crops. Secondary biomass Ugonoclus and co-products- wood residues, animal waste, municipal solid waste. Bioma production for fuel – algal cultures, yeasts (Lipid and carbohydrate). Production of biodiesel: Sources of Oils – edible and non-edible; Esterification ar transesterification. Free fatty acids; saponification; Single step and two step biodiesel productio Catalysts for biodiesel production – homogeneous (alkali/acidic) and heterogeneous; Lipa: mediated process. General procedure of biodiesel production and purification Quality Contre Aspects: GC analysis of biodiesel, fuel property measurements, ASTM (D-6751) and India standards (IS15607). Algal Biodiesel production. Production of Bioethanol: Bioethanol: Bioethanol production using Sugar; Starch and Lignocellulos feedstocks; Pretreatment of lignocellulosic feed stock Biohydrogen and Microbial Fuel Cells 15 Hours Enzymes involved in H2 Production; Photobiological H2 Production: Biophotolysis and Phot fermentation; H2 Production, Carbon sources, Detection and Quantification of H2. Reactors for bioridal Fuel Cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartment Microbial Cultures, Redox Mediators, Exchange Membrane, Power Density; MFC Performanc Power Dens	Teaching D	epartment: E	Biotechnology	
1. To learn the fundamental concepts of biofuels, types of biofuels, their production technologies. 2. To learn the concepts of feedstock utilization and energy conversion technologies. UNIT-I Liquid Biofuels Description and classification of Biofuels; Primary biomass: Plant Materials-Woody biomass Lignocellulosic and agroindustrial by-products, starchy and sugary crops. Secondary biomass Ugonoclus and co-products- wood residues, animal waste, municipal solid waste. Bioma production for fuel – algal cultures, yeasts (Lipid and carbohydrate). Production of biodiesel: Sources of Oils – edible and non-edible; Esterification ar transesterification. Free fatty acids; saponification; Single step and two step biodiesel productio Catalysts for biodiesel production – homogeneous (alkali/acidic) and heterogeneous; Lipa: mediated process. General procedure of biodiesel production and purification Quality Contre Aspects: GC analysis of biodiesel, fuel property measurements, ASTM (D-6751) and India standards (IS15607). Algal Biodiesel production. Production of Bioethanol: Bioethanol: Bioethanol production using Sugar; Starch and Lignocellulos feedstocks; Pretreatment of lignocellulosic feed stock Biohydrogen and Microbial Fuel Cells 15 Hours Enzymes involved in H2 Production; Photobiological H2 Production: Biophotolysis and Phot fermentation; H2 Production, Carbon sources, Detection and Quantification of H2. Reactors for bioridal Fuel Cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartment Microbial Cultures, Redox Mediators, Exchange Membrane, Power Density; MFC Performanc Power Dens	Course Objectives:			
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Enzymes involved in H ₂ Production; Photobiological H ₂ Production: Biophotolysis and Phot fermentation; H ₂ Production by Fermentation: Biochemical Pathway, Batch Fermentation, Facto affecting H ₂ production, Carbon sources, Detection and Quantification of H ₂ . Reactors for biohydrogen production. Microbial Fuel cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartmer Microbial Cultures, Redox Mediators, Exchange Membrane, Power Density; MFC Performance Methods: Substrate & Biomass Measurements, Basic Power Calculations, MFC Performance Power Density, Single vs Two-Chamber Designs, Wastewater Treatment Effectiveness; Advances in MFC. UNIT-III Recovery of Biological Conversion Products Bio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan	Catalysts for biodiesel production – h mediated process. General procedure of Aspects: GC analysis of biodiesel, fue standards (IS15607). Algal Biodiesel pro- Production of Bioethanol: Bioethanol	omogeneous of biodiesel pro l property m duction. production sic feed stock	(alkali/acidic) and heterogroduction and purification easurements, ASTM (D-67 using Sugar; Starch and	geneous; Lipase Quality Control (51) and Indian
Enzymes involved in H ₂ Production; Photobiological H ₂ Production: Biophotolysis and Phot fermentation; H ₂ Production by Fermentation: Biochemical Pathway, Batch Fermentation, Facto affecting H ₂ production, Carbon sources, Detection and Quantification of H ₂ . Reactors for biohydrogen production. Microbial Fuel cells: Biochemical Basis; Fuel Cell Design: Anode & Cathode Compartmer Microbial Cultures, Redox Mediators, Exchange Membrane, Power Density; MFC Performance Methods: Substrate & Biomass Measurements, Basic Power Calculations, MFC Performance Power Density, Single vs Two-Chamber Designs, Wastewater Treatment Effectiveness; Advances in MFC. UNIT-III Recovery of Biological Conversion Products Bio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan	Biohydrogen and Microbial Fuel Cells	1		15 Hours
Recovery of Biological Conversion Products10 HoursBio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan	fermentation; H ₂ Production by Ferment affecting H ₂ production, Carbon source biohydrogen production. Microbial Fuel cells: Biochemical Basis Microbial Cultures, Redox Mediators, E Methods: Substrate & Biomass Measu	ation: Biocher ces, Detectior s; Fuel Cell D xchange Mer irements, Bas	mical Pathway, Batch Ferme n and Quantification of H Design: Anode & Cathode nbrane, Power Density; MI ic Power Calculations, MF	Compartment, FC Performance C Performance
Recovery of Biological Conversion Products10 HoursBio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan		UNIT-III		
Bio gasification of municipal solid waste: Anaerobic processing; Types of digesters, Biogas plan	Recovery of Biological Conversion Pro			10 Hours
in India.			rocessing; Types of digeste	rs, Biogas plant
	in India.		-	-

Thermochemical processing: Planning an incineration facility, Incineration technologies: Mass burning system; Refuse derived fuel (RDF) system; modular incineration; Fluidized bed incineration; energy recovery; Fuel production through biomass incineration, Pyrolysis and gasification, hydrothermal processing.

Course Outcomes: At the end of the course student will be able to

1.	Mark the significance of biofuels and raw materials and Identify suitable feedstock
	for production of biofuels.
2.	Illustrate the production of liquid biofuels from various feed stocks.
3.	Demonstrate production of biohydrogen using microbial sources.
4.	Extend the concepts of microbial fuel cells towards development of specific
	application.
5.	Understand and apply the concepts of biochemical processing to harvest energy
	from waste products/streams

Course Outcomes Mapping with Program Outcomes

e outcomes mapping wit		e g. a										
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
BT1501-1.1	I	2	-	-	-	I	-	I	1	-	-	-
BT1501-1.2	1	2	-	-	-	1	-	1	1	-	-	-
BT1501-1.3	1	2	-	-	-	1	-	1	1	-	-	-
BT1501-1.4	1	2	-	-	-	1	-	1	1	-	-	-
BT1501-1.5	-	2	-	-	-	-	-	-	1	_	-	-

1: Low 2: Medium 3: High

VITTF

REFERENCE BOOKS:

- **1.** Drapcho, C. M., Nhuan, N. P.and Walker, T. H., "Biofuels Engineering Process Technology", Mc Graw Hill Publishers, New York, 2008.
- **2.** Jonathan R.M, Biofuels, "Methods and Protocols (Methods in Molecular Biology Series)", Humana Press, New York, 2009.
- **3.** Olsson L. (Ed.), "Biofuels (Advances in Biochemical Engineering/Biotechnology Series", Springer-Verlag Publishers, Berlin, 2007.
- **4.** Glazer, A. and Nikaido, H., "Microbial Biotechnology Fundamentals of Applied Microbiology", 2 Ed., Cambridge University Press, 2007.
- **5.** Godfrey Boyle (Ed). "Renewable Energy- Power for sustainable future", 3rd Ed. Oxford. 2012.
- **6.** Ramachandran, T. V., "Management of municipal solid waste", Environmental Engineering Series. Teri Press, 2016.

SOLID WASTE MANAGEMENT

UNIT-III	
Teaching Department: Biotechnology Course Objectives: 1. To learn types of solid wastes, collection, treatment and disposal methods. 2. To understand various processing techniques and regulations of treatment a disposal. UNIT-I Introduction to Solid Wastes and its Segregation & Transportation Solid waste - Definition, Sources of waste, Classification of Solid waste, Characteristics of Waste (Physical, Chemical, Biological), Solid waste problems – impact on environment and he Concept of waste reduction, recycling and reuse. Waste collection and segregation: Solid waste generation, Onsite handling and segregat wastes at source, Collection and storage of municipal solid wastes, Equipment used and man required in collection, Collection systems and routes. Transportation: Transportation: UNIT-II Processing Techniques, Recovery of Resources and Waste Disposal 15 He UNIT-II Processing Techniques: Unit operations for separations and processing, mechanical and the volume reduction, Incineration of solid wastes – process and types of incinerators (liquid ing rotary kiln and fluid bed), Biological processing – composting, vermicomposting, biomethar fermentation, Drying and dewatering of wastes. Recovery of Resources: Heat recovery in incineration process, energy recovery and convers products from biological processes. Dumping of	
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UNIT-III	
Legislative trends and impacts: Major legislations, Government agencies. Municipal Solid	urs
Management Act (1999), Hazardous Wastes (Handling and Management) Rules, Biomedical	
(Handling and Management) Rule (1998), e-Waste (Management and Handling) Rule 2011.	Vaste
Planning and developing a site for solid waste management, Site Remediation: Assessmer	Vaste
Inspection, Remedial techniques, Siting guidelines.	Vaste Vaste
	Vaste Vaste
Course Outcomes: At the end of the course student will be able to	Vaste Vaste
	Vaste Vaste
1. Identify the sources, classification and characteristics of solid wastes	Vas Vas

- 2. Develop insight into the collection, transfer, and transport of solid waste.
- **3.** Apply waste processing techniques and recovery of resources from the waste.
- **4.** Select the alternatives of solid waste disposals and its impacts.
- 5. Acquire knowledge about solid and hazardous waste management legislative rules.

Course Outcomes Mapping with Program Outcomes

		<u> </u>										
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
BT1502-1.1	1	-	-	-	-	-	-	-	1	-	-	-
BT1502-1.2	1	1	-	1	-	1	1	-	1	-	-	-
BT1502-1.3	-	2	-	-	-	-	-	-	1	-	-	-
BT1502-1.4	-	2	-	-	-	1	1	-	1	-	-	-
BT1502-1.5	1	-	-	-	-	-	-	-	1	-	-	1

1: Low 2: Medium 3: High

NITTE

REFER	ENCE BOOKS:
1.	Tchobanaglous, G., Theisen, H. and Vigil, S. A. "Integrated Solid Waste Management",
	McGraw – Hill. 1993.
2.	Tchobanoglous, G., Thiesen, H., Ellasen, "Solid Waste Engineering Principles and
	Management", McGraw – Hill, 1997.
3.	Landrefh, R. E. and Sundaresan, B. B. "Solid Waste Management in Developing
	Countries", Indian National Scientific Documentation Centre. New Delhi, 2000.

peemed to be	FUNDAME	NTALS OF A	I AND ML	
C οι	urse Code:	CS2501-1	Course Type:	OEC
Теа	ching Hours/Week (L: T: P: S):	3:0:0:0	Credits:	03
Tot	al Teaching Hours:	40+0+0	CIE + SEE Marks:	50
Pre	requisite	CS1002-1		
	Teaching Department	t: Computer So	cience & Engineering	
Coui	rse Objectives:			
1.	Analyze the most fundamenta	al knowledge	to the students so that	they can
	understand what the AI is.			
2.	Gain a historical perspective of			
3.	Investigate applications of AI	•	5 5 1	t systems,
4.	artificial neural networks and ot			tom chall
4.	Experience AI development to and/or data mining tool.	ois such as all	Al language, expert sys	stem snen,
5.	Explore the current scope, po	tential, limitatio	ons, and implications of	intelligent
	systems.			Jerre
		UNIT-I		
Intra	oduction			
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	ΓE						Curric	culum	– B.T	Tech. (Robotic	s & Arti	ficial Int	elligene
3.	Describe the awaren	ess a	ind a	fund	dame	ental	und	lersta	andi	ng o	fvaric	bus ap	plicati	ons o
	AI techniques in inte	ellige	ent a	agen	ts, e	xper	t sys	tem	s, ar	tificia	al neu	ural ne	etwork	ks and
	other machine learni	ng n	node	els										
4.	Identify and explain	the	pro	ficie	ncy (deve	lopiı	ng a	pplic	catio	ns in	an 'A	I lang	uage
	expert system shell, o	or da	ata m	ninin	g too	ol.								
5.	Explain the fundame	ntal	cond	cept	and	impo	ortar	ice o	of ma	chin	e lear	ning.		
Cours	e Outcomes Mappin	na w	ith F	Prog	ram	Out	com	65						
cours	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→	_				5	Ū		Ū					
	↓ Course													
	Outcomes													
	CS2501-1.1	3	3	-	-	-	-	-	-	-	-	-	-	
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	CS2501-1.3	3	3	-	-	-	-	-	-	-	-	-	-	
	CS2501-1.4	3	3	2	-	-	-	-	-	-	-	-	-	
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	v 2: Medium 3: High BOOKS:			I	- ence	-	- basi	- cs", 1	- Гуре	set ii	- n Bem	- 100 by	- v Wear	set Lt
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INTRODUCTION TO DATA STRUCTURES

	ırse Code:	CS2502-1	Course Type:	OEC
	ching Hours/Week (L:T:P:S):	3:0:0:0	Credits:	010
	al Teaching Hours:	40+0+0	CIE + SEE Marks:	50
	requisite	CS1001-1		50
Fiel				
	Teaching Departmen	t: Computer So	cience & Engineering	
	se Objectives:			
1.	Outline the concepts of data st			
2.	Implement linear data structu applications.	res stacks, que	ues and usage of stacks	in various
3.	Implement the operations of si	ngly linked lists		
4.	Identify and differentiate differe	ent types of bina	ary trees and binary search	trees data
	structures			
5.	Illustrate and classify threaded	binary trees.		
		UNIT-I		
Intro	oduction			15 Hours
Data	Structure, Classification (Primitive	•	•	ions, Arrays,
Data Point	Structure, Classification (Primitive ters and structures, Dynamic Men	•	•	ions, Arrays,
Data Point Linea	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks	nory Allocation	Functions,	
Data Point Linea Introd	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks duction and Definition, Represen	nory Allocation	Functions,	
Data Point Linea Introd	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks	nory Allocation	Functions,	
Data Point Linea Introo stack	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks duction and Definition, Represen	nory Allocation	Functions,	
Data Point Linea Introo stack Appl	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks duction and Definition, Represen ts, Operations on stacks,	nory Allocation tation of stack:	Functions, Array and structure repres	sentation of
Data Point Linea Introo stack Appl Conv	Structure, Classification (Primitive ters and structures, Dynamic Men ar Data Structures – Stacks duction and Definition, Represen as, Operations on stacks, lications of Stack	nory Allocation tation of stack: tion of expre	Functions, Array and structure repres	sentation of
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							Currio	culum	– B.7	Fech.	Robotic	cs & Arti	ificial Int	tellige
1.	Acquire the fundar pointers.	nent	al k	nowl	ledge	e of	var	ious	typ	es c	of dat	ta str	ucture	es a
2.	Apply the fundamen	tal p	orogr	amn	ning	kno	wled	ge o	f da	ta sti	ructur	es to	desig	n sta
	and use them for so	•						5					5	
3.	Apply the fundame	ntal	pro	gran	nmin	ig ki	nowl	edge	e of	dat	a stru	ucture	es to	desi
	queues and use ther	n for	r solv	/ing	prob	lem	S.							
4.	Design various funct	ions	for i	mple	emer	ntati	on o	f lin	ked	list.				
5.	Implement and app	oly tl	he c	once	ept c	of bi	nary	tree	es a	nd b	oinary	searc	ch tre	e da
	structure.													
Cours	e Outcomes Mappir	ng w	ith F		ram		com	es	1	-	r	T		1
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes												<u> </u>	
	CS2502-1.1	-	-	-	-	-	-	-	-	-	-	-	-	-
	CS2502-1.2	3	1	2	-	-	-	-	1	-	-	-	1	-
	CS2502-1.3	3	2	2	-	-	-	-	1	-	-	-	1	
	CS2502-1.4	3	2	-	-	-	-	-	1	-	-	-	1	
	CS2502-1.5	-	-	-	-	-	-	-	-	-	-	-	-]
1: Lov	v 2: Medium 3: High)												
	BOOKS:													
1.	Aaron M. Tenenba			-		-	n& I	Vlosľ	ne J.	Aug	enste	in, "Da	ata Sti	ructi
2	using C", Pearson I						امدم	t	Data	C+			// Drad	
2.	Ellis Horowitz and S Universities Press,		5	1111,	runc	Jame	entai	5 01	Data	Stru	icture	SINC	, zna	ean
DEEEE	RENCE BOOKS:	2014	ŀ.											
1.	Seymour Lipschut		Jata	Ctri	ictur	<u> </u>	Scha	um'c		tling	c″ P	ovicor	1 1 ct	adit
	McGraw Hill, 2014.		Jala	Suc	ictui	CS, .	Scha	ums			:5 , N	evised	1 131	eun
	ks / MOOCs/ NPTEL					-		~						
1.	Data Structures Us													
2.	Data Structures Us 2014	ing (_, Re	ema	Tha	reja,	2nd	edit	ion,	Oxto	ord Ur	niversi	ty Pre	SS,
3.	Introduction to Da	ta St	ruct	ures	by e	dx ,	URL:	<u>http</u>	s://v	vww	.edx.o	org/co	urse/	
4.	Data structures by	Berk	dey,	URL:	<u>http</u>	<u>)//s://p</u>	beop	le.ee	ecs.b	<u>erke</u>	<u>ley</u>			
5.	Advance Data Stru	cture	es by	/ MIT		w , l	JRL:	<u>http</u>	s://w	/ww.	mooc	lab.cl	ub/	
6.	Data Structure by I													rvar

Data Structure by Harvard Extension School, URL: <u>http://www.extension.harvard.</u> 6.



	Cu	rriculum – B.Tech. (Robotics &	c Artificial Intelligenece):
DISAS	STER MANA	GEMENT	
Course Code:	CV2501-1	Course Type	OEC
Teaching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CV1002-1	•	·
Teaching D	epartment: Ci	vil Engineering	
Course Objectives:			
1. Understand difference betwee	en Disaster, Ha	zard, Vulnerability, and	Risk.
2. Know the Types, Trends, Caus	ses, Consequen	ces and Control of Disa	sters
3. Apprehend Disaster Manager	ment Cycle and	Framework.	
4. Know the Disaster Manageme	ent in India		
5. Appreciate Applications of Sc	ience and Tech	nology for Disaster Ma	nagement.
	UNIT-I		
Understanding Disasters			04 Hours
Understanding the Concepts and de	finitions of Disa	ister, Hazard, Vulnerabil	ity, Risk, Capacity
- Disaster and Development, and di	saster manager	ment.	
Types, Trends, Causes, Consequen	ces and Contr	ol of Disasters	10 Hours
Geological Disasters (earthquakes,	landslides, ts	unami, mining); Hydro	o-Meteorological
Disasters (floods, cyclones, lightnin	0		
cold and heat waves) Biological Disa		-	-
Disasters (chemical, industrial, rad	-		-
collapse, rural and urban fire, road		0	
biological disasters) Global Disaster	Trends – Emerg	ging Risks of Disasters –	 Climate Change
and Urban Disasters			
	UNIT-II		
Disaster Management Cycle and F			10 Hours
Disaster Management Cycle and Fra		• •	-
in Disaster Management Pre-Disas		-	
zonation and Micro zonation, Prever	-	•	• •
Preparedness, Capacity Developme		-	
Communication – Search and Rescu		•	
System – Relief and Rehabilitation		-	
Restoration of Critical Infrastructure	-	•	Redevelopment;
IDNDR, Yokohama Strategy, Hyogo	Framework of	Action.	
Disaster Management in India		.	06 Hours
Disaster Management in India: Dis		-	
Lessons Learnt Disaster Managem	ent Act 2005 -	- Institutional and Fina	ncial Mechanism

Lessons Learnt, Disaster Management Act 2005 – Institutional and Financial Mechanism National Policy on Disaster Management, National Guidelines and Plans on Disaster Management; Role of Government (local, state and national), Non-Government and Inter-Governmental Agencies.

UNIT-III

Applications of Science and Technology for Disaster Management06 HoursGeo-informatics in Disaster Management (RS, GIS, GPS and RS) Disaster CommunicationSystem (Early Warning and Its Dissemination) Land Use Planning and Development

Regulations Disaster Safe Designs and Constructions Structural and Non Structural Mitigation of Disasters S&T Institutions for Disaster Management in India

Case Studies

NITTE

04 Hours

Study of Recent Disasters (at local, state and national level), Preparation of Disaster Risk Management Plan of an Area or Sector, Role of Engineers in Disaster Management

Course Outcomes: At the end of the course student will be able to

- Explain Concepts, Types, Trends, Causes of Disasters 1.
- Describe Consequences and Control of Disasters 2.
- Explain Disaster Management Cycle and Framework 3.
- Explain the lesson learnt from the disasters in India and discuss the financial 4. mechanism, roles and responsibilities of Non-Government and Inter-Governmental Agencies for Disaster management
- Describe the Applications of Science and Technology recent disasters, role of 5. engineers for Disaster Management and prepare a report of Disaster Risk Management Plan.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
CV2501-1.1	-	-	-	-	-	3	2	-	-	-	1	2
CV2501-1.2	-	-	-	-	-	3	2	-	-	-	1	2
CV2501-1.3	-	-	-	-	-	3	2	-	-	-	1	2
CV2501-1.4	-	-	-	-	-	3	2	-	-	-	1	2
CV2501-1.5	-	-	-	-	-	3	2	-	-	-	1	2

1: Low 2: Medium 3: High

 Noble, L. , "Introduction to environmental impact assessment. A Guide to Principles and Practice", 2nd edition, Oxford University Press, Don Mills, Ontario, 2010. Larry W. Canter, "Environmental Impact Assessment", McGraw Hill Inc. Singapore, 1996. REFERENCE BOOKS: Morris and Therivel, "Methods of Environmental Impact Assessment", 3rd edition. New York, NY: Routledge, 2009. Hanna, K. S., "Environmental impact assessment", Practice and Participation. 2nd edition. Oxford, University Press, Don Mills, Ontario, 2009. 	TEXTB	OOKS:
1996. REFERENCE BOOKS: 1. Morris and Therivel, "Methods of Environmental Impact Assessment", 3rd edition. New York, NY: Routledge, 2009. 2. Hanna, K. S., "Environmental impact assessment", Practice and Participation. 2nd	1.	
 Morris and Therivel, "Methods of Environmental Impact Assessment", 3rd edition. New York, NY: Routledge, 2009. Hanna, K. S., "Environmental impact assessment", Practice and Participation. 2nd 	2.	
 New York, NY: Routledge, 2009. 2. Hanna, K. S., "Environmental impact assessment", Practice and Participation. 2nd 	REFER	ENCE BOOKS:
	1.	
	2.	• •
E Books / MOOCs/ NPTEL	E Pool	

- http://nptel.ac.in/courses/120108004/ 1.
- http://nptel.ac.in/courses/120108004/module3/lecture3.pdf 2.

ENVIRONMENTAL HYGIENE, SANITATION AND WASTE MANAGEMENT

Course Code: CV2502-1 Course Type OEC

icu	ching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03				
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50				
Pre	Prerequisite CV1002-1							
	Teaching De	epartment: Ci	vil Engineering					
Cou	rse Objectives:	<u>.</u>						
1.	Creation of awareness among and the consequent responsib		Ith issues and Swachh Bh	arath missi				
2.	To understand the culture cleat (Open defecation free) conce Environmental Hygiene.	-	• • •					
3.	To know the importance of sa engineering technology in cor	-		sues & use				
4.	To know the importance of wa water treatment process.			dit and was				
5.	To study the role of student treatment process.	in Swachh Bh	arata Abhiyan, solid and	l waste wat				
_				_				
Was Intro Envir	pective: Environmental Hygie tewater oduction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar	n (SBM)-Missi nitation-Waste	on Objectives-Duration- (Management. Work op	06 Hou Component oportunities				
Was Intro Envir Envir Envir	tewater oduction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar ronmental Hygiene, Sanitation ronmental Hygiene, Sanitation ar	n (SBM)-Missi nitation-Waste and Waste M nd Waste Man	on Objectives-Duration- (Management. Work op lanagement. Participator agement.	06 Hou Component oportunities y Learning				
Was Intro Envir Envir Envir Soci wate	tewater oduction- Swachh Bharath Missio conmental Hygiene-Benefits-Sar conmental Hygiene, Sanitation conmental Hygiene, Sanitation ar ology of environmental hygien er and impacts	n (SBM)-Missi nitation-Waste and Waste M nd Waste Man e manageme	on Objectives-Duration- (Management. Work op lanagement. Participator agement. nt, solid waste and waste	06 Hou Component oportunities y Learning e 08 Hou				
Was Intro Envir Envir Envir Soci Wate Oper and Sche Abhi	tewater oduction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar ronmental Hygiene, Sanitation ronmental Hygiene, Sanitation ar ology of environmental hygien	n (SBM)-Missi nitation-Waste and Waste Man e manageme owards waste-o ects, Roles & ca Managemer nication, Role o astewater Disp	on Objectives-Duration- (Management. Work op lanagement. Participator agement. nt, solid waste and waste Goals of SBA. Community Responsibilities, Job Cha nt, Culture of Cleanliness (of Habits and Attitudes in	06 Hou Component oportunities (Learning e 08 Hou Consciousn rts, Frequer Swachh Bha Environme				
Was Intro Envir Envir Soci Wate Oper and Sche Abhi Hygi	tewater duction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar ronmental Hygiene, Sanitation ar ology of environmental hygien er and impacts In Defecation-Habits & attitude to Engagement on Sanitation Aspe- edules and Timelines in Swachhat yan), Behaviour Change Commun- ene Management, Waste and Wa	n (SBM)-Missi nitation-Waste and Waste Man d Waste Man e manageme wards waste- ects, Roles & a Managemer nication, Role	on Objectives-Duration- (Management. Work op lanagement. Participator agement. nt, solid waste and waste Goals of SBA. Community Responsibilities, Job Cha nt, Culture of Cleanliness (of Habits and Attitudes in	06 Hou Component oportunities (Learning e 08 Hou Consciousn rts, Frequer Swachh Bha Environmen				
Was Intro Envir Envir Soci Wate Oper and Sche Abhi Hygi Infra Cont Mair Toile Diffe	tewater oduction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar ronmental Hygiene, Sanitation ronmental Hygiene, Sanitation ar ology of environmental hygien er and impacts In Defecation-Habits & attitude to Engagement on Sanitation Aspe edules and Timelines in Swachhat yan), Behaviour Change Commun	n (SBM)-Missi nitation-Waste and Waste Man e manageme owards waste-0 ects, Roles & a Managemer nication, Role astewater Disp UNIT-II s —Toilet Typ Institutional a pilets, Gender S I Western. Fae	on Objectives-Duration- (Management. Work op lanagement. Participator agement. nt, solid waste and waste Goals of SBA. Community Responsibilities, Job Cha nt, Culture of Cleanliness (of Habits and Attitudes in posal; Change Manageme pes Evaluation of Con and Individual Sanitation Sensitive Sanitation Facilit	06 Hou Component oportunities y Learning e 08 Hou Conscioush rts, Frequer Swachh Bha Environmen nt. 08 Hou struction a Infrastruct ties, Ramps				
Was Intro Envir Envir Soci wate Oper and Sche Abhi Hygi Infra Cont Mair Toile Diffe Eco S	tewater duction- Swachh Bharath Missio ronmental Hygiene-Benefits-Sar ronmental Hygiene, Sanitation ar ology of environmental hygien er and impacts In Defecation-Habits & attitude to Engagement on Sanitation Aspe- edules and Timelines in Swachhat yan), Behaviour Change Communi- ene Management, Waste and War astructure for Sanitation rainment-Preparation of toilets Intenance of Community, Public, ets-Proportion and Number of to prently Abled, Types – Indian and	n (SBM)-Missi nitation-Waste and Waste Man e manageme owards waste-(ects, Roles & a Managemer nication, Role astewater Disp UNIT-II s –Toilet Typ Institutional oilets, Gender S I Western. Fae rerage.	on Objectives-Duration- (Management. Work op lanagement. Participator agement. nt, solid waste and waste Goals of SBA. Community Responsibilities, Job Cha nt, Culture of Cleanliness (of Habits and Attitudes in bosal; Change Manageme pes Evaluation of Con and Individual Sanitation Sensitive Sanitation Facilit cal Sludge treatment - Sin	06 Hou Component oportunities y Learning e 08 Hou Consciousn rts, Frequer Swachh Bha Environmen nt. 08 Hou struction a Infrastruct ties, Ramps ngle / Twin				



(Deemed to be l	Jniversity)			Į	JNI	-III								
Wast	e & Wastewater Audit												06 H	lours
Wast	e Audit -Environmen	tal	Impa	act	Asse	essm	ent,	Wa	ste	Chai	racter	izatio	n, Qu	Jantity
Deter	mination, Primary Colle	ctio	n Me	tho	ds, So	econ	dary	Trar	nspo	rtati	on.			
Wast	ewater Audit -Water Bu	ıdge	t, Tyj	oes c	of Wa	astev	vater	r, Sur	vey	of Di	stribu	tion N	letwo	rk and
	oility of Various Wastew					1etho	ods.							
Swac	hh Bharath Mission ar	nd In	clus	ivity	/								04 ⊢	lours
Swace	ch Bharath Mission in	rura	1&	Urba	an C	onte	xt-G	iend	er Is	sues	in sa	anitati	ion. R	ole of
wome	en in Sanitation.													
Cours	se Outcomes: At the er	nd of	the	cou	rse s	tude	nt w	ill be	e abl	e to				
1.	Creation of awareness	a m	ong	stud	ent's	s hea	lth i	ssue	s an	d Sw	achh	Bhara	ath mi	ssion
	and the consequent re													
2.	To understand the cu					-		-						
	(Open defecation free		ncep	ot, Ir	npoi	rtanc	e of	leg	al &	cult	ural i	ssues	relate	ed to
	Environmental Hygien													
3.	To know the importar					-			tive	sanit	tation	issue	es & u	se of
	engineering technolog													
4.	To know the importan		fwas	ste m	nana	gem	ent s	syste	m, w	aste	water	audit	t and v	vaste
	water treatment proce													
5.	To study the role of	stud	ent i	n Sv	vach	h Bh	arat	a A	bhiy	an, s	solid a	and w	aste v	water
	treatment process.													
Cours	se Outcomes Mapping									1		1	1	1
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes													
	CV2502-1.1	1	1	-	-	-	2	3	2	-	-	-	-	
	CV2502-1.2	1	1	-	-	-	2	3	2	-	-	-	-	
	CV2502-1.3	1	1	-	-	-	2	3	2	-	-	-	-	
	CV2502-1.4	1	1	-	-	-	2	3	2	-	3	-	-	
	CV2502-1.5	1	1	-	3	-	2	3	2	-	-	-	3	İ
1: Lo	w 2: Medium 3: High													

Joanne E. Drinan and Frank Spellman, "Water and Wastewater Treatment: A Guide
for the Non-engineering Professional".
M. S. Bhatt and Asheref Illiyan, "Solid Waste Management: An Indian Perspective".

3. Jagbir Singh, "Solid Waste Management: Present and Future Challenges".

4. M. S. Bhatt, "Solid Waste Management: An Indian Perspective".

5. T. V. Ramachandra, "Management of Municipal Solid Waste".

6. Syed R. Qasim, "Wastewater Treatment Plants: Planning, Design and Operation".

REFERENCE BOOKS:

(Deemed to be U)	University)
1.	Swachhbharatmission.gov.in/
2.	https://www.india.gov.in//swachh-bharat-mission-gramin-portal
3.	https://www.swachhsurvekshan2018.org/
4.	https://zerowasteeurope,eu/
5.	www.zerowasteindia.in/
E Boo	oks / MOOCs/ NPTEL
1.	http://www.un.org/waterforlifedecade/pdf/award_south_africa_eng_for_web.pdf
2.	http://www.sulabhinternational.org
3.	http://swachhbharatmission.gov.in/sbmcms/writereaddata/images/pdf/Guidelines
	/Complete-set-guidelines.pdf

ENVIRONMENTAL IMPACT ASSESSMENT

Course Code:	CV2503-1	Course Type	OEC
Teaching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CV1002-1		

Teaching Department: Civil Engineering

Course Objectives:

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1.	Identify the need to assess and evaluate the impact of projects on environment.
2.	Explain major principles of environmental impact assessment.
3.	Understand the different steps within environmental impact assessment.
4.	Appreciate the importance of EIA for sustainable development and a healthy
	environment.

UNIT-I

Evolution of EIA16 HoursConcepts of EIA, EIA methodologies (Adhoc, Network Analysis, Checklists, Map overlays,
Matrix method), Screening and scoping, Rapid EIA and Comprehensive EIA, General
Framework for Environmental Impact Assessment, EIA Specialized areas like environmental
health impact assessment, Environmental risk analysis.

UNIT-II

14 Hours

10 Hours

Baseline data study, Prediction, and assessment of impacts on physical, biological, and socio-economic environment, Legislative and environmental clearance procedures in India, Public participation, Resettlement, and rehabilitation.

UNIT-III

Fault free analysis, Consequence Analysis, Introduction to Environmental Management Systems, Environmental management plan-Post project monitoring Environmental Audit: Cost Benefit Analysis, Life cycle Assessment. Case studies on project, regional and sectoral EIA.

Cou	Course Outcomes: At the end of the course student will be able to					
1.	Understand phenomena of impacts and know the impact quantification of various					
	projects in the environment.					
2.	Liaise with and list the importance of stakeholders in the EIA process.					
3.	Know the role of public in EIA studies.					
4.	Overview and assess risks posing threats to the environment.					
5.	Assess different case studies/examples of EIA in practice.					

Course Outcomes Mapping with Program Outcomes



(Deemed to be Uni	versity)		1	1	1	1	1	1	1	1		1		1
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes →													
	↓ Course													
	Outcomes													
	CV2503-1.1	1	1	-	-	-	2	3	2	-	-	-	-	
	CV2503-1.2	1	1	-	-	-	2	3	2	_	-	-	-	
	CV2503-1.3	1	1	-	-	-	2	3	2	-	-	-	-	
	CV2503-1.4	1	1	-	-	-	2	3	2	-	3	-	-	
	CV2503-1.5	1	1	-	3	-	2	3	2	-	-	-	3	
1: Lov	w 2: Medium 3: High													
	~													
TEXTE	BOOKS:													
1.	Noble, L., "Introduction to environmental impact assessment. A Guide to Principles												nciples	
	and Practice", 2nd e	ditio	n, O	xforc	l Uni	vers	ity P	ress,	Don	Mil	ls, On	tario,	2010.	-
2.	Larry W. Canter, "En	viror	nmei	ntal I	Impa	act A	sses	smer	nt", I	ИсGı	raw H	ill Inc	. Sing	apore,
	1996.	, , , , , , , , , , , , , , , , , , , ,												
REFER	ENCE BOOKS:													
1.	Morris and Therivel,	"Me	etho	ds of	Env	iron	men	tal Ir	npad	t As	sessm	nent",	3rd e	dition.
	New York, NY: Routl	edge	e, 20	09.					-					
2.	Hanna, K. S., "Enviro	onme	ental	imp	bact	asse	ssme	ent. I	Pract	tice a	and P	articip	oation	". 2nd
	edition. Oxford, Univ			-								•		
E Boo	ks / MOOCs/ NPTEL		-											
1.	http://nptel.ac.in/co	urses	s/12(0108	004/	/								
2.	http://nptel.ac.in/co						dule3	S/lect	ture	3.pdf				
					/					1				



INTRODUCTION TO GEOINFORMATICS

Course Code:	CV2504-1	Course Type	OEC			
Teaching Hours/Week (L:T: P:S)	3:0:0:0	Credits	03			
Total Teaching Hours	40	CIE + SEE Marks	50+50			
Prerequisite CV1001-1, CV1002-1						

Teaching Department: Civil Engineering

Course Objectives:

1.	Explain the basic principles of Geoinformatics comprising Remote sensing,										
	Photogrammetry, GPS, GNSS & GIS.										
2.	Explain the stages and techniques of photogrammetry, aerial photo interpretation,										
	visual & digital image processing, enhancement and interpretation.										
3.	Explain and Appraise GIS - its components, data structures, process and operation,										

- Map and its projections, components, preparation and overlays
- **4.** Explain the GIS functionality and Appraise the significance of GEOINFORMATICS (Photogrammetry, RS, GPS, GNSS & GIS) in real world applications.

UNIT-I

16 Hours

Remote sensing and its Principles: Physics of remote sensing, EM spectrum, Blackbody concept, atmospheric windows, spectral response of common earth features.

Platforms & Sensors: Ground based, Air borne and Space borne platforms, Active and Passive Sensors, Photographic sensors, scanners, radiometers, RADAR and thermal infrared, hyper spectral remote sensing, Indian satellites and sensors: capabilities, data products **Photogrammetry**: Basic principles of Aerial photography and Photogrammetry, Flight procedures, Aerial Photo Interpretation and Analysis techniques.

Satellite Image Interpretation and Analysis techniques: Visual & Digital Image interpretation, Interpretation elements, False Colour Composites (FCC).

UNIT-II

15 Hours

Digital Image Processing and Analysis: Digital image formats, pre-processing and processing (DIP), image restoration/enhancement procedures, information extraction, pattern recognition concepts, post processing procedures.

Geographic Information System -concept and spatial models: Fundamentals of GIS, spatial and non-spatial data, vector and raster GIS, GIS Hardware and software, georeferencing, digitization, thematic maps, Overlay Analysis, Operation of GIS, Co-ordinate systems and map projections, Map scale, data display and cartography.

UNIT-III

09 Hours

Geoinformatics and Virtual GIS: Modern Surveying and Geoinformatics, GPS & GNSS, GIS Functionality: Introduction, data acquisition, preliminary data processing, data storage and retrieval, spatial search and analysis, graphics and interaction, Virtual GIS and Real world applications.



Course Outcomes: At the end of the course student will be able to

- Define and explain the principles of Remote Sensing and list various types of platforms, sensors & resolutions in RS with a special reference to Indian satellites and data products.
 Explain Photogrammetry, its basic principles elements of photo, interpretation
- Explain Photogrammetry, its basic principles, elements of photo interpretation, Visual & Digital Image interpretation techniques
- **3.** Explain different stages involved in Digital Image Processing, various image enhancement techniques, list and classify the digital image formats and the extracted information for various purposes.
- **4.** Explain and Appraise GIS its components, data structures, process and operation, Map and its projections, components, preparation and Overlays.
- **5.** Explain the GIS functionality and appraise the significance of GEOINFORMATICS (Photogrammetry, RS, GPS, GNSS & GIS) and Virtual GIS in real world applications.

Course Outcomes Mapping with Program Outcomes

 •••••••••••••••••••••••••••••••••••••••	,		- 9				-						
Program	1	2	3	4	5	6	7	8	9	10	11	12	
Outcomes→													
↓ Course													
Outcomes													
CV2504-1.1	2	2	-	-	-	2	-	-	-	-	-	-	
CV2504-1.2	2	2	-	-	-	2	1	-	-	-	-	-	
CV2504-1.3	2	2	-	-	-	2	1	-	-	-	-	-	
CV2504-1.4	2	2	-	-	-	2	1	-	-	-	-	-	
CV2504-1.5	2	2	-	-	-	2	1	-	-	-	-	-	

1: Low 2: Medium 3: High

TEXTB	OOKS:
1.	Anji Reddy, M, "Text Book of Remote Sensing and Geographical Information
	Systems", Fourth Edition, BS Publication, Hyderabad, 2012.
2.	Bhatta, Basudeva, "Remote Sensing and GIS", 2nd edition, Oxford University Press,
	N. Delhi, 2011.
3.	Lillesand, T.M., Kiefer, R.W and Chipman, J. W., "Remote sensing and Image
	Interpretations", 7th edition, John Wiley and sons, New Delhi, 2015.
REFER	ENCE BOOKS:
1.	Anji Reddy, M. and Hari Shankar, Y., "Digital Image Processing", BS Pub., Hyd, 2006.
2.	Bernhardsen, Tor, "Geographic Information Systems", 3rd Ed., Wiley India, Delhi,
	2002.
3.	Canada Centre for Remote Sensing, Fundamentals of Remote sensing-Tutorial,
	2011.
4.	Chang, Kang-tsung, "Introduction to Geographic Information Systems", 4th Ed.,
	Tata McGraw Hill Publishing Company Limited, New Delhi, 2008.
5.	Korte, George B., "The GIS Book", Onword Press, Thomson Learning Inc., USA, 2001.
6.	Kumar, S., "Basics of Remote sensing and GIS", Laxmi Publications (P) Ltd., Delhi,
	2008.

Deemed to be Un	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 2
7.	Longler, Paul A., Goodchild, Michael F., Maguire, David J., Rhind. David W., "Geographic Information Systems and Science", John Wiley & Sons Ltd., ESRI Press, 2004.
8.	Sabins, F. L., "Remote Sensing: Principles and Interpretation" 3rd edn. WH Freeman and Company, New York, 1997.
E Boo	ks / MOOCs/ NPTEL
1.	https://www.youtube.com/user/edusat2004
2.	https://eclass.iirs.gov.in/login

NITTE

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		ROSION SCI	EINCE										
Tea	rse Code:	CY2501-1	Course Type	OEC									
	ching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03									
Tota	al Teaching Hours	40	CIE + SEE Marks	50+50									
Prei	requisite	CY1001-1											
	Teaching	Department:	Chemistry										
Cour	se Objectives:												
1.	To provide fundamental under	standing aspe	cts of electrochemistry	and material									
science related to corrosion. To understand the types of corrosion attacking on the													
	 metal and its preventions. To impart knowledge on corrosion science and its applications to the engineering materials. 												
2.													
3. To identify practice for the prevention and remediation of the corrosion. To provide													
	methodologies for measuring the corrosion performance of materials.												
		UNIT-I											
Fund	amentals of Corrosion			09 Hours									
corro	sion, Electrochemical Aspects o	of corrosion,	Electrochemical react	tions, Different									
Envir	onmental aspects, polarizatio	n and pass	sivity, Corrosion Rat	e Expression,									
	rmination. Standard electrode	notontial ENA											
(Roul		potential, EM	F and Galvanic series	•									
-	oaix Diagram).		F and Galvanic series	s, Potential-pH									
Form	is of Corrosion			, Potential-pH									
Form Galva	as of Corrosion anic corrosion, Crevices corrosion	on, Filiform c	orrosion, Pitting corro	s, Potential-pH 08 Hours osion, Uniform									
Form Galva corro	as of Corrosion anic corrosion, Crevices corrosion and Atmospheric corrosion,	on, Filiform c Inter granular	orrosion, Pitting corro corrosion, Selective lea	5, Potential-pH 08 Hours osion, Uniform aching, Erosion									
Form Galva corro corro	as of Corrosion anic corrosion, Crevices corrosion	on, Filiform c Inter granular corrosion , Imp	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet	5, Potential-pH 08 Hours osion, Uniform aching, Erosion									
Form Galva corro corro	anic corrosion anic corrosion, Crevices corrosion asion and Atmospheric corrosion, asion, Cavitation damage, Stress c	on, Filiform c Inter granular corrosion , Imp	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet	5, Potential-pH 08 Hours osion, Uniform aching, Erosion									
Form Galva corro corro Corro	anic corrosion, Crevices corrosion anic corrosion, Crevices corrosion asion and Atmospheric corrosion, asion, Cavitation damage, Stress cosion fatigue, Hydrogen blistering	on, Filiform c Inter granular corrosion , Imp	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion,									
Form Galva corro corro Corrc	anic corrosion anic corrosion, Crevices corrosion asion and Atmospheric corrosion, asion, Cavitation damage, Stress of asion fatigue, Hydrogen blistering asion at Elevated Temperature	on, Filiform o Inter granular corrosion , Imp J, Hydrogen en UNIT-II	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement.	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours									
Form Galva corro Corro Corrc High	anic corrosion, Crevices corrosion anic corrosion, Crevices corrosion asion and Atmospheric corrosion, asion, Cavitation damage, Stress of asion fatigue, Hydrogen blistering asion at Elevated Temperature temperature materials, Metal oxid	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defec	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot									
Form Galva corro Corro Corro High corro	anic corrosion, Crevices corrosion anic corrosion, Crevices corrosion, asion and Atmospheric corrosion, asion, Cavitation damage, Stress of asion fatigue, Hydrogen blistering asion at Elevated Temperature temperature materials, Metal oxid asion, Corrosion of mineral acids-o	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defec	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al.									
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Form Galva corro Corro Corro High corro Corro	anic corrosion, Crevices corrosion anic corrosion, Crevices corrosion, asion and Atmospheric corrosion, asion, Cavitation damage, Stress of asion fatigue, Hydrogen blistering asion fatigue, Hydrogen blistering besion at Elevated Temperature temperature materials, Metal oxid asion, Corrosion of mineral acids-of asion Testing ht loss method, Tafel extrapolation	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed corrosion of ste	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours									
Form Galva corro Corro Corro High corro Corro Weig	anic corrosion, Crevices corrosion anic corrosion, Crevices corrosion, asion and Atmospheric corrosion, asion, Cavitation damage, Stress of asion fatigue, Hydrogen blistering asion fatigue, Hydrogen blistering besion at Elevated Temperature temperature materials, Metal oxid asion, Corrosion of mineral acids-of asion Testing ht loss method, Tafel extrapolation	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed corrosion of ste	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours									
Form Galva corro Corro Corro High corro Corro Weig meth	anic corrosion, Crevices corrosionsion and Atmospheric corrosion, origion, Cavitation damage, Stress or psion fatigue, Hydrogen blistering Desion at Elevated Temperature temperature materials, Metal oxidesion, Corrosion of mineral acids-origion, Corrosion of mineral acids-origion Testing ht loss method, Tafel extrapolatic od.	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed corrosion of ste	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours impedance									
Form Galva corro Corro Corro High corro Corro Weig meth	anic corrosion, Crevices corrosionsion and Atmospheric corrosion, osion, Cavitation damage, Stress of the sion fatigue, Hydrogen blistering Desion at Elevated Temperature temperature materials, Metal oxionsion, Corrosion of mineral acids-opsion Testing ht loss method, Tafel extrapolatic od.	on, Filiform c Inter granular corrosion , Imp , Hydrogen en UNIT-II des, Pilling bed corrosion of ste on test, linear p UNIT-III	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a polarization test and AC	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours impedance 08 Hours									
Form Galva corro Corro Corro High corro Corro Weig meth Corro Mate	anic corrosion, Crevices corrosionsion and Atmospheric corrosion, origion and Atmospheric corrosion, origion, Cavitation damage, Stress or posion fatigue, Hydrogen blistering originat Elevated Temperature temperature materials, Metal oxidosion, Corrosion of mineral acids-origion Testing ht loss method, Tafel extrapolatic od.	on, Filiform c Inter granular corrosion , Imp J, Hydrogen en UNIT-II des, Pilling bed corrosion of ste on test, linear p UNIT-III	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a polarization test and AC	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours impedance 08 Hours rosion, Control									
Form Galva corro Corro Corro High corro Corro Weig meth Mate of atu	anic corrosion, Crevices corrosionsion and Atmospheric corrosion, osion, Cavitation damage, Stress of the sion fatigue, Hydrogen blistering Desion at Elevated Temperature temperature materials, Metal oxionsion, Corrosion of mineral acids-opsion Testing ht loss method, Tafel extrapolatic od.	on, Filiform c Inter granular corrosion , Imp J, Hydrogen en UNIT-II des, Pilling bed corrosion of ste on test, linear p UNIT-III	orrosion, Pitting corro corrosion, Selective lea ingement attack, Inlet nbrittlement. worth rule, oxide defected, stainless steel, Cu a polarization test and AC	s, Potential-pH 08 Hours osion, Uniform aching, Erosion tube corrosion, 08 Hours it structure, Hot nd Al. 07 Hours impedance 08 Hours rosion, Control									

							C	urriculu	um – B.'	Гесh. (R	obotics &	z Artificia	l Intellige	enec
1.	Explain the fun	dam	enta	ls of	diffe	rence	e in el	ectro	de po	tential	acros	s an in	terface	in
	particular a metal/ electrolyte and the relationship between rates of electrochemical													
	reactions and the potential drop across interfaces.													
2.	Analyze the causes and mechanisms of various types of corrosion including uniform,													
	galvanic, crevice, pitting, inter granular and various modes of environmentally cracking. Acquire knowledge of influence of a materials composition, the effect of													
				-					•					
	an electrolytes composition on the corrosion of metals and microstructure on its													
3.	corrosion performance.													
5.	Identify the materials that will exhibit adequate corrosion resistance in a particular environment and remedial action that will reduce corrosion to a acceptable level.													
		Explain the concepts of different measuring techniques of corrosion.												
Cou	se Outcomes Mapping with Program Outcomes													
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
L	Outcomes→													
	↓ Course													
	Outcomes													
	CY2501-1.1	3	3	3	-	-	1	1	-	-	-	-	-	
	CY2501-1.2	3	3	3	-	-	1	1	-	-	-	-	-	
	CY2501-1.3	3	3	3	-	-	1	1	-	-	-	-	-	
1: Lo	ow 2: Medium 3:	Hig	h											
TEX	TBOOKS:													
1	Mars G Fontar	na, "C	orro	sion	Engi	neeri	ng", 3	rd Edi	ition, 1	ata M	cgraw	-Hill Ec	dition.	
REF	ERENCE BOOKS:													
1	Chamberlian a	and K	. Tre	ethwa	ay, "C	Corro	sion"	, Long	gman	scient	ific and	d tech	nical, J	oh
	Wiley and Son	c												



	(Deemed to be University)	PRODUCTS	CHEMISTRY	
	Course Code:	CY2502-1	Course Type	OEC
	Teaching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03
	Total Teaching Hours	40	CIE + SEE Marks	50+50
	Prerequisite	CY1001-1		
	Teaching	g Department	: Chemistry	
Со	urse Objectives:			
1.	Identify the structure of terpenoid	s and their bio	synthesis. Elucidate the str	ucture of
	β-carotene, haemoglobin and chlo			
2.	, , , , , , , , , , , , , , , , , , , ,	0		
	the different types of prostagland	ins as well as tl	neory and chemistry behin	d natural
	dyes.			<u> </u>
3.	5 5	nods of struct	ural determination of som	ne of the
	important alkaloids.	UNIT-I		
Ter	penoids & Carotenoids	UNIT-I		08 Hours
	oduction and classification, isoprene	rules genera	methods of determination	
	penoids. Structure elucidation of the	-		
•	nesol. Biosynthesis of terpenoids.	tonowing ter	gerund, a prime	
	oduction and classification of caroter	nes. Structural	elucidation of B-carotene.	
	rphyrins			07 Hours
	oduction to porphyrins, structure and	degradation	products of haemoglobin	and chlorophyll.
		UNIT-II		
Ste	roids			08 Hours
	oduction, Dile's hydrogenation. Cl	•		Barbier-Wielman
-	gradation, Oppenuer oxidation. Const			
	hormones: Chemistry of oestrone, p	rogesterone, a	ndrosterone and testoster	
D				
	ostaglandins & Natural Dyes			08 Hours
Intr	oduction, nomenclature, classificat			08 Hours
Intr elu	oduction, nomenclature, classificat cidation of PGE1, Biosynthesis of PGE2	and $PGF_{2\alpha}$.	logical role of prostag	08 Hours ladins. Structure
Intr elu	oduction, nomenclature, classificat	and $PGF_{2\alpha}$.	logical role of prostag	08 Hours ladins. Structure
Intr elu	oduction, nomenclature, classificat cidation of PGE1, Biosynthesis of PGE2	and PGF _{2α.} thods of dyein	logical role of prostag	08 Hours ladins. Structure
Intr eluo Intr	oduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ oduction, Witt's theory of colour, me	and $PGF_{2\alpha}$.	logical role of prostag	08 Hours ladins. Structure f alizarin.
Intr eluo Intr Alk	oduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ oduction, Witt's theory of colour, me a loids	and PGF _{2α.} thods of dyein UNIT-III	logical role of prostag g, chemical constitution o	08 Hours ladins. Structure f alizarin. 09 Hours
Intr elue Intr Alk Def	oduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ oduction, Witt's theory of colour, me a loids finition, Classification and isolation of	and PGF _{2α.} thods of dyein UNIT-III alkaloids. Gen	logical role of prostag g, chemical constitution o eral methods of structural	08 Hours ladins. Structure f alizarin. 09 Hours determination of
Intr eluo Intr Alk Def alka	roduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ roduction, Witt's theory of colour, me raloids finition, Classification and isolation of aloids. Detailed study of structure eluc	and PGF _{2α.} thods of dyein UNIT-III alkaloids. Gen	logical role of prostag g, chemical constitution o eral methods of structural	08 Hours ladins. Structure f alizarin. 09 Hours determination of
Intr eluo Intr Alk Def alka	oduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ oduction, Witt's theory of colour, me a loids finition, Classification and isolation of	and PGF _{2α.} thods of dyein UNIT-III alkaloids. Gen	logical role of prostag g, chemical constitution o eral methods of structural	08 Hours ladins. Structure f alizarin. 09 Hours determination of
Intr eluo Intr Alk Def alka anc	roduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ roduction, Witt's theory of colour, me a loids finition, Classification and isolation of aloids. Detailed study of structure eluc d nicotine.	and PGF _{2α.} thods of dyein UNIT-III alkaloids. Gen cidation of the	logical role of prostag g, chemical constitution o eral methods of structural following alkaloids- papay	08 Hours ladins. Structure f alizarin. 09 Hours determination of
Intr eluo Intr Alk alka anc	roduction, nomenclature, classificat cidation of PGE ₁ , Biosynthesis of PGE ₂ roduction, Witt's theory of colour, me raloids finition, Classification and isolation of aloids. Detailed study of structure eluc	and PGF _{2α.} thods of dyein UNIT-III alkaloids. Gen cidation of the	logical role of prostag g, chemical constitution o eral methods of structural following alkaloids- papav ill be able to	08 Hours ladins. Structure f alizarin. 09 Hours determination of verine, cinchonine

N	NITT (Deemed to be Uni	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 202
	2	State the basic reactions governing steroids and sex hormones. Explain the biological role and structure of prostaglandins and state the methods employed for dyeing.
	3	Apply the general methods of structural determination to elucidate the structure

of alkaloids like papaverine, cinchonine and nicotine.

Course Outcomes Mapping with Program Outcomes

<u> </u>														
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes													
	CY2502-1.1	3	3	-	-	-	1	1	-	-	-	-	-	
	CY2502-1.2	3	3	-	-	-	1	1	-	-	-	-	-	
	CY2502-1.3	3	3	-	-	-	1	1	-	-	-	-	-	

1: Low 2: Medium 3: High

DKS:
Agarwal, "Organic Chemistry of Natural Products", VolI & VolII, O.P. Goel Publishing
House, 2014.
CE BOOKS:
K. Nakanishi, T. Goso, S. Ito, S. Natori and S. Nozoe, "Natural Products Chemistry", Vol. I
& II, Academic Press, Ny, 1974.
Gurudeep R. Chatwal, "Organic Chemistry of Natural Products", Vol. I & II, Himalaya
Publishing House, 2013.
G.A. Swal, "An Introduction to Alkaloids", Backwell Scientific Publications, 1967.
Hand book of naturally occurring Compounds, Vol. II, terpenes, T.K. Davon, A.I. Scott,
Academic Press, Ny, 1974.
(

Co ι	ırse Code:	EC1501-1	Course Type	OEC							
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03							
	al Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50							
	2			I							
	Teaching Department: Ele	ctronics & Cor	nmunication Engine	ering							
Coui	rse Objectives:		*								
1.	To learn basic building blocks o	f ANNs and its	terminology								
2.	To understand the working o	f McCulloch-P	itts Neuron and diff	erent types of							
learning rules											
3.	To understand decision regions	, discriminant f	unctions and training	concept							
4.	To understand the working of p	erceptron as cl	assifier								
5.	To understand the mathematic	s behind diffe	rent types of single	layer feedback							
	networks			2							
		UNIT-I									
ntro	oduction to Artificial Neural net	works		16 Hours							
ntro	duction, Basic building blocks: n	etwork archite	cture, setting the we	ights, activatio							
unc	tions, ANN terminologies: weights,	, activation fund	ctions, bias, threshold,	McCulloch-Pitt							
	ron Model, Learning Rules										
		UNIT-II		I							
Sing	le Layer Perceptron Classifiers			15 Hours							
-	sification Model, Features, and	Decision Regi	ons, Discriminant Fu	unctions, Linea							
	hine and Minimum Distance Class										
	Classification Using the Discrete	•									
	inuous Perceptron Networks fo	•	• ·								
	le-Layer Perceptron Networks	, , , , , , , , , , , , , , , , , , ,									
		UNIT-III		I							
Sina	le-Layer Feedback Networks			09 Hours							
-	Concepts of Dynamical Systems,	Mathematical F	oundations of Discret								
	vorks, Mathematical Foundation			•							
	onse of Continuous-Time Netwo		• • •								
•	vorks		i woodening in Single	Layer recable							
VCLV											
ົດເມ	rse Outcomes: At the end of the c	ourse student	will be able to								
<u>1.</u>	Describe the building blocks of										
2.	Describe the working of neural		v								
<u>2.</u> 3.			2	 i+							
	Describe training of Single layer										
4.	Explain use of Single layer perce	eptron for linea	ny separable and mul	licalegory							
	problems										
5.	Explain the mathematics behind		· ا ا ا	بمباده							

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(Deemed to be Uni	versity)													
	Program Outcomes $ ightarrow$	1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
	EC1501-1.1	3	-	-	-	-	-	-	-	-	-	-	-	
	EC1501-1.2	3	-	-	-	-	-	-	-	-	-	-	-	
	EC1501-1.3	3	-	-	-	-	-	-	-	-	-	-	-	
	EC1501-1.4	3	-	-	-	-	-	-	-	-	-	-	-	
EC1501-1.5 3														
1: Low 2: Medium 3: High														
TEXTE	BOOKS:													
1.	S. N. Sivanandam, S. Su	umat	thi, S	. N.	Dee	oa, "	Intro	oduc	tion	to N	leural	Netv	vorks	Using
	MATLAB 6.0", Tata Mc	Graw	/-Hil	l Edu	ıcati	on, 2	2006	1						0
2.	Jacek M. Zurada "Intro	oduc	tion	to	Artif	icial	Νει	ıral	Syste	ems'	', 1st	Editi	on, St	. Paul
	West Publishers-USA, 2	1992							,					
3.	Michael A Neilsen, "N	eura	al Ne	etwo	rks a	and	Dee	p Le	earni	ng",	Dete	ermina	ation	Press,
	2015							•		5				

	INTRODUCTION TO MA	TLAB PROGR	AMMING: A HAND	S-ON						
Course Code:EC1502-1Course TypeOEC										
Teaching Hours/Week (L: T: P: S)2:0:2:0Credits03										
Total Teaching Hours27+0+26+0CIE + SEE Marks50+50										
Cour	se Objectives:	fered to Civil &	DI							
Cour										
1.	. To demonstrate basic understanding of MATLAB programming									
2.	To use and write functions									
3.	3. To use MATLAB programming for image processing									
			<u> </u>							
	Uı	nit-I		27 Hours						

Introduction to MATLAB: Starting MATLAB and familiarization with its user interface, syntax and semantics, ways in which MATLAB provides help, create plots in MATLAB.

Matrices and Operators: defining matrices, manipulation of matrices, extract parts of them and combine them to form new matrices, use of operators to add, subtract, multiply, and divide matrices, and we will learn that there are several different types of multiplication and division.

Functions: creating reusable functions, how the environment inside a function is separated from the outside via a well-defined interface through which it communicates with that outside world, define a function to allow input to it when it initiates its execution.

Programmer's Toolbox: polymorphism and how MATLAB exploits it to change a function's behavior on the basis of the number and type of its inputs, random number generator, how to get input from the keyboard, how to print to the Command Window, and how to plot graphs in a Figure window, how to find programming errors with the help of the debugger, how to print to the Command Window, and how to plot graphs in a Figure window, how to find programming errors with the help of the debugger.

Selection Statement and Loops: how to use the if-statement, how to use relational operators and logical operators, how to write polymorphic functions and how to make functions resistant to error, the for-loop and the while-loop, how the break-statement works, nested loops, logical indexing and implicit loops.

Data Types: character arrays and how the characters in them are encoded as numbers, string and datetime datatype, how to produce heterogeneous collections of data via structs and cells.

File Input/Output: reading and writing files, how to create, read from, and write into MAT-files, Excel files, text files, and binary files, how to navigate among folders with MATLAB commands.

Image Processing using MATLAB: pre-processing – conversion of color image to gray scale image, decomposition of color images to single color component image, histogram of image, thresholding

List of Experiments								
1 Starting MATLAB and familiarization with its user interface, syntax and semantics,								
ways in which MATLAB provides help, create plots in MATLAB.								

J	NITTE						Curr	iculur	n – B	.Tech	. (Roł	ootics &	Artific	ial Intel	ligenece): 2
	2	them to form new divide matrices, and	Defining matrices, manipulation of matrices, extract parts of them and combine them to form new matrices, use of operators to add, subtract, multiply, and divide matrices, and we will learn that there are several different types of multiplication and division.												
	3	creating reusable fur from the outside via with that outside wo execution.	nctic a a v	ons, l well-	defi	ned	inte	rface	e thi	roug	h w	hich	it cor	nmur	nicates
	4	Polymorphism and how MATLAB exploits it to change a function's behavior on the basis of the number and type of its inputs, random number generator, how to get input from the keyboard, how to print to the Command Window													
	5	the help of the debu	How to plot graphs in a Figure window, how to find programming errors with the help of the debugger, how to print to the Command Window, and how to plot graphs in a Figure window, how to find programming errors with the help												
	6	How to use the if- operators, how to v resistant to error.										•			-
	7	The for-loop and the logical indexing and			•		/ the	bre	ak-s	tate	men	t wor	ks, ne	ested	loops,
	8	Character arrays and	Character arrays and how the characters in them are encoded as numbers, string and datetime datatype, how to produce heterogeneous collections of data via												
	9	Reading and writing Excel files, text files MATLAB commands.	, ar												
	10	Reading an image, s	avin	g, ba	asic ı	man	ipula	ation	n of i	mac	jes, a	arithn	netic	opera	tions
	11	Pre-processing – cor of color images to si	ver	sion	of c	olor	ima	ge to	o gra	ay sc					
	12	Histogram processin	g.												
	13	Thresholding operat	ion.												
	Course (Dutcomes: At the end of	of th	e (0	urse	stu	dent	will	be a	able	to				
		e matrices and operato													
									9						
			and write functions; use MATLAB toolbox toolbox and selection statement in MATLAB programming												
		te MATLAB programs using loops and summarize data types													
		mmarize file input/output methods using MATLAB commands and apply pre-													
		cessing and thresholding operations on images													
μ			y	Spe				age	5						
\vdash	Courco	Uutcomes Mapping wi	th I)roa	ram	^	tron	nec							
╞			<u>τη κ</u> 1	2 2	ram 3	U	5	nes 6	7	8	9	10	11	12	
		Program Outcomes→ Course Outcomes	Т	2	5	4	ر	0	/	0	9	10	11	12	
	<u>↓</u>	EC1502-1.1	1	_	_	_	3	-	_	_	_	-	_	_	
		EC1502-1.2	1	-	-	-	3	-	_	_	_	_	_	_	
		EC1502-1.2	1	-	-	-	3	-	-	-	-	-	-	_	
			_	I	I	I		1	I	I	I		I		



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	EC1502-1.4	1	-	-	-	3	-	-	-	-	-	-	-	
	EC1502-1.5	1	-	-	-	3	-	-	-	-	-	-	-	
1: Low 2: Medium 3: High														
TEXTBOOKS:														
1.	1. Stormy Attaway, "Matlab: A Practical Introduction to Programming and Problem													
	Solving", Second Edi	Solving", Second Edition, Butterworth-Heinemann, 2011												
2.	Fitzpatrick and Lede	Fitzpatrick and Ledeczi, "Computer Programming with MATLAB", eBook, 2013												
3.	Rafael C. Gonzalez,	Rafael C. Gonzalez, Richard E. Woods and Steven L. Eddins, Digital Image												
	Processing using MA	Processing using MATLAB, first edition, Dorling Kindersley Pvt Ltd, 2006.												
REFERE	REFERENCE BOOKS:													
1.	1. Duane C. Hanselman, Bruce L. Littlefield, "Mastering MATLAB", first edition,													
	Pearson, 2011	Pearson, 2011												
E Books / MOOCs/ NPTEL														
1.	https://nptel.ac.in/co	ourse	es/1()3/1	06/1	.031	0611	.8/						
2.	https://www.courser	a.or	g/lea	arn/r	natla	<u>ab</u>								

ROBOTICS										
Course Code:	EC1503-1	Course Type	OEC							
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03							
Total Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50							

Teaching Department: Electronics & Communication Engineering

Course Objectives:

- 2. Analyse the robot motion using translation and rotational matrix.
- **3.** Discuss Robot trajectory planning and robot control.
- 4. Categorise the various sensors used in robotics
- 5. Understand the robot programming.

UNIT-I

Introduction

Definition, anatomy of robot, classification configurations, robot links and joints, robot specifications, resolution accuracy and repeatability, simple numerical problems, robot drive systems, hydraulic, pneumatic and electric drive systems, wrist and its motions, end effectors, types of end effectors, mechanical & Non-mechanical grippers, methods of constraining parts in grippers.

Motion analysis

Direct kinematics and inverse kinematics, 3D homogeneous transformations, rotation, translation and displacement matrix, composite rotation matrix, rotation matrix about an arbitrary axis.

UNIT-II

Control and trajectory planning

Trajectory planning, definition, steps in trajectory planning, joint space techniques, use of a p-degree polynomial as interpolation function, cubic polynomial trajectories, linear function with parabolic blends, joint space verses, simple numerical problems on joint space trajectory planning.

Sensors

Classification, Types- Contact & Non-Contact sensors.

Machine Vision

Programming

Machine vision, functions of machine vision system, sensing and digitizing, imaging devices, analog to digital signal conversion, quantization and encoding, simple numerical problems, image storage, image processing and analysis, image data reduction, segmentation, feature extraction, object recognition, robotic machine vision applications, inspection, identification, visual surveying and navigation.

UNIT-III

09 Hours

Introduction to robot programming, robot cell layout, work cell control and interlocks, manual programming, lead through and walkthrough programming, off-line programming, robot programming languages, examples

15 Hours

16 Hours

Cour 1.		r .					• • •						
1 1	se Outcomes: At the end										<u> </u>		
⊥.	Explain the working prir	•			•				rame	eters	ot rot	oots a	ind
	identify the types of rob											•.•	
2.	Discuss the concept of c												
	orientation of End-Effec											te the	
	applications of Denavit-	Hart	tenb	erg (DH)	metr	100 1	ror a	Inter	ent r	JODOT		
3.	configurations.	o of	train	stor	درمام	nnin		- ntra			oc for	robot	iaint
э.	Determine the techniqu		-				-			leme	25 101	10001	Joints
4.		Ind understand the types of the sensors used in robotics. Apply engineering knowledge in robot visual surveying and navigation.											
. 5.													
Э.	-	Analyze and formulate different types of robot cell layouts and use modern tools to write robot programs for different tasks.											
Cour	se Outcomes Mapping v							•					
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
F	↓ Course Outcomes	-	2				Ŭ	,	Ŭ		10		
-	EC1503-1.1	3	2	2	1	_	-	-	_	-	_	-	1
F	EC1503-1.2	3	3	2	2	-	-	-	-	3	3	-	1
_	EC1503-1.3	3	2	2	2	-	-	-	-	3	3	-	1
_	EC1503-1.4	3	2	2	1	-	-	-	-	-	-	-	1
Γ	EC1503-1.5	3	3	3	2	2	-	-	-	-	-	-	1
1.1.4	ow 2: Medium 3: High		1										
T . FC													
	BOOKS:												
	BOOKS:	gratł	n, "Re	obot	ics a	nd C	ontr	ol", T	Tata-	McG	iraw-ł	Hill Pu	ıblicati
ΓΕΧΤ	BOOKS:	gratł	n, "Ro	obot	ics a	nd C	ontr	ol", T	īata-	McG	iraw-I	Hill Pu	ıblicati
ΓΕΧΤ	BOOKS: R. K. Mittal and I. J. Nag 2007. Mikell P. Groover, Mite	chel	Weis	ss, Ro	oger	N. N	lagel	and	l Nic	hola	s G. O		
ТЕХТ 1. 2.	 BOOKS: R. K. Mittal and I. J. Nag 2007. Mikell P. Groover, Mite Robotics", McGraw-Hi 	chel	Weis	ss, Ro	oger	N. N	lagel	and	l Nic	hola	s G. O		
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CONSUMER ELECTRONICS

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	requisite		EC100	1-1							
	Teaching Departmen	t: Elec	tronic	s & Co	omm	unicat	on E	ngine	erino	a	
Cour	rse Objectives:							<u> </u>			
1.	To provide basic knowledge	e on so	ound a	nd tra	nsdu	cers					
2.	To provide basic knowledge						came	era			
3.	To understand the recordin	g proc	cess an	d stor	age n	nechar	ism				
4.	To provide basic knowledge	e on co	ommur	nicatio	n and	d broad	lcasti	ng			
5. To understand the working of various electronic gadgets											
			UN								
Sour	nd & Vision									15	Hour
Soun	nd: Definition and properties	of sou	und, Tr	ansdu	cers:	Micro	Phon	e – c	harac	terist	ics a
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Reco digita Thea Com recei and Fax n and Fax n and healt Cour 1. 2. 3. 4. 5.	ording and Playback: Audio mail recording, erasing method itre Sound, HiFi system. munications And Broadcastin vers - Tuned radio frequency TV broadcasting. Cellular com Er Electronic Systems machine, Xerox machine, elect refrigeration, ATM, Auto Elect th / Medicine. rse Outcomes: At the end of the Recall basics of sound and the Understand the working print Explain basic working of Recomparison of the Explain basics of communic Recall basics of communic Recall basic working of com-	ecordi ls, op ng: Mi receiv munic ronic (tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic tronic	ng me tical d odulati er and ation: UNI Calcula is, Indu urse st ucers. <u>s of dis</u> <u>ig, stor</u> and bro y used ram O	thods iscs- r on: A Super digital f-III tor, M istrial udent splay u age de badcas electro utcon	-mag record M, Fl rhete cellu icrow Elect will t units evices sting onic onic onic onic onic onic onic onic	ynetic i ding ai M PCN rodyne ilar pho vave ov ronics be able and CC s	ecorc nd pla I, Rad receip one, e ens, V and I to TV ca	aybac dio tr iver. F stabli Washi Robot	ng M ics, E	al rec m pr itters optics a ca 10 achir ilectro	ordir ojecto , Rad , Rad II. Hour es, A
Reco digita Thea Com recei and Fax n and Fax n and healt Cour 1. 2. 3. 4. 5.	ording and Playback: Audio real recording, erasing method al recording, erasing method itre Sound, HiFi system. munications And Broadcastin vers - Tuned radio frequency TV broadcasting. Cellular com er Electronic Systems machine, Xerox machine, elect refrigeration, ATM, Auto Elect th / Medicine. rse Outcomes: At the end of t Recall basics of sound and t Understand the working pri Explain basic working of Rec Explain basics of communic Recall basic working of com rse Outcomes Mapping with Program Outcomes→	ecordi ls, op ng: Mi receiv munic ronic (tronic tr	ng me tical di odulati er and cation: UNI Calcula cs, Indu urse st ucers. s of dis ng, stor and bro y used ram O 3 4	thods iscs- r on: A Super digital f-III tor, M istrial udent splay u age de badcas electro utcon	-mag record M, Fl rhete cellu icrow Elect will t units evices sting onic onic onic onic onic onic onic onic	ynetic i ding ai M PCN rodyne ilar pho vave ov ronics be able and CC s	ecorc nd pla I, Rad receip one, e ens, V and I to TV ca	aybac dio tr iver. F stabli Washi Robot	ng M ics, E	al rec m pr itters optics a ca 10 achir ilectro	ordir ojecto , Rad , Rad II. Hour es, A

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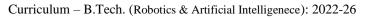
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EC2501-1.3

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NITTE (Deemed to be University)

(Deemed to be	University)			-		-								
	EC2501-1.4	1	-	-	-	-	1	-	-	-	-	2	2	
	EC2501-1.5	1	-	-	-	-	1	-	-	-	-	2	2	
1: Lo	1: Low 2: Medium 3: High													
TEXTE	BOOKS:													
1.	Anand, "Consumer Electr	onic	:s", K	han	na p	ublio	catio	ns, 2	2011	•				
2.	•													
REFEF	REFERENCE BOOK:													
1.	1. Gulati R. R. "Modern Television Engineering", Wiley Eastern.													



	PCB DESIG	GN AND FAB	RICATION	
Cou	ırse Code	EC2502-1	Course Type	OEC
Теа	ching Hours/Week (L: T: P: S)	1:0:4:0	Credits	03
Tota	al Teaching Hours	15+0+52+0	CIE + SEE Marks	50+50
Pre	requisite	EC1001-1		
	Teaching Department: Ele	ectronics & Con	nmunication Engin	eering
Cour	se Objectives:			
1.	To enable students to gain ki	nowledge of Sc	hematic Design teo	chniques & PCB
	design techniques			
2.	To expose students to complete	e PCB Design &	manufacturing proc	cess
		Unit-I		
	uit Schematic			05 Hours
	duction to Kicad schematic desig	n tool, features,	node connections,	labeling, creating
new	component.			
	1	Unit-II		
	Layout:			05 Hours
	duction to Kicad layout editor, fe	,		a auto routing ir
NICac	d, verification of footprint, creating	g lootprint for a	given component.	
		Unit-III		
DCR	Fabrication	01111-111		05 Hours
	erating and verifying the PCB G	erber file prep	aring artwork for a	
	cation, preparing PCB artwork for		-	-
	ing, green masking and through		, <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u></u> , <u>_</u> , <u></u>	in placing, legene
1				
	Lis	t of Experimen	ts	
1	Exploring the Kicad Schem	atic and layout t	ool	
2	Developing a schematic cir	cuit for microph	one preamplifier	
3	Designing a single side PC	B layout for micr	ophone preamplifie	er
4	Developing a schematic cir	cuit for a microo	ontroller developm	ent board
5	Designing a double side PC	CB layout for a n	nicrocontroller deve	lopment board
6	Choosing a new sensor/dis	splay module an	d building a schema	atic circuit for the
	user level application			
7	Building a layout using sing			
8	Preparing the film for the			op silk (legend) to
0	fabricate a single side PCB			1 1 1 1
9	Preparing the film for the t			
10	solder mask and legend to			emical process
10	PCB routing, etching, cuttir	ng and drilling u	sing CNC machine	
C -				
	rse Outcomes: At the end of the			
1.	Draw schematic circuit and crea		or single or multilaye	er PCB
2.	Fabricate single and double-lay	er PCB		

						Curr	iculur	n – B.	Tech.	(Rob	otics & A	Artificial	l Intellig	;enece
Course (Outcomes Mapping v	with	Pro	gran	ו Ou	tcor	nes							
Pr	ogram Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
↓ 0	Course Outcomes													
	EC2502-1.1	3	-	-	-	-	-	-	1	-	-	-	-	
	EC2502-1.2	3	-	-	-	-	-	-	-	-	-	-	-	
1: Low 2	2: Medium 3: High													-
TEXTBO	OKS:													
1.	Peter Dalmaris, "Kic	ad L	ike a	a Pro	", Te	ch Ex	xploi	ratio	n.					
REFEREN	NCE BOOKS:													
1.	Peter Dalmaris, "Kic	ad L	ike a	a Pro	", Te	ch Ex	xploi	ratio	n.					
2.	David L. Jones, "PCI	B De	sign	Tuto	orials	", Al	terna	ate z	one,	2004	4.			
E Books	/ MOOCs/ NPTEL													
1.	www.alternatezone	.com	ו											

SPACE TECHNOLOGY AND APPLICATIONS										
Cou	ırse Code:	EC2503-1	Course Type	OEC						
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03						
Tot	al Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50						
Pre	requisite	EC1001-1								
	Teaching Department: Electronics & Communication Engineering									
Cour	rse Objectives:			1						
1.	Understand the general laws go			neters.						
2.	Discuss effect of space environm									
3.										
4. Calculate the uplink / downlink subsystem characteristics.										
	5. know the effects on the EM waves in propagation through space.									
6.	Explain the satellite launch in the									
7.	Discuss the different communication									
8.	8. Summarise Advanced space systems for mobile communication, VSAT, GPS.									
Sata	UNIT-I									
	Ilite Technology Ilite communications: Introduction	n Konlor's law	c definitions orbital	15 Hours						
	perigee heights, orbit perturbation	•		element, apogee						
-	e environment: Earth's Atmosphe			effects on snace						
-	ems, propagation of signal, Transm	•	-	enects on space						
-	llite Technology: Space segment		•	liability, Satellite						
	munication systems.	-,		, ,						
		UNIT-II		-						
Spac	e Applications			15 Hours						
Laun	ch Vehicles: Working, stages, F	uel, payload p	rotection, Navigation	n, guidance and						
	rol, Reliability, launching into oute	•	• •							
-	e Applications: Digital DBS TV, I	-	_	trol Station and						
	nk Antennas. Introduction, Radio a		-							
	ote Sensing: Introduction to Rem	note Sensing, C	Concepts and Applica	tions of satellite						
Remo	ote sensing.									
A also	and Canada Caratama	UNIT-III		10 Hours						
Advanced Space Systems Satellite Access: Introduction, Single Access, Pre-assigned FDMA, Demai										
	A, Spade system.	e Access, Fie	-assigned FDIVIA, De	emanu-Assigneu						
	i y	bilo sonvicos V	SAT Radarsat orbital	communication						
	Advanced space systems: Satellite mobile services, VSAT, Radarsat, orbital communication. Global Positioning Satellite System (GPS).									
000	Global Positioning Satellite System (GPS).									
Cour	rse Outcomes: At the end of the c	ourse student	will be able to							
1.	Discuss the fundamental princip			ms.						
2.										
	2. Understand the Propagation impairments of satellite link.									

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NITI	ΓE					C	urricu	lum –	B.Te	ch. (R	obotics	& Artifi	cial Intel	lligene
3.	Explain various segme	ents	emp	loye	d in :	satel	lite a	and c	grou	nd st	tation	•		
4.	Discuss the satellite la												ote	
	sensing.													
5.	Understand the differ	ent d	comr	nuni	catio	on sy	stem	ns us	ed fo	or sa	tellite	acce	ss and	llist
	the recent satellites th	at h	ave l	been	laui	nche	d foi	· mo	bile	com	munio	cation	, GPS.	
Cours	e Outcomes Mapping	j wit	h Pr	ogra	am C	Dutc	ome	S	ı.	r		1		-
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes													
	EC2503-1.1	3	2	2	-	1	-	-	-	-	-	-	-	
	EC2503-1.2	-	3	-	-	2	1	-	-	-	-	-	-	
	EC2503-1.3	3	-	-	1	-	1	1	-	-	-	-	-	
	EC2503-1.4	-	-	-	-	-	1	3	-	-	-	-	-	
	EC2503-1.5	-	-	-	-	-	3	3	2	-	-	-	-	
1: Lov	w 2: Medium 3: High													
TEXTE	BOOKS:													
1.	Dennis Roddy, "Sate	llite	Com	nmur	nicat	ions'	", Mc	Grav	v Hil	l ,19	96.			
2.	Timothy Pratt, "Sate	llite	Com	mur	icati	ons"	, Wil	ey Ir	ndia	Ltd ,	2006			
3.	K Ramamurthy, "Roo	cket	Prop	oulsic	on", l	McM	lillan	Pub	lishe	ers In	idia Lt	d, 20	10.	
REFER	RENCE BOOKS:													
1.	George Joseph, "Fur	ndan	nenta	als o	f Rer	note	e Sen	sing	", Ur	niver	sities	press,	India	200
2.	B C Pande, "Remote	sen	sing	and	Арр	licat	ions'	′, VI∖	/A Bo	ooks	pvt lt	d, 200	09.	
3.	Meynart Roland, "Se	ensoi	rs sy	stem	s an	d ne	xt ge	enera	ation	sate	ellites	", SPIE		
	Publication.													
4.	Thyagarajan , "Space	e Env	/iron	men	t", IS	SRO	Hand	d Bo	ok Pi	ublic	ation			
E Boo	ks / MOOCs/ NPTEL													
1.	https://nptel.ac.in/co	ourse	es/10	0110	<u>6046</u>	5								



Course Code:	EE2501-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EE1001-1		
Teaching Department:	Electrical & I	Electronics Engineering)
Course Objectives:			
1 To familiarize various concepts	s of BMS		
2 To understand functional bloc	ks of BMS		
3 To study design steps of BMS			
4 To introduce hardware implen	nentation of B	MS	
	UNIT-I		
Battery System			08 Hours
Introduction, Cells, Batteries, and Pack	ks, Resistance,	Li-Ion Cells, Formats, Ch	emistry, Safety
Safe Operating Area, Efficiency, Aging, BMSs, BMS Definition, Li-Ion BMS Fun	ctions, Custon	n Versus Off-the-Shelf, L	-
SOC, DOD, and Capacity, Balance and	Balancing, SO	H	07 Hours
BMS Options Functionality, CCCV Chargers, Reg			
Functionality Comparison, Technology Comparison, Topology, Centralized,	, Simple (Analo	og), Sophisticated (Digita	al), Technolog
Functionality Comparison, Technology Comparison, Topology, Centralized,	, Simple (Analo	og), Sophisticated (Digita	al), Technolog
Functionality Comparison, Technology Comparison, Topology, Centralized, Comparison BMS Functions	r, Simple (Analo Modular UNIT-II	og), Sophisticated (Digita Master-Slave, Distribu	al), Technolog ted, Topolog 07 Hours
Functionality Comparison, Technology Comparison, Topology, Centralized, <u>Comparison</u> BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V	r, Simple (Analo Modular UNIT-II re, Current, on, Distributed ry, Resistance Vire, Dedicated	og), Sophisticated (Digita Master-Slave, Distribut Management, Protec Charging, Evaluation, S , State of Health (S d Digital Wire, Data Linl	al), Technolog ted, Topolog 07 Hours tion, Therma state of Charg SOH), Externa
Functionality Comparison, Technology Comparison, Topology, Centralized, <u>Comparison</u> BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V Telemetry, Off-the-Shelf BMSs, Cell Ma	r, Simple (Analo Modular UNIT-II re, Current, on, Distributed ry, Resistance Vire, Dedicated	og), Sophisticated (Digita Master-Slave, Distribut Management, Protec Charging, Evaluation, S , State of Health (S d Digital Wire, Data Linl	al), Technolog ted, Topolog tion, Therma state of Charg SOH), Externa k, Logging and
Functionality Comparison, Technology Comparison, Topology, Centralized, Comparison BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V Telemetry, Off-the-Shelf BMSs, Cell Ma Custom BMS Design Using BMS ASICs , BMS ASIC Compar Monitor, Analog Balancer, Analog Pro BMS Processor, Elithion's BMS Chip S Perkin's Open Source BMS, Texas I bq78PL114/bq76PL102, Custom Di Measurement, Current Measureme Switching, Logging, Cell Interface, Nor	y Simple (Analo Modular UNIT-II re, Current, on, Distributed y, Resistance Vire, Dedicated anufacturers' E otector, Ready Set, National S instruments' k igital BMS ent, Evaluatio	bg), Sophisticated (Digita Master-Slave, Distribut Management, Protect Charging, Evaluation, S , State of Health (S d Digital Wire, Data Link BMSs, Comparison BMS Design, Analog Reg -Made, Digital BMS De Semiconductors' Comple Semiconductors' Comple Semiconductors' Comple Semiconductors, Texa Design, Voltage and Dn, Communications,	al), Technology ted, Topology tion, Therma State of Charge SOH), Externa k, Logging and ola Hours gulator, Analog signs, ATMEL' ete BMS, Peter s Instruments Temperature Optimization
Functionality Comparison, Technology Comparison, Topology, Centralized, <u>Comparison</u> BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V Telemetry, Off-the-Shelf BMSs, Cell Ma Custom BMS Design Using BMS ASICs , BMS ASIC Compar Monitor, Analog Balancer, Analog Pro BMS Processor, Elithion's BMS Chip S Perkin's Open Source BMS, Texas I bq78PL114/bq76PL102, Custom Di Measurement, Current Measureme	r, Simple (Analo , Modular UNIT-II Tre, Current, on, Distributed anufacturers' E vire, Dedicated anufacturers' E otector, Ready Set, National S instruments' k igital BMS ent, Evaluation	bg), Sophisticated (Digita Master-Slave, Distribut Management, Protect Charging, Evaluation, S , State of Health (S d Digital Wire, Data Link BMSs, Comparison BMS Design, Analog Reg -Made, Digital BMS De Semiconductors' Comple Semiconductors' Comple Semiconductors' Comple Semiconductors, Texa Design, Voltage and Dn, Communications,	al), Technolog ted, Topolog 07 Hours tion, Therma state of Charg GOH), Externa k, Logging and 08 Hours gulator, Analog signs, ATMEL ete BMS, Peter s Instruments Temperatur Optimizatior
Functionality Comparison, Technology Comparison, Topology, Centralized, Comparison BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V Telemetry, Off-the-Shelf BMSs, Cell Ma Custom BMS Design Using BMS ASICs , BMS ASIC Compar Monitor, Analog Balancer, Analog Pro BMS Processor, Elithion's BMS Chip S Perkin's Open Source BMS, Texas I bq78PL114/bq76PL102, Custom Di Measurement, Current Measureme Switching, Logging, Cell Interface, Nor	y Simple (Analo Modular UNIT-II re, Current, on, Distributed y, Resistance Vire, Dedicated anufacturers' E otector, Ready Set, National S instruments' k igital BMS ent, Evaluatio	bg), Sophisticated (Digita Master-Slave, Distribut Management, Protect Charging, Evaluation, S , State of Health (S d Digital Wire, Data Link BMSs, Comparison BMS Design, Analog Reg -Made, Digital BMS De Semiconductors' Comple Semiconductors' Comple Semiconductors' Comple Semiconductors, Texa Design, Voltage and Dn, Communications,	al), Technology ted, Topology tion, Therma state of Charge SOH), Externa k, Logging and 08 Hours gulator, Analog signs, ATMEL' ete BMS, Pete is Instruments Temperature Optimization Charging
Functionality Comparison, Technology Comparison, Topology, Centralized, <u>Comparison</u> BMS Functions Measurement, Voltage, Temperatu Management, Balancing, Redistributio and Depth of Discharge, Capacit Communications, Dedicated Analog V Telemetry, Off-the-Shelf BMSs, Cell Ma Custom BMS Design Using BMS ASICs , BMS ASIC Compar Monitor, Analog Balancer, Analog Pro BMS Processor, Elithion's BMS Chip S Perkin's Open Source BMS, Texas I bq78PL114/bq76PL102, Custom Di Measurement, Current Measureme	r, Simple (Analo , Modular UNIT-II Tre, Current, on, Distributed anufacturers' E vire, Dedicated anufacturers' E otector, Ready Set, National S instruments' k igital BMS ent, Evaluation	bg), Sophisticated (Digita Master-Slave, Distribut Management, Protect Charging, Evaluation, S , State of Health (S d Digital Wire, Data Link BMSs, Comparison BMS Design, Analog Reg -Made, Digital BMS De Semiconductors' Comple Semiconductors' Comple Semiconductors' Comple Semiconductors, Texa Design, Voltage and Dn, Communications,	al), Technolog ted, Topolog tion, Therm state of Charg GOH), Extern k, Logging an 08 Hours gulator, Analo signs, ATMEL ete BMS, Pete s Instrument Temperatur Optimizatio

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Course Outcomes: At the end of the course student will be able to

1	Identify process to implement BMS
2	Describe various communication protocol involved in BMS
3	Illustrate functionality of BMS
4	Apply concepts of BMS using application specific IC
5	Analyse the hardware implementation aspects of BMS

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
EE2501-1.1	1	З	1	1	I	-	-	1	-	-	-	-
EE2501-1.2	1	З	1	1	I	-	-	1	1	-	-	-
EE2501-1.3	1	2	3	I	I	-	-	I	1	-	-	-
EE2501-1.4	1	2	2	3	-	-	-	-	-	-	-	-
EE2501-1.5	1	3	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

1	Davide Andrea, "Battery Management Systems for Large Lithium-Ion Battery Packs",
	ARTECH HOUSE 2010.

REFERENCE BOOKS:

1	Rui Xiong, "Ba	ttery Managemer	nt Algorithm for Elec	tric Vehicles", Springer 2019.
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2 Nicolae Tudoroiu, "Battery Management Systems of Electric and Hybrid Electric Vehicles", MDPI 2021



	BIOMEDICA	AL INSTRUM	MENTATION	
Cou	rse Code:	EE2502-1	Course Type	OEC
Teac	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tota	I Teaching Hours	40	CIE + SEE Marks	50+50
Prer	equisite	EC1001-1		
	Teaching Department:	Electrical &	Electronics Engineerin	g
Cours	se Objectives:			
1.	The course is designed to give	e the basic co	ncepts of Instrumentat	ion involved in
-	medical field and human phys			
2.	To introduce an fundamental		as applicable to physic	ology
3.	To explore the human body pa			
4.	To make the students underst	and the basic	concepts of forensic te	chniques.
5.	To give basic ideas about Elec	trophysiologic	cal measurements, med	ical imaging
		UNIT-I		
Physi	ology and transducers			08 Hours
neura	e nervous system, Structure of r Il communication, Cardiovascular	r system, resp	iratory system, Basic co	omponents of
	edical system, Transducers, sele		Piezo-electric, ultraso	nic transducers
remp	erature measurements Finer ont			
	erature measurements, Fiber opt			
Electi Electr	r o – Physiological measuremen odes: Limb electrodes, floating e	ts electrodes, pr	e .	ectrodes, Micro
Electr Electr needl ampli Typica	ro – Physiological measuremen	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro	blifiers, differential amp Lead systems and reco nment: shock hazards, l	ectrodes, Micro olifiers, choppe ording methods
Electr Electr needl ampli Typica	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Ampl fiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in r	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro	blifiers, differential amp Lead systems and reco nment: shock hazards, l	ectrodes, Micro olifiers, choppe ording methods
Electr Electr needl ampli Typica Instru Non-	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Ampl fiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in r iments for checking safety param	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II eents	blifiers, differential amp Lead systems and reco Inment: shock hazards, l edical equipment.	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours
Electr Electr needl ampli Typica Instru Meas functi Blood	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Ampl fiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in r iments for checking safety param	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II unts unts undiac output, Photo Pleth	blifiers, differential amp Lead systems and reco inment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Pla	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography
Electr Electr needl ampli Typica Instru Meas functi Blood ESR, C	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Ampl fiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in r iments for checking safety param electrical parameter measurem urement of blood pressure, Ca ion measurements, spirometer, I Gas analyzers : pH of blood, me GSR measurements	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II unts unts undiac output, Photo Pleth	blifiers, differential amp Lead systems and reco inment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Pla	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximete
Electr Electr needl ampli Typica Instru Mon- Meas functi Blood ESR, C Medi Radio MRI,	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Ampl fiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in r iments for checking safety param electrical parameter measurem urement of blood pressure, Ca ion measurements, spirometer, I Gas analyzers : pH of blood, me	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II UNIT-II nents rdiac output, Photo Pleth easurement of ques, X rays, C	olifiers, differential amp Lead systems and reco nment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Plo blood pCO2, pO2, fing omputer tomography,	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximete 07 Hours Mammography
Electr Electr needl ampli Typica Instru Mon- Meas functi Blood ESR, C Medi Radio MRI,	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Amplifiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in re- iments for checking safety parameter urement of blood pressure, Ca ion measurements, spirometer, I Gas analyzers : pH of blood, me GSR measurements cal Imaging ographic and fluoroscopic technic fMRI, Ultrasonography, Endosco	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II UNIT-II nents rdiac output, Photo Pleth easurement of ques, X rays, C	olifiers, differential amp Lead systems and reco nment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Plo blood pCO2, pO2, fing omputer tomography,	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximete 07 Hours Mammography
Electr Electr needl ampli Typica Instru Meas functi Blood ESR, C Medi Radio MRI, syster	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Amplifiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in re- iments for checking safety parameter urement of blood pressure, Ca ion measurements, spirometer, I Gas analyzers : pH of blood, me GSR measurements cal Imaging ographic and fluoroscopic technic fMRI, Ultrasonography, Endosco	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II ents rdiac output, Photo Pleth easurement of ques, X rays, C opy, Thermogr	olifiers, differential amp Lead systems and reco nment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Plo blood pCO2, pO2, fing omputer tomography,	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximete 07 Hours Mammography of biotelemetr
Electr Electr needl ampli Typica Instru Mon- Meas functi Blood ESR, C Medi Radio MRI, syster Assis	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Amplifiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in re- ments for checking safety parameter ments for checking safety parameter electrical parameter measurement urement of blood pressure, Ca ion measurements, spirometer, I Gas analyzers : pH of blood, me GSR measurements cal Imaging ographic and fluoroscopic technic fMRI, Ultrasonography, Endosco ms and patient monitoring	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II nents rdiac output, Photo Pleth easurement of ques, X rays, C opy, Thermogr UNIT-III	blifiers, differential amp Lead systems and reco onment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Plo blood pCO2, pO2, fing omputer tomography, raphy, Different types	olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximeter 07 Hours Mammography of biotelemetr
Electr Electr needl ampli Typica Instru Meas functi Blood ESR, (Medi Radio MRI, syster Pacer	ro – Physiological measurement odes: Limb electrodes, floating of e and surface electrodes, Amplifiers, Isolation amplifier. ECG, EE al waveforms. Electrical safety in re- iments for checking safety parameter urement of blood pressure, Ca- ion measurements, spirometer, I Gas analyzers : pH of blood, me GSR measurements cal Imaging ographic and fluoroscopic technic fMRI, Ultrasonography, Endosco ms and patient monitoring ting and therapeutic equipmen	ts electrodes, pr ifiers: Preamp G, EMG, ERG, nedical enviro eters of biom UNIT-II ents ordiac output, Photo Pleth easurement of ques, X rays, C opy, Thermogo UNIT-III ts: 5, Nerve and	blifiers, differential amp Lead systems and reco onment: shock hazards, l edical equipment. Heart rate, Heart so ysmography, Body Plo blood pCO2, pO2, fing omputer tomography, raphy, Different types	ectrodes, Micro olifiers, choppe ording methods eakage current 08 Hours und Pulmonar ethysmography er-tip oximete 07 Hours Mammography of biotelemetr

	D University)						Curric	ulum -	– B.I¢	cn. (R	obotics	& Artific	cial Intellig	;enece): 2
1	Understand the p	ohysi	olog	y of k	biom	edica	ıl sys [.]	tem						
2	Measure biomed	dical	and	physi	olog	ical i	nforn	natio	n					
3	Discuss the appli	catic	n of	Elect	ronic	s in o	diagr	ostic	s and	d the	rapeu	itic are	ea.	
4	Analyze the imag	jes a	nd do	сар	redic	tion	using	j ima	ge p	roces	ssing.			
5	Understand the c	liffer	ent e	quip	ment	's us	ed fo	r vari	ious ı	meas	urem	ents o	f physic	ology
C οι	irse Outcomes Mapp	oing	with	Prog	gram	Out	com	es	-		-			
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes													
	EE2502-1.1	3	3	-	2	1	1	-	-	-	-	-	-	
	EE2502-1.2	2	2	2	2	-	-	-	-	-	-	-	-	
	EE2502-1.3	3	2	2	1	2	1	-	-	-	-	-	-	
	EE2502-1.4	2	3	-	-	1	-	-	-	-	-	1	-	
	EE2502-1.5	3	3	-	-	2	-	-	-	-	-	2	-	
1: L	ow 2: Medium 3: Hig	gh												
TEX	TBOOKS:													
1.	Leslie Cromwell, I									ledic	al Ins	trume	ntation	and
-•	Measurements", II													
2.	R. S. Khandpur,			ok of	Bio	-Meo	dical	instr	ume	ntati	on", 1	Fata N	AcGraw	/ Hill
	Publishing CoLtd.,													
3.	J. Webster, "Medio													
4.	L. A. Geddes and			er, "F	Princi	ples	of A	pplie	d Bio	o-Me	dical	Instru	mentat	ion",
	John Wiley & Son													
5.	David. Cooney and	d Mi	chel l	Deck	ker, "	Bio-	Med	ical E	ngin	eerir	ig Prir	nciples	s", INC.	
REF	ERENCE BOOKS:													
	David Cooney, "				ngin	eerin	g Pr	incip	oles",	201	5, 1s	t Edit	ion, M	arcel
1	Deckker Pub Co.,	New	York	•										

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ELECTRIC VEHICLE TECHNOLOGY

Course Code:	EE2503-1	Course Type	OEC		
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03		
Total Teaching Hours	40+0+0	CIE + SEE Marks	50+50		
Prerequisite	EE1001-1				

Teaching Department: Electrical & Electronics Engineering

Course Objectives:

Vehicle Mechanics

1	To Understand the fundamental laws and vehicle mechanics.
2	To Understand working of Electric Vehicles and recent trends.
3	Ability to analyze different power converter topology used for electric vehicle application
4	Ability to develop the electric propulsion unit and its control for application of electric vehicles

UNIT-I

07 Hours

Roadway Fundamentals, Laws of Motion, Vehicle Kinetics, Dynamics of Vehicle Motion, Propulsion Power, Force-Velocity Characteristics, Maximum Gradability, Velocity and Acceleration, Constant FTR, Level Road, Velocity Profile, Distance Traversed, Tractive Power, Energy Required, Nonconstant FTR, General Acceleration, Propulsion System Design..

Electric and Hybrid Electric Vehicles 07 Hours Configuration of Electric Vehicles, Performance of Electric Vehicles, Traction motor characteristics, Tractive effort and Transmission requirement, Vehicle performance, Tractive effort in normal driving, Energy consumption Concept of Hybrid Electric Drive Trains, Architecture of Hybrid Electric Drive Trains, Series Hybrid Electric Drive Trains, Parallel hybrid electric drive train).

UNIT-II

08 Hours

08 Hours

10 Hours

Energy storage for EV and HEV Energy storage requirements, Battery parameters, Types of Batteries, Modelling of Battery, Fuel Cell basic principle and operation, Types of Fuel Cells, PEMFC and its operation, Modelling of PEMFC, Supercapacitors.

Electric Propulsion

EV consideration, DC motor drives and speed control, Induction motor drives, Permanent Magnet Motor Drives, Switch Reluctance Motor Drive for Electric Vehicles, Configuration and control of Drives.

Design of Electric and Hybrid Electric Vehicles

Series Hybrid Electric Drive Train Design: Operating patterns, control strategies, Sizing of major components, power rating of traction motor, power rating of engine/generator, design of PPS Parallel Hybrid Electric Drive Train Design: Control strategies of parallel hybrid

UNIT-III



drive train, design of engine power capacity, design of electric motor drive capacity, transmission design, energy storage design.

Course Outcomes: At the end of the course student will be able to

1	Explain the roadway fundamentals, laws of motion, vehicle mechanics and propulsion system design						
2	2 Explain the working of electric vehicles and hybrid electric vehicles in recent trends.						
3	Model batteries, Fuel cells, PEMFC and super capacitors.						

4 Analyze DC and AC drive topologies used for electric vehicle application.

5 Develop the electric propulsion unit and its control for application of electric vehicles.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
↓ Course Outcomes													
EE2503-1.1	2	3	-	-	-	-	-	-	-	-	-	-	
EE2503-1.2	1	2	3	-	-	-	-	-	-	-	-	-	
EE2503-1.3	1	2	3	-	-	-	-	1	-	-	-	-	
EE2503-1.4	1	2	3	-	-	-	-	-	-	-	-	-	
EE2503-1.5	1	2	2	-	-	_	-	-	_	-	3	-	

1: Low 2: Medium 3: High

TEXT	BOOKS:					
1	Iqbal Husain, "Electric and Hybrid Vehicles: Design Fundamentals", CRC Press, 2003.					
2	M. Ehsani, Y. Gao, S.Gay and Ali Emadi, "Modern Electric, Hybrid Electric, and Fuel					
2	Cell Vehicles: Fundamentals, Theory, and Design", CRC Press, 2005.					
REFE	RENCE BOOKS:					
1	Sheldon S. Williamson, "Energy Management Strategies for Electric and Plug-in					
-	Hybrid Electric Vehicles", Springer, 2013.					
2	C.C. Chan and K.T. Chau, "Electric Vehicle Technology", OXFORD University, 2001					
3	Chris Mi, M. Abul Masrur, David Wenzhong Gao, "Hybrid Electric Vehicles Principles					
5	And Applications with Practical Perspectives", Wiley Publication, 2001					
E Boo	oks / MOOCs/ NPTEL					
1.	Introduction to Mechanics Coursera					
2.	Electric Vehicles - Part 1 - Course (nptel.ac.in)					
3.	NPTEL: Electrical Engineering - Introduction to Hybrid and Electric Vehicles					
4.	Hybrid Vehicles (edX) MOOC List (mooc-list.com)					
5.	Electric Cars: Technology My MOOC (my-mooc.com)					



FUNDAMENTALS OF PLC AND ITS APPLICATIONS

O4-1 Course Type OEC 0 Credits 03 CIE + SEE Marks 50+50 01-1 cal & Electronics Engineering ctions, basic sequence of operation of PLC. guages and fundamental wiring diagrams. ter instructions, applying combinations of losed-loop control system, various forms of ctions cesses, structures of control systems and the ferent industrial processes
CIE + SEE Marks 50+50 01-1
D1-1 Cal & Electronics Engineering <u>ctions, basic sequence of operation of PLC.</u> <u>guages and fundamental wiring diagrams.</u> ter instructions, applying combinations of losed-loop control system, various forms of tions cesses, structures of control systems and the ferent industrial processes
ctions, basic sequence of operation of PLC. guages and fundamental wiring diagrams. ter instructions, applying combinations of losed-loop control system, various forms of tions cesses, structures of control systems and the ferent industrial processes
ctions, basic sequence of operation of PLC. guages and fundamental wiring diagrams. ter instructions, applying combinations of losed-loop control system, various forms of tions cesses, structures of control systems and the ferent industrial processes
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tions cesses, structures of control systems and the ferent industrial processes
esses, structures of control systems and the ferent industrial processes
ferent industrial processes
T-I
02 Hours
ation, PLC Size and Application.
05Hours
(CPU), Memory Design, Memory Types ine Interface (HMIs).
05Hours
al blocks, Program examples, instruction lis quential functions charts, branching an onal and iteration statements
agrams and Ladder Logic
03Hours
03Hours Notor Starters, Manually Operated Switches
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi F-II 02 Hours
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi F-II 02 Hours d Methods of Energy Storage (Classification)
03Hours Notor Starters, Manually Operated Switches out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi
03Hours Motor Starters, Manually Operated Switches Out Control Devices, Seal-In Circuits, Latching C Ladder Programs, Writing a Ladder Logi F-II 02 Hours d Methods of Energy Storage (Classification resentation)
c functions with timing diagram al blocks, Program examples, instr quential functions charts, branc onal and iteration statements

NIT	TE				(Curric	culum	1 – B.	Tech	. (Rol	ootics &	Artificial	Intelligen	ece
Prog	ram Control Instructions											0!	5 Hou	rs
Mast and I	er Control Reset Instruction, mmediate Output Instruction table Timed Interrupt, Fault	ns, F	orci	ng E	xter	nal I	[/0 /	Add	ress	es, S	Safety	Circuit	ry,	
	Manipulation Instructions		.mc,	TCH	ipoi	ary	LIIU	1113	iuci	.1011,	Jusp		2 Hou	
	Manipulation, Data Transfer		rati	ons	Dat	a Co	mn	are	Inst	ructi	ions D		- 1104	_
	pulation Programs, Numeric	•					•							
	Instructions												2 Hou	rs
Math	Instructions, Addition Instru	ictio	n, Sı	ubtra	actio	n Ir	nstru	ictio	n, N	1ulti	plicati	on Inst	ructio	n,
Divis	on Instruction, Other Word-	Leve	l Ma	ath I	nstr	uctio	ons,	File	Arit	hme	etic Op	peratio	ns	
				UNI	T-III									
Sequ	encer and Shift Register In	stru	ctio	ns								0	5 Hou	ſS
	anical Sequencers, Sequenc I Shift Operations.	er I	nstru	uctio	ons,	Seq	uen	cer	Pro	gran	ns, Bit	Shift	Registe	er
Proc	ess Control, Network Syste	ms,	and	SC	ADA							0!	5 Hou	ſS
Туре	s of Processes, Structure of	Co	ntro	l Sy	sten	ns, ()/On	Off	Con	trol,	PID (Contro	l, Mot	io
Control, Data Communications, Supervisory Control and Data Acquisition (SCADA).														
Cour	se Outcomes: At the end of	the	cou	rse s	stud	ent	will	be a	ble	to				
	Identify main parts, functions of PLC and describe basic circuitry for I/O modules to													
1.														
Apply suitable logic using various programming languages to achieve specific														
2.	2. control mechanism for a given application													
2	Identify timer/counter res	ourc	es c	ot a	PLC	. to	des	sign	cor	itrol	logic	for in	terface	эd
3.	device.			- 41- 3		:								
4.	Interpret data manipulation												-	
5.	Develop programs that use of a closed loop control sys			giste	ers a	na e	expl	ain i	unc	uon	S OF CC	ontrol e	lemen	lS
5.		sterr	1											
C		. D.			.									
Cour	se Outcomes Mapping wit	1	2	am (3	1		1	7	0	0	10	11	10	Г
	Program Outcomes→ , Course Outcomes	1	2	5	4	5	6	/	8	9	10	11	12	
_	EE2504-1.1	3												
	EE2504-1.1 EE2504-1.2	5	-3	-			-			_	_			•
	EE2504-1.2 EE2504-1.3	1	2	-	<u>-</u>	<u> </u>	<u>-</u>	-	<u> </u>			<u> </u>	_	•
	EE2504-1.5	1	2	3	-		-	<u> </u>	- -	<u> </u>		<u> </u>	-	
	EE2504-1.4 EE2504-1.5	1	2	3	<u>-</u>	<u> </u>	<u>-</u>	-	<u> </u>			<u> </u>	_	
1.1.		1		J	-		<u> </u>	-		-		L _	I -	J
1: L(ow 2: Medium 3: High													
TEVT	BOOKS:													
<u>ובאו</u> 1.	Frank Petruzella, "Program	min		aic	Con	troll	orc"	Cif.	th E	ditic	n			
<u> </u>	W Bolton, "Programmable			-									2015	
۷.	I vy bolton, Frogrammable	LUY	IL L	וחוו	uner	s, 0	uit	uiti	un, I	-126/	191-11	ewnes:	s, ZUIC	٠.

	NITT eemed to be Unive	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 20
	1.	John W Webb, Ronald A Reis, "Programmable logic controllers - principles and
		applications", 5th edition, 2nd impression, Pearson education, 2009
		L. A Bryan, E. A Bryan, "Programmable Controller Theory and Implementations", 2nd edition, 2003
	3.	S. P. Sukhumi, J. K. Nayak, "Solar Energy: Principles Collection and Storage", 3rd edition, McGraw-Hill Education (India), 2009.
E	Book	ss / MOOCs/ NPTEL
1	1.	https://library.automationdirect.com/category/product/programmable-control/
2		https://www.coursera.org/lecture/intelligent-machining/programmable-logic- controllers-plc-fGz3r
	3.	https://www.udemy.com/course/plc-programming-from-scratch/



Course Code:	EE2505-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	EE1001-1	•	·
Too shine Donortoo oot			

Teaching Department: Electrical & Electronics Engineering

Course Objectives:

NITTE

- **1.** Study architecture of induction motor and synchronous motor
- 2. Understanding control of AC motor
- **3.** Study principle of operation of different dc motors
- **4.** Understand the different types of control techniques
- **5.** Study different sensors and their role in control of a motor

UNIT-I

08 Hours

Introduction, Three phase AC motor architecture, Torque speed curve, wound rotor, Synchronous motors

Single phase AC motors, split phase motor, capacitor start and shaded pole motors, Universal and gear motors, AC Motor Specifications, Specifying an AC motor for an application.

AC Motor Control:

AC Motor Designs

AC motor Enclosures, AC motor control components, Manual motor starting systems, Direct On Line Starter, semi-automatic star delta starter, fully automatic star delta starter, control circuit for sequence operation of two motors

UNIT-II

DC Motors

DC motor principle of operation, Brushed DC motors, shunt, series and compound wound motors, Brushless DC motors, driving a brushless DC motor, Commutation, Specifying a DC motor

DC Motor Control and Stepper Motors

Stepper motor principles of operation, Illustrative example of a stepper motor drive, stepper motor specification and operation, commercial stepper motor drive chips and packages, Direction Controller- H Bridge, Speed Controller: Pulse Width Modulation (PWM), Armature Controller: Variable resistance, DC vs.AC motors

UNIT-III

Sensors

Unipolar Hall Effect Switches, Omnipolar Hall Effect Switches, Latched Hall Effect Switches, Current Sensors: Shunt resistor, Current-sensing transformer, Hall effect current sensor, Speed/position sensors: Quadrature encoder, Hall effect tachometer, Back EMF/Sensorless control method, BLDC motor control with Hall sensor, Block diagram approach of BLDC Fan and Motor Control

08 Hours

07 Hours

10 Hours

07 Hours

10 Ho

Course Outcomes: At the end of the course student will be able to

1.	Demonstrate an understanding of the general principles of AC Motor.
	Understand the basic principles of AC motor controls which includes starters,
2.	contactors, and control relays
3.	Demonstrate an understanding of the general principles of DC Motor.
	Understand the basic principles of DC motor controls which includes starters,
4.	contactors, and control relays
5.	Set up sensors in order to give feedback to a control circuit

Course Outcomes Mapping with Program Outcomes

Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes→												
↓ Course												
Outcomes												
EE2505-1.1	3	-	-	-	-	-	-	-	-	-	-	-
EE2505-1.2	2	3	3	-	-	2	-	-	-	-	-	-
EE2505-1.3	3	-	-	-	-	-	-	-	-	-	-	-
EE2505-1.4	2	3	3	-	-	2	-	-	-	-	-	-
EE2505-1.5	2	3	3	-	-	2	-	-	-	-	-	-
1: Low 2: Medium 3: H	ligh		•	•	•		•	•	•			·

TEXTBOOKS:

NITTE

1.	S. K. Bhattacharya Birjindersingh, "Control of electrical machines", New Age
	International.
2.	Gary J. Rockis & Glen A. Mazura, "Electrical Motor Controls", 5th Edition, ISBN
	number is 9780826912268

REFERENCE BOOKS:

1.	L. Stephen L. Herman, "Industrial Motor Control", Delmar Publishers, Inc., latest Edition.							
E Books / MOOCs/ NPTEL								
1.	https://www.coursera.org/learn/motors-circuits-design							
2.	http://ww1.microchip.com/downloads/en/appnotes/00894a.pdf							



NON-CONVENTIONAL ENERGY SOURCES

Co ι									
1	urse Code:	EE2506-1	Course Type	OEC					
Теа	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03					
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50					
Pre	erequisite	EE1001-1							
Teaching Department: Electrical & Electronics Engineering									
Cou	rse Objectives:								
1.	To understand the princip nonconventional sources	le of extracti	on of energy from c	onventional,					
2.	To understand the working principle and applications of solar based thermal								
3.	To justify the usage of energy storage techniques and understand the process of								
4.To understand the process of design and implement biomass based energy conversion systems									
		UNIT-I							
Ener	rgy Sources			03 Hours					
Reso	antages, Limitations, Comparisor ources, World Energy Scenario, Ind ar Energy Basics			05 Hours					
Intro Sola and	oduction, Solar Constant, Basic Sur r Radiation Geometry (numerical p	Introduction, Solar Constant, Basic Sun-Earth Angles – definitions and their representation, Solar Radiation Geometry (numerical problems), Estimation of Solar Radiation of Horizontal and Tilted Surfaces (numerical problems), Measurement of Solar Radiation Data –							
	J			of Horizontal					
Juid	r Thermal Systems			of Horizontal					
Princ Colle	e <mark>r Thermal Systems</mark> ciple of Conversion of Solar Radiat ectors), Solar Cookers – Box type, C aces, Solar Green House.		Solar Water Heaters (Flat	of Horizontal ation Data – 04 Hours Plate					
Princ Colle Furn	ciple of Conversion of Solar Radiat ectors), Solar Cookers – Box type, C		Solar Water Heaters (Flat	of Horizontal ation Data – 04 Hours Plate					
Prince Colle Furn Solar Colle Disac cons	ciple of Conversion of Solar Radiat ectors), Solar Cookers – Box type, C aces, Solar Green House.	Concentrating on neration, Sola Dish, Centra olar Cell funda y. Solar PV Syst lighting and S	Solar Water Heaters (Flat dish type, Solar driers, So r Pond and Concen I Tower Collector), Adv mentals, characteristics, rems- stand-alone and gr	of Horizontal ation Data – 04 Hours Plate blar Still, Solar 04 Hours trating Solar vantages and classification, rid connected,					
Princ Colle Furn Sola Colle Disa cons Appl	ciple of Conversion of Solar Radiat ectors), Solar Cookers – Box type, C aces, Solar Green House. IT Electric Systems r Thermal Electric Power Ger ector(Parabolic Trough, Parabolic dvantages; Solar Photovoltaic – So struction of module, panel and array lications- Street lighting, Domestic	Concentrating on neration, Sola Dish, Centra olar Cell funda y. Solar PV Syst	Solar Water Heaters (Flat dish type, Solar driers, So r Pond and Concen I Tower Collector), Adv mentals, characteristics, rems- stand-alone and gr	of Horizontal ation Data – 04 Hours Plate blar Still, Solar 04 Hours trating Solar vantages and classification, rid connected, tems.					
Princ Colle Furn Sola Colle Disa cons Appl Ener Intro	ciple of Conversion of Solar Radiat ectors), Solar Cookers – Box type, C <u>aces, Solar Green House.</u> I r Electric Systems Ir Thermal Electric Power Ger ector(Parabolic Trough, Parabolic dvantages; Solar Photovoltaic – So struction of module, panel and array	Concentrating on neration, Sola Dish, Centra olar Cell funda y. Solar PV Syst lighting and S UNIT-II rage and Meth	Solar Water Heaters (Flat dish type, Solar driers, So r Pond and Concent I Tower Collector), Adv mentals, characteristics, ems- stand-alone and gr olar Water pumping system ods of Energy Storage	of Horizontal ation Data – 04 Hours Plate blar Still, Solar 04 Hours trating Solar vantages and classification, rid connected, tems. 04 Hours					

Curriculum - B.Tech. (Robotics & Artificial Intelligenece): 2022-26

Introduction, Wind and its Properties, History of Wind Energy Wind Energy Scenario – World and India. Basic principles of WECS, Classification, Parts of a WECS, Derivation for Power in the wind, Electrical Power Output and Capacity Factor of WECS.

Wind site selection consideration, Advantages and Disadvantages of WECS.

Biomass Energy

NITTE

06 Hours

Introduction, Photosynthesis process, Biomass fuels, Biomass conversion technologies, Urban waste to Energy Conversion, Biomass Gasification, Biomass to Ethanol Production, Biogas production from waste biomass, Factors affecting biogas generation, types of biogas plants- KVIC and Janata model, Biomass program in India

UNIT-III

Energy From Ocean

Tidal Energy – Principle of Tidal Power, Components of Tidal Power Plant, Classification of Tidal Power Plant, Estimation of Energy – Single basin and Double basin type TPP (no derivations, Simple numerical problems), Advantages and Limitation of TPP. Ocean Thermal Energy Conversion (OTEC): Principle of OTEC system, Methods of OTEC power generation – Open Cycle (Claude cycle), Closed Cycle (Anderson cycle), Hybrid cycle, Site-selection criteria, Biofouling, Advantages & Limitation of OTEC

Emerging Technologies

Fuel Cell, Small Hydro Resources, Hydrogen Energy and Wave Energy (Principle of Energy generation using block diagrams, advantages and limitations)

Course Outcomes: At the end of the course student will be able to

1	Describe non-conventional energy sources and solar radiation geometry to estimate
1.	and measure solar radiation.
2	Apply the principle of solar radiation into heat to understand the operation of solar
2.	thermal and solar electric systems.
2	Describe energy storage methods and wind-energy conversion systems to
3.	understand the factors influencing power generation.
	Review the biomass conversion technologies to design biomass-based energy
4.	systems.
F	Describe tidal, ocean thermal and fuel cell energy conversion systems to understand
5.	emerging non-conventional energy technologies.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
↓ Course Outcomes													
EE2506-1.1	2	3	-	1	I	1	2	1	-	1	-	-	
EE2506-1.2	2	3	-	1	I	1	2	1	-	1	-	-	
EE2506-1.3	2	3	-	-	-	1	2	1	-	-	-	-	
EE2506-1.4	2	3	-	-	-	1	2	1	-	-	-	-	
EE2506-1.5	2	3	-	-	-	1	2	1	-	-	-	-	

05 Hours

05 Hours

1: Low 2: Medium 3: High

TEXTBOOKS:

NITTE

1. Rai G. D., "Non-Conventional Sources of Energy", 4th Edition, Khanna Publishers, New Delhi, 2007.

REFERENCE BOOKS:

- Mukherjee D. and Chakrabarti, S., "Fundamentals of Renewable Energy Systems", New Age International Publishers, 2005.
- 2. Khan, B. H., "Non-Conventional Energy Resources", TMH, New Delhi, 2006.
- **3.** S. P. Sukhumi, J. K. Nayak "Solar Energy: Principles Collection and Storage", 3rd edition, McGraw-Hill Education (India), 2009.

E Books / MOOCs/ NPTEL

1. https://nptel.ac.in/courses/108108078



Cοι	urse Code:	HU1501-1	Course Type	OEC			
Теа	ching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03			
Tot	al Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50			
	Teaching Depar	tment: Mechan	ical Engineering				
Cou	rse Objectives:						
1.	To give a brief history of the de	evelopment of Y	oga				
2.	Identify names of different clas	sical texts on Yo	oga				
3.	To illustrate how Yoga is impor	tant for healthy	living				
4.	To explain the Asanas and othe	er Yogic practice	S				
5.	To explain, how Yoga practices	can be applied	for overall improvemen	it			
		UNIT-I					
Yoga	9			09 Hours			
	ning and initiation, definitions a	nd basis of you	a History and develop				
	-			ment, Astanga			
voda		s for nealthy live	ING				
	a, Streams of yoga. Yogic practice eral quidelines for Yoga practices	•	-				
Gene	eral guidelines for Yoga practices	for the beginne	-	07 Hours			
Gene Class	eral guidelines for Yoga practices sification of Yoga and Yogic tex	for the beginne cts	ers: Asanas, Pranayama.	07 Hours			
Gene Class Yoga	eral guidelines for Yoga practices	for the beginne cts	ers: Asanas, Pranayama.	07 Hours			
Gene Class Yoga	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p	for the beginne cts	ers: Asanas, Pranayama.	07 Hours			
Gene Class Yoga	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p	for the beginne	ers: Asanas, Pranayama.	07 Hours			
Gene Class Yoga banc	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p	for the beginne cts practices- Asan	ers: Asanas, Pranayama.	07 Hours			
Gene Class Yoga banc	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas.	for the beginne xts practices- Asan UNIT-II	ers: Asanas, Pranayama. as, Pranayama, Dharan	07 Hours a, Mudras and 06 Hours			
Gene Class Yoga banc Yoga Cond	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health	for the beginne xts practices- Asan UNIT-II	ers: Asanas, Pranayama. as, Pranayama, Dharan	07 Hours a, Mudras and 06 Hours			
Gene Class Yoga banc Yoga Cond	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog	for the beginne xts practices- Asan UNIT-II	ers: Asanas, Pranayama. as, Pranayama, Dharan	07 Hours a, Mudras and 06 Hours			
Gene Class Yoga banc Yoga Conc disea	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog	for the beginne cts practices- Asan UNIT-II ic concept of b	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours			
Gene Class Yoga banc Voga Conc disea Yogi conc	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health.	for the beginne xts practices- Asan UNIT-II ic concept of b & regulations, y	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours			
Gene Class Yoga banc Yoga Conc disea Yogi conc App	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa	for the beginne cts practices- Asan UNIT-II ic concept of k & regulations, y tion	ers: Asanas, Pranayama. as, Pranayama, Dharan oody – pancakosa vivel yogic diet, ahara, vihara	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours			
Gene Class Yoga banc Yoga Conc disea Yogi conc App	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health.	for the beginne cts practices- Asan UNIT-II ic concept of k & regulations, y tion	ers: Asanas, Pranayama. as, Pranayama, Dharan oody – pancakosa vivel yogic diet, ahara, vihara	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perso	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa	for the beginne xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel yogic diet, ahara, vihara	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours cific guidelines			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perso	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa onality development- physical le	for the beginne xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve n development,	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel yogic diet, ahara, vihara	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours cific guidelines			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perso and	eral guidelines for Yoga practices sification of Yoga and Yogic tex- asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa onality development- physical le Yoga practices for - Concentratio	for the beginne xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel yogic diet, ahara, vihara	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours cific guidelines			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perse and	eral guidelines for Yoga practices sification of Yoga and Yogic tex- asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa onality development- physical le Yoga practices for - Concentratio a and physical development	for the beginner xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve n development, UNIT-III	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel vogic diet, ahara, vihara el, emotional level. Spec Memory development	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours cific guidelines 05 Hours			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perse and	eral guidelines for Yoga practices sification of Yoga and Yogic tex asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa onality development- physical le Yoga practices for - Concentratio	for the beginner xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve n development, UNIT-III	ers: Asanas, Pranayama. as, Pranayama, Dharan body – pancakosa vivel vogic diet, ahara, vihara el, emotional level. Spec Memory development	 07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours Yogic 04 Hours cific guidelines and Benefits. 			
Gene Class Yoga banc Yoga Conc disea Yogi conc App Perso and Yoga Minc	eral guidelines for Yoga practices sification of Yoga and Yogic tex- asutra of Patanjali, Hatha yogic p dhas. a and Health cept of health and Diseases-Yog ase according to Yoga Vasistha. c concept of healthy living- rules cept of holistic health. lied Yoga for elementary educa onality development- physical le Yoga practices for - Concentratio a and physical development	for the beginne xts practices- Asan UNIT-II ic concept of k & regulations, y tion vel, mental leve n development, UNIT-III d their types. D	ers: Asanas, Pranayama. as, Pranayama, Dharan oody – pancakosa vivel yogic diet, ahara, vihara el, emotional level. Spec Memory development	07 Hours a, Mudras and 06 Hours ka, Concept of 04 Hours . Yogic 04 Hours . Yogic 05 Hours and Benefits. 05 Hours			

At the end of the course student will be able to
--

- Understand a brief history of the development of Yoga 1.
- Know important practices and principles of Yoga 2.
- Explain how Yoga is important for healthy living 3.

4. Practice meditation to improvement of concentration etc.

NITTE

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5. Have knowledge about specific guidelines of yoga practices

	se Outcomes Mapping v	vith	Pro	gran	ו Ou	tcor	nes							
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
	HU1501-1.1	1	-	-	-	-	1	-	-	1	-	-	1	
	HU1501-1.2	I	-	-	-	I	1	-	-	1	I	-	3	
	HU1501-1.3	-	-	-	-	-	2	-	-	1	-	-	3	
	HU1501-1.4	-	-	-	-	-	3	-	-	2	-	-	3	
	HU1501-1.5	-	-	-	-	-	2	-	-	2	-	-	3	
1: Lo	w 2: Medium 3: High													
TEXT	BOOKS:													
1.	B. K. S. Iyengar, "Light o					sic G	iuide	to \	/oga	by t	he W	orld's	Forer	nost
	Authority", Thorsons pu													
2.	Makarand Madhukar Gore, "Anatomy and Physiology of Yogic Practices:													
						-		-				0		
	Understanding of the	Yogi	c Co	oncep	ots a	nd I	Physi	iolog	gical	Mec		0		
<u></u>		Yogi	c Co	oncep	ots a	nd I	Physi	iolog	gical	Mec		0		
3.	Understanding of the	Yogi rsida	c Co ass P	oncep ublis	ots a shers	nd I ; 6 e	Physi ditio	iolog n (20	gical 016).	Mec	hanis	m of	the Y	'ogic
3.	Understanding of the " Practices", Motilal Bana	Yogi rsida	c Co ass P	oncep ublis	ots a shers	nd I ; 6 e	Physi ditio	iolog n (20	gical 016).	Mec	hanis	m of	the Y	'ogic
	Understanding of the Practices", Motilal Bana Swami Satyananda Sat	Yogi rsida	c Co ass P	oncep ublis	ots a shers	nd I ; 6 e	Physi ditio	iolog n (20	gical 016).	Mec	hanis	m of	the Y	'ogic
	Understanding of the Practices", Motilal Bana Swami Satyananda Sat Publications Trust.	Yogi rsida rasw	c Cc ass P ati,	oncep ublis "Asa	ots a shers na, f	nd I ; 6 e Prana	Physi ditio ayan	iolog n (20 na, N	gical 016). Audr	Mec a ar	hanis nd Ba	m of ndha:	the Y 1", ነ	'ogic
REFE	Understanding of the " Practices", Motilal Bana Swami Satyananda Sat Publications Trust. RENCE BOOKS:	Yogi rsida rasw	c Cc ass P ati,	oncep ublis "Asa	ots a shers na, f	nd I ; 6 e Prana	Physi ditio ayan	iolog n (20 na, N	gical 016). Audr	Mec a ar	hanis nd Ba	m of ndha:	the Y 1", ነ	'ogic
REFE	Understanding of the Practices", Motilal Bana Swami Satyananda Sat Publications Trust. RENCE BOOKS: Ann Swanson, "Science	Yogi rsida rasw of Y	c Co ass P ati, oga:	ncep ublis "Asa Unc	ots a shers na, I lerst	rand I ; 6 e Prana and	Physi ditio ayam the A	iolo <u>c</u> n (20 na, N Anate	gical 016). Audr omy	Mec a ar and	hanis nd Ba Physi	m of ndha: ology	the Y 1", ነ	'ogic
REFE 1. 2.	Understanding of the Practices", Motilal Bana Swami Satyananda Sar Publications Trust. RENCE BOOKS: Ann Swanson, "Science Perfect Your Practice".	Yogi rsida rasw of Y	c Co ass P ati, oga:	ncep ublis "Asa Unc	ots a shers na, I lerst	rand I ; 6 e Prana and	Physi ditio ayam the A	iolo <u>c</u> n (20 na, N Anate	gical 016). Audr omy	Mec a ar and	hanis nd Ba Physi	m of ndha: ology	the Y 1", ነ	'ogic
REFE 1. 2.	Understanding of the Practices", Motilal Bana Swami Satyananda Sat Publications Trust. RENCE BOOKS: Ann Swanson, "Science Perfect Your Practice". Dianne Bondy, "Yoga fo	Yogi rsida rasw of Y or Ev	c Co ass P ati, oga: eryo	ncep ublis "Asa Unc ne :	ots a shers na, I lerst	and I ; 6 e Prana and	Physi ditio ayam the A For	iolog n (20 na, N Anato Ever	gical 016). Audr omy y Typ	Mec a ar and	hanis nd Ba Physi	m of ndha: ology	the Y 1", ነ	'ogic



NITTE

Cοι										
	urse Code	HU1502-1	Course Type	OEC						
Tea	aching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03						
Tot	tal Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50						
Teaching Department: Humanities										
Cou	rse Objectives:									
1.	Understand the creativity compo	nent in intellec	tual property, different	types of legal						
protection of intellectual properties and other basic concepts of Intellectual property.										
2. Analyze different types of protection for inventions, different types of agreements										
and treaties for Intellectual properties with an ability to examine patent types,										
•	specifications and patent search									
3.	Understand the basic procedure									
	forms of intellectual property rig protection of inventions like pate		to examine the protoc	or involved in						
L										
		UNIT - I								
Intro	oduction to Intellectual Property	1		08 Hours						
Inve	ntion and Creativity - Intellectual F	Property (IP) –	Importance, Jurisprude	ential definition						
and	concept of property, rights, duties	and their corre	lation; History and eval	luation of IPR –						
	Patents, Trademarks, Copyright	& Related R	ights, Industrial Desig	gn, Traditional						
Knov	wledge, Geographical Indications.									
۰	coments and Treaties									
	eements and Treaties ory - General Agreement on Trade	and Tariff (GA	IT). Indian Position vis-	08 Hours						
Histo Strat Inter and	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir endment) Rules, 2017	d Agreement; ellectual Prope	Hague Agreement; \ rty - Establishment of \	a-vis WTO and NIPO Treaties; NIPO - Mission						
Histo Strat Inter and	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir	d Agreement; ellectual Prope ndian Patent Ac	Hague Agreement; \ rty - Establishment of \	a-vis WTO and NIPO Treaties; NIPO - Mission						
Histo Strat Inter and (Amo	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir	d Agreement; ellectual Prope ndian Patent Ac UNIT - II	Hague Agreement; \ rty - Establishment of \	a-vis WTO and NIPO Treaties; NIPO - Mission						
Histo Strat Inter and (Amo	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir endment) Rules, 2017	d Agreement; ellectual Prope idian Patent Ac UNIT - II or Art	Hague Agreement; N rty - Establishment of N t 1970 & recent amend	a-vis WTO and NIPO Treaties; NIPO - Mission ments – Patent 08 Hours						
Histo Strat Inter and (Amo Basi Intro	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir endment) Rules, 2017	d Agreement; ellectual Prope ndian Patent Ac UNIT - II DATT Datent applica	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT,	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional,						
Histor Strat Inter and (Amo Basi Intro Divis	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p	d Agreement; ellectual Prope adian Patent Ac UNIT - II Dr Art Datent applica	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees						
Histo Strat Inter and (Amo Basi Intro Divis Inve	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec	d Agreement; ellectual Prope ndian Patent Ac UNIT - II or Art patent applica difications: Prov Patent database	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internatio	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees						
Histo Strat Inter and (Amo (Amo Basi Intro Divis Inve Cour	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO,	d Agreement; ellectual Prope ndian Patent Ac UNIT - II or Art patent applica difications: Prov Patent database	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internatio	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases;						
Histor Strat Inter and (Amo Basi Intro Divis Inve Cour Pate	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; Ir endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO,	d Agreement; ellectual Prope adian Patent Ac UNIT - II DATE Datent applica difications: Prove Patent database EPO, WIPO, IPO	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internatic D, etc.)	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours						
Histo Strat Inter and (Amo (Amo Basi Intro Divis Inve Cour Pate Natio	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO, ent filing procedures onal & PCT filing procedure; Time f	d Agreement; ellectual Prope adian Patent Ac UNIT - II or Art Datent applica difications: Prove Patent database EPO, WIPO, IPO rame and cost;	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internatic D, etc.) Status of the patent ap	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours plications filed;						
Histor Strat Inter and (Amo Basi Intro Divis Inve Cour Pate Nation	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric mational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO, ent filing procedures onal & PCT filing procedure; Time f cture of Patent document, Precau	d Agreement; ellectual Propendian Patent Ac UNIT - II DATE Datent applica difications: Prove Patent database EPO, WIPO, IPO rame and cost; utions while pa	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internatic D, etc.) Status of the patent ap atenting – disclosure/r	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours plications filed; non-disclosure;						
Histo Strat Inter and (Amo (Amo Basi Intro Divis Inver Cour Natio Struc Final	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Prio oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO, ent filing procedures onal & PCT filing procedure; Time f cture of Patent document, Precau ncial assistance for patenting - int	d Agreement; ellectual Propendian Patent Acc UNIT - II or Art Datent applica difications: Prove Patent database EPO, WIPO, IPO rame and cost; utions while paroduction to e	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internation D, etc.) Status of the patent ap atenting – disclosure/r xisting schemes; Paten	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours plications filed; non-disclosure;						
Histo Strat Inter and (Amo (Amo Basi Intro Divis Inve Cour Pate Natio Struc Final	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric mational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Pric oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO, ent filing procedures onal & PCT filing procedure; Time f cture of Patent document, Precau	d Agreement; ellectual Propendian Patent Acc UNIT - II or Art Datent applica difications: Prove Patent database EPO, WIPO, IPO rame and cost; utions while paroduction to e	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internation D, etc.) Status of the patent ap atenting – disclosure/r xisting schemes; Paten	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours plications filed; non-disclosure;						
Histo Strat Inter and (Amo (Amo Basi Intro Divis Inve Cour Pate Natio Struc Final	ory - General Agreement on Trade tegies; TRIPS Agreement; Madric rnational convention relating to Int Activities – Budapest Treaty; PCT; In endment) Rules, 2017 ics of Patents and Concept of Prio oduction to Patents; Types of p sional and Patent of Addition; Spec ntion in the context of "prior art"; F ntry-wise patent searches (USPTO, ent filing procedures onal & PCT filing procedure; Time f cture of Patent document, Precau ncial assistance for patenting - int	d Agreement; ellectual Propendian Patent Acc UNIT - II or Art Datent applica difications: Prove Patent database EPO, WIPO, IPO rame and cost; utions while paroduction to e	Hague Agreement; N rty - Establishment of N t 1970 & recent amend tions: Ordinary, PCT, isional and complete; F es; Searching Internation D, etc.) Status of the patent ap atenting – disclosure/r xisting schemes; Paten	a-vis WTO and MIPO Treaties; MIPO - Mission ments – Patent 08 Hours Conventional, Forms and fees onal Databases; 08 Hours plications filed; non-disclosure;						

Patents: Biological Cases - i) Basmati rice ii) Turmeric iii) Neem; Non-biological cases – (i) TVS V/S Hero, (ii) Samsung V/S Nokia – Copyright and related rights – Trade Marks – Trade secrets - Industrial design and Integrated circuits – Geographic indications – Protection against unfair competition; Technology transfer and license agreements (US anti-HIV drug license to Africa).

Course Outcomes: At the end of the course student will be able to

1. Have a General understanding of the Intellectual Property Rights.

- **2.** Have awareness of different forms of intellectual property rights, national and international IPR related legislations.
- **3.** Have a general understanding about the provisions, privileges and limitations of intellectual property right holders with an understanding of the legal aspects (civil or criminal) of the use of intellectual property rights.
- **4.** Acquire Knowledge of National and International Trade Agreements and Agencies functioning in relation to intellectual property rights
- 5. Be aware and have a general understanding of patenting procedures and licensing.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
↓ Course Outcomes													
HU1502-1.1	-	3	З	2	1	З	I	1	2	2	1	3	
HU1502-1.2	2	2	3	-	1	3	I	3	1	1	2	2	
HU1502-1.3	2	-	-	2	-	3	-	-	2	2	2	3	
HU1502-1.4	-	-	1	1	-	3	-	-	1	2	-	3	
HU1502-1.5	3	2	1	-	-	3	-	-	3	1	-	2	

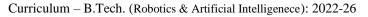
1: Low 2: Medium 3: High

NITTE

REFERENCE MATERIALS:

1.	BAREACT, "Indian Patent Act 1970 Acts & Rules", Universal Law Publishing Co. Pvt.
	Ltd., 2007.
2.	Kankanala C., "Genetic Patent Law & Strategy", 1st Edition, Manupatra Information
	Solution Pvt. Ltd., 2007.
3.	Subbaram N.R., "Handbook of Indian Patent Law and Practice", S. Viswanathan
	(Printers and Publishers) Pvt. Ltd., 1998.
4.	Eli Whitney, United States Patent Number: 72X, Cotton Gin, March 14, 1794.
5.	Intellectual Property Today: Volume 8, No. 5, May 2001.
6.	M B Rao, "WTO and International Trade", Vikas Publishing House Pvt. Ltd.
7.	Correa, Carlos M. "Intellectual property rights, the WTO and developing countries: the
	TRIPS agreement and policy options", Zed Books, New York 2000.
8.	Wadehra, B. L. "Law relating to patents, trademarks, copyright designs & geographical
	indications", 2 ed. Universal Law Publishing 2000.
9.	Sinha, Prabhas Chandra, "Encyclopedia of Intellectual Property Rights", 3 Vols. Eastern
	Book Corporation, 2006.
10.	Rachna Singh Puri and Arvind Vishwanathan, "Practical Approach to Intellectual
	Property Rights"; I. K. International Publishing House Pvt. Ltd.

(Deemed to be	e University)								
E-RE	SOURCES:								
1.	L. http://www.w3.org/IPR/								
2.	http://www.wipo.int/portal/index.html.en								
3.	http://www.ipr.co.uk/IP_conventions/patent_cooperation_treaty.html								
4.	www.patentoffice.nic.in								
5.	www.iprlawindia.org/								



INTRODUCTION TO GERMAN LANGUAGE

<u>(</u>	INTRODUCTIOI	HU1503-1		OEC
	aching Hours/Week (L:T:P: S)	3:0:0:0	Course Type Credits	03
	tal Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50
100				50+50
	-	Department: M	lechanical	
	rse Objectives:			
1.	Distinguish - definite and indefine by adding certain endings to the		-	•
	indirect objects and construct se			is, objects and
2.	Differentiate between nomnative			and intransitive
	verbs, and negation with Kein/e/	/er		
3.	Differentiate use of dative obje	ct besides the	subject for some spe	cific verbs and
	Apply the grammar principles o	•	•	titute for noun
_	as per the case, number and ger			
4.	Differentiate preposition forms v or on combination of the two ca		usively in akkusative c	or Dative forms
5.	Differentiate conjugation of ve		present-perfect and	nast narticiple
٥.	tenses, separable and inseparab	•		
	and position of modal verb in a	• •		
		UNIT - I		
				15 Hour
	oduction: Mein Name ist (saying v	, ,		, , , ,
	ng people where they come from a	-		
	politischen Karte der Welt, Nation and talking about daily routine, Ta			
Jahre		age der woche,	die Monate, die vier 5	ameszenten, an
	geht es gut: Asking people how tl	hey are, saying	how you are, saying v	which cities and
	nries people come from, Language			
	schreibt man das (how do you wr		-	•
•	ling our names and words, talki	ng about us a	and them. Language	points: Yes-no
ques	stions			
Δrtib	el (Articles): As in English, there	are definite (c	ler/die/das) and inde	finite (ein/eine
artic	-	are definite (t		innte (entrente
	· der/die/das; a/an · ein/eine			
	vier Fälle (The four cases): Nomina	tiv, Akkusativ, D	Dativ, Genitiv(Not in le	vel A-1)
Dekl	ination des bestimmten Artikels d	er/die/das		
	ination des unbestimmten Artikels	-		
	lination/Declension: the variation			ective, by whicl
	rammatical case, number, and gen	ider are identifi	13	
-	ination von Substantiven (Declens			



(German nouns are declined by attaching certain endings to them, according to case, number and gender. This helps to differentiate between subjects, objects and indirect objects).

Nominativ und Akkusativ(nominative and accusative cases)

The verb determines the case of the noun. Some verbs only go with the nominative, others only with the accusative (or the dative). Thus, German verbs are either transitive or intransitive.

(Nominative and accusative cases) Intransitive Verben (intransitive verbs) Transitive Verben (transitive verbs)

Negation "kein/e/er "(negation with "kein/e/er ")

(Singular und Plural)

The negation of the indefinite article (ein/eine/ein) is kein/keine/kein. For this, you just have to put a "k" at the beginning of the declined form of ein/eine/ein.

Peter sieht ein Haus. · Negation · Peter sieht kein Haus.

(Peter sees a house. · negation · Peter does not see a house.)

(With examples, writing and hearing exercises, and German to English Glossary as applicable)

UNIT - II

14 Hours

Dativ (the dative)

(You are already familiar with verbs which require a direct accusative object in addition to the subject, which is in the nominative case. But there also some verbs which require a dative object besides the subject. To identify the dative object you ask "(To) whom?")

Der Plural (the plural)

There are many different forms of the plural in the German language. Principally, the gender and the ending of the noun determine the plural form. Then, you either attach a plural ending

to the noun, change a vowel, or keep the noun as it is in the singular.

Das Personalpronomen (the personal pronoun)

The personal pronoun is a substitute for a noun. Its forms are determined by the case, number and gender of the noun which is to be replaced.

Die Formen des Personalpronomen im Nominativ (The nominative forms of the personal pronoun):

Präpositionen (prepositions)

German prepositions are followed by an object, either in the accusative or the dative case.Some prepositions always take an accusative object, others always a dative object. But thereare also prepositions which can be followed by both. In this case, the question "Where(to)?"

NITTE (· accusative) or "Where?" (· dative) determines the case of the object. Präpositionen mit Akkusativ und Dativ (Prepositions with accusative and dative) 1. Präpositionen mit Akkusativ (prepositions with accusative) 2. Präpositionen mit Dativ (prepositions with dative) 3. Präpositionen mit Akkusativ oder Dativ (prepositions with accusative or dative) (With examples, writing and hearing exercises, and German to English Glossary as applicable) UNIT - III **11 Hours** Konjugation von Verben im Präsens (Conjugation of verbs in present tense) Verbs are conjugated by attaching certain endings, depending on the person and number ofthe subject. Trennbare und untrennbare Verben (separable and inseparable verbs) Verbs with prefixes are dinstinguished between separable and inseparable verbs. The prefix of an inseparable verb must never be separated from the stem. Here the stress is on the stem: be-kommen. The prefix of a separable verb gets separated from the stem when the verb is conjugated. In the infinitive, the stress is on the prefix: an-kommen 1.Trennbare Verben (separable verbs) 2.Untrennbare Verben (inseparable verbs) Konjugation von Verben im Perfekt (Conjugation of verbs in present perfect) The present perfect (Perfekt) describes something which happened in the past and isespecially used in spoken German. It is formed with the present tense form of "haben" or "sein" and the past participle of the main verb. 1. Die Bildung des Partizips (the formation of the past participle) 2. Die Bildung des Perfekts mit "haben" und "sein" (the formation of the present perfect with "haben" and "sein") Modalverben (modal verbs) A modal verb is rarely used as a main verb; instead, it usually modifies the main verb. While the main verb remains in the infinitive, the modal verb is conjugated. In German, there are 7 modal verbs: können (can/be able), dürfen (may/be allowed), wollen (want), müssen (must/have to), sollen (shall), mögen (to like), möchten (wish/would like) 1. Konjugation der Modalverben (Conjugation of the modal verbs)

2. Stellung des Modalverbs im Satz

(Position of the modal verb within a sentence)

(With examples, writing and hearing exercises, and German to English Glossary as applicable)

Course Outcomes: At the end of the course student will be able to

- Distinguish definite and indefinite articles, declension of singular and plural nouns by adding certain endings to them to differentiate between subjects, objects and indirect objects and construct sentences of simple day to day usage.
- 2. Differentiate between nomnative and akkusative cases with transitive and intransitive verbs, and negation with Kein/e/er
- **3.** Differentiate use of dative object besides the subject for some specific verbs and Apply the grammar principles of use of personal pronoun as a substitute for noun as per the case, number and gender of the noun.
- **4.** Differentiate preposition forms when used exclusively in akkusative or Dative forms or on combination of the two cases
- **5.** Differentiate conjugation of verbs in present, present-perfect and past participle tenses, separable and inseparable verbs, application of conjugation of modal verbs and position of modal verb in a sentence.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
HU1503-1.1	-	-	-	-	-	3	-	-	2	1	-	1
HU1503-1.2	-	-	-	-	-	3	-	-	2	1	-	1
HU1503-1.3	-	-	-	-	-	3	-	I	2	1	-	1
HU1503-1.4	-	-	-	-	-	3	-	-	2	1	-	1
HU1503-1.5	-	-	-	-	-	3	-	-	2	1	-	1

1: Low 2: Medium 3: High

TEXT BOOKS:

- **1.** Ulrich Haessermann, Georg Dietrich, Christianne C. Guenther, Diethelm Kaminski, Ulrike Woods and Hugo Zenker, Sprachkurs Deutsch Neusaffung 1, Unterrichtswerk fuer Erwachsene, Verlag Moritz Diesterweg, Universitaetsdruckerei H. Stuertz AG Wuerzburg, 1989.
- 2. Paul Coggle and Heiner Schenke, Teach Yourself German (a complete course in understanding, speaking and writing), Teach Yourself Books, Hodden & Stoughton Educational, UK, 2001
- **3.** Langenscheidt German In 30 Days: Book + Cd Paperback, www.amazon.in, 1 September 2011

REFERENCE MATERIALS:

- **1.** Deutsche Sprachlehre für Ausländer.
- **2.** Themen Aktuell (Text and workbook).
- **3.** Deutsch als Fremdsprache 1A.
- 4. Tangram Aktuell 1A/1B (Text and workbook).



5. Wherever required the Videos/Audios are also played in the class room sessions

E-KE	SOURCES:
1.	https://onlinecourses.nptel.ac.in/noc21_hs30/preview
	NPTEL-Swayam, German-I by Prof. Milind Brahme IIT Madras
2.	https://www.traingerman.com/en/
	powered by Sprachinstitut TREFFPUNKT Online

INTRODUCTION TO JAPANESE LANGUAGE

NITTE

Course Code		HU	J150	4-1	C	ours	е Ту	pe			OEC		
Teaching Hours/Week (L:T:P:	:S)	3:0	0:0:0		С	redi	ts				03		
Total Teaching Hours		40	+0+	0+0	С	IE +	SEE	Mar	'ks	50+50			
	Теа	hing	Dep	bartn	nent	:				L			
Course Objectives:													
1. Have basic spoken comm	unicat	ion sł	cills										
2. Write Simple Sentences													
3. Listen and comprehend b	asic Ja	pane	se sp	oker	n Jap	ane	se						
4. Read and understand bas	ic Japa	anese	char	acte	rs in	cludi	ing k	Canji					
		U	NIT ·	- I									
(Lessons 1-6)										15	Hours		
Grammar – Introduction, Alpha Vocabulary – Numbers, Days, w													
		U	- TIV	II									
(Lessons 7-13)										14	Hours		
Communication skills – Time,	Addec	tive,	Seas	ons,	Cor	nvers	atio	n, Q	&A, I	Hobby	, 5-W/1-ŀ		
Entering School/Company, Body Pa	arts, Co	olours,	Feat	ures	etc.								
(Lessons 14-20) Japanese Counting System, Bir Success/Failure, Kanji Characters	s, and	sente	nce	maki	ng, \	/ideo	o Cli	ps	Resta		, My da		
Course Outcomes: At the end o													
1. Understand Simple words					nten	ces,	sрок	en s	lowly	and d	istinctly		
2. Speak slowly and distinct					+								
3. Read and Understand con													
 Ask Basic questions and s Write Hiragana/Katakana 													
5. Write Hiragana/Katakana	and K	anji (.	L20) (cnara	acter	S.							
Course Outcomes Mapping wi	ith Pr	arar		itcor	noc								
Program Outcomes→	1 2	3	4	5	6	7	8	9	10	11	12		
\downarrow Course Outcomes	- ²		-			/		9	10				
HU1504-1.1		_	_	_	3	_	_	2	1	_	1		
HU1504-1.2	_ + -				3	_	_	2	1	_	1		
HU1504-1.2		<u> </u>	+-	+-	3	_	-	2	1	<u> </u>	1		
HU1504-1.4	_ + -	<u> </u>	+	+	3	_	_	2	1		1		
1701304*1.4		-	-	<u> </u>	3	_		2	1	<u> </u>	1		
			1 -	-	J			2	Т		–		
HU1504-1.5													
HU1504-1.5 1: Low 2: Medium 3: High					· •	<u></u>							
HU1504-1.5		S: OI CAPA				ON	, FU	NC	TION	IS AI	ND		



	urse Code	HU1505-1	Course Type	OEC
Теа	ching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50
	Teaching	Department: C	hemistry	
Cou	rse Objectives:			
1.	To create evolved youth, who w the nation.	ill be equipped	to contribute in the de	evelopment of
2.	To train students so as to achie body language of smart sold commanding the troop under h	lier and to in		•
3.	To inculcate spirit of adventure, qualities and risk-taking abilities	, undertake adv	enture activities, to ho	one leadership
4.	To understand and develop life of the student.		and to improve emot	ional quotient
5.	To impart basic military trainin and expose learners to military		awareness about the c	defense forces
		UNIT - I		
NCC	: Aims, Objectives and Organiza	tion		07 Hours
	General, Aims, Objectives and Org		C. Duties of NCC Cade	
				, ,
Type	es and Conduct. National Integratio	on: Importance	and Necessity, Unity in	n Diversity.
	sonality Development	on: Importance	and Necessity, Unity in	n Diversity. 07 Hours
Pers		•		07 Hours
Pers Self-	onality Development Awareness, Empathy, Critical and	Creative Thin	king, Decision Making	07 Hours g and Problem
Pers Self- Solvi	onality Development	Creative Thin ng with stress	king, Decision Making and emotions. Lea	07 Hours g and Problem dership: Traits
Pers Self- Solvi Indic	onality Development Awareness, Empathy, Critical and ing. Communication Skills, Copi	Creative Thin ng with stress	king, Decision Making and emotions. Lea	07 Hours g and Problem dership: Traits
Pers Self- Solvi Indic	onality Development Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values	Creative Thin ng with stress	king, Decision Making and emotions. Lea	07 Hours g and Problem dership: Traits
Pers Self- Solvi Indic	onality Development Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values	Creative Thin ng with stress	king, Decision Making and emotions. Lea	07 Hours g and Problem dership: Traits
Pers Self- Solvi Indic Deve	onality Development Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values	I Creative Thin ng with stress s, Honor Cod UNIT - II	king, Decision Making and emotions. Lea	07 Hours g and Problem dership: Traits
Pers Self- Solvi Indic Deve	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment.	d Creative Thin ng with stress s, Honor Cod UNIT - II hip	king, Decision Making and emotions. Lea e. Social Service ar	07 Hours g and Problem dership: Traits nd Community 08 Hours
Pers Self- Solvi Indic Deve	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment.	d Creative Thin ng with stress s, Honor Cod UNIT - II hip	king, Decision Making and emotions. Lea e. Social Service ar	07 Hours g and Problem dership: Traits nd Community 08 Hours
Pers Self- Solvi Indic Deve Nav Nava requ	Awareness, Empathy, Critical and Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na	king, Decision Making and emotions. Lead e. Social Service ar avigation: Navigation	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic
Pers Self- Solvi Indic Deve Nava Nava requ Sean	Awareness, Empathy, Critical and Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work.	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic
Pers Self- Solvi Indic Deve Nava Rava requ Sean pulli	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling.	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic
Pers Self- Solvi Indic Deve Nava Nava requ Sean pulli Disa	Awareness, Empathy, Critical and Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca vork, Rigging Ca ructions. Ship N	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling.	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic ts of Boat, Boat
Pers Self- Solvi Indic Deve Nava Nava requ Sean pulli Disa	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst ster management and environm	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca cructions. Ship N nental awarene	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling.	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic ts of Boat, Boat
Pers Self- Solvi Indic Deve Nava Nava requ Sean pulli Disa Disa	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst ster management and environm ster Management- Organization, T	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca vork, Rigging Ca vork, Rigging Ca fypes of Disaster vities.	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling. ers, Essential Services, A	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic ts of Boat, Boat 08 Hours Assistance, Civi
Pers Self- Solvi Indic Deve Nava Nava requ Sean pulli Disa Disa	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst ster management and environm ster Management- Organization, T ence organization. Adventure Activ	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca vork, Rigging Ca vork, Rigging Ca fypes of Disaster vities.	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling. ers, Essential Services, A	07 Hours g and Problem dership: Traits, dership: Traits, nd Community 08 Hours of Ships- Basic ts of Boat, Boat 08 Hours Assistance, Civit
Pers Self- Solvi Indic Deve Nava Rava requ Sean pulli Disa Defe Dos	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst ster management and environm ster Management- Organization, T ence organization. Adventure Activ	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca vork, Rigging Ca	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling. ers, Essential Services, A	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic ts of Boat, Boat 08 Hours Assistance, Civi
Pers Self- Solvi Indic Deve Nava Rava Sean pulli Disa Defe Dos	Awareness, Empathy, Critical and ing. Communication Skills, Copi cators, motivation, moral values elopment. al Communication and Seamans al Communication: Introduction, S irements, Chart work. nanship: Introduction to Anchor w ng instructions, Whaler sailing inst ster management and environm ster Management- Organization, T ence organization. Adventure Activ and Don'ts, Fire services and Firefi	d Creative Thin ng with stress s, Honor Cod UNIT - II hip Semaphore, Na vork, Rigging Ca vork, Ri vork, Rigging Ca vork, Rigging Ca vork, Rigg	king, Decision Making and emotions. Lead e. Social Service an avigation: Navigation apsule, Boat work- Par Modeling. ers, Essential Services, A amental Awareness and	07 Hours g and Problem dership: Traits nd Community 08 Hours of Ships- Basic ts of Boat, Boat Assistance, Civi d Conservation. 10 Hours



Border and Coastal areas: Security Challenges & role of cadets in Border management

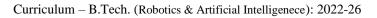
Course Outcomes: At the end of the course student will be able to

1.	Display sense of patriotism, secular values and shall be transformed into motivated youth who will contribute towards nation building through national unity and social cohesion.
2.	Demonstrate the sense of discipline, improve bearing, smartness, turnout and develop the quality of immediate and implicit obedience of orders, with good reflexes.
3.	Acquaint, expose & provide knowledge about Army/Navy/ Air force and acquire information about expanse of Armed Forces, service subjects and important battles.

Course Outcomes Mapping with Program Outcomes

Program Outcomes→	1	2	3	4	5	6	7	8	9	1	1	1	PS	50
5										0	1	2		Ļ
↓ Course Outcomes													1	2
HU1505-1.1	-	-	-	I	-	3	3	1	-	-	-	-	-	-
HU1505-1.2	-	-	-	-	-	3	3	-	-	-	-	-	-	-
HU1505-1.3	-	-	-	-	-	-	-	-	1	-	-	-	-	-
: Low 2: Medium 3: High														
REFERENCE BOOKS:														

1. R.K. Guptha, "Cadets Handbook", Ramesh Publishing House, New Delhi.





NITTE

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	urse Code	HU1506-1	Course Type	OEC
	aching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03
Tot	tal Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50
	Teaching D)epartment: H	umanities	
Cou	rse Objectives:			
1.	To understand the relevance of	Culture in Hum	nan Life, dynamism of	Indian Culture
	and Arts through ages.			
2.	To understand the local culture a	and its vibranci	es.	
3.	To develop awareness about Ind			
4.	To comprehend different dimens		ts of the Indian cultur	e and arts.
5.	To appreciate cultural performar	nces in India.		
		UNIT - I		
Kno	wing Culture			08 Hours
Wha	it is Culture, Different aspects of Cu	ulture, Cultural	expression, Importan	ce of Culture
Influ	uence of Culture			07 Hours
Rela	tionship of Culture with: Language	, Religion and	History, Gender	
		UNIT - II		
	lia and Culture			07 Hours
	of News Papers, Indian Cinema, N	lusic, Advertise	ements	
	guages, Literature and Culture			07 Hours
	of Sanskrit, Vedas, Upanishads, R			
	ature, Buddhist and Jain Literature		nguages and Literatu	re, North Indiar
Lang	guages and Literature, Subaltern Lit	lerature		
		UNIT - III		
Arts	and Culture			07 Hours
	an Theatre and Performing Arts, I	Ritual perform	ances, and Tuluva cu	Itural and ritua
perfo	ormances.	-		
(Self	f-study Component)			04 Hours
Cont	tribution of Indian History to Cu	lture		
Anci	ent India – Persian and Macedo	onian invasion	s and its impact on	Indian Culture
	elopment of Culture and Arts dur	5 ,	•	the Guptas, the
	th Indian Dynasties – the Cholas, N		-	
	lieval India – Life of People under			
	ne of India, Bhakti Movement, Folk			•
	lern India – British Ruling and its im	•		ligious Reforms
	an National Movement and Achiev			
Cou	rse Outcomes: At the end of the c			
-	Examine how the culture has a	very importar	nt role in human life	and growth of
1.				-
1.	human civilization and have a ge of Indian Culture and Arts.	neral awarenes		-

						Curr	iculur	n – B.	Tech.	(Robo	otics & A	Artificial	Intellig	enece):
2.	Appreciate their own loc	al cu	ulture	e fro	m ar	n aca	dem	ic pe	erspe	ective	e.			
3.	Know about the impact and also its impact on In- language in connecting religion and ages.	dian	Cult	ure a	and <i>i</i>	Arts	and	able	to a	ppre	ciate	and th	ne role	e of
4.	Take interest in learning these forms of arts, and also appreciate and preserve them for the future generations feeling proud of Indian Culture, Arts and Architecture.													
5.	Appreciate art performa artistic sphere, which even										•		ed to	an
Cou	rse Outcomes Mapping v	vith	Prog	gran	n Ou	tcor	nes							
	Program Outcomes→ ↓ Course Outcomes	1	2	3	4	5	6	7	8	9	10	11	12	
	HU1506-1.1	-	1	-	-	-	3	-	3	3	1	-	3	
	HU1506-1.2	-	-	-	2	-	3	-	2	3	3	-	3	
	HU1506-1.3	-	-	-	-	-	3	-	1	-	-	-	1	
	HU1506-1.4	-	-	-	-	-	3	-	2	1	2	-	3	
	HU1506-1.5	-	-	-	-	-	3	-	3	3	3	-	2	
1: Lo	ow 2: Medium 3: High													

	urse Code	HU1507-1	Course Type	OEC						
	aching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03						
	tal Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50						
10				50.50						
.	-	g Department:	Visiting							
<u>1.</u>	rse Objectives: To provide a new understandin	a based on wh	nich one can move to	overcome the						
⊥.	current problems, both at the ind	0								
2. To introduce an orientation course for humanities courses in general and for										
philosophy courses in particular.										
3.	To relate philosophy to literature		ty and lived experience							
4.	To train students in already avail	lable philosoph	ical systems.							
5.	To bridge the gap between theo	ory and practice).							
		UNIT - I								
	wledge (Vidya) and Ignorance (A	Avidya)		14 Hour						
•	nishads									
	systems orthodox and Heterodox s	chools of India	n philosophy							
	ek philosophy									
	gin of the universe									
	idiyaSukta: "Who really knows?"	Upanichad: No	on Colf roal and unroal							
	adaranyaka Upanishad; Chandogya hriya Upanishad: SikshaValli	i upanishau. Nu	Sil-Sell, fedi allu ullfedi							
	o's Symposium: Lack as the source	if desire and k	nowledge							
	ratic method of knowledge as disco		nowieuge.							
	guage: word as root of knowledge	-	/akvapadivam)							
-	rteen Knowledge basis as a source of		, <u>,</u>	ces (vedangas)						
	ana, Nyaya, Mimamsa and Dharma			eee (* ee.a gae,						
		UNIT - II								
	wledge as Power			16 Hour						
	cis Bacon. Knowledge as both pov	ver and self- rea	alization in Bhagavad G	iita.						
	wledge as Oppression									
	oucault. Discrimination between R	am and Satyan	n in Indian Philosophy.							
K no	wledge as Invention	·								
	dern definition of creativity; scientif ast through technology.	ic activity in the	e claim that science inve	ents new thing						
Мос	ast through technology.									
Мос		UNIT - III								
Moc at le	wledge about the self, transcender			10 Hour						

NITTE

Course Outcomes: At the end of the course student will be able to

(Deemed to	o be oniversity)													
1.	To provide a new under		-											the
	current problems, both a	at th	e inc	lividu	ual le	evel a	as we	ell as	s at t	he so	ocieta	l leve	l	
2.	To introduce an orient	atio	n co	urse	for	hur	nani	ties	coui	rses	in ge	eneral	and	for
	philosophy courses in pa	articu	ular.											
3.	To relate philosophy to l	itera	ture	, cult	ture,	soci	ety a	and I	ived	expe	erienc	e.		
4.	To train students in alrea	ady a	availa	able	philo	osop	hical	syst	ems					
5.	To bridge the gap between theory and practice.													
Coi	urse Outcomes Mapping v	vith	Pro	aran		tcor	nes							
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
		-	2				Ŭ	'			10		12	
	HU1507-1.1	_	_	_	_	_	3	_	_	2	1	_	1	-
	HU1507-1.2	_	_	_	_	_	3	-	-	2	1	_	1	1
	HU1507-1.3 3 2 1 - 1									-				
	HU1507-1.4													
	HU1507-1.5	_	_	-	_	_	3	_	-	2	1	_	1	
1 • 1	.ow 2: Medium 3: High				l	l				-			-	
4. E	ow 2. Meanant 5. Thigh													
RFF	ERENCE MATERIALS:													
1.	Copleston, Frederick, "His	torv	of P	hilo	sonh	v" V	'ol 1	Gre	at B	ritair	n. Cou	tinuu	m	
2.	Hiriyanna, M. , "Outlines													Fifth
	Reprint edition, 2009.	011	naia		mose	pily	,	otha	i bui	iai și	aass		, ners,	
3.	Sathaye, Avinash, "Transla	ation	of	Jasa	diva	Sukt	a"							
4 .	Raju, P. T. "Structural Dep							han	r Sta	tell	nivers	itv of	New	York
т.	Press.			aiuii	110	agiit		Surry	. 514		invers	ity Of		
5.	Plato, Symposium, Hamilt	on F	Press											
5.			1033											

NITTE (Deemed to be University)

PRINCIPLES OF PHYSICAL EDUCATION

Course Code HU1508-1 Course Type										
Теа	ching Hours/Week (L:T:P: S)	3:0:0:0	Credits	03						
Tot	al Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50						
Teaching Department: Physical Education										
	Teaching Dep	oartment: Physi	cal Education							
Coui	Teaching Dep rse Objectives:	oartment: Physi	cal Education							
Coui 1.	5 1									

- **3.** Grasp understanding of first aid and physical education
- **4.** Awareness on the importance of exercise
- **5.** Leadership skills and the rules of different sports

UNIT - I

15 Hours

History of Physical Education - Olympic games, Modern Olympic games, Olympic Ideals & Objectives, Olympic Symbols, Olympic Flag, Olympic Emblem, Olympic Motto, Olympic Flame, Asian games

International Olympic Committee (IOC), Indian Olympic Association (IOA)

Sports awards - Eligibility, Objectives & Criteria

Yoga - Meaning and Importance

NITTE

World Health organization (WHO)

UNIT - II

14 Hours

Concept of Health - Meaning of Health, Health Definition, Factors Affecting Health, Qualities of Healthy Person. Health Hazards of College Students, Physical Fitness and Exercises.

Food and Nutrition - Food & Nutrition Defined, Nutrients and their Functions - i) Proteins ii) Carbohydrates iii) Fats iv) Vitamins

Balanced Diet & Malnutrition

Health Education - Meaning of Health Education, Health Education Defined, Scope of Health Education, Importance of Health Education.

Posture - Concept of Posture, Correct Postures, Common Postural Defects

First Aid - First Aid Defined, Need and importance of First Aid, The Requisites of First Aid, Scope of First Aid, Qualities of a First Aider, Fundamental Principles to be followed and the Duties to be performed by the First Aider, First Aid in Different Cases.

Physical Education - Concept of Physical Education, Physical Education Defined, Importance of Physical Education, Scope of Physical Education, Aims and Objectives of Physical Education.

Teaching Aid in Physical Education

Competition - Introduction, Types of competition, Knock out, League or Round Robin Tournament.

UNIT - III



11 Hours

Training in Sports – Meaning, Principles, Warming Up & Limbering Down Importance of Anatomy and Physiology in Physical Education, Oxygen Debt and Second wind

Leadership and Supervision – Leadership, Qualities of a good leader in Physical Education, Types of Leadership in Physical Education - 1. Teacher Leadership 2. Student Leadership. Measurement & specification of various playing fields – Cricket, Volley Ball, Basket Ball, Badminton, Ball Badminton, Foot Ball, Hand Ball & their basic playing skills.

Course Outcomes: At the end of the course student will be able to

- **1.** Demonstrate knowledge of structure of the world sports organizations
- 2. Display understanding of different type of food and nutrition for a healthy diet
- **3.** Comprehend awareness of first aid and physical education
- **4.** Elucidate about training and the importance of Physical Education
- **5.** Aware of leadership skills and the knowledge of various sports

Course Outcomes Mapping with Program Outcomes

ise outcomes mapping with riogram outcomes												
Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes→												
↓ Course												
Outcomes												
HU1508-1.1	-	-	-	-	-	3	-	-	2	1	-	1
HU1508-1.2	-	I	-	-	I	З	-	1	2	1	-	1
HU1508-1.3	-	-	-	-	-	3	-	-	2	1	-	1
HU1508-1.4	-	-	-	-	-	3	-	-	2	1	_	1
HU1508-1.5	-	_	-	-	-	3	-	-	2	1	-	1

1: Low 2: Medium 3: High



LINGUISTICS & LANGUAGE TECHNOLOGY

CO	urse Code	HU2501-1	Course Type	OEC
Теа	aching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03
Tot	tal Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50
Pre	e-requisite	HU1001-1 (Technical English)	
	Teaching	g Department:	Humanities	
Cou	rse Objectives:			
1.	Introspect about the consciou	ısness in one's l	anguage	
2.	Learn pronunciation and how	the process he	lps to communicate effe	ectively.
3.	Build contextual speech and v	vriting with the	pedagogy in sentence s	structure.
4.	Improve skill of applying lang			
5.	Progress on the speech aspec	ts by understar	nding the acquisition of s	Second
	Language.			
		UNIT - I		
	• •• • • • • •			
	oduction to Linguistics			
Broa	ad understanding of Linguisti			tures, Scientific
Broa				tures, Scientific
Broa Lang	ad understanding of Linguisti	lysis (Phonetic	s, Phonology, Morpholo	tures, Scientific
Broa Lang Sem	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics	lysis (Phonetic	s, Phonology, Morpholo	tures, Scientific ogy, Syntax and
Broa Lang Sem Pho	ad understanding of Linguisti guage, Levels of Linguistic Ana aantics); Approach to Linguistics nology and Morphology	llysis (Phonetics (Traditional, St	s, Phonology, Morpholo ructural and Cognitive).	tures, Scientific ogy, Syntax and 08 Hours
Broa Lan <u>c</u> Sem Pho Pers	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen	Ilysis (Phonetics (Traditional, Str nes, Allophones	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, N	tures, Scientific ogy, Syntax and 08 Hours
Broa Lan <u>c</u> Sem Pho Pers	ad understanding of Linguisti guage, Levels of Linguistic Ana aantics); Approach to Linguistics nology and Morphology	Ilysis (Phonetics (Traditional, Str nes, Allophones	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, N	tures, Scientific ogy, Syntax and 08 Hours
Broa Lan <u>c</u> Sem Pho Pers	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen	Ilysis (Phonetics (Traditional, Str nes, Allophones	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, N	tures, Scientific ogy, Syntax and 08 Hours
Broa Lan <u>c</u> Sem Pho Pers	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, N	ogy, Syntax and 08 Hours
3roa Lang Sem Pho Pers Mor Synt	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process tax stituent structure (Simple Sente	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica UNIT - II ence, Noun Phr	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, M Il Analysis. rase, Verb Phrase, Prepo	tures, Scientific ogy, Syntax and 08 Hours Aorphology and 16 Hours
3roa Lang Sem Pho Pers Mor Synt	ad understanding of Linguisti guage, Levels of Linguistic Ana aantics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica UNIT - II ence, Noun Phr	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, M Il Analysis. rase, Verb Phrase, Prepo	tures, Scientific ogy, Syntax and 08 Hours Aorphology and 16 Hours
3roa Lang Sem Pho Pers Mor Synt	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process tax stituent structure (Simple Sente	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica UNIT - II ence, Noun Phr ructure Rules), T	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, M Il Analysis. rase, Verb Phrase, Prepo	tures, Scientific ogy, Syntax and 08 Hours Aorphology and 16 Hours
3roa Lan <u>c</u> Sem Pho Pers Mor Syn1 Con:	ad understanding of Linguisti guage, Levels of Linguistic Ana aantics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process tax stituent structure (Simple Sente ective Phrase, Adverb Phrase, Str	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica UNIT - II ence, Noun Phr ructure Rules), 1 UNIT - III	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, N Il Analysis. rase, Verb Phrase, Prepo Free Diagrams, Case	tures, Scientific ogy, Syntax and 08 Hours Aorphology and 16 Hours ositional Phrase
3roa _anc Sem Pho Pers Vor Synt Con: Soci	ad understanding of Linguisti guage, Levels of Linguistic Ana antics); Approach to Linguistics nology and Morphology pectives in Linguistics, Phonen phemes, Word building process tax stituent structure (Simple Sente ective Phrase, Adverb Phrase, Str iolinguistics & Psycholinguisti	Ilysis (Phonetics (Traditional, Str nes, Allophones , Morphologica UNIT - II ence, Noun Phr ructure Rules), T UNIT - III CS, Artificial In	s, Phonology, Morpholo ructural and Cognitive). s, Phonemic Analysis, M Il Analysis. rase, Verb Phrase, Prepo ree Diagrams, Case telligence	tures, Scientific ogy, Syntax and 08 Hours Aorphology and 16 Hours ositional Phrase 08 Hours
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1990.9. Sinclair, J. M. C. H. and R. M. Coulthard. "Towards an Analysis of Discourse". Oxford:		Longman, 1974.													
9. Sinclair, J. M. C. H. and R. M. Coulthard. "Towards an Analysis of Discourse". Oxford:	8.	Salkie, R. "The Chomsk	y Up	date	e: Lin	guis	tics a	and I	Politi	cs".	Lonc	lon: U	nwin	Hyma	n Ltd.,
	9.	Sinclair, J. M. C. H. and	1 R. I	И. C	oulth	hard.	"To	warc	ls an	Ana	lysis	of Di	scour	se". C	xford:
		OUP, 1975.													
10. Thomas, Linda. "Beginning Syntax". Oxford: Blackwell, 1993.	10.	Thomas, Linda. "Begin	ning	Syn	tax".	Oxfo	ord:	Black	well	, 199	93.				
11. Verma, S. K. and N. Krishnaswamy. "Modern Linguistics: An Introduction". New Delhi:	11.	Verma, S. K. and N. Kri	shna	swa	my. '	'Moo	dern	Ling	uisti	cs: A	n Int	roduc	tion".	. New	Delhi:
OUP, 1989.		OUP, 1989.													
12. Wekker, Herman and Liliane Haegeman. "A Modern Course in English Syntax". Kent:	12.	Wekker, Herman and I	Liliar	ne Ha	aege	man	. "A	Mod	lern	Coui	rse ir	n Engl	ish Sy	ntax"	. Kent:
Croom Helm, 1985.		Croom Helm, 1985.													



PROFESSIONAL & COGNITIVE COMMUNIQUE

Course Code	HU2502-1	Course Type	OEC				
Teaching Hours/Week (L:T:P:S)	3:0:0:0	Credits	03				
Total Teaching Hours	40+0+0+0	CIE + SEE Marks	50+50				
Pre-requisite	HU1001-1 (Technical English)						

Teaching Department: Humanities

Course Objectives:

- To Problematize Commonsense & Apply Critical thinking skills 1.
- 2. Comprehend etiquettes and manners in different situations
- Be gender sensitive in both offline and online behavior 3.
- Exhibit better comprehension of the social implications of human body 4.
- 5. Understand the importance of reading and writing skills

UNIT - I

Common sense and Emotional Intelligence

Common sense, Commonsensical Consensus, Critical thinking, Unsettling commonsensical Consensus, Role of language in Common sense and Critical Thinking; Nature & Functions of Emotional Intelligence, Emotions, Intelligence and Creativity, Growth of Emotional Intelligence

Etiquettes & Workplace

Etiquette, Workplace Etiquettes, Workplace Readiness Skills, Significance of Cross-Cultural Understanding; Cultural Sensitivity, Impact of social media in Workplace

UNIT - II

Social Networking Sites and its Impacts

Emergence of social media, Impact on Gender and Self Representation, Regulatory and Liberatory aspects of social media, Offline Norms & Online Behaviour

Gender and Body

Gender & Sex, Genderization, Homogeneity and Heterosexuality, Gender Expressions, Gender Schooling, Representations of Body, Objectification, Gender Perspectives of Body, Different Ways of Seeing the Body, Discipline & Coercion, ISA & RSA

UNIT - III

10 Hours

15 Hours

15 Hours

Writ	ing	10 Hours						
Types of Writing, Note Taking Methods, Plagiarism								
Reading								
Style	Styles of Reading, Types of Reading, Scanning, Skimming							
Cou	rse Outcomes: At the end of the course student will be able to							
1.	Problematize Commonsense & Apply Critical thinking skills							
2.	Comprehend etiquettes and manners in different situations							
3.	Be gender sensitive in both offline and online behavior							
4.	Exhibit better comprehension of the social implications of human body							
5.	Understand the importance of reading and writing skills							

Course Outcomes Mapping with Program Outcomes

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	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
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	HU2502-1.2	-	2	-	-	-	-	-	3	2	3	-	2	
	HU2502-1.3	-	3	-	-	-	-	-	-	2	2	-	3	
	HU2502-1.4	-	3	-	-	-	-	-	-	2	2	-	3	
	HU2502-1.5	-	2	-	-	-	-	-	-	3	3	-	2	
1: Low 2: Medium 3: High														
REFERENCE MATERIALS:														
1.														
2.	Bailey, Jane, et al. "Negot	iatin	g wi	th G	ende	er St	ereo	type	s Or	Soc	cial Ne	etwor	king S	ites:
	From "Bicycle Face" to Fa	cebc	ok."	Jour	rnal	of Co	omm	nunic	atio	n En	quiry	37.2 (2013):	91-
	112.													
3.	Barry, Peter. "Beginning Theory". New Delhi: Viva Books, 2010.													
4.	Berger, John. "Ways of Seeing". London: Penguin Books, 1977.													
5.	Cranny-Francis, Anny, et a	al. "O	iend	er St	udie	s: Te	rms	and	Deb	ates	". Nev	v York	: Palg	rave
	Macmillan, 2003.													
6.	Gauntlett, David. "Media,	Ger	der	and	Ider	ntity:	An 3	Intro	duct	ion"	. Lond	don: F	Routle	dge,
	2008													
7.	Pilcher, Jane, and Imelda	Wh	eleh	an. "	50 k	Key (Conc	epts	in (Genc	ler St	udies'	'. Lon	don:
	Sage, 2004. Print.													
8.	Jeanne, Haraway Donna.	Sim	ians	, Cyl	oorg	s, ar	nd V	Vom	en. l	ond	on: F	ree A	ssocia	ition
-	Books, 1991. Web.													
9.	Koskela, Hille. "Webcams							one	s: Em	ipow	vering	Exhit	oitioni	sm."
	Surveillance & Society 2.3	(20	J4): :	199-	215.	Web	•							
	ESOURCES:							-			<u></u>			
1.	http://www.cyberpsycholo											•		
2.	http://www.surveillance-a			ty.or	ˈɡ/ar	ticle	s2(2)	/we	ocan	ns.pc	lt			
3.	http://eprints.rclis.org/19	790/	>.											

(Deemed to be University) INTRODUCTION TO CYBER SECURITY										
Course Code:	IS2501-1	Course Type	OEC							
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03							
Total Teaching Hours	40	CIE + SEE Marks	50+50							
Prerequisite	IS1651-1									
Teaching Department	: Information	Science & Engineering								
Course Objectives:										
1. Define the area of cybercrime a	nd forensics a	nd to understand the sec	curity threat							
2. Explain the motive and causes f	or cybercrime,	detection, and handling								
3. Investigate Areas affected by cybercrime.										
4. Illustrate tools used in cyber forensic										
	UNIT-I		1							
Introduction to Cyber Security			15 Hours							
Concepts of Cyber Security, Formal		-								
Confidentiality, Integrity and Authen	,		, ,							
Security attacks, Security services, S	ecurity Mech	anısms, Fundamental se	ecurity design							
principles, Types of Cyber Threat.										
Table and south a descending Colored	UNIT-II		1411							
Tools and methods used in Cybercri		widens and the draw To	14 Hours							
Introduction, Proxy Servers and An	-									
Cybercrimes. Network Threats: Active/		•	•							
 Worms –Virus – Spam's – Ad ware - Bots – IP, Spoofing - ARP spoofing - 		-								
Theft (ID Theft).	Session njaci	ang, introduction to Fill.	sining, identity							
	UNIT-III									
Understanding Computer Forensics			11 Hours							
Introduction, Digital Forensics Science	e, The Need fo	or Computer Forensics, (Cyberforensics							
and Digital Evidence, Forensics Analy	sis of E-Mail,	Digital Forensics Life C	ycle, Chain of							
Custody Concept, Network Forensics	, Approaching	a Computer Forensics	Investigation,							
Setting up a Computer Forensics Lab	-	J	•							
Forensics and Steganography, Releva										
Forensics and Social Networking Site	-									
from Compliance Perspective, Chall	-	nputer Forensics, Speci	ial Tools and							
Techniques, Forensics Auditing, Antifo										
Course Outcomes: At the end of the		t will be able to								
1. Comprehend the Cybercrime and its origin										
2. Analyse Security Threat Management and understand the security elements.										
3. Apply tools and methods used in Cyber crimes										
4. Analyse Phishing and ID Theft										
5. Comprehend Digital Forensics										
Course Outcomes Mapping with Pro	ogram Outcor	nes								

ITTE

(Deemed to be University)	
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[Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
-		-	-	5	•	5	Ŭ	,	Ŭ	2				
	IS2501-1.1	2	-	-	_	-	1	-	3	-	-	_	-	
-	IS2501-1.2	_	3	-	1	-	2	-	-	2	-	_	_	
-	IS2501-1.3	_	3	2	_	_	_	_	_	_	-	-	_	
ŀ	IS2501-1.4	2	-	-	-	-	2	-	-	-	-	_	_	
-	IS2501-1.5	-	-	-	-	-	-	-	3	-	-	-	-	
1:	Low 2: Medium 3: High									1				1
TEX	TBOOKS:													
1.	William Stallings, "Crypto	arar	bhy	and	Ne	etwo	rk :	Seci	ıritv	: Pr	inciple	es and	Practi	ce".
	Pearson Education, 2006.	5 1	J		-				-)		- 1-			,
2.		ex, "	Thre	eat N	Лod	elino	a", N	Micr	oso	ft Pr	ess, 2	004.		
3.													er Crin	nes,
	Computer Forensics and Le											5		
	21791, Publish Date 2013.	5		•		•		,						
REF	ERENCE BOOKS:													
1.	Thomas J. Mowbray, "Cyb	erse	ecuri	ity: I	Man	agi	ng S	Syste	ems	, Co	nduct	ing Te	esting,	and
	Investigating Intrusions", Jo						0					0		
2.	<u> </u>													
	Dec 2010. Anti- Hacker T					-								
	Graw-Hill.													
3.	Santosh B. J., K. V. S. S. S	. S.	Sair	ram,	Sh	ubh	am	Kun	nar,	Cha	andu .	Jagan	Sekhar	M,
	"Information and Cyber Se											-		
	978-93-5625-694-1.		, .									5	-	

PYTHON APP	LICATION PF	ROGRAMMING	
Course Code:	IS2502-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	CS1002-1		
Teaching Department	t: Information	Science & Engineering	g
Course Objectives:			1
1. Construct Python programs us	• • •		
2. Design object-oriented Python			
3. Design useful stand-alone and	CGI application	ns in	
	UNIT-I		
Functions, Classes and OOP	UNIT-1		15 Hours
Functions: Design with functions: his	ding redundan	y complexity: argume	
values; formal vs actual arguments,	-		
Recursive functions	numea argan	ients. Program structu	re una acsign.
Classes and OOP: Classes, objects, a	ttributes and m	nethods [,] defining class	es: design with
classes, data modelling; persistent sto		-	-
overloading (_eq_, _str_, etc); abstract			
		on nananing, a y brook	
	UNIT-II		
Lists, Tuples, and Dictionaries			14 Hours
Lists, tuples, and dictionaries: Basic list	t operators, rep	lacing, inserting, remov	ing an element;
searching and sorting lists; dictionar	· ·		-
replacing values; traversing dictionarie	•		U
File Handling: Reading From Text Files	, Writing to Tex	t Files, Working with Ex	cel Sheets ,CSV,
PDF, Word,	_	_	
	UNIT-III		
Essential Python Libraries			11 Hours
Working with SciPy, Numpy, Matplotli			
Graphical user interfaces: event-driv		0 1 0	o ,
buttons, labels, entry fields, dialogs; v	widget attribute	es - sizes, fonts, colors	layouts, nested
frames Simple CGI form.			
Course Outcomers At the and of the	course et alert	will be able to	
Course Outcomes: At the end of the			looning
1. Demonstrate the basics of Pyth			ooping
2. Apply the basic data structures			
3. Experiment with usage of functions of functions of the second			
4. Develop Objects by creating cl			
5. Develop applications in Pythor	i using File Prog	gramming & User Interfa	ace
Course Outcomes Manning with Dr	ogram Outcom	200	
Course Outcomes Mapping with Pr	ogram Outcon	1162	

(Decined to	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
	IS2502-1.1	2	-	-	-	2	-	I	١	I	I	-	3	
	IS2502-1.2	2	-	-	-	2	-	I	١	I	I	-	3	
	IS2502-1.3	2	-	-	-	2	-	I	١	I	I	1	3	
	IS2502-1.4	I	-	-	-	-	-	I	١	I	I	-	-	
	IS2502-1.5	I	-	-	-	-	-	I	١	I	I	-	-	
1: L	ow 2: Medium 3: High													
TEX	TBOOKS:													
1.	Kenneth A. Lambert, "The	Fund	dam	enta	als c	of Py	/tho	n: F	irst	Prog	grams	", 2011	L, Ceng	jage
	Learning, ISBN: 978-11118	227	05.											



	urse Code:	IS2503-1	Course Type	OEC
	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	CS1002-1		
		: Information	Science & Engineerin	ng
	rse Objectives:			
1.	Outline software engineering pr	rinciples and a	ctivities involved in bui	lding large
	software programs.			c.
2.	Explain the importance of archit			itware.
3.	Describe the process of Agile pr			
4.	Recognize the importance of sc	oftware testing	g and describe the intric	cacies involved
-	in software evolution.			al avvalation the a
5.	Identify several project plann	-	mation techniques and	d explain the
	importance of software quality.			
		UNIT-I		
ntra	oduction	UNIT-I		15 Hours
	d for Software Engineering, Profe	scional Softw	ara Dovelenment Soft	
	cs, Case Studies.		are Development, Sont	
	ware Processes			
		Model and Sr	iral Model [.] Process acti	vities
Mod Req Func Requ	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional rec uirements Elicitation and Analysis	quirements, 5, Requiremer	Requirements enginee ts specification, Softwa	ering processes are requirement
Mod Req Func Requ docu	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional rec	quirements, 5, Requiremer	Requirements enginee	ering processes
Mod Req Func Requ docu	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional rec uirements Elicitation and Analysis ument, Requiren	quirements, 5, Requiremer	Requirements enginee ts specification, Softwa	ering processes are requirement
Mod Req i Reqi doci man	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional rec uirements Elicitation and Analysis ument, Requiren	quirements, 5, Requiremer nents	Requirements enginee ts specification, Softwa	ering processes are requirement
Mod Requ Func Requ docu man	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional rec uirements Elicitation and Analysis ument, Requiren agement.	quirements, s, Requiremer nents UNIT-II	Requirements enginee ts specification, Softwa validation	ering processes are requirement {
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Mod Requ Func Requ docu man Syst Cont T Ar Arch Desi Obje Agile Man Risk Proj	lels: Waterfall Model, Incremental uirements Engineering ctional and non-functional reconstructional and non-functional reconstruction uirements Elicitation and Analysis ument, Requiren agement. em Models text models, Interaction models, State chitectural Design itectural design decisions. Archite gn and implementation ect oriented Design using UML. e methods, Plan-driven and agile agement. ett Management management, Teamwork. ect Planning	quirements, s, Requiremer nents UNIT-II tructural mod ctural Views a e developmer UNIT-III	Requirements enginee its specification, Softwa validation els, Behavioral models. nd patterns, Application it, Extreme Programmin	ering processes are requirement { 15 Hours n architectures.
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Software quality, Reviews and inspections, Software measurement and metrics, Software standards.

Cour	rse Outcomes: At the end of the course student will be able to
1.	Recognise the basics of software system, component, process and Software Requirement Specification to meet desired needs within realistic constraints and outline the professional and ethical responsibility
2.	Describe the waterfall, incremental and iterative models and architectural design in implementing the software
3.	Make use of the techniques, skills, modern engineering design tools and agile methods necessary for engineering practice.
4.	Describe the methods for maintaining software system.
5.	Discuss project planning and management and illustrate the quality of software products

Course Outcomes Mapping with Program Outcomes

		-										
Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
IS2503-1.1	-	3	1	-	-	-	-	2	-	-	-	-
IS2503-1.2	1	3	1	-	-	-	-	-	-	-	-	-
IS2503-1.3	1	1	3	-	-	-	-	-	-	-	-	-
IS2503-1.4	1	3	2	-	-	-	-	-	-	-	-	-
IS2503-1.5	1	2	2	-	-	-	-	-	-	-	-	-
ow 2: Medium 3: High												

TEXTBOOKS:

1:

IEAI	BOOKS:
1.	Ian Sommerville, "Software Engineering", 9th Edition, Pearson Education, 2012.
REFE	RENCE BOOKS:
1.	Roger S. Pressman: "Software Engineering-A Practitioners approach", 7th Edition, Tata
	McGraw Hill, 2017.
2.	Pankaj Jalote: "An Integrated Approach to Software Engineering", Wiley, India, 2010.
E Boo	oks / MOOCs/ NPTEL
1.	http://agilemanifesto.org/
2.	http://www.jamesshore.com/Agile-Book/
3.	https://www.mooc-list.com/course/uml-class-diagrams-software-engineering-edx
4.	https://www.mooc-list.com/course/enterprise-software-lifecycle-management-edx

6	WEB	TECHNOLO	DGIES	
Cou	rse Code:	IS2504-1	Course Type	OEC
Tea	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
	requisite	CS1002-1		
	Teaching Department	: Information	Science & Engineering	
Cour	se Objectives:			
1.	Illustrate the Semantic Structure	e of HTML and	I CSS	
2.	Compose forms and tables usin			
3.	Design Client-Side programs us			ms using PH
4.	Illustrate the Database connect			
5.	Examine JavaScript frameworks	such as jQuer	у	
		UNIT-I		
Intro	duction to HTML			15 Hou
	L tags and simple HTML form	s, web site s	tructure. HTML table N	
	duction to CSS, basic syntax and s			
	erties, manipulating texts, using			
	ioning using CSS, Selectors, The C		-	
Stylin			Styles Intelact, The DOX IV	
Stym	iy.			
		UNIT-II		
Clier	t side Scripting	<u> </u>		15 Hou
	duction to JavaScript: JavaScript			
Intro		language – (declaring variables, scop	be of variab
	ions, event handlers (on click,			
funct		on submit e	etc.), Document Object	Model, For
funct valida	ions, event handlers (on click,	on submit e aring variables	etc.), Document Object , data types, arrays, strin	Model, For gs, operatio
funct valida expre	ions, event handlers (on click, ations. Introduction to PHP: Decla	on submit e aring variables	etc.), Document Object , data types, arrays, strin	Model, For gs, operation
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funct valida expre Boxes Boxes PHP Basic datat table and S is jQu Event	ions, event handlers (on click, ations. Introduction to PHP: Decla essions, control structures, functi s, radio buttons, lists etc., Databases command with PHP examples, base, listing database, listing tal s, queries, deleting database, dele Superglobals, Arrays, \$_GET and \$ uery, Adding jQuery in to your	on submit e aring variables ons, Reading UNIT-III Connection to ble names creating data and _POST Superg web pages, jC	etc.), Document Object , data types, arrays, strin data from web form cor o server, creating databa eating a table, inserting tables, File Handling in P lobal Arrays, jQuery Intro Query Syntax, jQuery Sel	Model, For gs, operatio ntrols like Te 10 Hou se, selecting data, alteri HP, PHP Arra
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funct valida expre Boxe Boxe Boxe Boxe Boxe Cour PHP Basic datable and S is jQu Event Cour	ions, event handlers (on click, ations. Introduction to PHP: Decla essions, control structures, functi s, radio buttons, lists etc., Databases command with PHP examples, base, listing database, listing tal s, queries, deleting database, dele Superglobals, Arrays, \$_GET and \$ uery, Adding jQuery in to your ts. se Outcomes: At the end of the Adapt HTML and CSS syntax an	on submit e aring variables ons, Reading UNIT-III Connection to ole names creating data and _POST Superg web pages, jC course studen	etc.), Document Object s, data types, arrays, strin data from web form con o server, creating databa eating a table, inserting tables, File Handling in P lobal Arrays, jQuery Intro Query Syntax, jQuery Sel t will be able to	Model, For gs, operatio ntrols like Te 10 Hou se, selecting data, alteri HP, PHP Arra
funct valida expre Boxes Boxes PHP Basic datak table and S is jQu Event	ions, event handlers (on click, ations. Introduction to PHP: Decla essions, control structures, functi s, radio buttons, lists etc., Databases command with PHP examples, base, listing database, listing tal s, queries, deleting database, dele Superglobals, Arrays, \$_GET and \$ uery, Adding jQuery in to your ts. se Outcomes: At the end of the	on submit e aring variables ons, Reading UNIT-III Connection to ble names creating data and _POST Superg web pages, jC course studen	etc.), Document Object s, data types, arrays, strin data from web form con o server, creating databa eating a table, inserting tables, File Handling in P lobal Arrays, jQuery Intro Query Syntax, jQuery Sel t will be able to <u>b build web pages</u> as using HTML and CSS.	Model, For gs, operatio ntrols like Te 10 Hou se, selecting data, alteri HP, PHP Arra oduction: Wh lectors, jQue

	be University				(Curri	culur	n – E	B.Tec	h. (R	obotics &	Artificia	l Intellige	enece
5.	Inspect JavaScript framewo	orks	like	jQı	iery	whi	ch f	acil	itate	es d	evelop	ers to	focus	on
	core features.			-	-						-			
Cou	rse Outcomes Mapping with	ו Pr	ogra	am	Out	com	ies							
	Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12	
	↓ Course Outcomes													
	IS2504-1.1	1	2	-	2	-	-	-	-	-	_	-	1	1
	IS2504-1.2	1	-	-	2	-	-	-	-	-	-	-	1	1
	IS2504-1.3	1	2	-	2	3	-	-	-	-	-	-	1	1
	IS2504-1.4	1	2	-	2	3	-	-	-	-	-	-	1	1
	IS2504-1.5	1	-	-	2	3	-	-	-	-	-	-	1]
1: L	ow 2: Medium 3: High		•		•				•	•		•		-
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TEX	TBOOKS:													
1.	Randy Connolly, Ricardo I	Ноа	r, "F	unc	lam	enta	ls c	of W	/eb	Dev	elopm	ent", 1	1 st Edit	tion
	Pearson Education India. (I													
E Bo	ooks / MOOCs/ NPTEL													
1.		5084	/11											

(Deemed to b		RAPH THEOF	RY	
Cοι	urse Code:	MA1501-1	Course Type	OEC
Теа	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
	Teaching D	epartment: Ma	athematics	
Cou	rse Objectives:			
1.	Explain subgraphs, bipartite gra	aphs, isomorph	ic graphs etc. Apply	the concept of
	trees and its properties			
2.	Distinguish between Hamilton a	and Eulerian gra	aph. Distinguish betw	een planar and
	nonplanar graphs and apply the	eir properties to	solve problems.	
3.	Represent a graph in terms of ac	djacency matrix	, incidence matrix etc.	and vice-versa.
4.	Find the shortest path between	two vertices in	a graph. Find minima	l spanning tree.
		UNIT-I		
Intro	oduction to graphs			15 Hours
Conr	norphism of graphs. Complement on nectivity-point and line connectivity r and Hamilton graphs and their a	ty. Trees and its		
		UNIT-II		
	ar graphs			09 Hours
	r's polyhedron formula, outer plan	ar graphs, appl	lications	
	prability		· · · · · · · · ·	07 Hours
	omatic number, five color theor ring	em, chromatic	polynomial, Applica	ations of graph
colo	rix representation of graphs			
	icency matrix, incidence matrix, circ	cuit matrix cut	set matrix Path matr	iv IIIIIII
naju	include the matrix, includence matrix, en	curt matrix, cut	Set matrix, rath matri	
		UNIT-III		
Netv	work Flows			04 Hours
Max	-flow and Min-cut Theorem(state	ment), problem	IS.	
	rtest paths in weighted graphs	·		
	stra's algorithm to find shortest pa	ths.		
Spar	nning trees			05 Hours
Algo	prithms to find a spanning tree, min	nimal spanning	tree-Kruskal's & Prin	n's algorithm.
Cou	rse Outcomes: At the end of the c	course student	will be able to	
1.	Distinguish between bipartite a	nd complete bi	ipartite graphs, identi	fy whether two
	araphe are icomorphic find cub	graphs of a gra	ph etc.	
	graphs are isomorphic, find sub	51 5		
2.	Distinguish between Eulerian an			
2. 3.	Distinguish between Eulerian an Identify whether a graph is plan	nd Hamiltonian ar and to find t	graphs.	nial of a graph.
	Distinguish between Eulerian an	nd Hamiltonian ar and to find t Matrices.	graphs. he chromatic polynoi	

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Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes →	_											
↓ Course												
Outcomes												
MA1501-1.1	3	3	-	-	-	-	-	-	-	-	-	-
MA1501-1.2	2	1	-	-	-	-	-	-	-	-	-	-
MA1501-1.3	2	3	-	-	-	-	-	-	-	-	-	-
MA1501-1.4	3	2	-		-	_		-	-	-	-	-
MA1501-1.5	3	2	-	-	-	-	-	-	-	-	-	-
EXTBOOKS:1.F. Harary, "Graph the										and	Comp	o. Scie
 Narsing Deo, "Grap PHI,1974. Kannath H. Basan 				-				t a a			а″ Та	.t. N/
				athe		cs a	nd i	ts a	pplic	ation	is", Ta	ata M
PHI,1974. 3. Kenneth H. Rosen, Hill, VEdition-2003.				athe		cs a	nd i	ts a	pplic	cation	ıs", Ta	ata M
PHI,1974. 3. Kenneth H. Rosen, Hill, VEdition-2003.	"Dis	crete	e Ma		mati				pplic	cation	ıs", Ta	ata M
PHI,1974. 3. Kenneth H. Rosen, Hill, VEdition-2003. EFERENCE BOOKS:	"Dis	crete	e Ma	The	mati ory",	PHI,	2002	1.		cation	ns", Ta	ata M
PHI,1974. 3. Kenneth H. Rosen, Hill, VEdition-2003. EFERENCE BOOKS: 1. D. B. West, "Introduct 2. Chartrand and Zhang	"Dis	crete	e Ma	The	mati ory",	PHI,	2002	1.		cation	os", Ta	ata M
PHI,1974. 3. Kenneth H. Rosen, Hill, VEdition-2003. REFERENCE BOOKS: 1. D. B. West, "Introduct	"Dis tion	crete to Gi <u>rst C</u>	e Ma raph <u>ours</u>	The	mati ory",	PHI,	2002	1.		cation	ıs", Ta	ata M

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	urse Code:	MA1502-1	Course Type	OEC
	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	tal Teaching Hours	40	CIE + SEE Marks	50+50
	Teaching D	epartment: M	athematics	
Cou	rse Objectives:			
1.	Understand the divisibility of int	teaers, study of	prime numbers and b	asic properties
	of congruences.			
2.	Study Fermat's little theorem a	nd understand	Euler's function.	
3.	Study the existence of primitive	roots and qua	dratic residues.	
4.	Study the cryptographic applica	itions in numbe	er theory.	
		UNIT-I		
	sibility and the theory of congru			15 Hours
	sion algorithm, Euclid's algorithm	-		•
equa	ations. Prime numbers, fundame	ental theorem	of arithmetic. Basic	properties o
-	gruences, Linear congruences and			-
		UNIT-II		
				07 Hours
				U/ Hours
erm	nat's theorem, Wilson's theorem, E	uler's Phi funct	ion, Euler's theorem.	U/ Hours
			ion, Euler's theorem.	
Prim	nitive roots and Quadratic congr	uences		08 Hours
Prim Orde	nitive roots and Quadratic congr er of an integer modulo n, primitiv	uences		08 Hours
Prim Orde	nitive roots and Quadratic congr	uences		08 Hours
Prim Orde	nitive roots and Quadratic congr er of an integer modulo n, primitiv	r uences re roots for prin		08 Hours
Prim Orde and	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties.	uences		08 Hours egendre symbo
Prim Orde and Cryp	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. otography	vences e roots for prin UNIT-III	nes, Euler's criterion, L	08 Hours egendre symbo 10 Hours
Prim Orde and Cryp	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. Ditography Doduction to public key cryptograph	vences e roots for prin UNIT-III	nes, Euler's criterion, L	08 Hours egendre symbo 10 Hours
Prim Orde and Cryp	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. otography	vences e roots for prin UNIT-III	nes, Euler's criterion, L	08 Hours egendre symbo 10 Hours
Prim Orde and Cryp	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. Deformany D	r uences e roots for prin UNIT-III ly, RSA cryptosy	nes, Euler's criterion, Lo vstem, an application o	08 Hours egendre symbo 10 Hours
Prim Orde and Cryp	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. Ditography Doduction to public key cryptograph	r uences e roots for prin UNIT-III ly, RSA cryptosy	nes, Euler's criterion, Lo vstem, an application o	08 Hours egendre symbo 10 Hours
Prim Orde and Cryp Intro to cr	nitive roots and Quadratic congression of an integer modulo n, primitivity its properties.	uences e roots for prin UNIT-III ly, RSA cryptosy	nes, Euler's criterion, Lo ystem, an application o will be able to	08 Hours egendre symbo 10 Hours f primitive root
Prim Orde and Cryp	nitive roots and Quadratic congression of an integer modulo n, primitivits properties.	r uences e roots for prin UNIT-III ly, RSA cryptosy course student common divi	nes, Euler's criterion, Lo ystem, an application o will be able to sor in Euclidean alo	08 Hours egendre symbo 10 Hours f primitive root
Prim Orde and Cryp Intro to cr Court 1.	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. Diagraphy Deduction to public key cryptograph cyptography. rse Outcomes: At the end of the of Use divisibility and Greatest Diophantine equations. Identify	UNIT-III UNIT-III Ny, RSA cryptosy course student common divi prime factoriza	nes, Euler's criterion, Lo ystem, an application of will be able to sor in Euclidean alo	08 Hours egendre symbo 10 Hours f primitive root
Prim Orde and Cryp Intro to cr	hitive roots and Quadratic congr er of an integer modulo n, primitivits properties. otography oduction to public key cryptography. rse Outcomes: At the end of the of Use divisibility and Greatest Diophantine equations. Identify Understand the properties of comparisonal context of the properties of comparisonal context of the properties of the properties of	e roots for prin UNIT-III y, RSA cryptosy course student common divi prime factoriza ongruences. Us	nes, Euler's criterion, Lo ystem, an application of will be able to sor in Euclidean alo	08 Hours egendre symbo 10 Hours f primitive root
Prim Orde and Cryp Intro to cr Court 1. 2.	nitive roots and Quadratic congr er of an integer modulo n, primitiv its properties. Diography oduction to public key cryptograph cyptography. rse Outcomes: At the end of the of Use divisibility and Greatest Diophantine equations. Identify Understand the properties of co solution of system of linear con	e roots for prin UNIT-III y, RSA cryptosy course student common divi prime factoriza ongruences. Us gruences	nes, Euler's criterion, Lo vstem, an application o will be able to sor in Euclidean alg ation of an integers. se Chinese reminder th	08 Hours egendre symbo 10 Hours of primitive root gorithm. Solve
Prim Orde and Cryp Intro to cr Cour 1. 2. 3.	hitive roots and Quadratic congr er of an integer modulo n, primitivitis properties. otography oduction to public key cryptography oduction to public key cryptography. rse Outcomes: At the end of the of the of the of the properties. Use divisibility and Greatest Diophantine equations. Identify Understand the properties of consolution of system of linear consolu	vuences e roots for prin UNIT-III y, RSA cryptosy course student common divi prime factoriza ongruences. Us gruences d Wilson's Thec	nes, Euler's criterion, Lo ystem, an application of will be able to sor in Euclidean alg ation of an integers. se Chinese reminder the prem. Use of Euler's Ph	08 Hours egendre symbo 10 Hours f primitive root gorithm. Solve neorem to find i function.
Prim Orde and Cryp Intro to cr Cour 1. 2. 3. 4.	hitive roots and Quadratic congr er of an integer modulo n, primitivitis properties. otography oduction to public key cryptography oduction to public key cryptography. rse Outcomes: At the end of the of Use divisibility and Greatest Diophantine equations. Identify Understand the properties of consolution of system of linear consolution of an integration of an integration.	e roots for prin UNIT-III y, RSA cryptosy course student common divi prime factoriza ongruences. Us gruences d Wilson's Theo egers. Apply Eu	nes, Euler's criterion, Lo ystem, an application of will be able to sor in Euclidean alg ation of an integers. se Chinese reminder the prem. Use of Euler's Photecology	08 Hours egendre symbo 10 Hours f primitive root gorithm. Solve neorem to find i function.
Prim Orde and Cryp Intro to cr Cour 1. 2. 3.	hitive roots and Quadratic congr er of an integer modulo n, primitivitis properties. otography oduction to public key cryptography oduction to public key cryptography. rse Outcomes: At the end of the of the of the of the properties. Use divisibility and Greatest Diophantine equations. Identify Understand the properties of consolution of system of linear consolu	e roots for prin UNIT-III y, RSA cryptosy course student common divi prime factoriza ongruences. Us gruences d Wilson's Theo egers. Apply Eu	nes, Euler's criterion, Lo ystem, an application of will be able to sor in Euclidean alg ation of an integers. se Chinese reminder the prem. Use of Euler's Photecology	08 Hours egendre symbo 10 Hours f primitive root gorithm. Solve neorem to find i function.

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	Outcomes													
	MA1502-1.1	2	3	-	-	-	-	-	-	-	-	-	-	
	MA1502-1.2	2	3	-	-	-	-	-	-	-	-	-	-	
	MA1502-1.3	2	3	-	-	-	-	-	-	-	-	-	-	
	MA1502-1.4	2	3	-	-	-	-	-	-	-	-	-	-	
	MA1502-1.5	2	3	-	-	-	-	-	-	-	-	-	-	
1: Lo	w 2: Medium 3: High			•	•	•			•					
	-													
TEXTE	BOOKS:													
1.	D. Burton, "Elementary Number Theory", McGraw-Hill, 2005.													
2.	Niven, H.S. Zuckerman & H.L. Montgomery, "Introduction to the Theory of													
	Numbers", Wiley, 2000.													
REFER	RENCE BOOKS:													
1.	H. Davenport, "The H	ighe	er Ari	thm	etic"	, Car	nbrio	dge I	Jniv	ersity	/ Pres	s, 200	8.	
2.	G. A. Jones & J. M. Jo	nes,	"Ele	men	tary	Num	nber	Theo	ory",	Spri	nger l	JTM, 2	2007.	
3.	Thomas Koshy, "Elem 2007.	enta	iry N	umb	er Tl	heor	y wit	h Ap	plica	ation	s", 2n	d edit	ion, E	lsevier,
4.	William J. LeVeque, "I	unc	lame	ental	s of I	Num	ber	Thec	ory".					
E Boo	ks / MOOCs/ NPTEL													
1.	http://refkol.ro/matek/	math	bool	ks/ro	.matl	n.wik	ia.coi	<u>m%2</u>	520v	/iki%	2520Fi	<u>isiere</u>		
	pdf incarcate/													
	Elementary-Number-Th				•									
2.	https://nptel.ac.in/cour													
3.	https://nptel.ac.in/courses/111103020													



(Deemed to be University)	NEAR ALGEB	RA	
Course Code:	MA3501-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Prerequisite	MA1001-1 a	and MA2009-1	
Teaching D	epartment: Ma	athematics	
Course Objectives:			
1. Understand the concepts of vec	ctors, bases.		
2. Determine the kernel, range, ra		of a linear transforma	ition and apply
them suitably in their field of st			
3. Find the canonical forms and ap			
4. Make use of Gram-Schmidt pro			S.
5. Learn the concepts of singular v		sition and PCA.	
	UNIT-I		
Vector spaces			08 Hours
Vector spaces, subspaces, bases and	d dimensions,	coordinate vecotrs, r	null spaces and
column spaces of the matrices.			
Linear Transformations			07 Hours
Linear transformations, rank-nullity th	-		-
basis, linear operators, linear functiona	als, transpose of	t a linear transformati	on.
	UNIT-II		
Canonical Forms	UNIT-II		08 Hours
Review of characteristic values, similari	ity of matrices, (Cayley Hamilton theor	
polynomials, invariant subspaces, Jord	•		
Inner Product Spaces			07 Hours
Inner products; inner product space	es; orthogonal	sets and projections	Gram-Schmidt
process; QR-factorization, Least-squar	es problems.		
	UNIT-III		
Symmetric Matrices and Quadratic			10 Hours
Diagonalization, quadratic forms, con			
and principal component analysis. App	olications to line	ear recurrence relatior	IS.
Course Outcomes: At the end of the			
1. Interpret vectors in two and	three-dimensio	onal spaces both alg	jebraically and
geometrically.	transformation	ac a manning from a	
2. Analyze the concept of a linear			
to another and be able to calculate and nonstandard bases.	ate its matrix re	presentation with resp	ect to standard
	dan and ration	al canonical forms	
3. Understand the concepts of Jor	uan anu fationa	ai canonicai ionns.	
4. Make use of Gram-Schmidt pro	cess to produce		
4. Make use of Gram-Schmidt pro to use least square approximati system.	cess to produce		

N	NIT.	TE					C	urricu	ılum -	- B.Te	ch. (F	Robotics	& Artifi	icial Inte	lligenece):
	5.	Apply techniques of	cons	strair	ned	opti	miza	tion	sinc	jular	valu	ie de	comp	ositio	n and
		PCA for problems aris	ingi	in va	riou	s eng	gine	ering	, fiel	ds.					
	Cours	se Outcomes Mapping	g wit	th Pi	rogr	am (Outo	ome	es						
		Program	1	2	3	4	5	6	7	8	9	10	11	12	
		Outcomes→													
		↓ Course													
		Outcomes													
		MA3501-1.1	3	2	-	-	-	-	-	-	-	-	-	-	
		MA3501-1.2	2	2	-	-	-	-	-	-	-	-	-	-	
		MA3501-1.3	3	1	-	-	-	-	-	-	-	-	-	-	
		MA3501-1.4	3	2	-	-	-	-	-	-	-	-	-	-	
		MA3501-1.5	3	2	-	-	-	-	-	-	-	-	-	-	
		w 2: Medium 3: High BOOKS: Kenneth Hoffman an	d Ra	av Ki	INZA	"I ir	near	Alge	hra	יי י nd	edit	tion 1	Dearso	n Edu	Ication
	_ .	(Asia) Pte. Ltd, 2004.		ay itt		, בוו	icui	/ lige		2	cun		curse		
	2.	David C. Lay, "Linear	· Alc	ebra	a and	d its	Apr	olicat	tions	",3 rd	edit	ion, F	Pearsc	n Edu	ucation
		(Asia) Pte. Ltd, 2005.		•			• •								
	REFE	RENCE BOOKS:													
	1.	M. Artin, "Algebra", P	rent	ice F	- all c	of Ind	dia, 2	2004.							
	2.	Gilbert Strang, "Linear Algebra and its Applications", 4th edition, Thomson Learning Asia, 2003.													
	3.	Bernard Kolman and David R. Hill, "Introductory Linear Algebra with Applications", Pearson Education (Asia) Pte.Ltd, 7 th edition ,2003.													
	4.	Sheldon Axler, "Linea Edition, 2015.	r Alg	gebra	a Doi	ne R	ight'	, Spr	ringe	er Inte	erna	tional	l Publi	catior	n, Third

Course Code:	ME1501-1	Course Type	OEC					
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03					
Total Teaching Hours	40	CIE + SEE Marks	50+50					
Teaching Depar	tment: Mechar	nical Engineering						
Course Objectives:								
1. Get an idea on the different co	mponents of an	engine and its types v	vith lubrication					
system.			_					
2. Understand the fuel supply sys	stem and ignitio	n systems used in auto	omobiles.					
3. Demonstrate the working of tr	ansmission system	em.						
4. Explain the importance of suspension system, steering geometry and drives in								
automobiles								
5. Know the concept of braking system, tyres and emission control.								
	UNIT-I							
Engine Components and Cooling & SI & CI engines, Cylinder arrangemer			08 Hours					
methods of cooling, thermost crankshaft/flywheel position sensor temperature sensor.			5					
Fuel Supply Systems for SI and CI E	Ingines		08 Hours					
Fuel mixture requirements for SI eng		carburetors, si mple c	arburetor, multi					
point and single point fuel injection	systems, CRDI	, fuel transfer pumps:	AC Mechanical					
Pump, SU Electrical Pumps, injectors,	Fuel gauge sen	sor, Throttle position s	sensor, Mass air					
flow sensors.								
Ignition Systems : Battery Ignition systems	ystems, magnet	o Ignition system, Tra	nsistor assisted					
contacts. Electronic Ignition, Autor	matic Ignition	advance systems, Lig	hting systems,					
Rain/Light sensors, starting device (Be								
Pedagogy: Chalk and talk method, Po		entation						
	UNIT-II							
Power Trains			07 Hours					
Clutches - Single plate, multiplate a	-							
ratios in transmission, Constant m	0	, ,	· ·					
automatic transmission, Vehicle Sp	eed Sensors, o	calculation of gear ra	atios, Types of					
transmission systems. No numerical.			08 Hours					
Drive to Wheels								

AUTOMOTIVE ENGINEERING

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Propeller shaft, universal joints, Hotchkiss. and torque tube drives, differential, rear axle, steering geometry, camber, king pin inclination, included angle, castor, toe in & toe out, condition for exact steering, power steering, over steer, under steer & neutral steer, Steering angle sensors, numerical problems.

Suspension and Springs: Requirements, leaf spring, coil spring, Torsion bar suspension systems, independent suspension for front Wheel, Air suspension system. Collective



bargaining; Characteristics, Necessity, Forms Safety & Health; Industrial accidents, Safety Quality circle; Meaning, Structure

Pedagogy: Chalk and talk method, Power Point Presentation

UNIT-III

Brakes09 HoursTypes of brakes, mechanical, compressed air, vacuum and hydraulic braking systems,
construction and working of master and wheel cylinder, brake shoe arrangements, Disk
brakes, Drum brakes.

Tyres: Desirable tyre properties, Types of tyres.

Automotive Emission: Automotive exhaust emissions, sources and emission control method: EGR, SCR, Emission Standards, Exhaust sensors.

Electric Vehicles.

Pedagogy Chalk and talk method, Power Point Presentation

Course Outcomes: At the end of the course student will be able to

- **1.** Describe and demonstrate the layout of an automobile and components of an automobile engine. Explain cooling and lubrication systems.
- **2.** Explain and demonstrate the fuel supply and Ignition systems for SI and CI engines.
- **3.** Describe and demonstrate the transmission system
- **4.** Explain and demonstrate the components of drive to wheel and suspension system, calculate the parameters of steering geometry.
- **5.** Describe and demonstrate automotive braking system. Explain types and construction of tyres and wheels. Explain the significance of automotive emissions and its controlling methods

Course Outcomes Mapping with Program Outcomes

1	2	3	4	5	6	7	8	9	10	11	12	
3	1	-	1	-	1	-	-	3	1	-	1	
3	1	-	1	-	1	-	-	3	1	-	1	
3	1	1	1	-	1	-	-	3	1	-	1	
2	3	1	-	-	1	-	-	3	1	-	1]
3	1	1	-	-	1	1	1	3	1	-	1	
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1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** S. Srinivasan, "Automotive Mechanics", Tata McGraw Hill, 2003.
- **2.** Kirpal Singh, "Automobile Engineering", Vol I and II, 2013.
- **3.** A. K. Babu, "Automotive Electrical and Electronics", Khanna Publishers, 2nd edition, 2016.

REFERENCE BOOKS:

- **1.** R. B. Gupta, "Automobile Engineering", Satya Prakashan, 4th Edn., 1984.
- **2.** Naran G, "Automobile Engineering", Khanna Publishers 2002



NITTE

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Cou	ırse Code:	ME1502-1	Course Type	OEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
	Teaching Depart	ment: Mechan	ical Engineering	
Cour	rse Objectives:			
1.	Know the Consequences of poll over the last few decades, nece	essity of mode	rn awareness on pollut	
2.	carbon audit can help in develop Identify the Importance of Met			bal warming
۷.	various types of plume dispersi height for different pollutants.	••••	-	-
3.	Distinguish Particulates and fly a electrostatic precipitator efficien	•		one separator,
4.	Illustrate Formation, measureme pollutants.	ent and contro	l techniques for Smoke	and gaseous
5.	Summarize the Effects of wate techniques, Different Pollution (how these acts can help in bring	Control Acts, Le	egal aspects of pollutio	
		UNIT-I		
	oduction to Pollution			08 Hours
envir	and the environment, types conmental management concept, s rious pollutants, permissible conce	sustainable ind	ustrial growth, carbon a	
Mete	eorology			08 Hours
Mete	eorology, Wind rose, Lapse rate, pl gogy: Chalk and talk method, Pow	•	•	
		UNIT-II		
Sepa	ration techniques			08 Hours
Diffe Matt	rent types of Particulates, Need er Fly Ash Electrostatic precipitat lems), Bag House fabric filter Cy	or (Problems)	Theory of settling prod	cesses (Design
Smo	ke and gaseous pollutants:			08 Hours
Smol Meas Smol Co, L	ke- White, blue and black smok surement of stack smoke intensity ke meter, Domestic and Industrial JBHC, Nox their ill effects and & co	/ using Ringler Incinerators-E ontrol methods	nann Chart and Smoke Design factors, Pollutan 5.	scope &Bosch
Peda	gogy: Chalk and talk method, Pow	ver Point Prese	ntation	



Water, soil, noise, and odor pollution, their control in India, brief details of Euro and BS standards Pedagogy: Chalk and talk method, Power Point Presentation Course Outcomes: At the end of the course student will be able to 1. Identify the various types of pollutants and distinguish between them with regards to Particulate matters and AQI. 2. Outline the instruments for Meteorological measurements, distinguish types of plume dispersions and its effect; analyze the concentration of various gaseous pollutants from T-Z diagrams 3. Explain the Particulates and fly ash separation techniques, compare and Interpret their efficiency 4. Illustrate Formation, measurement and control techniques for Smoke and gaseous pollutants 5. Identify Effects of water, soil, plastics and odor pollution on environmental Pollution and explain the Legal aspects of pollution control. Course Outcomes Mapping with Program Outcomes 9 10 11 12 4 Explain the Legal aspects of pollution control. Image: student st														08	Hours	
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Course Code:	ME1503-1	Course Type	OEC
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
Teaching Depart	ment: Mechar	nical Engineering	
Course Objectives:			
1. To provide the knowledge, s	kills, attitudes	and values necessa	ry to address
sustainable development challe	nges		
2. Address the global challenge	• •		mate change,
environmental degradation, pea	ace and justice.		
3. To learn more and take action.			
4. Addresses critical global challer			
5. Analyze how sustainable develo	pment can be	achieved in practice.	
	UNIT-I		
	UNIT-I		00 11
The origin development and idea o	f the SDCc Hi	istony and origins of t	08 Hours
The origin, development and idea o Development Goals. What are the			
perspectives? How are they related to			thouology and
SDGs and Society			08 Hours
Ensuring resilience and primary needs	in society In-o	depth discussion and a	
related to poverty, hunger, health & w			je e gee
Pedagogy: Chalk and talk method, Pov	5		
	UNIT-II		
SDGs and Society			14 Hours
Strengthening Institutions for Sustai related to gender equality, affordable			, ,
and peace, justice & strong institution			
SDGs and the Economy: Shaping a Su		omy In-depth discussi	on and analysis
of goals related to work & econor			•
inequalities, responsible production &	-		
Pedagogy: Chalk and talk method, Pow	wer Point Prese	entation	
	UNIT-III		
SDGs and the Biosphere			10 Hours
Development within Planetary Bounda	ries In-depth c	liscussion and analysis	
to clean water, climate, life below wate	•	•	<u> </u>
Realizing the SDGs: Implementation the			discussion and
analysis of SDG 17 which aims to ir	-		
technology and the development of co	oherence betw	een policies.	
Pedagogy: Chalk and talk method, Pow	wer Point Prese	entation	
Course Outcomes At the and of the	cource ctudent	will be able to	
Course Outcomes: At the end of the o	Louise student		

J)	NIT (Deemed to be U						Ci	urricul	lum –	B.Teo	ch. (Re	obotics &	& Artific	cial Intel	ligenece): 20
	1.	Summarize the UN"	s Su	ustai	nable	e D	evel	opm	ent	Goa	ls a	nd h	ow t	heir	aims,
		methodology and per	spec	tives	5.										
	2.	Analyze the major iss	ues	affeo	ting	sust	taina	ble	deve	elopn	nent	and	how s	sustai	nable
		development can be a	ichie	ved	in pr	actic	ce.								
	3.	Identify and apply						-		ach	nieve	ment	/possi	ibilitie	s of
		sustainable developm	ent i	n Nit	tte g	ram	pan	chay	ath.						
	4.	Evaluate the implication	ons c	ofov	eruse	e of I	reso	urces	5, ро	pula	tion	growt	h and	l econ	omic
		growth. sustainability	& Ex	plore	e the	chal	leng	es th	ne so	ciety	/ face	es in n	naking	g trans	sition
		to renewable resource	e use	•											
	5.	Create skills that will e	nabl	e stu	Iden	ts to	und	ersta	and a	attitu	des	on inc	dividu	als, sc	ociety
		and their role rega	rding	g ca	uses	s an	id s	oluti	ons	in	the	field	of s	sustaii	nable
		development.													
	Cours	se Outcomes Mapping	ı wit	h Pr	ogra	nm C)utc	ome	S						
		Program	1	2	3	4	5	6	7	8	9	10	11	12	
		Outcomes→													
		↓ Course													
		Outcomes													
		ME1503-1.1	1	2	1	1	1	3	3	1	1	1	-	2	

1.	Sachs, Jeffrey D. "The age of sustainable development" Columbia University Press,
	2015

TEXTBOOKS:

Gagnon, B., Leduc, R., and Savard, L., "Sustainable development in engineering: a 2. review of principles and definition of a conceptual framework", Cahier de recherche / Working Paper 08-18, 2008.

REFERENCE BOOKS:

ME1503-1.2

ME1503-1.3

ME1503-1.4

ME1503-1.5

1: Low 2: Medium 3: High

Elliott, Jennifer, "An introduction to sustainable development", Routledge, 2012. 1.

E Books / MOOCs/ NPTEL

1. https://www.un.org/sustainabledevelopment/poverty/

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TECHNOLOGICAL INNOVATION

			INNOVATION		
Cou	urse Code:	ME1504-1	Course Type	OEC	
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03	
Tot	al Teaching Hours	40	CIE + SEE Marks	50+5	50
	Teaching D	epartment: M	echanical Engineering)	
Cour	rse Objectives:				
1.	Understand basics of operations	s management	and Quality.		
2.	Define the concept of technolog	gical innovatior	۱.		
3.	Discuss Innovation manageme	ent and the	difference between I	nvention a	and
4.	Appreciate the importance of In management techniques.	novation as a r	nanagement process a	ind Innovat	tion
5.	Discuss the Innovation syste management and Transfer and		•	f Technol	ogy
		UNIT	-I		
Prod	luction and Operations Manage	ment and Intr	oduction to Quality C	oncepts	04 Hours
Intro Basic Inno ^v Perfo	uality - Concept of cost of quality oduction to Technological Innov c Concepts and Definitions: Tech vation - The Concept of Tech ormance - Innovation Measuremen novations – Innovation Process.	r ation inology - Tech inological Inno	nology Management ovation - Innovation	Posture,	Propensity and
	tup Idea Pitching				03 Hours
					1
		UNIT	-II		-
Intro	oduction to Innovation Manage	ment and Inno	ovation & Competitiv	eness	07 Hours
Knov and (oduction to Innovation Manage wledge and Education – Types of I Characteristics of Innovation.	Learning - Diffe	erence Between Innova	ition and Ir	vention - Types
	vation and Competitiveness: Case			ompetitive	08 Hours
	vation as a Management Proces		tion Management of	Tachnolog	
Corp Chall	vities to enhance companies' capa porate Perspective, National Pers lenges in Technological Innovat agement - Innovation Manageme	spective, Theor ion Managem	retical Perspective and ent - Case Study in	d Individua	al Perspective
	genne	UNIT-			
Inno	ovation Systems and Technology				04 Hours
	vation Systems: The Concept of	Innovation Sys		ystems: Se	



Introduction to Technological Forecasting

05 Hours

Introduction - Applications & Limitations of Technological Forecasting – Technology Forecasting Techniques – Exploratory Forecasting – Normative Forecasting – Delphi Technique – Problems of Technological Forecasting

Cour	se Outcomes: At the end of the course student will be able to						
1.	Define operations management and quality.						
2.	Describe technological innovation and its key features for business.						
3.	Discuss innovation management and the difference between invention and innovation.						
4.	Explain innovation as a management process, its management and perspectives.						
	Understand Innovation management techniques.						
5.	Explain innovation systems, technology management transfer and basics of						
	technological forecasting.						

Course Outcomes Mapping with Program Outcomes

comes mapping man	-	9										
Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes→												
↓ Course												
Outcomes												
ME1504-1.1	3	2	-	-	-	1	1	-	1	-	-	1
ME1504-1.2	3	2	-	-	-	1	1	-	1	-	-	1
ME1504-1.3	2	2	-	-	-	1	1	-	1	-	-	1
ME1504-1.4	2	2	-	-	-	1	1	-	1	-	-	1
ME1504-1.5	3	2	-	-	-	1	1	-	1	-	-	1

1: Low 2: Medium 3: High

TEXTB	BOOKS:
1.	Carayannis, Elias G., Samara, Elpida T., Bakouros, Yannis L., "Innovation and Entrepreneurship
	Theory, Policy and Practice", Springer, 2015.
REFER	ENCE BOOKS:
1.	Dick Whittington, "Digital Innovation and Entrepreneurship", Cambridge University Press, 2018.
E Boo	ks / MOOCs/ NPTEL
1.	https://krishi.icar.gov.in/jspui/bitstream/123456789/46063/1/21_Technological%20forecasting.
	pdf dtd 12/06/2022
2.	http://www.oipec.eu/wp-content/uploads/2017/07/Introduction-to-Technology-
	Forecasting.pdf dtd 12/06/2022

HUMAN RES	OURCE MAI	NAGEMENT	
Course Code:	MG1501-1	Course Type	OEC

Teaching Hours/Week (L: T: P	: S) 3:0:0:0	Credits	03
Total Teaching Hours	40	CIE + SEE Marks	50+50
	epartment: Mech	anical Engineering	•
Course Objectives:		<u> </u>	
	understanding of H	HRM theory, functions and p	ractices.
2. To understand concepts a	nd skills recruitme	nt.	
3. To understand the concep			
		nd health types of organizat	ions.
5. To understand the concep	ts of e-HRM.		
	UNIT-I		
Human Resource Management	: & HRP		08 Hour
Introduction, meaning, nature,	scope of HRM.	Major functions of HRM	, Personn
Management vs Human Resource	e Management, jol	b design, job evaluation, job	analysis, jo
specification, job enlargement, jo	ob enrichment. Ro	le of HR Manager.HR Plann	ing. Proces
HRP.			[
Recruitment			08 Hour
Definition, Sources and Metho		nt Selection: Definition and	Process of
Selection. Cost benefit analysis o			
Placement: Meaning, Induction			Promotio
Demotion and Employee Separat			
Pedagogy: Chalk and talk method	d, Power Point Pre	sentation	
Tusining and development	UNIT-II		07
Training and development	a in turining. Turi	ning Matheda Evenutive D	07 Hour
Training v/s development, stage Methods and Development of Ma	5	5	•
	anagement Develo	phient, Career and Succession	
Compensation			08 Hour
Employee remuneration, rewards	Wage and Salar	Administration Bonus frin	
Internal Mobility, External Mobility			ge benent
Employee Grievances: Employee			
Collective bargaining; Characteris	•		al accident
Safety Quality circle; Meaning, St	•	inis Salety & Health, industri	
Pedagogy: Chalk and talk method		sentation	
redayogy. Chaik and taik method	u, rower romt rie	sentation	
	UNIT-III		1
IHRM and e-HRM			09 Hour
IHRM and e-HRM Managing IHRM e-HR Activitie		ment selection expatriate	
Managing IHRM. e-HR Activitie	es, Global recruit	•	
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic	es, Global recruit on and Settlement		09 Hour s. Industria
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic Aspects of e-HRM,e-Job design &	es, Global recruit on and Settlement & Analysis, Ethical	issues in employment	
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic Aspects of e-HRM,e-Job design & Pedagogy: Chalk and talk method	es, Global recruit on and Settlement & Analysis, Ethical d, Power Point Pre	issues in employment sentation	
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic Aspects of e-HRM,e-Job design & Pedagogy: Chalk and talk method Course Outcomes: At the end of	es, Global recruit on and Settlement & Analysis, Ethical d, Power Point Pre f the course stude	issues in employment esentation nt will be able to	
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic Aspects of e-HRM,e-Job design & Pedagogy: Chalk and talk method Course Outcomes: At the end of 1. Describe the basic conception	es, Global recruit on and Settlement & Analysis, Ethical d, Power Point Pre f the course stude ts of HRM & HRP.	issues in employment sentation nt will be able to	
Managing IHRM. e-HR Activitie conflict –Causes, Types, Preventic Aspects of e-HRM,e-Job design & Pedagogy: Chalk and talk method Course Outcomes: At the end of	es, Global recruit on and Settlement & Analysis, Ethical d, Power Point Pre f the course stude ts of HRM & HRP. ns of recruitment,	issues in employment sentation nt will be able to selections, and appraisal.	

- NITTE Identify the employee grievances to spell out the remedial measures. 4. 5. Infer the concepts of e-HRM and I-HRM. **Course Outcomes Mapping with Program Outcomes** 2 8 11 12 Program 1 3 4 5 6 7 9 10 **Outcomes**→ ↓ Course Outcomes 3 MG1501-1-1.1 -_ _ 1 1 1 1 -_ _ _ 3 1 1 1 1 MG1501-1-1.2 _ _ _ _ _ _ 3 _ _ _ _ 1 1 1 1 MG1501-1-1.3 _ _ _ 3 MG1501-1-1.4 1 1 1 1 _ _ _ _ _ _ _ 3 _ 1 1 1 1 MG1501-1-1.5 _ _ _ _ _ _ 1: Low 2: Medium 3: High **TEXTBOOKS:** 1. P Courseba Rao, "Essentials of Human Resource Management & Industrial Relations", Third Revised Edition. **REFERENCE BOOKS:** John M. Ivancevich, "Human Resource Management", 10/e, McGraw Hill. 1.
 - 2. Flippo, "Human Resource Management".

E Books / MOOCs/ NPTEL

http://edx.nimt.ac.in/courses/course-v1:nimtX+PGDM1212+2017_H1/about 1.

05 Hours



Financial Statement

Cash Flow Statement Analysis

(Deemed to be l	Jniversity)					
	MANAGEMENT ACC		ND CONTROL SYST	EM		
Cours	se Code:	MG1502-1	Course Type	OEC		
Teacl	ning Hours/Week (L: T: P: S)	ours/Week (L: T: P: S) 3:0:0:0 Credits 03				
Total	Total Teaching Hours40CIE + SEE Marks50+50					
	Teaching I	Department: N	lanagement			
Course	e Objectives:	-				
1.	Apply Cost Accounting concepts and techniques in the decision making process.					
2.	Make decisions such as pricing, special order pricing, make-or-buy and elimination					
	of a part of the company or replacement of equipment.					
3.	Understand the relevance of	different types	of costs in the decision	making process		
	such as relevant sorts suply s	acte ar controll	abla casta	2.		

	such as relevant costs, sunk costs or controllable costs.
4.	Understand fundamental concepts in Financial, Cost & Management Accounting.
5.	Develop analytical skills associated with the preparation and interpretation of

UNIT-I

Introduction to Cost and Management Accounting and Marginal Costing07 HoursCost Accounting – Meaning, Objectives and Scope, Management Accounting – Meaning,
Objectives and Scope, Tools and Techniques of Management Accounting, Relationship of Cost
Accounting, Financial Accounting, Management Accounting and Financial Management,
Conflicts in Profit versus Value Maximization Principle, Role of Management Accountant in

Decision Making.Marginal Costing08 HoursMeaning, Advantages, Limitations and Applications. Breakeven Analysis, Cost Volume Profit
Analysis, P/V Ratio and its Significance, Margin of Safety, Absorption Costing: System of Profit
Reporting and Stock Valuation, Difference between Marginal Costing and Absorption Costing,
Income Measurement under Marginal Costing and Absorption Costing. (Practical Problems)

UNIT II	
Standard Costing and Budgetary Control	07 Hours
Standard Costing - Definition, Significance and Applications, Various Types	of Standards,
Installation of Standard Costing System-for Material, Labour, and Overhead. Va	riance Analysis
for Materials, Labour and Overheads, Accounting Treatment of Variances. Ber	hchmarking for
Setting of Standards, Variance Reporting to Management. (Practical Problems)	
Budgetary Control	08 Hours
Budget Concept, Manual, Fixed and Flexible Budgets, Preparation and Monitor	ing of Various
Types of Budgets, Budgetary Control System- Advantages, Limitations and Inst	allation. Zero
Base Budgeting, Programme and Performance Budgeting. (Practical Problems)	
UNIT III	
Fund Flow and Cash Flow Statement	05 Hours
Fund Flow Statement Analysis - Definition, Features, Steps for Preparation	of Fund Flow
Statement.	

261



Classification, Preparation of Cash Flow Statement, Uses of Cash Flow statement, Difference between Cash Flow and Fund Flow Statement. (Practical Problems)

Cour	rse Outcomes: At the end of the course student will be able to
1.	Describe the Cost Accounting concepts and techniques in the decision making
	process.
2.	Elucidate the Make decisions such as pricing, special order pricing, make-or-buy and
	elimination of a part of the company or replacement of equipment.
3.	Apply the relevance of different types of costs in the decision making process such as
	relevant costs, sunk costs or controllable costs.
4.	Identify fundamental concepts in Financial, Cost & Management Accounting.
5.	Infer the analytical skills associated with the preparation and interpretation of Financial
	Statement
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Course Outcomes Mapping with Program Outcomes

<u> </u>			9										
Program	1	2	3	4	5	6	7	8	9	10	11	12	
Outcomes→													
↓ Course													
Outcomes													
MG1502-1-1.1	3	1	-	I	1	1	1	-	1	1	-	1	
MG1502-1-1.2	3	1	1	I	1	1	1	-	1	1	-	1	
MG1502-1-1.3	3	-	-	-	-	1	-	-	1	1	-	1	
MG1502-1-1.4	3	-	-	-	-	1	-	-	1	1	-	1	
MG1502-1-1.5	3	1	1	1	-	1	1	-	1	1	-	1	

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	M.Y. Khan and P.K. Jain. "Management Accounting", McGraw-Hill Education
2.	Robert N. Anthony, "Management Accounting", Richard Dirwin.
3.	I.M. Pandey, "Management Accounting", Vikas Publishing House.
4.	Paresh shaw, "Management Accounting", Oxford University Press.
5.	A. Murthy and S. Gurusamy , "Management Accounting", McGraw Hill.
6.	NM Singhvi and Ruzbeh J. Bodhanwala, "Management Accounting", PHI learning Pvt.
	Ltd.



	se Code:	MG1503-1	Course Type	OEC			
	ning Hours/Week (L: T: P: S)	3:0:0:0	Credits	03			
lotal	Teaching Hours	40	CIE + SEE Marks	50+50			
		Department: M	lanagement				
<u>.ourse</u> 1.	e Objectives: Define production/operations	management	Differentiate between P	roduction and			
1.	service system and types of	-		ntinuous and			
	intermittent production syste		-				
	CRM and ERP systems.	ins with then a		lages. Discuss			
2.	Solve problems on fundamen	ntals of statisti	cs and normal distributi	on. Draw and			
	Analyze variable process control charts and determine process capability.						
3.	Discuss Total Quality Management tools and methods. Calculate reliability of series						
	and parallel systems using the information on failure rate and time.						
4.	Solve decision-making prob	5	•				
	methods. Apply the concepts	-		•			
	faculty location using break	•	•	nethod. Solve			
	problems related to product a						
5.	Use concepts of replacement	theory to solve	problems of replacing it	ems that fail			
	gradually and suddenly.						
		UNIT-I					
Produ	ction and Operations Manage			06 Hours			
	uction, Functions within busines		s, the operation manage	ment function			
	ication of production systems, P						
o Cus	tomer Relationship Managemen	it (CRM) and En	terprise Resource Planni	ng (ERP).			
Philos	ophy of statistical process con	trol and mode	eling process quality	11 Hours			
	al distribution tables, Finding the			-			
lorma	of variation Statistical Pasis of	the Control Cha	orte (hacie principlae, cha				
Norma auses	of variation, Statistical Basis of		ints (basic principles, cho	ices of control			
Norma auses imits,	significance of control limits, wa	rning limits)					
Norma causes imits, Contro	significance of control limits, wa I charts for variables: Control Cl	rning limits)					
Norma causes imits, Contro Simple	significance of control limits, wa ol charts for variables: Control Cl e Numerical Problems,	rning limits) narts for X-Bar (and R- Charts, Type I and	d Type II errors			
Norma causes imits, Contro Simple Proces	significance of control limits, wa ol charts for variables: Control Cl e Numerical Problems, s capability: The foundation of p	rning limits) narts for X-Bar a process capabili	and R- Charts, Type I and ty, Natural Tolerance lim	d Type II errors its, c _p – proces			
Norma causes imits, Contro Simple Proces capabi	significance of control limits, wa ol charts for variables: Control Ch e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process	rning limits) harts for X-Bar process capabili performance	and R- Charts, Type I and ty, Natural Tolerance lim	d Type II errors its, c _p – proces			
Norma causes imits, Contro Simple Proces capabi Nume	significance of control limits, wa ol charts for variables: Control Cl e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process rical problems. Concept of Six si	rning limits) harts for X-Bar process capabili performance ii igma.	and R- Charts, Type I and ty, Natural Tolerance lim ndex, summary of proc	d Type II errors its, c _p – proces			
Norma causes imits, Contro Simple Proces capabi Nume	significance of control limits, wa ol charts for variables: Control Ch e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process	rning limits) harts for X-Bar process capabili performance ii igma.	and R- Charts, Type I and ty, Natural Tolerance lim ndex, summary of proc	d Type II errors its, c _p – proces			
Norma causes imits, Contro Simple Proces capabi Nume	significance of control limits, wa ol charts for variables: Control Cl e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process rical problems. Concept of Six si	rning limits) harts for X-Bar process capabili performance ii igma.	and R- Charts, Type I and ty, Natural Tolerance lim ndex, summary of proc	d Type II errors its, c _p – proces			
Norma causes limits, Contro Simple Proces capabi Numer Pedage	significance of control limits, wa ol charts for variables: Control Cl e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process rical problems. Concept of Six si	rning limits) harts for X-Bar process capabili performance i igma. ver Point Prese	and R- Charts, Type I and ty, Natural Tolerance lim ndex, summary of proc	d Type II errors its, c _p – proces			
Norma causes imits, Contro Simple Proces capabi Numer Pedage Qualit	significance of control limits, wa of charts for variables: Control Cl e Numerical Problems, is capability: The foundation of p lity index, c _{pk} , p _p – process rical problems. Concept of Six si ogy: Chalk and talk method, Pov	rning limits) harts for X-Bar process capabili performance in igma. ver Point Presen UNIT II	and R- Charts, Type I and ty, Natural Tolerance lim ndex, summary of proc ntation	d Type II errors its, c _p – proces cess measures 06 Hours			

TOTAL Quality Management: Definition, Principles of TQM, Gurus of TQM, Benefits of TQM. Managing Quality: Quality circles, Continuous Improvement- Juran's Trilogy, PDSA cycle, Kaizen, 7 QC tools.



Introduction to reliability, Mean time to failure, Mean time between failures, Bath tub curve, Reliability of series and parallel systems, Numerical problems on the above topics.

Operations Management activities	12 Hours

Decision Making: The decision process, characteristics of operations decisions, use of models - decision making environments. Break even Analysis, Decision trees.

Capacity Planning: Importance of capacity decisions, defining and measuring capacity, determinants of effective capacity. Design, System an actual capacity. System efficiency and utilization. Determination of Equipment requirement for a single stage production processes. Numerical problems on the above.

Facilities location planning: Need for location decisions, nature of locations decisions, general procedure for making locations decisions, Use of Breakeven analysis and Transportation algorithms for making location decisions.

Facilities layout planning: Need for layout decisions. Minimizing material handling cost in process ayout using Load distance analysis, Simple line balancing problems in product layout.

UNIT III

05 Hours

Replacement Theory

Replacement policy for equipment which deteriorates gradually. Replacement of items that fail suddenly.

Pedagogy: Chalk and talk method, Power Point

Course Outcomes: At the end of the course student will be able to

0001	course outcomes. At the end of the course student will be usie to					
1.	Define production/operations management. Differentiate between Production and service system and types of production systems Discuss continuous and intermittent production systems with their advantages and disadvantages. Discuss CRM and ERP systems.					
2.	Solve problems on fundamentals of statistics and normal distribution. Draw and Analyze variable process control charts and determine process capability.					
3.	Discuss Total Quality Management tools and methods. Calculate reliability of series and parallel systems using the information on failure rate and time.					
4.	Solve decision-making problems using break even analysis and decision tree methods. Apply the concepts of Design and System capacity. Solve problems on faculty location using break even analysis and transportation method. Solve problems related to product and process layouts.					
5.	Use concepts of replacement theory to solve problems of replacing items that fail gradually and suddenly.					

Course Outcomes Mapping with Program Outcomes

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Program Outcomes→	1	2	3	4	5	6	7	8	9	10	11	12
↓ Course Outcomes												
MG1503-1-1.1	2	1	1	I	1	-	1	1	I	-	2	-
MG1503-1-1.2	2	2	I	1	1	-	1	I	1	-	2	-
MG1503-1-1.3	1	1	1	1	1	-	1	1	1	-	2	-
MG1503-1-1.4	3	2	1	1	1	-	1	1	1	-	3	-
MG1503-1-1.5	1	1	-	-	-	-	-	-	-	-	1	-
<u> </u>												

1: Low 2: Medium 3: High

	Curriculum – B.Tech. (Robotics & Artificial Intelligenece): 20							
TEXTBO	DOKS:							
1. Joseph G Monks, "Production / Operations Management", McGraw Hill E								
2.	William J Stevenson, "Production and Operations Management", Tata McGraw Hill, 8th Edition.							
3.	RC Gupta, "Statistical Quality Control", Khanna Publishers, New Delhi, 2005.							
4. N.D. Vohra, "Quantitative Techniques in Management", Tata McGraw Hill, 2015								
REFERENCE BOOKS:								
1.	E.L. Grant and R.S. Leavenworth, "Statistical Quality Control", 7th edition, McGraw- Hill publisher, 2004.							
2.	Prem Kumar Gupta, D S. Hira, "Operations Research", S Chand Publications, New Delhi, 2 nd edition 2008, Prentice Hall.							
3.	W S Messina, "Statistical Quality Control for Manufacturing Managers", Wiley & Sons, Inc. New York, 1987							
4.	Montgomery, Douglas, "Statistical Quality Control", 5th Edition, John Wiley & Sons, Inc. 2005, Hoboken, NJ.							
5.	Jerry Banks, "Principles of Quality Control", Wiley & Sons, Inc. New York.							



ORGANIZATIONAL BEHAVIOUR							
Course Code: MG1504-1 Course Type OEC							
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03				
Total Teaching Hours	40	CIE + SEE Marks	50+50				
Teaching Department: Management							

Course	urse Objectives:									
1.	Describe the Nature and Characteristics, Determinants and Approaches of									
	Organizational Behaviour. Describe the concepts of Perception, Attitudes and values and their implications.									
2.	Describe the concepts of learning and motivation along with their managerial									
	implications.									
3.	Describe the concepts of Leadership along with their managerial implications.									
4.	Discuss the concepts of group dynamics and conflict management along with their									
	implications.									
5.	Discuss the concepts of Organization culture and change and conflict management									
	along with their implications.									

UNIT-I

15 Hours

Introduction: Conceptual Foundation of Organisational Behaviour; Nature and Characteristics; Determinants; Contributing Disciplines; Challenges and Opportunities for Organisational Behaviour, Models and Approaches of Organizational Behaviour, OB and Emotional Intelligence.

Perception, Attitude, and Values: Nature, Process, Importance, Factors Influencing Perception; Attribution Theory of Perception; Issues Involved in Perception: Selective Perception, Halo Effect, Contrast Effect, Projection, Stereotyping; Concept of Pygmalion Effect; an overview of Emotions and feelings, Values, Beliefs and Attitudes with Managerial Implications.

Learning: Concept; Theories of Learning: Conditioning, Social Learning, Managerial Implication of Learning Theories. Reinforcement.

Motivation: Concept, Major Theories and Process of Motivation: Maslow's Need-Hierarchy Theory; Herzberg's Motivation-Hygiene Theory; McGregor's Theory X and Theory Y; Goal-Setting Theory; ERG Theory; Vroom's Expectancy Theory; Equity Theory; Managerial implications of Various Theories.

UNIT II

15 Hours

Leadership: Concept and Functions; Style and Theories of Leadership: Traits, Behavioural and Situational/ Contingency Groups of Theories; Inspirational approaches to Leadership; Charismatic Leadership, Transformational Leadership, and Transactional Leadership, Contemporary Leadership Roles; Challenges to the Leadership Construct; Substitutes and Neutralizers to Leadership.

Group Behaviour: Groups: Concept and Classification; Stages of Group Development; Group Structure; Roles and Norms; Premise and Issues; Group Decision-Making: Group vs Individual;

Groupthink and Groups Shift; Group Decision Making Techniques and Process.

Conflict Management: Concept; Causes; Types; Stages; Effects; Management of Conflicts.



Organizational Culture: Concept; Dominant Culture; Strong vs Weak Cultures ; Creating and Sustaining Culture; Employees Learning of The Culture; Creating a Customer-Responsive Culture.

Organizational Changes: Concept and Forces for Change; Managing Planned Changes; Resistance to Change; Approaches to Manage Organizational Change; Organizational Development;

Culture-Boundedness of Managing the Change.

Cour	se Outcomes:	At the end	of the	course	student wil	l be able to	

- **1.** Describe the Nature and Characteristics, Determinants and Approaches of Organizational Behaviour. Describe the concepts of Perception, Attitudes and values and their implications.
- **2.** Describe the concepts of learning and motivation along with their managerial implications.
- **3.** Describe the concepts of Leadership along with their managerial implications.
- **4.** Discuss the concepts of group dynamics and conflict management along with their implications.
- **5.** Discuss the concepts of Organization culture and change and conflict management along with their implications.

Course Outcomes Mapping with Program Outcomes

Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes→												
↓ Course												
Outcomes												
MG1504-1-1.1	2	1	1	-	1	-	1	1	3	1	-	-
MG1504-1-1.2	2	-	1	-	-	-	-	-	3	1	-	-
MG1504-1-1.3	1	-	-	-	-	-	-	-	3	1	-	-
MG1504-1-1.4	3	1	1	-	-	-	-	-	3	1	-	-
MG1504-1-1.5	1	-	-	-	-	_	-	-	-	1	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:							
1.	Robbins, SP Stephen P, Timothy Judge and Nehasika Vohra, "Organisational						
	Behaviour", 12th or 16th edition, Pearson Education, 2011.						
2.	Fred Luthans, "Organisational Behaviour", 11th edition, Mc Graw Hill, 2009.						
REFERE	NCE BOOKS:						
1.	W. Newstrom, John, "Organisational Behaviour", 10 th edition, Tata Mc Graw –Hill						
	2009.						
2.	Paul Heresy, Kenneth H. Blanchard, and Dewey E. Johnson, "Management of						
	Organisational Behaviour", Leading Human Resources, 2008.						
3.	Dr S S Khanka, "Organisational Behaviour", S. Chand & Co, New Delhi, 2008.						
4.	Sanghi Seema, "Organisational Behaviour", Pearson, 2011.						
	TAXATION FOR ENGINEERS						

Cou	rse Code:	MG1505-1	Course Type	OEC					
Teac	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03					
Tota	al Teaching Hours	40	CIE + SEE Marks	50+50					
	Teaching D) Department: N	lanagement						
Cours	Course Objectives:								
1.	To make students understand the overview of Income Tax Law in India.								
2.	To make students understand	l the basic con	cepts of income tax su	ch as residential					
	status, tax incidence.								
3.	To make students understand	l the income ta	x provisions involved i	n determination					
	of income from salary, House	e property, bus	iness and profession, o	capital gain and					
	other sources.								
4.	To help students understand	the determinat	ion of tax liability Indiv	idual assessees.					
5.	To make students understand	the deduction	s u/s 80.						

UNIT-I

Basic concepts and Explanation under various Heads of Income 15 Hours

Basic concepts: Assessment Year, Previous Year, Person, Assessee, Income, Charges on Income, Gross Total Income, Capital and Revenue Receipts, Residential status, Connotation of income, Deemed to accrue or arise in India, Incidence of tax, Tax Planning, Tax Evasion, Tax Management. (Problems on Residential Status of Individual assessee)

Explanation under various Heads of Income: Income from Salary (theory, basic and full-fledged problems on allowances, perquisites and retirement benefits)

UNIT II

Income under the head Profit and gains of Business or Professions and 15 Hours Income under Capital Gain

Income under the head Profit and gains of Business or Professions and its computation - basis - Method of accounting - Scheme of business deductions/ allowance - Deemed profits maintenance of books, (Problems on computation of Income from Business/ Profession of Individual assessee)

Income under Capital Gain: Basis of charge, Transfer of capital asset, inclusion & exclusion from Capital Asset, Capital Gain, Computation of Capital Gains (theory & problems), Exemptions/deductions from capital gains

UNIT III						
Income from House Property and Other Sources	10 Hours					
Income from House Property - Basic problems on House Property						
Income from Other Sources (theory only)						
Deductions under section 80C to 80U (No problems - Provisions only)						
Course Outcomes: At the end of the course student will be able to						

course outcomes. At the end of the course student will be usie to					
1.	Exhibit an understanding of the Income Tax Law in India.				
2.	Identify the nature of Incomes and their tax incidence.				
3.	Demonstrate how to determine the income from salary, house property, business and				
	profession, capital gain.				

- 4. Demonstrate the determination of tax liability of Individual assessees.
- 5. Exhibit a clear understanding of various provisions of deductions u/s 80.

Course Outcomes Mapping with Program Outcomes

Program	1	2	3	4	5	6	7	8	9	10	11	12									
Outcomes→																					
↓ Course																					
Outcomes																					
MG1505-1-1.1	2	-	-	-	-	1	-	-	1	-	2	1									
MG1505-1-1.2	2	-	-	-	-	1	-	-	1	-	2	1									
MG1505-1-1.3	3	-	-	-	-	1	-	-	1	-	2	1									
MG1505-1-1.4	3	-	-	-	-	1	-	-	1	-	2	1									
MG1505-1-1.5	3	I	-	-	I	1	I	I	1	-	2	1									

1: Low 2: Medium 3: High

REFERENCE BOOKS:

NITTE

1.	Vinod Singhania, "Students Guide to Income Tax", Taxman Publications.
2.	Mehrotra & Goyal, "Direct Tax", Sahitya Bhavan.
3.	Lal & Vashisht, "Direct Tax", Pearson Ed. 28E.
4.	V S Datey, "Indirect Taxes", Taxman Publications.
5.	Vinod Singhania, "Direct Taxes", Taxman Publications.
6.	T N Manoharan, "Students Guide to Income Tax", Snow White.
7.	Kul Bushan, "How to deal with VAT", Pearson Education/PHI, 1/e.
8.	Mahesh Chandra & Shukla , "Income Tax Law & Practice", Pragathi Publications.
9.	Dr.Pillai, "VAT", Jaico Publications.



WORKING CAPITAL MANAGEMENT									
Course Code:	MG1506-1	Course Type	OEC						
Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03						
Total Teaching Hours	40	CIE + SEE Marks	50+50						

Need of the Course: The course will enable the student to manage activities in the area of working capital in an enterprise and help the students to do advance study in the field of financial-management through detailed analysis of financial statements, liquidity crises, cash optimization, credit analysis etc. The student will learn how to apply sound techniques for managing inventory.

Description of the Course: Every business needs adequate liquid resources in order to maintain day-to-day cash flow. It needs enough cash to pay wages and salaries as they fall due and to pay creditors if it is to keep its workforce and ensure its supplies. Maintaining adequate working capital is not just important in the short-term. Sufficient liquidity must be maintained in order to ensure the survival of the business in the long-term as well. Even a profitable business may fail if it doesn't have adequate cash flow to meet its liabilities as they fall due.

Teaching Department: Management

Cours	Course Objectives:								
1.	Discuss the importance of working capital management.								
2.	Evaluate working capital requirement.								
3.	Assess the challenges faced in managing working capital in domestic and international operations.								
4.	Plan for financing working capital requirement.								

UNIT-I

Working Capital Decisions, Working Capital Management and Sources of Working Capital

15 Hours

Working Capital Decisions: Meaning, Concepts, components Importance & types of working Capital.

Working Capital Management: Meaning, objectives, Principles, Importance of adequate working capital & consequences of inadequate working capital, Dangers of excessive working capital, determinants of working capital - operating cycle and Cash cycle. Approaches to determine an appropriate financing mix, Estimation of working capital requirements (problems) important working capital ratios.

Sources of Working Capital: Financing of long term working capital & short term working capital. Factoring - Meaning mechanism, Functions, types, merits & demerits.

UNIT II	
Liquidity Management and Receivable Management	15 Hours
Liquidity Management: Cash Management - Meaning - Objectives of Cash N	lanagement -
Nature of Cash - Motives of holding cash - Cash Management planning a	spects - Cash
Budgets (Problems), Cash Management control aspects - Concentration banki	ng - Lock box



Inventory Management

system - Playing the float - Cash Management models - William J Baumol Model - Miller-Orr Model (Problems using these models)

Receivable Management: Definition, Objectives, cost and benefits of receivable. Credit policy & its variables. Types of Credit policy & their merits & demerits, Factors influencing the size of investment in receivables. Control of receivables. Framing optimum credit policy & Average collection period (Problems)

UNIT III

10 Hours

Meaning of Inventory - Need/Purpose of holding inventory - Benefits of holding inventory - Risk and cost of holding inventory - Management of Inventory - Objectives of Inventory Management - Techniques of Inventory Management - Economic Order Quantity (EOQ) - Determination of Stock levels - ABC analysis - Just in Time (JIT).

1.	Understand the meaning of working capital							
2.	Realize the importance of management of working capital in an organization							
3.	Learn about some key liquidity ratios used to understand more about a business' working capital position							
4.	Understand various techniques used to manage working capital.							
5.	Be aware of the techniques of cash, inventory and receivables management.							

Course Outcomes Mapping with Program Outcomes

outcomes mapping with Frogram outcomes													
Program	1	2	3	4	5	6	7	8	9	10	11	12	
Outcomes→													
↓ Course													
Outcomes													
MG1506-1-1.1	2	1	1	-	-	1	-	1	-	1	2	1	
MG1506-1-1.2	2	-	-	-	-	1	-	-	-	1	2	1	
MG1506-1-1.3	2	-	-	-	-	1	-	-	-	1	2	1	
MG1506-1-1.4	2	1	-	-	-	1	-	-	-	1	2	1	
MG1506-1-1.5	2	-	-	-	-	1	-	-	-	1	2	1	

1: Low 2: Medium 3: High

REFERE	NCE	BOOK	(S:

1.	Sekhar Satya G.V., "Working Capital Management", 1/e; New Delhi: Wiley, 2014.
2.	Bhalla V. K., "Working Capital Management", 1/e; New Delhi: S. Chand Publishing,
	2014.
3.	Sagner James S., "Working Capital Management, Applications and Cases", 1/e, New
	Delhi: Wiley, 2015.



	ENGINEERING ECONO	MICS & FIN	ANCIAL MANAGEN	/IENT				
Cour	se Code:	MG1507-1	Course Type	OEC				
Teac	hing Hours/Week (L: T: P: S)	3:0:0:0	Credits	03				
Tota	I Teaching Hours	40	CIE + SEE Marks	50+50				
	Teaching Depar	tment: Mecha	nical Engineering					
Cours	e Objectives:							
<u>1.</u>	Analyse the time value of mo	nev						
2.	Evaluate the worth of creation		n the alternatives visa vi	is the cost (cost-				
	benefit analysis).	s, sy company	g the alternatives visa, vi					
3.	Take decisions with the limited	d resources, the	relevant course of action	on, with the help				
	of suitable tools.	,		· · · · · · · · · ·				
4.	Determine the depreciated va	lues of assets a	nd also cost involved in	each operation,				
	a product should undergo with an aim to fix suitable selling price for the products.							
5.	Know the fundamentals of Fir			·				
		UNIT-I		1				
Funda	amental economic concepts			07 Hours				
	imer goods, Producer goods, Fa	•						
-	/, Law of demand, Exceptions to			inants of supply				
	f increasing returns and law of d	iminishing retu	rns(No exercises)					
Inter				07 Hours				
	of interest, Determining rate of int			•				
	st, Nominal and effective interes	•	5					
-	e payment, uniform series and	-	radient only], problem	is using interes				
formu	lae [discrete compounding only]							
		UNIT II						
Econe	omic Analysis of Alternatives			09 Hours				
	sis based on: Present Worth [ed	qual life and ur	equal life situations], F	uture Worth,				
,	alent Annual Worth, Exercises. A	•	•					
	eciation			04 Hours				
Cause	es of depreciation, Depletion, N	Methods of de	preciation [Straight lir	ne, Declining				

Causes of depreciation, Depletion, Methods of depreciation [Straight line, Declining balance, Double declining balance] Exercises. 03 Hours

Estimating and Costing

Components of cost [Material cost, Labour cost, Overhead expenses, Prime cost, Factory cost, Total cost], Determination of selling price of a product, Exercises.

UNIT III				
Financial management	05 Hours			
Terminologies used in accounting, Journal and ledger, Profit and loss statement, Balance sheet,				
Understanding basic financial ratios, Simple exercises.				
Working Capital Management	05 Hours			



Factors influencing working capital requirement, determination of operating cycle and working capital.

Capital Budgeting: Risk analysis in Capital Budgeting

Cour	Course Outcomes: At the end of the course student will be able to									
1.	Explain the fundamental economic concepts.									
2.	Use simple interest and compound interest to determine compounded and									
	discounted amount.									
3.	Compare the alternatives using Present Worth, Equivalent Annual Worth, Future Worth									
	and IRR methods.									
4.	Calculate the depreciated amount of a given assets using Straight line, Declining									
	balance, Double declining g balance method. Estimate the selling price of given									
	product.									
5.	Prepare Balance Sheet & Profit and Loss account for given data of a firm. Estimate									
	working capital. Explain capital budgeting.									

Course Outcomes Mapping with Program Outcomes

-		-										
1	2	3	4	5	6	7	8	9	10	11	12	
3	1	-	-	-	1	-	-	1	1	-	1	
2	3	-	-	-	1	-	-	1	1	-	1	
2	3	-	-	-	1	-	-	1	1	-	1	
2	3	-	-	-	1	-	-	1	1	-	1	
2	3	-	-	-	1	-	-	1	1	-	1	
	1 3 2 2 2	1 2 3 1 2 3 2 3 2 3 2 3	1 2 3 3 1 - 2 3 - 2 3 - 2 3 - 2 3 -	1 2 3 4 3 1 - - 2 3 - - 2 3 - - 2 3 - - 2 3 - - 2 3 - -	1 2 3 4 5 3 1 - - - 2 3 - - - 2 3 - - - 2 3 - - - 2 3 - - - 2 3 - - -	3 1 1 2 3 1 2 3 1 2 3 1 2 3 1 2 3 1	1 2 3 4 5 6 7 3 1 - - - 1 - 2 3 - - - 1 - 2 3 - - - 1 - 2 3 - - - 1 - 2 3 - - - 1 - 2 3 - - - 1 -	1 2 3 4 5 6 7 8 3 1 - - - 1 - - 2 3 - - - 1 - - 2 3 - - 1 - - 2 3 - - 1 - - 2 3 - - 1 - - 2 3 - - 1 - -	1 2 3 4 5 6 7 8 9 3 1 - - 1 - - 1 2 3 - - 1 - - 1 2 3 - - 1 - - 1 2 3 - - 1 - - 1 2 3 - - 1 - - 1 2 3 - - 1 - - 1	1 2 3 4 5 6 7 8 9 10 3 1 - - 1 - - 1 1 2 3 - - 1 - - 1 1 2 3 - - 1 - - 1 1 2 3 - - 1 - - 1 1 2 3 - - 1 - - 1 1 2 3 - - 1 - - 1 1	1 2 3 4 5 6 7 8 9 10 11 3 1 - - 1 - - 1 1 - 2 3 - - 1 1 - 1 1 - 2 3 - - 1 1 - 1 1 - 2 3 - - 1 1 - 1 1 - 2 3 - - 1 1 - 1 1 - 2 3 - - 1 1 - 1 1 - 2 3 - - 1 - 1 1 -	1 2 3 4 5 6 7 8 9 10 11 12 3 1 - - 1 - - 1 1 - 1 2 3 - - 1 1 - 1 1 - 1 2 3 - - 1 - - 1 1 - 1 2 3 - - 1 - - 1 1 - 1 2 3 - - 1 - - 1 1 - 1 2 3 - - 1 - 1 1 - 1 2 3 - - 1 - 1 1 - 1

1: Low 2: Medium 3: High

TEXTBOOKS:

1.	Riggs J.L., "Engineering Economics", 4th edition, Tata McGraw-Hill, 2004.								
2.	Banga and Sharma, "Mechanical Estimating and Costing", 16 th edition, Khanna								
	Publishers, 2012.								
3.	I M Pandey, "Financial Management", Vikas Publishing House, 2002.								

REFERENCE BOOKS:

1.	E Paul Degarmo, "Engineering Economy", Macmillan Publishing, 2001.
2.	Gerald J Thuesen & W J Fabrycky, "Engineering Economy", Prentice Hall of India, 9th
	ed.
3.	Tarachand, "Engineering Economics", Nemchand & Bros, 1996.

E Books / MOOCs/ NPTEL

1. http://nptel.ac.in/courses/112107209/

-	NAN	IOTECHNOL	OGY						
Course Co	ode:	PH2501 -1	Course Type	OEC					
Teaching	Hours/Week (L: T: P: S)	3:0:0:0	Credits	03					
	ching Hours	40	CIE + SEE Marks	50+50					
Prerequis	ite	PH1001 -1							
	Teaching	Department:	PHYSICS						
Course Ob	jectives:								
1 . To u	inderstand the basic scien	tific concepts	of nanoscience, prope	rties of nano					
mate	erials, synthesis and fabrica	tion of nano ma	aterials.						
2. To u	nderstand the various char	acterization tec	hniques of nano materi	als.					
3. Stud	y of carbon nano technolog	gy and its chara	octerizations.						
4. To u	nderstand the applications	of nano techno	ology in various science	, engineering					
and	technology fields.								
		UNIT-I							
Properties	of Materials			07 Hours					
Introductio	n: History of nano scienc	e, definition o	of nano meter, nanom	naterials, nano					
technology	. Classification of nano ma	terials. Crystal	symmetries, crystal dire	ections, crystal					
planes, Ban	d structure.								
Properties	Of Materials: Mechanical p	properties, elect	trical properties, dielec	tric properties,					
thermal pro	perties, magnetic propertie	es, opto electro	nic properties. Effect of	size reduction					
on properti	es, electronic structure of r	ano materials.							
Synthesis a	on properties, electronic structure of nano materials.								
	Synthesis and Fabrication 08 Hou								
Synthesis o	f bulk polycrystalline sampl	0	5 , ,	•					
Synthesis o preparatior	f bulk polycrystalline sampl n of nano particle – Botto	m Up Approac	h – sol gel synthesis,	techniques for hydro thermal					
Synthesis o preparatior growth, thiu	f bulk polycrystalline sampl o of nano particle – Botto o film growth, PVD and CVD	m Up Approac ; Top Down Apj	h – sol gel synthesis, proach – Ball milling, mi	techniques for hydro thermal cro fabrication,					
Synthesis o preparatior growth, thiu lithography	f bulk polycrystalline sampl o of nano particle – Botto o film growth, PVD and CVD o, Requirements for realizin	m Up Approac ; Top Down Apj	h – sol gel synthesis, proach – Ball milling, mi	techniques for hydro thermal cro fabrication,					
Synthesis o preparatior growth, thin	f bulk polycrystalline sampl o of nano particle – Botto o film growth, PVD and CVD o, Requirements for realizin	m Up Approac ; Top Down Apj	h – sol gel synthesis, proach – Ball milling, mi	techniques for hydro thermal cro fabrication,					
Synthesis o preparatior growth, thiu lithography	f bulk polycrystalline sampl o of nano particle – Botto o film growth, PVD and CVD o, Requirements for realizin	m Up Approac ; Top Down App g semiconduct	h – sol gel synthesis, proach – Ball milling, mi	techniques for hydro thermal cro fabrication,					
Synthesis o preparatior growth, thiu lithography for nano stu	f bulk polycrystalline sampl of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizin ructures.	m Up Approac ; Top Down Apj	h – sol gel synthesis, proach – Ball milling, mi	techniques for hydro thermal cro fabrication, vth techniques					
Synthesis o preparatior growth, thin lithography for nano str Characteriz	f bulk polycrystalline sampl of nano particle – Botto of film growth, PVD and CVD y, Requirements for realizin ructures. zation Techniques	m Up Approac ; Top Down App g semiconduct UNIT-II	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov	techniques for hydro thermal cro fabrication, vth techniques 15 Hours					
Synthesis o preparatior growth, thiu lithography for nano stu Characteri X-Ray diffra	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizin fructures. Exation Techniques Action and Scherrer method	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron					
Synthesis o preparatior growth, thiu lithography for nano stu Characteri X-Ray diffra microscopy	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizin fructures.	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micr	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron oscopy (AFM),					
Synthesis o preparatior growth, thiu lithography for nano stu Characteri X-Ray diffra microscopy piezorespo	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures. zation Techniques faction and Scherrer method of (TEM), scanning probe r nse microscopy, X-ray ph	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micro ectroscopy, XANES an	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle					
Synthesis o preparatior growth, thiu lithography for nano str Characteri X-Ray diffra microscopy piezorespo resolved p	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures.	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp by, diffuse refle	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micro ectroscopy, XANES an ectance spectra, photo	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence					
Synthesis o preparatior growth, thin lithography for nano str Characteriz X-Ray diffra microscopy piezorespo resolved p spectra, U	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures. zation Techniques action and Scherrer method of (TEM), scanning probe r nse microscopy, X-ray ph hotoemission spectroscop V-VIS-IR Spectrophotome	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp by, diffuse refle	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micro ectroscopy, XANES an ectance spectra, photo	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence					
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Synthesis o preparatior growth, thin lithography for nano str Characteriz X-Ray diffra microscopy piezorespo resolved p spectra, U	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures. zation Techniques action and Scherrer method of (TEM), scanning probe r nse microscopy, X-ray ph hotoemission spectroscop V-VIS-IR Spectrophotome	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp py, diffuse refle ters, Magnetic	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micro ectroscopy, XANES an ectance spectra, photo	techniques for hydro thermal cro fabrication, vth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence					
Synthesis o preparatior growth, thiu lithography for nano stu Characteri X-Ray diffra microscopy piezorespo resolved p spectra, U' Infrared/ Ra	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizin fructures. zation Techniques action and Scherrer method of (TEM), scanning probe r nse microscopy, X-ray ph hotoemission spectroscop V-VIS-IR Spectrophotome aman, EPR and NMR	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp by, diffuse refle	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micro ectroscopy, XANES an ectance spectra, photo	techniques for hydro thermal cro fabrication, wth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence urements and					
Synthesis o preparatior growth, thir lithography for nano str Characteriz X-Ray diffra microscopy piezorespo resolved p spectra, U ^T Infrared/ Ra Carbon Na	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures.	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp by, diffuse refle ters, Magnetic UNIT-III	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micr ectroscopy, XANES an ectance spectra, phote and electrical meas	techniques for hydro thermal cro fabrication, wth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence urements and 05 Hours					
Synthesis o preparatior growth, thiu lithography for nano stu Characteri X-Ray diffra microscopy piezorespo resolved p spectra, U' Infrared/ Ra Carbon Na Characteriz	f bulk polycrystalline sample of nano particle – Botto of film growth, PVD and CVD of, Requirements for realizing fuctures. zation Techniques action and Scherrer method of (TEM), scanning probe rest not and Scherrer method of (TEM), scanning probe rest not and Scherrer method of (TEM), scanning probe rest not and Scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not second scherrer method of (TEM), scanning probe rest not scherer method of (TEM), scanning pr	m Up Approac ; Top Down App g semiconduct UNIT-II , scanning elect nicroscopy (SE otoelectron sp by, diffuse refle ters, Magnetic UNIT-III	h – sol gel synthesis, proach – Ball milling, mi or nano structure, grov ron microscopy, transm M), atomic force micr ectroscopy, XANES an ectance spectra, phote and electrical meas diamond – nucleation	techniques for hydro thermal cro fabrication, wth techniques 15 Hours hission electron oscopy (AFM), d XAFS, angle oluminescence urements and 05 Hours n of diamond,					
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N

NITTE



Applications in material science, biology and medicine, surface science, energy and environment. Applications of nano structured thin films, applications of quantum dots.

Course Outcomes: At the end of the course student will be able to

- **1.** Ability to choose the appropriate nano material to meet the requirerment of a particular application.
- **2.** Identify the essential concepts used in nanotechnology.
- **3.** Identify the materials, properties, synthesis and fabrication of nanomaterials.
- 4. Understand the various characterization techniques of nano materials.
- **5.** Applications of nanomaterials in various fields

Course Outcomes Mapping with Program Outcomes

Program	1	2	3	4	5	6	7	8	9	10	11	12
Outcomes→												
↓ Course												
Outcomes												
PH2501-1.1	3	3	-	-	1	-	-	-	-	-	-	-
PH2501-1.2	3	3	-	-	-	-	-	-	-	-	-	-
PH2501-1.3	3	3	-	-	-	-	-	-	-	-	-	-
PH2501-1.4	3	3	-	_	-	-	-	-	_	-	-	-
PH2501-1.5	3	3	-	-	-	-	-	-	-	-	-	-

1: Low 2: Medium 3: High

TEXTBOOKS:

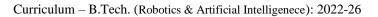
1. M.S. Ramachandra Rao, Shubra Singh, "Nano science and nano technology", Wiley publishers.

REFERENCE BOOKS:

- **1.** Charles P. Poole, Jr. Frank J. Owens, "Introduction to Nano Technology", Wiley publishers.
- **2.** Jermy J Ramsden, "Nanotechnology", Elsevier publishers.
- **3.** A. K. Bandyopadhyay, "Nano Materials", New Age publishers.
- **4.** T. Pradeep, "Nano Essentials", TMH.
- **5.** M. A. Shah, "Nanotechnology the Science of Small", Wiley publishers.
- **6.** Phani Kumar, "Principles of Nanotechnology", Scitech.

E Books / MOOCs/ NPTEL

- **1.** https://youtu.be/ebO38bbq0_4
- 2. https://youtu.be/0MzIh7wkgMs





OPTOELECTRONIC DEVICES

		-		
Course Code:		PH2502-1	Course Type	OEC
Teaching Hours/W	/eek (L: T: P: S)	3:0:0:0	Credits	03
Total Teaching Ho	urs	40	CIE + SEE Marks	50+50
Prerequisite		PH1001 -1	•	·
Teaching Departme	ent: PHYSICS			
Course Objectives:				
1. To understand	d the basic princi	iples of constr	uction, working and a	applications of
various optoe	lectronic devices.			
2. Study of source	ces of radiation lik	e lasers and LE	D, their specific proper	ties and hence
their use for a				
=		ke semiconduc	tor detector, diode as	detector and
photo multipl				
	-		s of optical fibers, optic	cal modulators
and waveguid	les for optical com			
• • •		UNIT-I		
			es & Optical fibers	
	•			
Elements of optica	tructure, direct aı	nd indirect ba	nd gap semiconducto	ors, generation-
Elements of optical distribution, band s				
•			processes.	
distribution, band s recombination mech	anisms, absorptio	n and emissior	-	devices, plasma
distribution, band s recombination mech Display devices- cat	anisms, absorptio	n and emissior	processes. play, charge coupled o	devices, plasma
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distribution, band s recombination mech Display devices- cath display. Optical fibers- types	anisms, absorptio hode ray tube, liq of fibers, modes	n and emissior Juid crystal dis	olay, charge coupled o	
distribution, band s recombination mech Display devices- cath display. Optical fibers- types	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages.	n and emissior Juid crystal dis of propagatior	olay, charge coupled o	
distribution, band si recombination mech Display devices- cath display. Optical fibers- types communication syste Optical Sources and	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages. d Detectors	n and emission Juid crystal dis of propagatior UNIT-II	olay, charge coupled on, attenuation and loss	es, optical fiber
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distribution, band si recombination mech Display devices- cath display. Optical fibers- types communication syste Optical Sources and Lasers- basic princip Nd-YAG, CO2, Exc heterojunction laser, Light emitting diode-	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages. d Detectors les, optical resona imer laser, Sem quantum well lase electroluminesce	n and emission Juid crystal dis of propagation UNIT-II tor-types, moc hiconductor la er, applications ince in p-n junc	olay, charge coupled on a, attenuation and loss les and quality factor, ser- basic structure, tion, LED characteristic	es, optical fiber 15 Hours practical lasers- laser action,
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distribution, band si recombination mech Display devices- cath display. Optical fibers- types communication syste Optical Sources and Lasers- basic princip Nd-YAG, CO2, Exc heterojunction laser, Light emitting diode- responsivity, Heteroj Photo detectors- ph avalanche photo dio Integrated Optics a Modulation of light- Semiconductor diod effect), Electro-abso structure, waveguide	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages. I Detectors les, optical resona timer laser, Sem quantum well lase electroluminesce unction LED, Surfa noto conductor d de. Photo multipli nd Modulators - Analog and digi e laser (SDL). Exte rption modulators e devices – wave	n and emission Juid crystal dis of propagation UNIT-II tor-types, moc hiconductor la er, applications ince in p-n junc ace-Emitting LE letector, junction er tube. UNIT-III tal modulation rnal modulation s. Acousto-opt guide lenses,	play, charge coupled on a, attenuation and loss les and quality factor, ser- basic structure, tion, LED characteristic D and Edge emitting L on photo diode, p-i-r on photo diode, p-i-r n - Electro-optic modulation - n - Electro-optic modulation ic modulation. Wave ight bending devices,	es, optical fiber 15 Hours practical lasers- laser action, s, efficiency and ED. n photo diode, using LED and ulators (Pockels eguides- device , optical power
distribution, band si recombination mech Display devices- cath display. Optical fibers- types communication syste Optical Sources and Lasers- basic princip Nd-YAG, CO2, Exc heterojunction laser, Light emitting diode- responsivity, Heteroj Photo detectors- ph avalanche photo dio Integrated Optics a Modulation of light- Semiconductor diod effect), Electro-abso structure, waveguide dividers, directiona	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages. d Detectors les, optical resona timer laser, Sem quantum well lase electroluminesce unction LED, Surfa noto conductor d de. Photo multipli nd Modulators - Analog and digi e laser (SDL). Exte rption modulators e devices – wave l couplers, wav	n and emission puid crystal dis of propagation UNIT-II tor-types, moc niconductor la er, applications nce in p-n junc ace-Emitting LE letector, junction er tube. UNIT-III tal modulation rnal modulation s. Acousto-opt guide lenses, la eguide polari	play, charge coupled on a, attenuation and loss les and quality factor, ser- basic structure, tion, LED characteristic D and Edge emitting L D and Edge emitting L on photo diode, p-i-r n photo diode, p-i-r n - Electro-optic modu ic modulation. Wave ight bending devices, zer, wavelength mu	es, optical fiber 15 Hours practical lasers- laser action, s, efficiency and ED. n photo diode, using LED and ulators (Pockels eguides- device , optical power
distribution, band si recombination mech Display devices- cath display. Optical fibers- types communication syste Optical Sources and Lasers- basic princip Nd-YAG, CO2, Exc heterojunction laser, Light emitting diode- responsivity, Heteroj Photo detectors- ph avalanche photo dio Integrated Optics a Modulation of light- Semiconductor diod effect), Electro-abso structure, waveguide	anisms, absorptio hode ray tube, liq of fibers, modes em, advantages. d Detectors les, optical resona imer laser, Sem quantum well lase electroluminesce unction LED, Surfa noto conductor d de. Photo multipli nd Modulators - Analog and digi e laser (SDL). Exte rption modulators e devices – wave l couplers, wav eguide coupling. (n and emission puid crystal dis of propagation UNIT-II tor-types, moc niconductor la er, applications nce in p-n junc ace-Emitting LE letector, juncti- er tube. UNIT-III tal modulation rnal modulation s. Acousto-opt guide lenses, la eguide lenses, la potoelectronic	play, charge coupled on a, attenuation and loss les and quality factor, ser- basic structure, tion, LED characteristic D and Edge emitting L on photo diode, p-i-i on photo diode, p-i-i n - Electro-optic modu ic modulation. Wave ight bending devices, zer, wavelength mu integrated circuit	es, optical fiber 15 Hours practical lasers- laser action, s, efficiency and ED. n photo diode, using LED and ulators (Pockels eguides- device , optical power

NIT						C	urricu	ılum -	- B.Te	ch. (F	Robotics	& Artif	icial Inte	lligene
1.	Ability to choose the	арр	propi	iate	dev	ice t	o me	eet t	he r	equi	remer	nt of	a part	ticula
	application.		•							•			•	
2.	Making modifications	s to	devi	ce st	ruct	ures	by ι	unde	erstai	ndin	g the	facto	rs affe	ectin
	their performance.						-				_			
3.	Attempting better eff	icier	ісу а	nd u	tility	thro	bugh	an	unde	ersta	nding	of th	e prin	ciple
	of performance.													
4.	Use the technical kn	owle	edge	асс	quire	d to	tro	uble	shoc	ot ar	nd rec	tify c	device	s an
	circuits.													
5.	Explore the possibility	of of	desig	Ining	g dev	vices	with	bet	ter c	hara	cteris	tics.		
Cour	se Outcomes Mapping				1			I		_		<u>г</u>	T	1
	Program	1	2	3	4	5	6	7	8	9	10	11	12	
	Outcomes→													
	↓ Course													
	Outcomes	2												_
	PH2502-1.1	3	3	-	-	-	-	-	-	-	-	-	-	
	PH2502-1.2	3 3	3	-	-	-	-	-	-	-	-	-	-	_
	PH2502-1.3	-	3	-	-	-	-	-	-	-	-	-	-	
	PH2502-1.4	3	3	-	-	-	-	-	-	-	-	-	-	_
1.1.	PH2502-1.5	3	3	-	-	-	-	-	-	-	-	-	-	
1: LO	w 2: Medium 3: High													
ТЕХТ	BOOKS:													
1.	P.R.Sasikumar, "Pho	tonia	<u>-</u> s – a	n in	trod	uctic	n". P	нті	earn	ina F	Pvt I to	d.Nev	w Delh	ni. 20
	edition.						, .					,		, _•
2.	Pallab Bhattacharya	, "S	emic	ond	ucto	r Op	oto E	lect	ronic	: De	vices"	, Prei	ntice	Hall
	India Pvt., Ltd., New													
REFE	RENCE BOOKS:													
1.	J.Wilson and J.Hauk	es, "	'Opt	o ele	ectro	nics	- an	intro	oduc	tion'	', Prer	ntice	Hall o	f Inc
	New Delhi.													
2.	Jasprit Singh, '"Op	to e	elect	ronic	cs- a	an ir	ntroc	lucti	on t	to N	lateri	als ai	nd De	evice
	McGraw Hill interna													
3.	A.Ghatak and Thy	-	-	ז, "]	Intro	duct	ion	to	opt	o e	lectro	nics",	Nev	v A
	International Publica	atior	۱.											
	• • • • • • • • • • • • • • • • • • • •													
	oks / MOOCs/ NPTEL													
1.	http://nptel.ac.in/co	urco	c/11	5102	2026	/								



Car		IOUS MOBI	LE ROBOTS	
	urse Code:	RI2501-1	Course Type	OEC
Теа	ching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
Tot	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	requisite	EC 1001-1,	ME 1003-1	
	Teaching Department	: Robotics and	d Artificial Intelligend	ce
Cou	rse Objectives:			
1.	Explain different types of locom	notion in mobi	le robots to obtain a re	equired task.
2.	Understand the different types	of kinematics	s and dynamics involv	ved in a mobile
	robot.		-	
3.	Study the different types of sen	sors used in a	n autonomous mobile	robot.
4.	Understand the different types	of algorithms	to identify the positio	n of the mobile
	robot.	-		
5.	Understand the various algorith	ms for plannir	ng and navigation of th	e mobile robot.
		UNIT-I		
Rob	ot locomotion			07 Hours
Туре	es of locomotion, hopping ro	bots, legged	robots, wheeled r	obots, stability,
man	euverability, and controllability.			-
	bile robot kinematics and dynam	nics		09 Hours
Forw	vard and inverse kinematics, ho	lonomic and	nonholonomic constr	raints, kinematio
mod	lels of simple car and legged robo	ts, dynamics s	imulation of mobile ro	bots.
		UNIT-II		
Perc	eption	UNIT-II		07 Hours
	eption prioceptive/Exteroceptive and pass		sors, performance mea	
Prop	-	ive/active sens	-	sures of sensors,
Prop sens	prioceptive/Exteroceptive and pass	ive/active sens al positioning	system (GPS), Dopp	sures of sensors,
Prop sense sense	prioceptive/Exteroceptive and pass ors for mobile robots like glob	ive/active sens al positioning	system (GPS), Dopp	sures of sensors,
Prop sense sense Loca	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta	ive/active sens al positioning inty in sensing	system (GPS), Dopp , filtering.	isures of sensors, iler effect-based 07 Hours
Prop sense sense Loca Odo	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta	ive/active sens al positioning inty in sensing ef representa	system (GPS), Dopp , filtering. tion, probabilistic m	isures of sensors, iler effect-basec 07 Hours apping, Markov
Prop sense sense Loca Odo	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta Ilization metric position estimation, beli	ive/active sens al positioning inty in sensing ef representa	system (GPS), Dopp , filtering. tion, probabilistic m	isures of sensors, iler effect-based 07 Hours apping, Markov
Prop sense sense Loca Odo	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta Ilization metric position estimation, beli	ive/active sens al positioning inty in sensing ef representa	system (GPS), Dopp , filtering. tion, probabilistic m	isures of sensors, iler effect-based 07 Hours apping, Markov
Prop sense sense Loca Odor local	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta Ilization metric position estimation, beli	ive/active sens al positioning inty in sensing ef representa nan localizatio UNIT-III	system (GPS), Dopp , filtering. tion, probabilistic m	isures of sensors, iler effect-based 07 Hours apping, Markov
Prop sense Loca Odo local Intro Path	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta alization metric position estimation, beli lization, Bayesian localization, Kalr oduction to planning and naviga planning algorithms based or	ive/active sens al positioning inty in sensing ef representa nan localizatio UNIT-III ation n A-star, Dijk	system (GPS), Dopp , filtering. tion, probabilistic m n, and positioning bea stra, Voronoi diagrar	oler effect-based 07 Hours apping, Markov acon systems. 10 Hours ms, probabilistic
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Prop sense Loca Odo local Intro Path road stock	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta alization metric position estimation, beli lization, Bayesian localization, Kalm oduction to planning and naviga planning algorithms based or lmaps (PRM), rapidly exploring rar hastic dynamic programming (SDF	ive/active sens al positioning inty in sensing def representa nan localizatio UNIT-III ation n A-star, Dijk ndom trees (RI P).	system (GPS), Dopp , filtering. tion, probabilistic m n, and positioning bea stra, Voronoi diagrar RT), Markov Decision F	oler effect-based 07 Hours apping, Markov acon systems. 10 Hours ms, probabilistic
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Prop sense Loca Odo local Intro Path road stock	prioceptive/Exteroceptive and pass ors for mobile robots like glob ors, vision-based sensors, uncerta alization metric position estimation, beli lization, Bayesian localization, Kaln oduction to planning and naviga planning algorithms based or maps (PRM), rapidly exploring ran hastic dynamic programming (SDF rse Outcomes: At the end of the of Explain different types of locom	ive/active sens al positioning inty in sensing ef representa nan localizatio UNIT-III ation A-star, Dijk ndom trees (RI P). course student notion in mobil nematics and	system (GPS), Dopp , filtering. tion, probabilistic m n, and positioning bea stra, Voronoi diagrar RT), Markov Decision F t will be able to le robots to obtain a re dynamics involved in a	apping, Markov acon systems. 10 Hours 10 Hours ms, probabilistic Processes (MDP), equired task. a mobile robot.
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	RI2501-1.3	3	3	3	3	2	1	-	-	-	-	-	3	
	RI2501-1.4	3	3	3	3	2	1	-	-	-	-	-	3	
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TEXT	BOOKS:													
1.	R. Siegwart, I. R. Nourl	hakh	sh "	Intro	nduc	tion	to A	utor	omo	א וור	Mohil	e Roh	ots"	The MIT
	Press, 2011.	Jun	511,	111010	Juuc	tion	1071	ator		5451	vio bii			
2.	Peter Corke, "Robotic		icior	<u>, , , , , , , , , , , , , , , , , , , </u>		ntro	l. Ei	Inda	mon	+-1 /	Vlaori	thmc	in M	
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3.	S. M. LaValle, "Planni					Cam	brid	ge u	nive	ersity	Pres	s, 200	J6. (A	vallable
	online http://planning	J.CS.L	liuc.	edu/)									
REFE	RENCE BOOKS:													
1.	Thrun, S., Burgard, W	., an	d Fc	ox, D	., "P	roba	bilis	tic R	obo	tics"	. MIT	Press	, Carr	nbridge,
	MA, 2005.													
2.	Melgar, E. R., Diez, C	. C.,	"Arc	duin	o, ai	nd K	inec	t Pro	oject	s: D	esign,	Build	d, Blo	w Their
	Minds", 2012.													
3.	H. Choset, K. M. Lync	:h, S	. Hu	tchir	nson	, G.	Kant	tor, ۱	W.B	urga	ard, L	. E. Ka	avraki	, and S.
	Thrun, "Principles of F													
	Ltd., 2005.					,	,							,
F Boo	oks / MOOCs/ NPTEL													
1.	https://archive.nptel.a	cin		rcoc	/112	/106	/110	106	202/					
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	MED	ICAL ROBO	TICS	
	·	or All except A		
	urse Code:	RI2502-1	Course Type	PEC
	aching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03
	al Teaching Hours	40	CIE + SEE Marks	50+50
Pre	erequisite		IS 1001-1, CY 1001-1	
	Teaching Department:	: Robotics and	d Artificial Intelligenc	e
	rse Objectives:			
1.	Understand the types of medica			re.
2.	Explain the various localization a	0		
3.	Understand the applications of s			
4.	Understand Rehabilitation of lin	nbs and brain	machine interface with	the help of
	few case studies			
5.	Understand the design methodo	ology of medi	cal robots.	
		UNIT-I		
Intro	oduction			07 Hours
Туре	es of medical robots - Navigation	- Motion Rep	lication - Imaging - Re	habilitation and
Pros	thetics - State of art of robotics in	the field of he	althcare. Localization A	And Tracking
Posi	tion sensors requirements			09 Hours
Trac	king - Mechanical linkages - Opt	ical - Sound-	based - Electromagnet	ic -Impedance-
base	ed - In-bore MRI tracking - Video r	natching - Fib	er optic tracking	
		UNIT-II		
Cont	trol Modes Radiosurgery			07 Hours
Orth	opedic Surgery - Urologic Sur	gery and Ro	botic Imaging - Car	diac Surgery –
Neu	rosurgery – case studies.			
Reha	abilitation			07 Hours
	abilitation for Limbs - Brain-Machi	ne Interfaces -	Steerable Needles – ca	
		UNIT-III		
Desi	gn of Medical Robots			10 Hours
Char	racterization of gestures to the des	ign of robots-	Design methodologies	- Technological
choi	ces - Security			
Cou	rse Outcomes: At the end of the c	course student	: will be able to	
1.	Describe the types of medical r	robots and the	e concepts of navigation	on and motion
	replication.			
2.	Describe about the sensors used	d for localizati	on and tracking	
3.	Explain the applications of surgi	cal robots		
4.	Explain the concepts in Rehabili	tation of limbs	and brain machine int	erface
5.	Classify the types of assistive	e robots and	analyze the design	characteristics,



	Program	1	2	3	4	5	6	7	8	9	10	11	12
	Outcomes→												
	Course												
(Outcomes												
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	RI2502-1.2	3	-	1	-	-	-	-	-	-	-	-	1
	RI2502-1.3	3	-	1	-	-	-	-	-	-	-	-	1
	RI2502-1.4	3	-	1	-	-	-	-	-	-	-	-	1
	RI2502-1.5	3	-	3	-	-	-	-	-	-	-	-	1
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Teaching Hours/Week (L: T: P: S) 3:0:0:0 Credits 03 Total Teaching Hours 40 CIE + SEE Marks 50+50 Prerequisite EE 1001-1, EC 1001-1 Teaching Department: Robotics and Artificial Intelligence Course Objectives: To design various hydraulic system components. 3. To design various pneumatic system components. 3. To design various types of applications in fluid power circuits using PLC. 4. Learn various types of applications of fluid power, Application of fluid power system. Spes of fluid power, Applications of Pascal's Law Vigraulic system components round of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic cutators-Single acting and double acting cylinders, Rotary actuators - Fluid motors.	Course Code:	RI2503-1	Course Type	OEC		
Prerequisite EE 1001-1, EC 1001-1 Teaching Department: Robotics and Artificial Intelligence Course Objectives: 1. To understand the fundamentals of fluid power transmission systems 2. To design various hydraulic system components. 3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits. 5. Learn various types of applications in fluid power circuits using PLC. UNIT-I Fluid power systems and fundamentals for of fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of Pascal's Law Very Mydraulic System components Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators: Single acting and double acting cylinders, Rotary actuators: Enlear thydraulic control valve - valve terminology - Various center positions. Shuttle valve - check ralve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves, Quicl exhaust valves and pneumatic circuit design O7 Hours Ortendomonents 07 Hours Introduction to fluidic devices, simple circuits. Introduction to Electrohydraulic reuit design Orth	Teaching Hours/Week (L: T: P: S)	3:0:0:0	Credits	03		
Teaching Department: Robotics and Artificial Intelligence Course Objectives: 1. To understand the fundamentals of fluid power transmission systems 2. To design various hydraulic system components. 3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits using PLC. Sources of hydraulic and pneumatic power circuits using PLC. UNIT-I Pluid power systems and fundamentals Of Huid power, Advantages of fluid power, Application of fluid power system. Types of fluid power, Advantages of fluids - Properties of hydraulic fluids - Fluid power system. Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic for pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators- Single acting and double acting cylinders, Rotary actuators - Fluid motors. Control Components Of Hours Other system components Other system c		40	CIE + SEE Marks	50+50		
Course Objectives: 1. To understand the fundamentals of fluid power transmission systems 2. To design various hydraulic system components. 3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits. 5. Learn various types of applications in fluid power circuits using PLC. UNIT-I Fluid power systems and fundamentals Introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power, Advantages of fluids - Properties of hydraulic fluids - Fluid Dower systems and fundamentals Introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power system. Types of fluid power system. Types of fluid power system. System components Os Hydraulic System components Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators. Control Components Other transmission system components. UNIT -II <td colspan="2" pr<="" th=""><th>Prerequisite</th><th>EE 1001-1,</th><th>EC 1001-1</th><th></th></td>	<th>Prerequisite</th> <th>EE 1001-1,</th> <th>EC 1001-1</th> <th></th>		Prerequisite	EE 1001-1,	EC 1001-1	
1. To understand the fundamentals of fluid power transmission systems 2. To design various hydraulic system components. 3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits using PLC. 5. Learn various types of applications in fluid power circuits using PLC. INIT-1 Fluid power systems, General types of fluid power, Application of fluid power system. Types of fluid power system. Sonces of Hydraulics-Applications of Pascal's Law Hydraulic system components OF Hydraulic System components Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic fluids -Fluid motors. Control Components Of Hours Direction control valve - Valve terminology - Various center positions. Shuttle valve - check valve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - Fixed and adjustable Safety valves. UNIT-II Pneumatic System components: Properties of air. Compressors. FRL Unit -Air control valves, Quicle schaust valves and pneumatic actuators- cylinders, air motors. Basics of low-cost automation Fluidics & Pneumatic circuit design O7 Hours Pneumatic System components: Prope	Teaching Departmen	t: Robotics and	d Artificial Intelligence	1		
2. To design various hydraulic system components. 3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits. 5. Learn various types of applications in fluid power circuits using PLC. UNIT-I Fluid power systems and fundamentals O6 Hours INTO duction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of fluids - Properties of hydraulic fluids -Fluid power systems. Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators-Single acting and double acting cylinders, Rotary actuators - Fluid motors. Control Components O 4 Hours Direction control valve - Valve terminology - Various center positions. Shuttle valve - check valve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - Fixed and adjustable Safety valves. UNIT-II Pneumatic System components O7 Hours Preumatic circuit design O 4 Hours Control Components UNIT-I	Course Objectives:					
3. To design various pneumatic system components. 4. Learn various types of hydraulic and pneumatic power circuits. 5. Learn various types of applications in fluid power circuits using PLC. UNIT-I Fluid power systems and fundamentals Of Hours INTOduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of fluids - Properties of hydraulic fluids -Fluid power symbols. Basics of Hydraulics-Applications of Pascal's Law Hydraulic system components Sources of Hydraulic duble acting cylinders, Rotary actuators - Fluid motors. Control Components O4 Hours Direction control valve - Valve terminology - Various center positions. Shuttle valve - check valve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - Fixed and adjustable Safety valves. UNIT-II O7 Hours Pneumatic System components O7 Hours LINIT-II Preumatic System components O7 Hours Preumatic System components O7 Hours	1. To understand the fundamenta	ls of fluid powe	r transmission systems			
4. Learn various types of hydraulic and pneumatic power circuits. 5. Learn various types of applications in fluid power circuits using PLC. UNIT-1 Fluid power systems and fundamentals Of Hours Introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of fluids - Properties of hydraulic fluids -Fluid power system components O5 Hours Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators-Single acting and double acting cylinders, Rotary actuators - Fluid motors. Control Components O1 Hours Direction control valve - Valve terminology - Various center positions. Shuttle valve - check valve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - Fixed and adjustable Safety valves. UNIT-II Pneumatic System components O7 Hours Preumatic System components O7 Hours Direction control valve - pressure reducing valve, sequence valve. Flow control valves, quicle exhaust valves and pneumatic actuators- cylinders, air motors.	2. To design various hydraulic syst	tem component	ts.			
5. Learn various types of applications in fluid power circuits using PLC. UNIT-I Fluid power systems and fundamentals O6 Hours introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of fluids - Properties of hydraulic fluids - Fluid sower symbols. Basics of Hydraulics-Applications of Pascal's Law Hydraulic system components Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators-Single acting and double acting cylinders, Rotary actuators - Fluid motors. Control Components O1 44 Hydraulic Power: Pumping theory - Various center positions. Shuttle valve - check ralve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - Fixed and adjustable Safety valves. UNIT-II Pneumatic System components UNIT-II Pneumatic Components: Properties of air. Compressors. FRL Unit -Air control valves, Quicid exhaust valves and pneumatic actuators- cylinders, air motors. Basics of low-cost automation Pneumatic logic circuit, PLC applications in fluid power control, Sequential circuit design UNIT-III Fluidics & Pneumatic circuit design UNIT-III Fluid power circuits UNIT-III Fluid power circuits UNIT-III Fluid power circuits I 10 Hours Components I 10 Hours	3. To design various pneumatic sy	stem compone	nts.			
UNIT-I 06 Hours Fluid power systems and fundamentals 06 Hours introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, General types of fluids - Properties of hydraulic fluids - Fluid power symbols. Basics of Hydraulics-Applications of Pascal's Law Hydraulic system components 05 Hours Sources of Hydraulic Power: Pumping theory - Pump classification - construction and working of pumps - Variable displacement pumps, pump performance. Actuators: Linear hydraulic actuators-Single acting and double acting cylinders, Rotary actuators - Fluid motors. Control Components 04 Hours Direction control valve - Valve terminology - Various center positions. Shuttle valve - check valve - pressure control valve - pressure reducing valve, sequence valve. Flow control valves - fixed and adjustable Safety valves. Pneumatic system components 07 Hours Pneumatic System components 07 Hours Pneumatic Components: Properties of air. Compressors. FRL Unit -Air control valves, Quicle exhaust valves and pneumatic actuators- cylinders, air motors. Basics of low-cost automation Pneumatic logic circuit, PLC applications in fluid power control, Sequential circuit design for simple applications using classic, cascade, logic with Karnaugh- Veitch Mapping and combinational circuit design methods. UNIT-II 10 Hours Electrical control of pneumatic and hydraulic circuits-use of relays, timers, counters, Ladde diagram. Programmable logic cont	4. Learn various types of hydraulic	and pneumation	c power circuits.			
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- **1.** Compare the basics of hydraulics to the performance of fluid power systems
- **2.** Explain the working principle of hydraulic systems including pumps and control components.
- **3.** Explain the working principle of pneumatic systems and their components.
- **4.** Design various types of Electrohydraulic and electro pneumatic circuits
- **5.** Design various types of applications in fluid power circuits using PLC.

Course Outcomes Mapping with Program Outcomes

outcomes mapping			grui										
Program	1	2	3	4	5	6	7	8	9	10	11	12	
Outcomes→													
↓ Course													
Outcomes													
RI2503-1.1	3	2	3	2	3	-	-	-	-	-	-	3	
RI2503-1.2	3	2	3	2	З	-	-	-	-	-	-	3	
RI2503-1.3	3	2	3	2	3	-	-	-	-	-	-	3	
RI2503-1.4	3	2	3	2	3	-	-	-	-	-	-	3	
RI2503-1.5	3	2	3	2	3	-	-	-	-	-	-	3	

1: Low 2: Medium 3: High

TEXTBOOKS:

- **1.** Majumdar S.R., "Pneumatic systems Principles and maintenance", Tata McGraw Hill, 2008.
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- **3.** Michael J, Prinches and Ashby J. G, "Power Hydraulics", Prentice Hall, 2011.
- **4.** Dudelyt, A. Pease and John T. Pippenger, "Basic Fluid Power", Prentice Hall, 2011.

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- 1. https://nptel.ac.in/courses/108/105/108105088/
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